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*Article*

# Evaluation of SFRP Lugs with SLM Bushing Load Capacity and Dependence of CZM Mode II Model Parameters on Embedded Elements Surface Roughness

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**Abstract:** This paper describes the load capacity of short fiber-reinforced polymer lugs with Ti-6Al-4V selective laser-melted bushings with the original embedded element surface roughness and after sandblasting and vibratory finishing. Lugs are an important part of pin-joints. Adhesion between PA6 and SLM produced titanium is not fully studied. The cohesive zone material Mode II model parameters were calibrated experimentally by extruding a cylindrical bushing along the lug axis. The values of the maximum equivalent tangential contact stress were fitted for cases with investigated embed element roughness. The critical fracture energy for tangential slip was also estimated. Validation of the constructed CZM Mode II models with the results of strength experiments was performed. In both the experiment and the calculation, greater bushing roughness provides greater lug load-bearing capacity. The presented models can be used for the preliminary evaluation of SFRP PA6 parts with titanium embedded elements bearing capacity.

**Keywords:** CZM model; strength; roughness; experiment; adhesion

## 1. Introduction

Composite materials are increasingly being introduced into various industries, including the aerospace industry [1,2].

The strength of pin-joints has a great influence on the strength of the product. Lugs are an important element in aerospace designs because they connect wings to the fuselage, engines to pylons, flaps, ailerons and spoilers to wings [3]. During operation, the lugs are subjected to cyclic loads [4,5]. High stress concentrations can lead to cracks and their subsequent growth under loading [5,6]. It is important to develop damage-resistant design criteria and analysis methods to ensure the high performance and reliability of aircraft lug attachments [7,8].

To transfer local reinforcement in products made of composite materials, it is necessary to use embedded elements or bushings in places where concentrated loads are applied [9,10]. Currently, the design and production of embedded elements is based on the use of simple standard shapes manufactured by mechanical processing [11]. Such embedded elements are characterized by excess weight, which has a particularly negative impact on the weight efficiency of aerospace products consisting of many parts. The use of topology optimization methods implies working with one material in the design area and does not allow considering the stiffness of the material surrounding the load-bearing design elements [12–14]. Injection molding methods [15] and additive technologies [16] are often used to produce topologically complex designs. Low adhesion of embedded elements

to the base material has a significant impact on the stress-strain state of the design and leads to a multiple reduction in its load-bearing capacity [17].

About 50% of titanium used in the aerospace industry is Ti-6Al-4V alloy, which has a good combination of performance and technological properties [18,19]. The high strength of Ti-6Al-4V alloy is achieved through heat treatment [20]. Compared with commercial pure titanium, Ti-6Al-4V alloy is more suitable for large-scale industrial applications, such as titanium hybrid bonding [21]. According to test data [22], the tensile strength of the Ti-6Al-4V alloy produced using selective laser melting (SLM) technology is slightly inferior to the tensile strength of the alloy obtained by rolling and stamping [23], which indicates the high performance properties of the material. One of the main goals of the aerospace industry is to create lightweight designs. One approach is to use different materials, resulting in dissimilar bonds, such as metals and fiber-reinforced composites [24]. The following technologies are used for titanium/polyamide bonding: induction technologies [25]; adhesion; hot-pressing technology [26]; mechanical assembly (such as riveting, screwing or snap jointing) or welding [27,28]. Surface preparation is the most important step in the process and influences the quality of the adhesive bond [29]. Various methods have been used to increase the adhesive strength between the connecting part and the embedded element [30–33]. A method for treating metal surfaces to enhance adhesion is chemical treatment [34,35]. The authors [36] showed that the thickness of the oxide layer significantly influences the mechanical characteristics of the bond. The titanium/polyamide bond with a thick oxide layer showed lower load capacity, and with UV irradiation, a more pronounced decrease in bond strength was observed. Experimental studies [37] revealed that surface cleaning, surface modification, and sodium hydroxide anodization of titanium resulted in significantly high peel strengths for a titanium/aluminum bond. Recent testing of adhesive bonds has shown that pre-treating the metal surface with a laser can also significantly increase the strength of the entire pin-joint [37–39]. The modern method for producing hybrid bonds is injection molding, which combines automation, process speed, cost-effectiveness, and dimensional accuracy [40]. The mechanical properties of a bond are also affected by the manufacturing process: in-mold assembly and post-mold assembly [41]. A method for bonding titanium to the molding polymer designs is described in [42].

