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Posted Date: 7 May 2024

doi: 10.20944/preprints202405.0358.v1

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Article

3-Dimension Epithelial Segmentation in Optical Coherence Tomography of the Oral Cavity Using Deep Learning

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Simple Summary: Diagnosis of oral cancer can require multiple biopsies to increase the likelihood of sampling the most pathologic site within a lesion. Optical coherence tomography (OCT) enables the examination of subsurface morphology and has shown potential in biopsy guidance. OCT captures changes in tissue stratification related to depth, topology, and presence of the epithelial-stromal boundary which are structural biomarkers for pre-invasive and invasive oral cancer. This study presents a neural network pipeline to simplify OCT interpretation by providing information about epithelial depth and stratification through simple *en face* maps. U-net models were employed to segment the boundaries of the epithelial layer, and supporting convolutional neural networks were used for identification of the imaging field and artifacts. Non-cancerous, precancerous, and cancerous pathologies across the oral cavity were evaluated. Predictions demonstrate as-good-as or better agreement than inter-rater agreement, suggesting strong predictive power.

Abstract: Purpose: To simplify the application of optical coherence tomography (OCT) for examination of subsurface morphology in the oral cavity and reduce barriers towards adoption of OCT as a biopsy guidance device. The aim of this work was to develop automated software tools for simplified analysis of the large volume of data collected during OCT. Methods: Imaging and corresponding histopathology were acquired in-clinic using a wide-field endoscopic OCT system. An annotated dataset (n = 294 images) from 60 patients (34 male, 26 female) was assembled to train four unique neural networks. A deep learning pipeline was built using convolutional and modified u-net models to detect the imaging field of view (network 1), detect artifacts (network 2), identify the tissue surface (network 3), and identify the presence and location of the basement membrane (network 4). Results: The area under the curve of the image and artifact detection networks was 1.00 and 0.94 respectively. The Dice similarity score for the surface and basement membrane segmentation networks was 0.98 and 0.83 respectively. Conclusion: Deep Learning (DL) techniques can identify the location and variations in the epithelial surface and basement membrane in OCT images of the oral mucosa. Segmentation results can be synthesized into accessible *en face* maps to allow easier visualization of changes.

Keywords: optical coherence tomography; oral cancer; deep learning; segmentation

1. Introduction

Early detection and diagnosis of cancer improves patient prognosis and potential for successful treatment. In the United States, the 5-year survival rate is 86% for localized head and neck cancers but decreases to 69% for regional cancers and 40% for distant metastatic cancers [1]. Unfortunately, only 28% of head and neck cancers are detected at the localized stage [2]. Screening methods consist

primarily of incisional biopsy and histopathologic examination, which is a burden on both the patient and the healthcare system. The most common treatment for oral cancer is surgical resection; this procedure can result in devastating physiological and psychological effects [3–5].

The multi-step progression of healthy oral mucosa through grades of dysplasia to cancer is very well understood. Dysplastic changes typically originate just above the basement membrane, a thin acellular layer separating the superficial epithelial tissue from the deeper stromal tissue [6]. The World Health Organization (WHO) has identified architectural (presence and degree of epithelial stratification), and cytological (cellular atypia) changes as key indicators of dysplastic progression [7]. Malignant lesions are classified by having breached the basement membrane, surpassing the barrier preventing the spread of cancerous cells into connective tissue, and allowing for potential metastasis [8]. The most prevalent invasive tumor is oral squamous cell carcinoma (OSCC), accounting for over 90% of oral tumors [9]. There are several structural biomarkers for invasive cancer accessible through histological staining, however ensuring that a biopsy sample contains the most pathologic tissue is difficult. Multiple biopsies are often taken to reduce false negatives as the clinical presentation of benign lesions may appear similar to occult lesions [10].

Optical coherence tomography (OCT) is a volumetric imaging technique that generates images through reconstruction of backscattered light from a low coherence source. While the most widespread clinical application of OCT is retinal imaging [11,12], the utility of OCT as an adjunct screening tool for oral cancer has been previously explored [13–16]. OCT allows for non-invasive *in vivo* measurement of epithelial thickness and visualization of architectural changes relating to stratification and structure within the oral cavity [17–19]. Bridging the resolution-gap between ultrasound and microscopy, OCT has an axial resolution of ~5-10 μm , providing information at the microstructure level that was previously only available through biopsy, as morphological features imaged in OCT are strongly correlated to those observed in histology [20]. The primary limitation of OCT is a shallow imaging depth, generally collecting data up to 2-3 mm into tissue. Yet, this depth is comparable to that of histological data collection, making it an excellent tool for examining changes to near-surface tissue [21].

Clinical adoption of oral OCT requires data analysis tools that can provide rapid and reproducible assessment of tissue morphology, as the large volume of data collected during imaging makes manual assessment intractable. This work proposes applying deep learning methodologies for automated assessment of OCT data to extract tissue layer stratification. The intersection of deep learning and image analysis has been documented in OCT applications, with substantial evidence indicating utility in image segmentation [22–26] and image classification [27–29] tasks. We build upon previously presented classical methods for segmentation of oral OCT [30], which were limited in clinical applicability due to poor generalizability and lengthy processing times. There is a gap in the existing literature for image analysis of oral OCT, where no pathology agnostic, site agnostic, rapid and repeatable tool exists to identify structures of interest. We posit that this tool should *not* provide diagnostic suggestions, but instead empower clinical decision-making by providing additional data through easily interpreted visualization of subsurface morphology.

2. Materials and Methods

2.1 Imaging System

Images were collected using a custom-built swept-source OCT system. The system, described previously [15], employs a 1310 ± 50 nm laser (Axsun Technologies) to achieve ~7 μm axial resolution in tissue. A helical scanning pattern is facilitated using a rotary pullback device, which collects images up to 90 mm in length, thus allowing large tissue sites to be collected in a single scan. A single-mode fiber delivers light to and collects light from the sample; during *in vivo* imaging, the optical fiber is packaged into a 1.5 mm diameter catheter which is filled with water to provide refractive index matching and reduce friction during rotation. Two catheter sheath holders were developed to allow imaging of various sites in the oral cavity: a modified dental mirror and a modified saliva injector.

Images are acquired in a 3-dimensional cylindrical coordinate system (Figure 1) that includes radial (z), azimuthal (θ), and pullback (y) axes. Unwrapping the volume along the azimuthal axis and applying a mean intensity projection along the radial (A-line) axis creates a 2-dimensional *en face* projection, shown in (b). Slicing the volume perpendicular to the pullback axis, at the purple dashed line, provides the cross-section shown in (c). Slicing perpendicular to the azimuthal axis, at the red

dashed line, provides the longitudinal view, shown in (d). A magnified inset (yellow dashed box) is shown in (e). The epithelial surface and basement membrane are identified by the white dashed line, highlighting biomarkers of interest for oral cancer visualized through OCT: epithelial thickening and changes in stratification. Co-registered features can be seen in the histology slice in (f), depicting regions of normal and abnormal tissue. These features can be observed in the longitudinal image but are challenging to identify in the *en face* projection. Water-filled catheters sometimes introduce air bubbles into the optical pathway. Air bubbles can be observed in the *en face* (Figure 1 (b), indicated with 'B'), longitudinal and cross section views, and may obscure the tissue underneath.