Advances in additive manufacturing have enabled the use of reliable industrial lasers, high-performance software, cost-effective equipment, and advanced raw materials for aerospace manufacturing [43]. Selective laser manufacturing parts can achieve full compaction with minimal defects if process parameters are carefully optimized [44,45]. Thus, process parameters must be correctly selected for each new material system [46]. Article [47] reviews the critical aspects of optimizing processing parameters affecting the properties of selective laser manufacturing titanium alloys and titanium matrix composites and critically evaluates the future prospects of such materials.

The cohesive zone material (CZM) model [48], depending on the normal component (mode I) and the tangential component (mode II), is usually used to describe the mechanics of adhesive interaction. A comparative modes analysis is presented in [49]. Delaminations can grow rapidly under mode I or mode II interlaminar fatigue loads [50–52], which significantly limits the acceptable damage size for aircraft composite designs. In some cases, a mixed mode model is used, which considers both directions of destruction [53]. It was noted in [54,55] that materials demonstrate higher resistance to mode II crack propagation compared to mode I. The work [56] shows the effectiveness of increasing the roughness of the bushing and using stiffeners to reduce the mass of the bond. It was noted that mode II has the greatest impact on reducing the mass of the entire lug. Coefficients of the CZM model for composite/metal bonds are defined in [57–61]. The work [62] also notes a higher critical strain energy release rate for mode II compared to mode I. Moreover, mode I is difficult to measure and requires long samples [63]. The parameters of the contact interaction between metals and polymers are presented in [40]. Among the forty studies presented, contact interaction with titanium is presented only in one work [42] using the example of assessing the interaction of the PPS30GF/Ti6Al4V bond, therefore, assessing the parameters of contact of carbon filled PA6 with titanium alloys is relevant.

The goals of this study are to evaluate the parameters of the contact interaction model between parts made of thermoplastic short-reinforced composite materials based on polyamide-6 and embedded elements with different surface roughness values, made of titanium alloys manufactured by selective laser melting; and to evaluate the influence of the roughness of titanium embedded elements on the load-bearing capacity of designs. The study of the adhesive interaction model was carried out using lugs as an example because they are often encountered in practice, are easy to manufacture, and allow, through various loading methods, to obtain the characteristics of the contact model and verify this model.

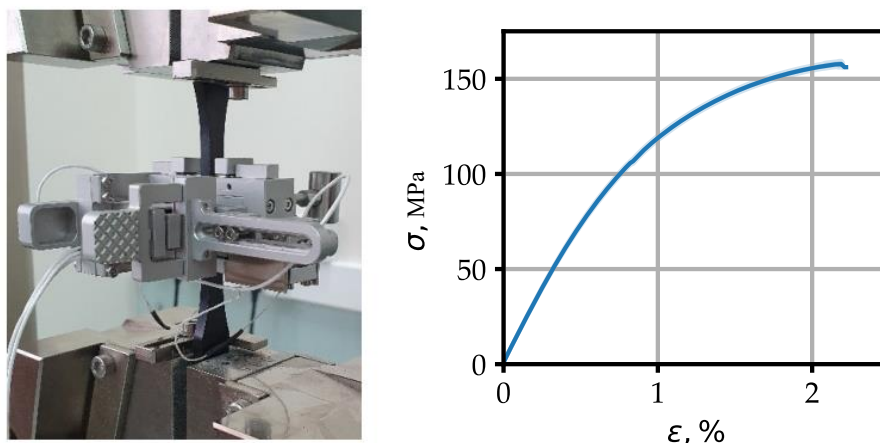
Chapter 2 describes the materials and methods used in this study. An experimental tool was manufactured to obtain the contact properties and load-bearing capacity characteristics of lugs. Chapter 3 describes the experimental results and shows the fabricated designs: molding lugs and selective laser melting bushings with different roughnesses. Chapter 4 compares the load-bearing capacity of two types of lugs with bushings having different surface roughness values. Chapter 5 describes the obtained results.