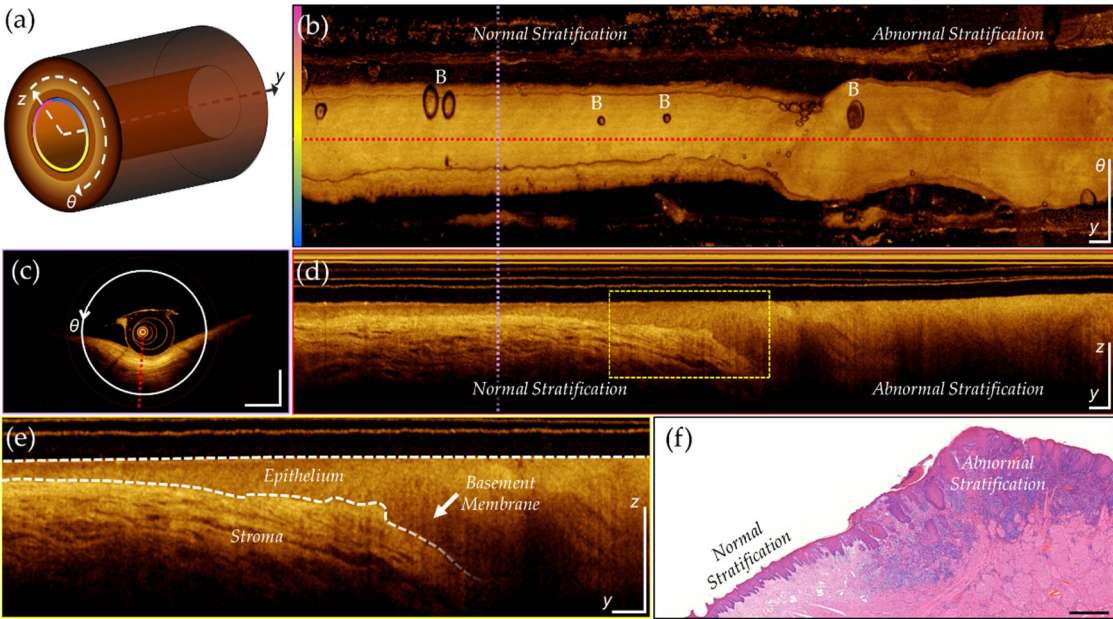


Figure 1. OCT of lateral tongue with biopsy confirmed OSCC. (a) Helical scanning coordinate system illustrating z (A-line), θ (azimuthal, pink to blue color gradient), and y (pullback) axes; (b) *en face* mean intensity projection, unwrapped along pink to blue gradient of (a), with air bubbles marked by B; (c) cross-sectional view at purple dashed line in (b) and (d); (d) longitudinal view at dashed red line in (b); (e) Inset magnified from yellow dashed box in (c), highlighting appearance of epithelial and stromal layers in OCT. Epithelial surface and basement membrane marked by white dashed lines; (f) Histology section with regions of normal and abnormal stratification, with corresponding regions marked in (b) and (d). Scale bars 1 mm.

2.2 Data Collection and Assembly

In vivo imaging of the oral mucosa was approved by the Research Ethics Board of the University of British Columbia and the British Columbia Cancer Agency (H11-02516). Images used in this study were collected from 2014-2017. The most pathologic site was identified, and one to six scans were performed over the lesion (including some tissue before and after the lesion when possible); a contralateral pullback was also taken when possible. If deemed clinically necessary, a biopsy was performed after image collection to confirm diagnosis, which could be co-registered to the OCT.

For this study, 184 volumetric scans were selected from 60 patients (34 male, 26 female). The mean age (M) was 62 years (standard deviation, SD = 14.3). Visual analysis was used to ensure good OCT quality by minimizing the presence of imaging artifacts ($\leq 40\%$ of image). Scans were required to be ≥ 30 mm in length, with pullback speeds ≤ 10 mm/s and azimuthal scan rates of 100 Hz. Each scan contained 504-512 longitudinal images. One patient was held out of the discovery sets for whole-volume evaluation. Up to three longitudinal images (minimum azimuthal separation of 15°) were selected from the remaining scans for annotation. Images included a variety of sites and pathologies to encourage robustness and generalizability, summarized in Table 1 and Table 2.

Table 1. Summary of dataset pathology

Diagnosis	No. Scans	% of Dataset	No. Longitudinal Images	% of Dataset
Contralateral (assumed normal)	59	31.6	133	45.2
Benign (pathology confirmed)	14	7.5	19	6.5
Scar	3	1.6	4	1.4
Trauma	1	0.5	1	0.3
Reactive Fibroma	1	0.5	1	0.3
Actinic Cheilitis	2	1.1	3	1.0
Hyperplasia	2	1.1	2	0.7
Verrucous Hyperplasia	3	1.6	4	1.4
Dysplasia Grade 1	24	12.8	31	10.5
Dysplasia Grade 2	21	11.2	25	8.5
Dysplasia Grade 3	12	6.4	18	6.1
Carcinoma In Situ	5	2.7	7	2.4
Lentigo Maligna	4	2.1	5	1.7
OSCC	27	14.4	32	10.9
Verrucous Carcinoma	9	4.8	9	3.1
Total	187	100.0	294	100.0

Table 2. Summary of dataset imaging site

Site	No. Scans	% of Dataset	No. Longitudinal Images	% of Dataset
Buccal Mucosa	23	12.3	38	12.9
Floor Of Mouth	8	4.3	13	4.4
Gingiva	10	5.3	11	3.7
Labial Mucosa	4	2.1	8	2.7
Lip	1	0.5	1	0.3
Tongue - Dorsal	4	2.1	6	2.0
Tongue - Lateral	55	29.4	86	29.3
Tongue - Ventral	76	40.6	124	42.2
Vestibule	6	3.2	7	2.4
Total	187	100.0	294	100.0

2.3 Rater Annotations

Supervised deep learning models were used in this study, and thus the discovery set required ground truth reference data. Annotations were generated by five raters experienced with analyzing OCT. Manual segmentation of the (1) epithelial surface, (2) basement membrane, and (3) imaging artifacts was completed using in-house annotation software. Artifacts such as air bubbles cause a decrease or complete loss of image intensity and may confound other processing steps. Each image was annotated by three randomly assigned raters. Data was anonymized prior to distribution, blinding raters to identifiers and disease status. A single rater combined these impressions to generate a single reference annotation for each image. Images with high inter-rater disagreement were discussed and a consensus annotation was created in a panel review session.

2.4 Pipeline Architecture

A three-step automated pipeline was built to pre-process the volumetric scans, generate predictions via four deep learning networks, and post-process predictions and synthesize for visual analysis. The second step of the pipeline employed the following networks:

1. Field-of-view (FOV) detection. A convolutional neural network (CNN) was used to predict either complete tissue contact, or partial/no tissue contact for each longitudinal image.
2. Artifact detection. A CNN was used to classify any regions that contained artifacts (bubbles, sheath markers) that might lead to incorrect segmentation predictions.

3. Surface segmentation. A shallow u-net was used to segment the (epithelial) tissue surface.
4. Basement membrane segmentation. A shallow u-net was used to segment the basement membrane.

Post-processing steps are unique to individual tasks and described below. Predictions are presented as thickness maps which provide information about changes to epithelial thickening, stratification, and presence of imaging artifacts. Pre- and post-processing methods were completed in MATLAB. Networks were implemented with PyTorch framework using NVIDIA Cuda v11.4 and Python 3.6.9. All experiments were performed on a Windows 10 operating system, with CPU Intel Core i7-4770 3.40 GHz, GPU NVIDIA GeForce GTX 1660, and 32 GB of RAM.

2.5. Data Preparation and Augmentation

Longitudinal images were averaged in the azimuthal direction (out of plane, 5-pixel average) and resampled for isotropic pixel size (10 μm square in tissue). After resampling, images were 382 pixels (3.82 mm) high and 4000 pixels (4 cm) to 9000 pixels (9 cm) wide, depending on the pullback length. The logarithmic intensity (dB) of each image was scaled between the OCT noise floor and the maximum intensity of the image. Images were partitioned into overlapping square tiles to create uniform, memory-aware input information for model training.

The discovery sets are summarized in Table 3. As the classification task required less contextual information, classification tiles were smaller (128 x 128) to allow faster training. Conversely, segmentation tiles were selected to be the maximum base-2 size (256 x 256) without resampling. The deepest 126 pixels contained no relevant information due signal attenuation and were discarded from each image. Tiles were overlapped (by half their width) to encourage attention at both the left and right side of the image and increase the amount of data available for training.

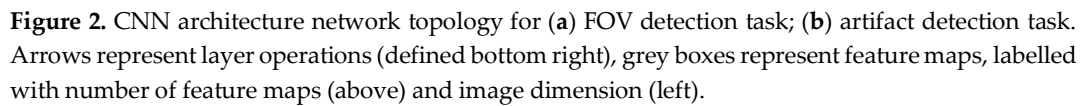
In the FOV detection task, longitudinal images were randomly selected from a subset of 9 volumetric scans. Images with no tissue present (no probe-tissue contact) were defined as class 0 while those with tissue present (probe-tissue contact over the entire width of the image) were defined as class 1. Images with partial tissue contact were rejected. Similarly, for the artifact detection task, images with no artifacts were defined as class 0 while those with artifacts were defined as class 1. Training, tuning, and test images for this task were selected from the pool of annotated images. Tiles with small artifacts (<30% of the tile) occurring at the edge of the tile were discarded. Segmentation tasks also used annotated images for training, with annotations being converted to ground truth masks. Prior to tiling, images were cropped to remove any regions that did not have an epithelial surface annotation.

Table 3. Summary of discovery sets for deep learning tasks.

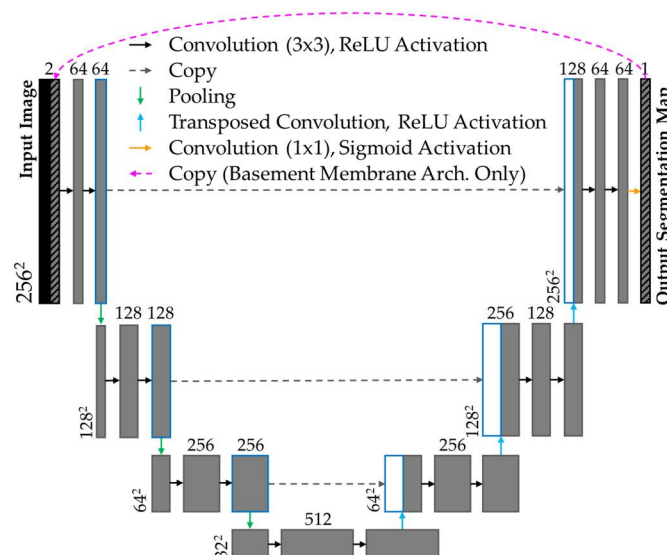
Task	Model	No. Patients	No. Scans	No. Images	No. Tiles	Tile Size (overlap) [pixels]
FOV Detection	Classification	9	9	2427	Class 0: 64,250	256x256 (128)
					Class 1: 87,376	
Artifact Detection	Classification	59	864	288	Class 0: 20,467	128x128 (64)
					Class 1: 1,459	
Epithelial Surface	Segmentation	59	864	288	11,356	256x256 (128)
Basement Membrane	Segmentation	59	864	288	11,356	256x256 (128)

2.6. Convolutional Neural Network Architectures

A custom CNN was trained for tile classification in the FOV and artifact detection tasks. Shown in Figure 2 (a), the feature detection layers of the FOV detection network comprised two convolutional layers with ReLU activation and 2x2 max pooling. The network was terminated with



Modified u-nets [32] were implemented to identify the epithelial surface and basement membrane. The epithelial surface task used a shallow u-net (encoder: 4 convolutional layers, 3x3 kernel, ReLU activation, 2x2 max pooling; decoder: 3 convolutional layers, 3x3 kernel, ReLU activation, 2x2 transposed convolution layers). Shown in Figure 3, the basement membrane task used the same u-net topology with an additional connection, used during training only, concatenating the prediction of the prior epoch to the input of the subsequent epoch.



2.8. Model Training

For each task, the discovery set was divided into training, tuning and test cohorts with approximately 70%, 15%, 15% distribution, ensuring no patient overlap between intra-task cohorts. Stratified sampling was used to promote uniform representation of features of interest across the cohorts. The distribution of features by deep learning task is summarized in Table 4. The epithelial surface task did not have a feature of interest; cohort distribution matched the basement membrane task.

Table 4. Distribution of features by deep learning task.

Task	Feature of Interest	Distribution
FOV Detection	Tissue Contact	In FOV: ~60% Out of FOV: ~40%
Artifact Detection	Presence of Artifact	Present: 7% Absent: 93%
Epithelial Surface	N/A	N/A
Basement Membrane	Epithelial Stromal Transition	Complete: ~70% Broken: ~15% Absent: ~15%

To reduce imbalanced mask content during segmentation tasks, reference annotations were thickened in the vertical (z or A-Line) direction. Various training protocols were explored, evaluating the utility of thickening the segmentation masks. For the epithelial surface task, three models were compared, trained with ± 24 pixel masks, ± 12 pixel masks and ± 4 pixel masks. The basement membrane task also explored thickened training masks, and analyzed pre-training with coarser masks, and fine-tuning with more precise masks. Figure 4 (a) depicts a raw epithelial surface reference tile overlaid on the image tile. Figure 4 (b) details the training reference tile after thickening (displayed with transparency to allow visualization of image tile).

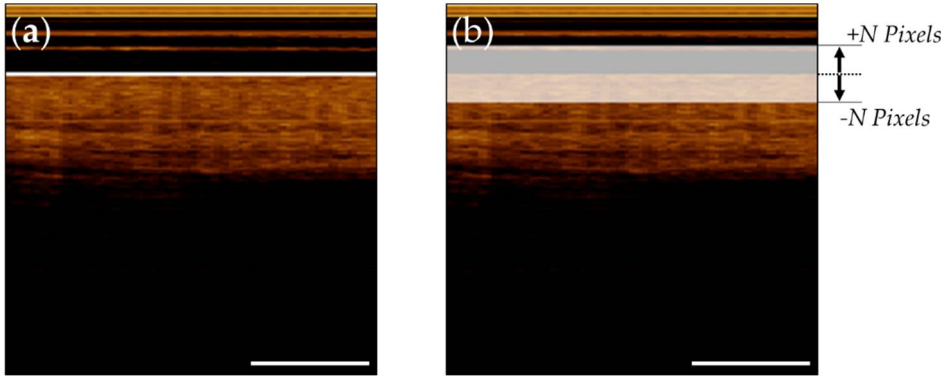


Figure 4. Epithelial surface tile with reference annotation overlaid. (a) Raw annotation; (b) thickened annotation. Scale bars 1 mm.

2.9 Post-Processing

The FOV detection task class predictions were aggregated by original image. To reduce errors arising from incorrect prediction due to imaging artifacts, poor catheter contact, or off-target structures (e.g. gloved hand touching the catheter, mucus), >90% of the image tiles in each longitudinal image were required to be classified as containing tissue (class 1) to continue to subsequent networks. Examples of longitudinal images pulled from the center (approved, blue) and the edge (rejected, red) of the FOV is shown in Figure 5 (a).

Post-processing steps for segmentation tasks were developed using model predictions of the test cohort. Steps from the basement membrane task are summarized graphically in Figure 5 (b), with the final step in magenta, and the reference in green. In both tasks, the raw predictions approximately matched the thickness of the training reference masks. A single pixel thick boundary was created by

extracting the median A-Line depth (z-direction) of each tile. Neighboring tiles were then stitched and overlapping regions were averaged.

For the epithelial surface task, simple morphological operations eliminated small (<10 pixels) regions and subsequently connected any gaps between predictions. Boundaries were smoothed by resampling at every 10th pixel and reconnecting using the pchip algorithm [33]. Figure 5

In the basement membrane task, morphological operations were used to (1) connect small gaps (< 10 pixels along the pullback (y) axis) through linear interpolation, (2) remove small predictions (< 25 pixels), (3) connect small gaps (< 30 pixels along the pullback axis) through linear interpolation, and (4) smooth predictions through resampling and interpolation with the p-chip algorithm. In steps (1) and (3), regions that were within the pullback-axis limits but were more than 10-pixels apart along the A-Line depth were not connected, to best represent biological organization of oral tissue.