## 2. Materials and Methods

### 2.1. Materials and Material Models

The material chosen for the lug is polyamide-6, reinforced with 30% short carbon fibers - a structural material with high weight efficiency and the technological ability to be molded using thermoplastic machines at temperatures from 220 to 270 °C. The study of the characteristics of the short-reinforced polyamide used for the manufacture of lugs is presented in detail in [64] and includes the determination of the parameters of anisotropic models of the material used in the current work for numerical modeling. VT6 titanium, widely used for the SLM process and capable of withstanding high contact stresses, was chosen as the material for the embedded elements. A detailed study of the characteristics of the VT6 alloy used is presented in [21].

Tensile tests were performed on type 1BA samples according to the ISO 527-2 standard of polyamide-6 reinforced with 30% of the mass with short carbon fibers (Gamma-plast UPA 6 30 M) on a universal testing machine Zwick/Roell Z050 TE (see Figure 1). The compliance of the material model used in the strength calculations [64] with the mechanical characteristics of the samples in molding direction was confirmed.



**Figure 1.** Tensile test samples PA6+30% carbon fibers ISO 527-2 type 1BA (average value+standard deviation).

### 2.2. Methods

#### 2.2.1. Problem Statement and Lugs Geometry

The study of the adhesion interaction model was conducted using lugs as an example (see Figure 2). A previous study of the sensitivity of lug sizes to the characteristics of contact interaction [56]



showed that the maximum permissible stress in mode II of failure in the contact between the lug and the bushing has the greatest influence on the optimal lug bridge size. We will determine the dimensions of the lugs based on the experience gained in [56] in optimizing the sizes of lugs depending on the characteristics of the contact interaction. The diameter of the lug axis is 12 mm, the lug length from the axis to the embedment is 56 mm, the size of the lugs for embedding in the experimental study is 12 mm, and the thickness of the lugs is 5 mm. The lug width is determined by the size of bridge  $b$ . Assuming the transmission of force at a level of 5000N, we will choose lugs of two standard types S and M, differing in the width of the bridge  $b$  for S type  $b$  is 5 mm, for M type  $b$  is 10 mm. The S type is suitable for cases where the contact interaction strength between the bushing and the lug material exceeds 4 MPa. The M type is better suited with respect to type S when adhesion between the bushing and lug can be neglected. The thickness of the bushing for such a lug, based on the strength limits of titanium and the manufacturability of production, is 1 mm.

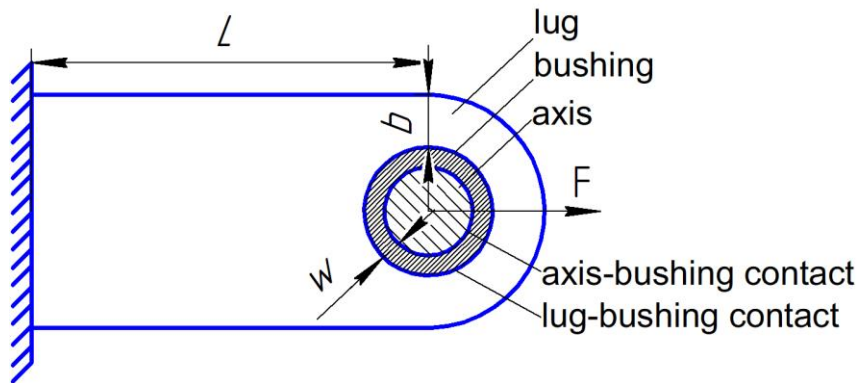


Figure 2. Statement of the problem.

### 2.2.1. CZM Model

The adhesive layer was considered by using contact elements in Ansys Mechanical APDL. The bilinear CZM model was used [65]. Since mode II has the greatest impact on reducing the mass of the entire lug [64], we choose a model based on mode II as the basis for predicting the load-bearing capacity of the lugs.