The artifact detection task post-processing steps are summarized in Figure 5 (c), with class 1 tiles outlined in cyan, and class 0 tiles outlined in black. Classified tiles were stitched into longitudinal images and overlapping tile regions were classified using logical conjunction (i.e. AND), allowing artifact localization within a 64-pixel resolution.

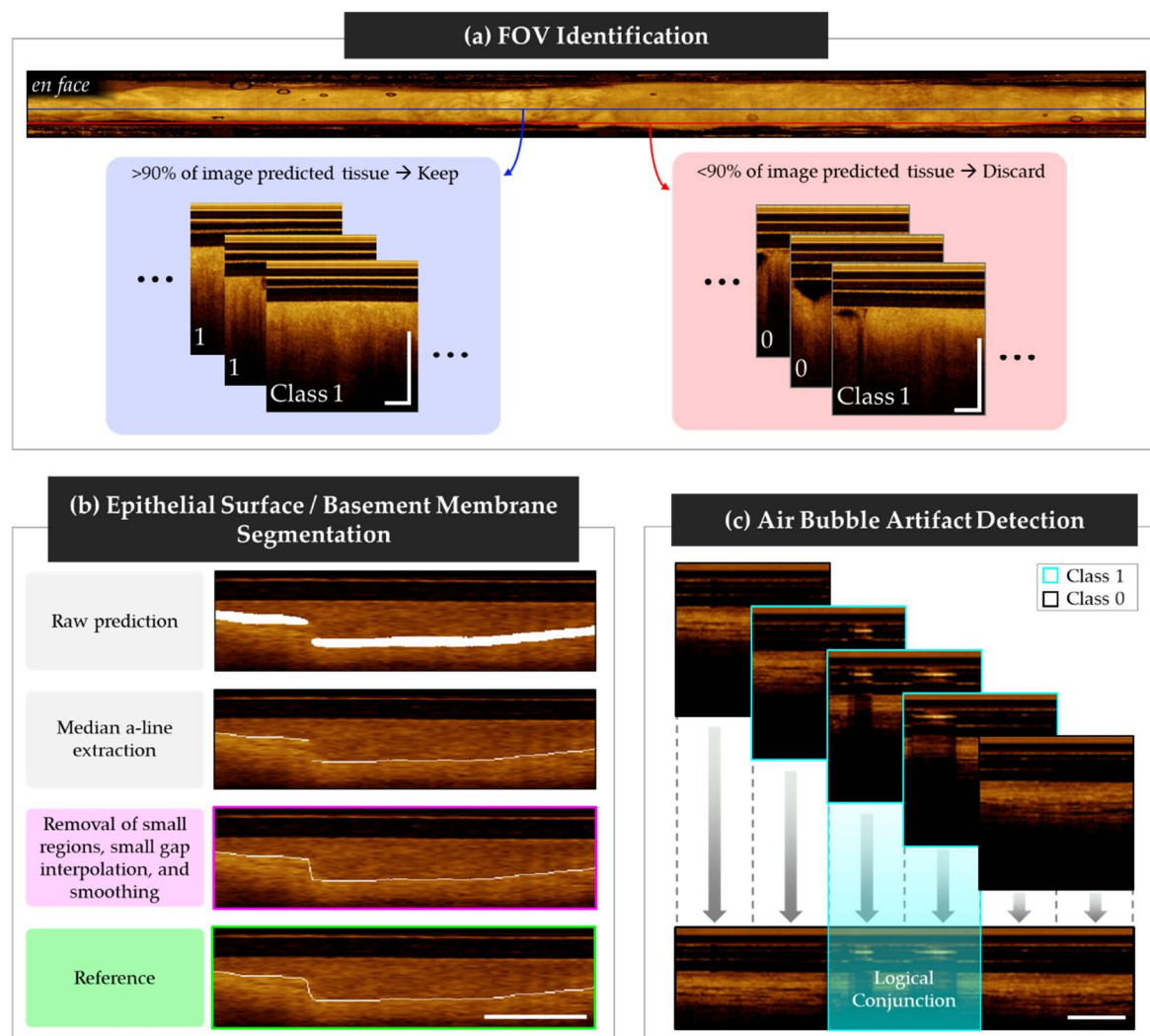


Figure 5. Network post-processing steps. (a) Tile aggregation for FOV classification task. Includes example of accepted longitudinal image (left, blue) pulled from center of the *en face* projection (blue line), and a rejected longitudinal image (right, red) pulled from the tissue-air transition of the *en face* projection (red line); (b) Prediction cleaning for surface segmentation tasks, listed top to bottom: stitched raw prediction; single pixel boundary taken at median A-Line; remove small objects, connect gaps, and smooth prediction (end of process – magenta); reference data (green); (c) Tile aggregation for air bubble detection, with overlapping regions classified using logical conjunction. Scale bars 1 mm.

2.10 Evaluation Metrics

All metrics were calculated from the test cohort of the discovery set. Balanced accuracy, sensitivity, and specificity are reported for classification tasks, as well as the receiver operating characteristic (ROC) curve, and the precision recall (PR) curve. The area under the ROC curve (AUC) and mean average precision (mAP) are also presented.

For segmentation tasks, the dice similarity score (DSC), percent of positive agreement (PA), percent of negative agreement (NA) and mean A-line error (ME) are reported. The dice similarity score [34],

$$DSC = \frac{2 |Reference \cap Prediction|}{|Reference| + |Prediction|} \quad (1)$$

is included for comparability to other segmentation tools; however, this metric demonstrates a bias towards larger objects. Error in comparing small shapes (such as a thin boundaries) is amplified in the DSC, as the small positive sample size is greatly outweighed by the overall sample size (pixel count). Conversely, large shapes may exhibit high DSC despite containing numerous pixels that have been inaccurately segmented [35].

To accommodate this limitation, we also calculate percent of positive and negative agreement,

$$PA = \frac{2TP}{2TP+FP+FN}, \quad NA = \frac{2TN}{2TN+FP+FN}, \quad (2)$$

to represent agreement about boundary existence within each A-line; these metrics are only calculated for the basement membrane task as the epithelial surface post-processing methods guarantee the presence of a boundary. PA and NA are calculated by comparing the annotations for each A-line per tile. For this application, true positive (TP) is defined by boundary presence in the reference and prediction, and true negative (TN) is defined by boundary absence in the reference and prediction. False positive (FP) and false negative (FN) are counted, with the reference used as the ground truth. The ME metric is used to quantify positional (depth) disagreement in each A-line position between predicted versus reference masks; a positive value indicates the prediction is shallower than the reference, while a negative value indicates the opposite. Regions used to calculate PA and NA are shown graphically in Figure 6 (a). The blue dashed box in Figure 6 (b) demonstrates A-line depth errors used to calculate the ME. Per-image metrics are presented as a single value averaged from all test set predictions.

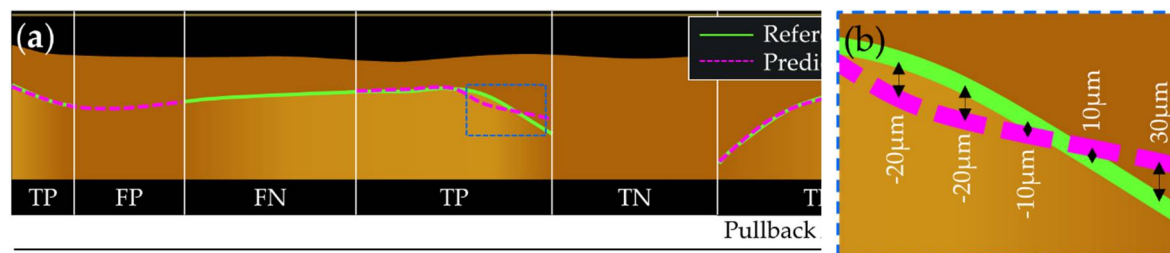


Figure 6. Segmentation metrics. (a) Regions of TP, TN, FP and FN used to calculate PA and NA; (b) regions of depth disagreement used to calculate ME, enhance from blue dashed box in (a).

2.11 3-Dimensional Volumes

Two scans from the excluded patient in the discovery set were analyzed: a grade 2 dysplasia of the lateral tongue, and its contralateral. 504 longitudinal images were generated from each pullback. Each longitudinal image was pre-processed, passed through the four-network pipeline, and post-processed. Predictions were combined to reconstruct a 3-dimensional volume detailing the epithelial layer and imaging artifact. Epithelial thickness maps are corrected for refractive index of water ($n = 1.33$), which closely matches that of tissue. A small Gaussian blur was applied to the epithelial thickness maps (10x10 pixel kernel), and artifact identification map (5x5 pixel kernel) to smooth the edges. Qualitative evaluation is used in the *en face* view as manual annotation of complete volumes was not practical.

3. Results

3.1 Final Models

For each model, z-score normalization was applied to the discovery set calculated from the mean and standard deviation of the training cohort. Model weights were initialized per the Kaiming He method [36]. Data augmentation of horizontal flips (50% likelihood) and y-axis shifting ($\pm 10\%$) was applied to the training cohort. Binary cross entropy [37] and Adam [38] were used as the criterion and optimization functions. Summarized in Table 5, hyperparameters unique to each task were determined through iterative experimentation.

Table 5. Training hyperparameters for model development.

Task	No. of Epochs (Early Stopping Epoch)	Early Stopping Scheme	Batch Size	LR Scheduler
FOV Detection	10 (2)	patience = 5, $\Delta_{\min} = 0.01$ mode = min. loss	64	patience = 3, factor = 0.1, min. LR = 1×10^{-8}
Epithelial Surface	30 (19)	patience = 5, $\Delta_{\min} = 0.01$ mode = min. loss	8	patience = 5, factor = 0.1, min. LR = 1×10^{-8}
Basement Membrane	20 (9, 8)*	patience = 5, $\Delta_{\min} = 0.01$ mode = min. loss	8	patience = 5, factor = 0.1, min. LR = 1×10^{-8}
Artifact Detection	30 (18)	patience = 5, $\Delta_{\min} = 0.01$ mode = min. loss	64	patience = 3, factor = 0.1, min. LR = 1×10^{-7}

*Number of epochs for pre-training and fine-tuning

3.2 Convolutional Neural Networks Performance

Classification metrics for the FOV and artifact detection models are reported in Table 6; ROC and PR curves are presented in Figure 7, demonstrating improvement over an unskilled model. Evaluation metrics, ROC, and PR curves are calculated from the test set for the respective task.

Table 6. Test Set Metrics for FOV and Artifact Detection CNNs.

Task	No. Tiles	Bal. Accuracy (%)	Sensitivity (%)	Specificity (%)	AUC	mAP
FOV	17,404	100.0*	100.0*	100.0*	1.00	1.00
Artifact Detection	2,345	75.5	99.1	52.3	0.94	0.68

* After aggregating tiles

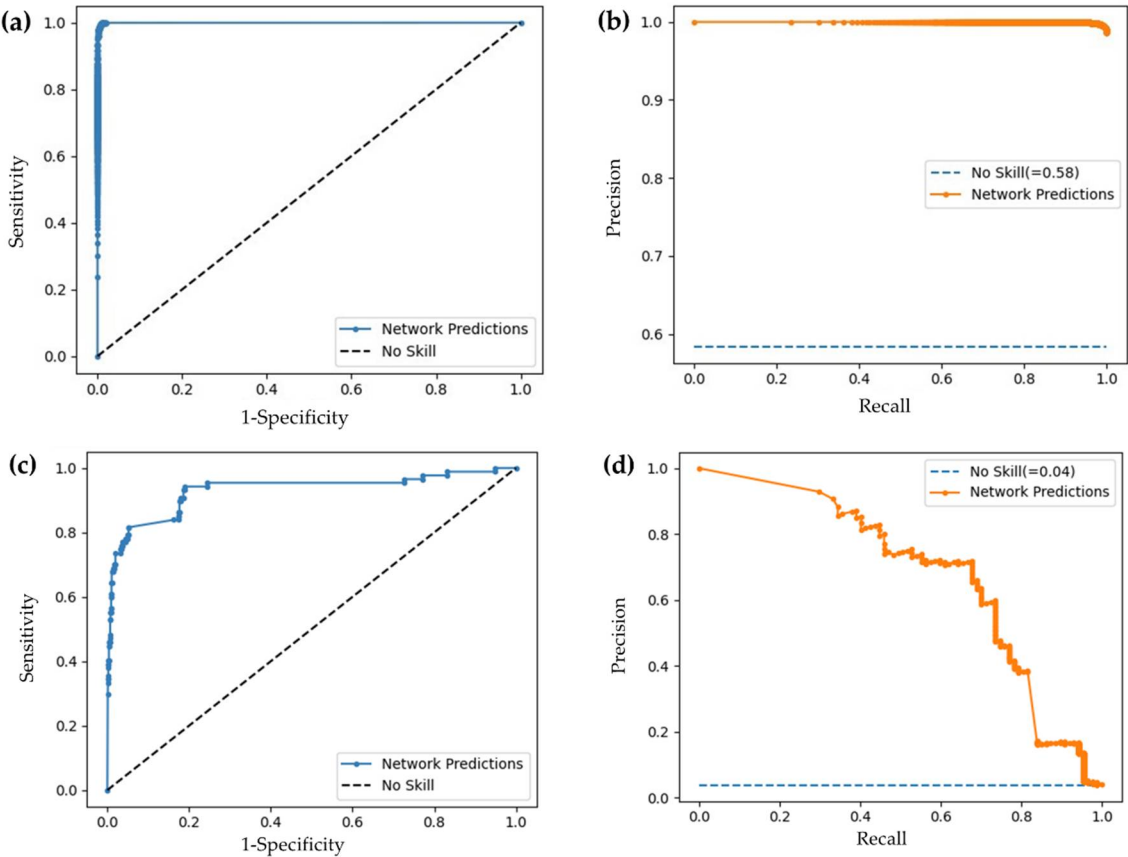


Figure 7. (a) ROC and (b) PRC curves for FOV classification task; (c) ROC and (d) PR curves for artifact classification task.

3.3 U-Net Performance

Segmentation metrics are calculated on stitched, post-processed predictions from the test set. DSC values are calculated after thickening the reference and prediction masks; remaining metrics are calculated on the single pixel boundary.

Three training protocols were evaluated for the epithelial surface segmentation task, exploring the benefit of thickened training masks. Results are detailed in Table 7. With the metrics being nearly equivalent, and acknowledging the bias of the DSC towards larger objects, selection of the smallest pixel error mean and standard deviation indicated the model trained with annotations thickened by ± 12 pixels as superior.

Table 7. Test set metrics for epithelial surface training protocols. Best results marked in **bold**.

Training Protocol	DSC	ME (mm) (M $\pm$ SD)
± 24 pixels	0.99	0.4 ± 9.9
± 12 pixels*	0.98	0.4 ± 9.1
± 4 pixels	0.94	-0.9 ± 10.4

* Selected training protocol.