When describing the contact interaction tangential stress and were considered [65]:

$$\sigma_t = k_t u_t (1 - d_t),$$

where  $\sigma_t$  – tangential contact stresses, MPa,  $k_t$  – tangential contact stiffness, N/mm<sup>3</sup>,  $u_t$  – tangential slip distance, mm,  $u_t = \sqrt{u_1^2 + u_2^2}$ ,  $u_1$  and  $u_2$  – slip distances in the two principal direction in the tangent plane,  $d_t$  – debonding parameter. In the presence of compressive forces, the CZM model prevents penetration of the contacting surfaces. In case of unloading and subsequent reloading CZM model considering the debonding parameter [19] which is defined as follows:

$$d_t = \left( \frac{u_t - \bar{u}_t}{u_t} \right) \left( \frac{u_t^c}{u_t^c - \bar{u}_t} \right),$$

for  $\Delta_t > 1$  and  $d_t = 0$  for  $\Delta_t \leq 1$  where,  $\Delta_t = u_t / \bar{u}_t$ ,  $\bar{u}_t$  – tangential slip distance at the maximum tangential contact stress, mm.

The tangential critical value  $u_t^c$  calculate based on critical energy release rate  $G_t$  and maximum critical stress  $\sigma_t^c$ , which are parameters of the contact model [65]:

$$u_t^c = \frac{2G_t}{\sigma_t^c}.$$

The process of convergence of the Newton-Raphson algorithm at a nonlinearity of the debonding type can be challenging; therefore, artificial damping was used to accelerate and stabilize the convergence process, which limits the amplitude of the change in the destruction parameter during the transition from one iteration to another:

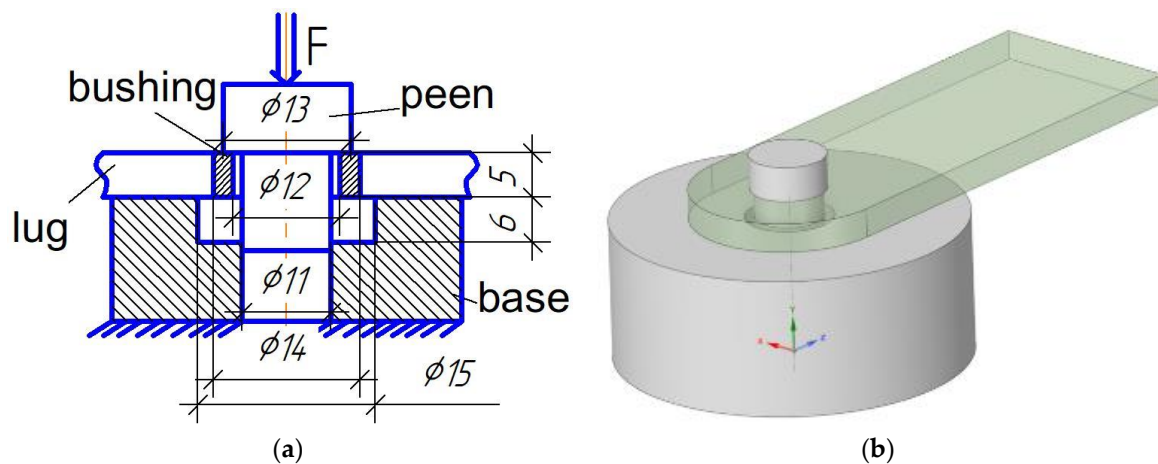
$$d_v = \frac{d\Delta t + d_{old}\eta}{\Delta t + \eta},$$

where  $\Delta t$  – the time step (in the case of a static calculation, the time varies from 0 to 1 and is fictitious, determining simply the current load value),  $d_{old}$  – the destruction parameter in the previous step,  $\eta$  – the damping coefficient. The damping coefficient must be small compared to the time step to avoid introducing significant errors into the calculation. In this study, the damping coefficient was set to 0.01.

The values that determine the properties of the contact interaction of the bushing and the lug body were  $\sigma_t^c$ ,  $G_t^c$ ,  $\eta$ .

## 2.2.2. Determination of Contact Properties

To determine the parameters of adhesive interaction in mode II, which determines the destruction caused by shear, extrusion tests were performed on bushings with varying degrees of roughness along the lug axis (see Figure 3). The tool for bushing extrusion along the axis consists of a base and peen (Figure 3) and is intended for use in conjunction with sample compression grips on a universal testing machine Zwick/Roell Z050 TE. The diameter of the top of the peen is 13 mm, allowing overlap of half the bushing thickness, while the base hole diameter is 15 mm, which is 1 mm larger than the external bushing diameter. The tool design allows us to organize the shear loading during bushing extrusion.