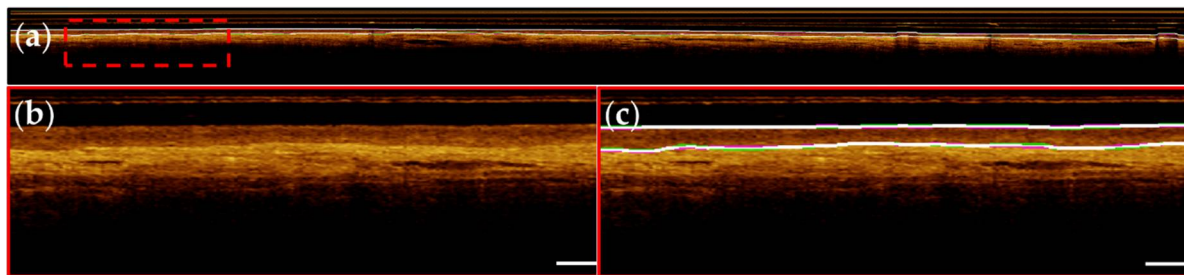
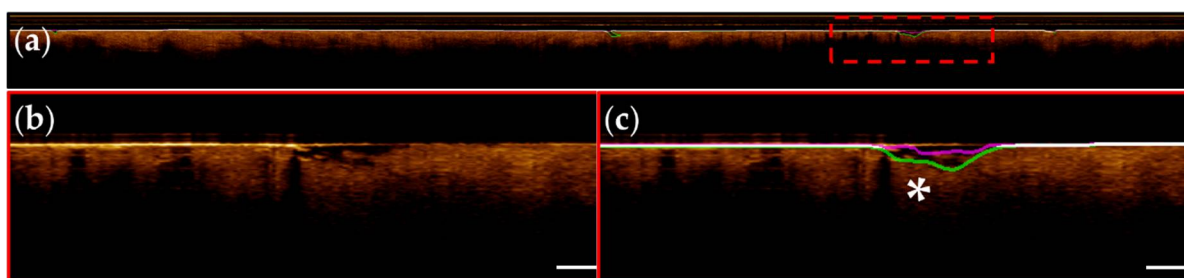
We also explored the effects of thickening the training masks in the basement membrane task, but also analyzed pre-training with coarser masks, and fine-tuning with more precise masks. Results are summarized in Table 8. The affinity of the DSC towards larger objects is again observed. Yet, this protocol performed poorly in other metrics. While protocol 2 presents superior ME metrics, this simpler protocol suffered from the lowest PA and NA values, indicating poor representation of basement membrane detection. Protocol 3 yielded the highest DSC among comparable models and the highest PA and NA values, indicating the best agreement with regions both with and without an identifiable visible basement membrane. The remaining metrics are similar in protocols 3-5.

Table 8. Test set metrics for basement membrane training protocols. The best results are **bolded**.

Training Protocol	DSC	PA (%)	NA (%)	ME (mm) (M $\pm$ SD)
± 12 pixels	0.91	95.8	80.9	2.9 ± 21.5
± 4 pixels	0.76	93.1	75.1	0.1 ± 16.2
$\pm 12 \wedge \pm 4$ pixels*	0.83	95.8	81.7	-0.5 ± 19.3
$\pm 24 \wedge \pm 4$ pixels	0.76	95.1	80.1	1.5 ± 20.3
$\pm 24 \wedge \pm 12 \wedge \pm 4$ pixels	0.79	95.3	81.2	-0.1 ± 19.8

* Selected training protocol.

Representative images from patients within the segmentation test set are presented below; Images are taken from apparent normal (contralateral, Figure 8) and pathologic (biopsy confirmed OSCC, Figure 9) scans of the ventral tongue. Whole images are presented in (a) and magnified insets are presented unannotated in (b) and annotated in (c). Results from the surface segmentation u-net and basement membrane segmentation u-net are included. Reference and prediction annotations are shown in green and magenta, respectively; regions of agreement are highlighted in white. Good agreement between epithelial boundaries can be visualized in the contralateral image (Figure 8). Folds in the tissue surface, which were infrequent in the training set, are shown to confound the surface segmentation model - marked by a white star in Figure 9 (c). The complete loss of epithelial stratification characteristic of OSCC is captured by the basement membrane segmentation model, an example of a correctly classified true negative region.

**Figure 8.** Contralateral ventral tongue. (a) Image with reference (green) and prediction (magenta) annotations; white annotations indicate overlap; (b) Magnified region of red dashed box in (a); (c) With annotation overlay (bolded for visualization). Scale bars 1mm.**Figure 9.** OSCC of the ventral tongue. (a) Image with reference (green) and prediction (magenta) annotations; white annotations indicate overlap; (b) Magnified region of red dashed box in (a); (c) With annotation overlay (bolded for visualization), white star indicates region of tissue fold confounding the network. Scale bars 1mm.

3.4 Evaluation of 3-Dimensional Volumes

Synthesis of the 3-dimensional prediction data volumes are shown for the contralateral volume (Figure 10) and the dysplastic volume (Figure 11). For each volume, a mask highlighting imaging artifacts is included in (a) and in (b) an epithelial thickness map, identifying regions of broken or missing basement membrane. Epithelial thickening is demonstrated with the MATLAB parula colormap, with darker blue regions indicating thinner epithelium, and yellow regions indicating thickened epithelium. In (c), an unannotated *en face* is included for reference with a red dashed line

indicating location of a sample longitudinal image. This image is shown annotated in (d) with epithelial layer prediction (magenta) and artifact locations (cyan, Figure 10 only). Insets of Figure 10 (d, blue dashed box) is shown in (e) and (f). Insets of Figure 10 (d, yellow and blue dashed boxes) are included in (e)-(h). Annotated panels include green line identifying rater segmentation for dysplastic insets.

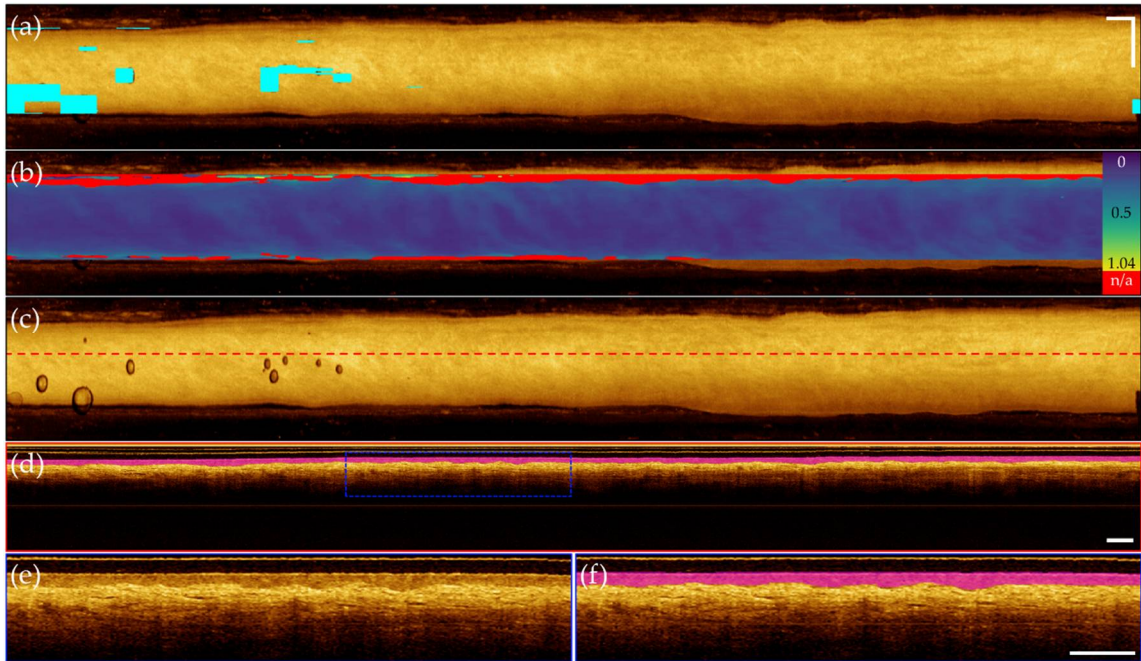


Figure 10. Contralateral pullback of the lateral tongue. (a) *En face* projection with artifact overlay; (b) *En face* projection with epithelial thickness map. Color bar indicates 0 to 1.04mm thickness, with bright red indicating no visible basement membrane; (c) unannotated *en face* projection with red dashed line indicating location of longitudinal image in (d); (d) longitudinal image with predicted epithelial layer overlay (magenta); (e) inset of blue dashed box in (d), unannotated; (f) inset of blue dashed box in (d), mirroring inset of (e) with annotation. Scale bars 1mm.

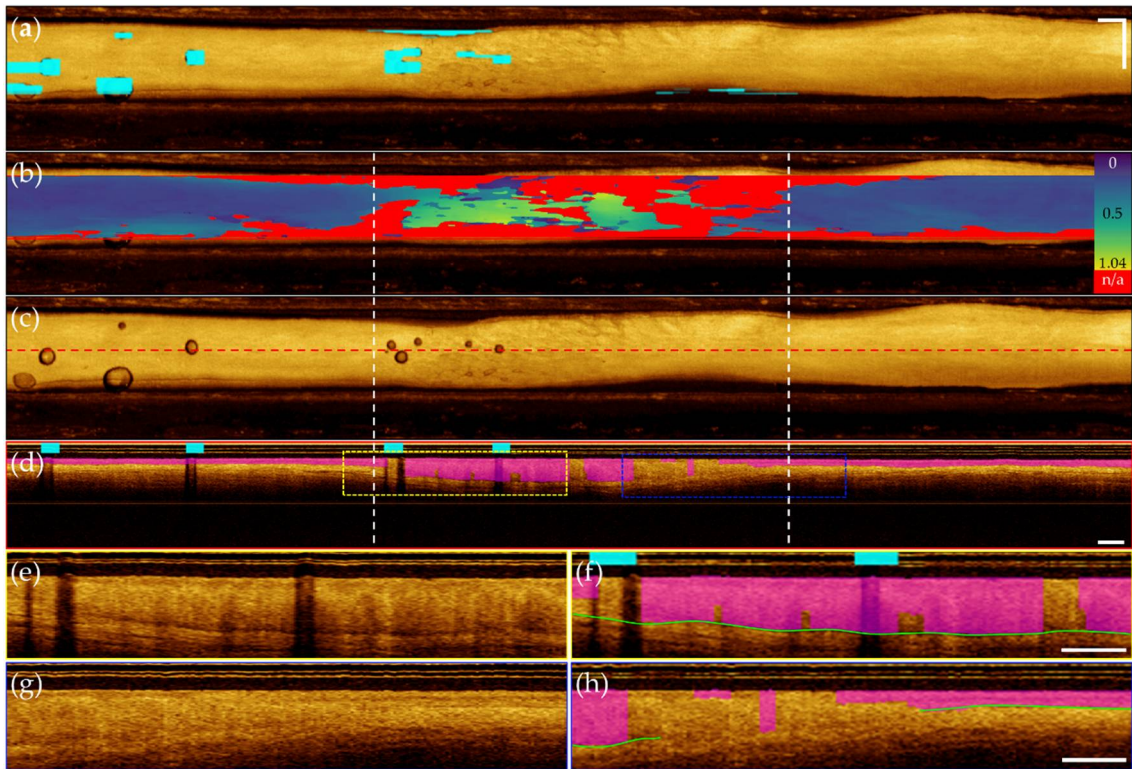


Figure 11. Grade 2 dysplasia of the lateral tongue. (a) *En face* projection with artifact overlay (cyan); (b) *En face* projection with epithelial thickness map. Blue to yellow color bar indicates 0 to 1.04mm thickness, with red indicating no visible basement membrane. White dashed lines flank predicted region of epithelial thickening and loss, also seen in (c) and (d); (c) unannotated *en face* projection with red dashed line indicating location of longitudinal image in (d); (d) longitudinal image with predicted epithelial layer overlay (magenta) and identified artifact overlay (cyan); (e) inset of yellow dashed box in (d), unannotated; (f) inset of yellow dashed box in (d) mirroring inset of (e) with annotation, green line indicating rater segmentation; (g) inset of blue dashed box in (d), unannotated; (h) inset of blue dashed box in (d), mirroring inset of (h) with annotation, green line indicating rater segmentation. Scale bars 1 mm.

Both volumes demonstrated accurate localization of the imaging artifacts shown in (a), as well as good identification of the FOV, seen in (b). Evaluation of the contralateral volume (Figure 10) displays near uniform epithelial thickness in (b), aligning with the expected biology of the tissue. Precise segmentation of the epithelial surface and basement membrane is observed, supported by isolating a single longitudinal image in (d), with insets in (e)-(f) demonstrating accurate epithelial layer identification. Comparatively, evaluation of the dysplastic volume (Figure 11) demonstrates epithelial thickening and loss of the basement membrane characteristic to oral dysplasia in (b). From the left, the map indicates a slow thickening of the epithelial layer, while the right indicates a sharp transition from stratified into non-stratified tissue. Isolation of a longitudinal image shown in (d), pulled from the center of the imaging FOV allows easier visualization of this phenomena. While inconsistencies in the segmentation of the basement membrane are present, with errors highlighted by rater segmentation (green line) in (f) and (h), the general trend of abnormal tissue towards the center of the tissue, compared to the more normal stratification tissue towards the image edges is captured.

4. Discussion

We present a novel pipeline for automated segmentation of oral OCT, using deep learning and image processing methods to provide repeatable, time-sensitive information about epithelial status. Our approach is unique as it employs segmentation strategies to characterize the epithelial layer, rather than classify disease status. This contrasts prior *in vivo* oral OCT studies, which were used to triage healthy, pre-cancerous and cancerous samples [16,39,40] or classify states of dysplasia [39]. While these methods achieved high agreement they are constrained by rigid classification labels, and either have limited transparency in the diagnostic process or employ explainability methods to foster physician trust. Instead, we propose a tool to retrieve oral cancer biomarkers and empower clinicians with morphological information upon which to make treatment plan recommendations.

The processing pipeline employed four independent deep learning networks, preventing the propagation of errors through the analysis pipeline, while simplifying the adaptation (domain-transfer) of these networks to other datasets (lung or cervical OCT, for example). Further investigation into generalizability across oral cavity sites is warranted, where changes in imaging site and pathology may influence network predictions. The networks presented in this research are unavoidably biased towards the more prevalent presentation of oral cancer of the tongue, comprising 71.7% of our data. Whereas the presentation of the epithelial surface (tissue surface) is consistent across imaging site and pathology, the site imbalance in training data may influence network predictions of the basement membrane in sites other than the tongue.

4.1. Convolutional Neural Networks

Training data for the FOV classification task excluded images near the tissue-air transition, as inconsistent contact required manual labelling of tiles. However, this step of the pipeline is designed to discard entire longitudinal images and misclassification of individual tiles is mostly managed through averaging during post-processing. Current methods may be too lenient at the edges of tissue contact, for example at the upper border of Figure 10 (b). While these images contain oral tissue, the lack of visible basement membrane is likely not attributed to epithelial thickening, but rather a result of the incident angle of the scanning beam approaching perpendicular to the tissue surface. Consequentially, these images proceed to segmentation steps and are either predicted with thickened

epithelium, or marked as N/A. Another potential limitation of this approach includes an intolerance for scans experiencing non-uniform rotational distortion, an occasional artifact due to the helical scanning endoscopic OCT system [41]. However, this effect occurs primarily when the imaging catheter movement is restricted during collection, which is rare when collecting oral OCT due to the accessibility of the site of interest.

Training data for the artifact classification task excluded image tiles that featured small, borderline artifacts. Potential errors arising from under-representing this type of image are accommodated through overlapping tiles. Stitching tiles using logical conjunction allows for more focal identification of the regions of artifact. However, as observed in Figure 10 (a) and Figure 11 (a), applying classification labels to whole tiles results in over-identification of artifact regions; a better suited method may be segmentation of the *en face* projection. If the artifacts of most concern are air bubbles, *en face* projections could be examined over a reduced A-Line depth to readily identify the sheath and holder region. This would reduce pre-processing time.

4.2. U-Nets

U-net models were trained on thickened masks to reduce class imbalance. Size bias is apparent in the DSC metrics of the thicker training masks, yet limitations of these training protocols can be observed in the other metrics. Selection of the ± 12 pixel thick mask for the epithelial surface task allowed the necessary precision to avoid basing predictions on the imaging core artifacts, but provided sufficient spatial information that remained useable at the lowest levels of the network. For the more complex basement membrane segmentation task, fine-tuning with thinner masks generated improvements in protocols 3 and 5. This difference may be attributed to the more challenging task, or the adaptation of the network topology, where the input layer contained both the input image tile, and the prediction of the previous epoch. Training protocol 3 exhibited the best response to post-processing methods, despite the algorithm being developed using the predictions of protocol 5.

The uniqueness of this approach limits its comparability with prior studies as, to our knowledge, no other deep learning segmentation applications have been applied to oral OCT. To validate the success of our models, we present our evaluation metrics calculated against the reference annotations, shown in Table 9. Segmentation is a laborious and subjective task, resulting in human raters being prone to error or differences of opinion regarding boundary location. Model success may be indicated if the reference-prediction metrics are within the distribution of inter-rater metrics.

Table 9. Rater-Reference metrics for segmentation networks.

Task	Metric	Model	Rater 1	Rater 2	Rater 3	Rater 4	Rater 5
Epithelium	DSC	0.98	0.96	0.96	0.97	0.97	0.95
	ME	0.4 ± 9.1	5.4 ± 11.4	2.1 ± 11.2	2.4 ± 11.1	3.6 ± 10.7	7.2 ± 13.5
	(µm)						
Basement Membrane	DSC	0.83	0.78	0.64	0.75	0.75	0.73
	PA (%)	95.8	97.2	89.2	95.1	95.4	87.9
	NA (%)	81.7	85.3	69.1	67.9	74.0	56.8
	ME	-0.5 ± 19.3	0.6 ± 24.2	2.9 ± 32.8	-3.8 ± 24.8	-1.7 ± 18.5	-0.5 ± 14.7
	(µm)						

Comparison of these results to reference prediction metrics for the epithelial surface task and the basement membrane task demonstrates that deep learning methods offer an improvement over manual annotation metric. The A-Line resolution of these images is 10 µm, thus errors beyond this resolution indicate high agreement. Some poor inter-rater agreement may be attributed to labelling errors rather than misidentification of the surface of interest: this type of error supports the motivation for automated methods.

Challenges identified in the epithelial surface segmentation task include a limited selection of images containing unique features: longitudinal images where unknown materials occlude the image (n = 3) and tissue folds occurring in softer mucosal membranes (n = 2). An example of this can be seen in Figure 9 (c), denoted by a white star. Generally, models struggled to decipher irregular substances (e.g. mucous, keratinization) or structures (e.g. tissue folds and gaps) resulting in incorrect

predictions. This error may be addressable with increased sample size including more cases in the training data.

It is evident that segmentation of the basement membrane is a more complex task for both manual and automated methods, in comparison to the epithelial surface task. The loss of stratification characteristic of cancerous and pre-cancerous oral lesions is difficult to quantify using manual annotations, and some cases required the raters to use contextual information present in the entire longitudinal slice. Accordingly, the image tiling step introduces a network limitation as this context is lost.

4.x Comparison of Predictions for Contralateral and Dysplastic OCT Volumes

The distinction between epithelial and stromal layers in the contralateral volume is well captured by model predictions, particularly clear in the longitudinal image shown in Figure 10 (d), with inset comparisons in (e) and (f). The basement membrane was segmented for 91.5% of the in-FOV tissue, with the missing 8.5% occurring at the tissue edges. The average predicted epithelial thickness is 208 μ m, in agreement with prior research measuring the epithelial thickness of the lateral tongue using OCT (216 $\pm$ 59 μ m) [42].

Conversely, the delineation between the epithelial and stromal layers becomes more nuanced in the dysplastic case, shown in Figure 11, particularly in the region of epithelial thickening indicated by white dashed lines in (b) – (d). The transition across the layers becomes less sharp and while normal tissue morphology dictates the basement membrane is visible across the entire image, the network delivers a discontinuous prediction. We hypothesize a few scenarios that result in incorrect model predictions. As discussed above, the loss of contextual information restricts available data upon which to make segmentation predictions. Moreover, as the epithelial layer thickens, the transitional zone moves lower in the longitudinal image and approaches the maximum imaging depth of our system. At this depth, the signal to noise ratio decreases as the light attenuates towards the level of the noise floor, and the transition between the two layers is more difficult to delineate. In cases with extreme epithelial thickening, the basement membrane cannot be visualized at all. Finally, as oral tissue transitions through pre- and potentially-malignant lesions towards cancer, changes in cell size, content and organization alters the scattering properties [43] of the tissue and OCT images become more homogeneous in appearance, further complicating the basement membrane segmentation task. Continued development of complex architectures may improve such errors. Currently, the basement membrane was segmented for 68.7% of the in-FOV tissue and the average predicted epithelial thickness is 319 μ m. Both the loss of visible stratification and increased epithelial thickness agree with the expected changes arising in dysplastic tissue.

This work highlights the opportunity for automated depth analysis of OCT data, wherein differences in tissue content are non-obvious in the *en face* view, and the quantity of longitudinal images renders manual assessment unmanageable. Additionally, presenting depth information in the *en face* view allows for qualitative image interpretation.

5. Conclusions

A novel deep learning pipeline is presented as a tool to detect and quantify the presence and depth of the epithelial layer in OCT images, potentially decreasing barriers towards clinical applications of oral OCT. Defining the tissue analysis task to be completed through segmentation allows for a more generalized approach, not restricted by specific oral sites and diseases. Built with two CNNs, for FOV and artifact detection, and two modified u-nets, for epithelial layer isolation, this pipeline provides fast and reproducible results. Comparison of inter-rater agreement to network predictions demonstrate as-good-as or better agreement, and evaluation of whole OCT volumes of exemplifies ability to identify pathological progression.

Potential impacts for this work include monitoring of pre- and potentially malignant oral lesions, guiding biopsy site selection to reduce false negative biopsies and intra-operative margin assessment during tumor resection procedures.

Author Contributions: Conceptualization, CH and PL; methodology, CH, JM and CM; image collection, CP, SN and KL; software, CH; validation, CH; formal analysis, CH; investigation, CH; resources, CP, CM and PL; data curation, CH, JM and CP; writing—original draft preparation, CH; writing—review and editing, CH, JM, CP,

CM and PL; visualization, CH and JM; supervision, CM and PL; project administration, PL; funding acquisition, CM, CP and PL. All authors have read and agreed to the published version of the manuscript.

Funding: This research was funded by a Collaborative Health Research Project (CHRP) grant co-sponsored by the Canadian Institutes of Health Research (CIHR, FRN 134740) and the Natural Sciences and Engineering Research Council of Canada (NSERC, Appl ID 462490-2014). CH acknowledges scholarship support from NSERC and Simon Fraser University. JM acknowledges fellowship support from the University of British Columbia, the Mitacs Accelerate program, and the British Columbia Cancer Foundation. KL acknowledges fellowship support from CIHR.

Institutional Review Board Statement: The study was conducted in accordance with the Declaration of Helsinki and approved by the Research Ethics Board of the University of British Columbia and the British Columbia Cancer Agency (H11-02516, amended for this study August 19, 2014).

Informed Consent Statement: Informed written consent was obtained from all subjects involved in the study.

Data Availability Statement: The raw data supporting the conclusions of this article and the code used to process it will be made available by the authors on request.

Acknowledgments: We thank our collaborators in Integrative Oncology, our clinical partners in Oral Medicine & Oral Pathology, the patients who participated in this study, and the members of the Optical Cancer Imaging Lab (OCIL).

Conflicts of Interest: The authors declare no conflict of interest. The funders had no role in the design of the study; in the collection, analyzes, or interpretation of data; in the writing of the manuscript; or in the decision to publish the results.

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