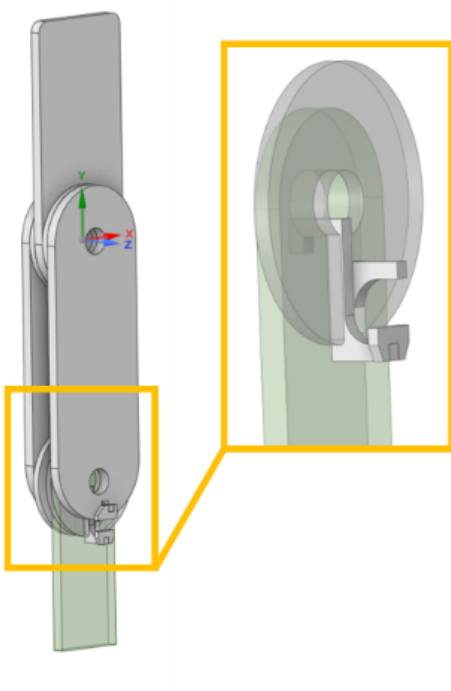


**Figure 3.** Test scheme for determining the characteristics of the adhesion interaction model in mode II (tangential), (a) scheme of load, (b) 3d model of tool.

## 2.2.2. Determination of the Load-Bearing Capacity of Lugs with Bushings

The load-bearing capacity of lugs with various embedded elements was assessed by tensile tests on a servo-hydraulic machine Shimadzu EHF-E.

A tool for the tensile testing of lugs has been manufactured (see Figure 4). The tool allows you to measure both the movements of the entire lug and separately control the displacement of the rear wall of the lug axis by installing an extensometer.



**Figure 4.** Test scheme for determining the load-bearing capacity of lugs.

2.2.3. Manufacturing of Embedded Elements

The production of titanium embedded mold elements was carried out using an additive installation 3DLAM Mid. The 3DLAM Mid selective laser melting system is designed for single and small-scale production of arbitrary-shaped parts by layer-by-layer selective fusion of metal powders with grain size 50 μm. Process parameters were controlled using the software 3DLAM Slicer (see Table 1). After assigning the main technological parameters of the selective laser melting (SLM) process, a work file for manufacturing the part was generated. The manufacturing process is shown in Figure 5.



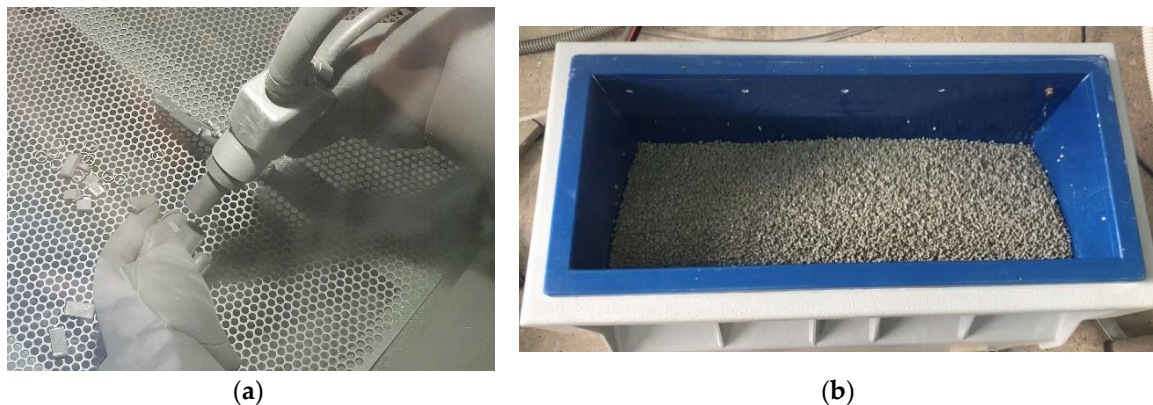
**Figure 5.** Manufacturing process of embedded elements.

**Table 1.** Technological parameters of the SLM process.

Parameter	Value
Laser power, W	240
Scanning speed, mm/s	800
Scanning step, mm	0,09
Layer thickness, μm	280

Separation of the workpieces from the construction platform was performed using electrical discharge machining. After separation from the construction platform, mechanical processing of the samples was performed to bring the landing dimensions to the accuracy required for the molding process. Providing gaps between the mold and the embedded element in the range of 0.05–0.1 mm allowed for easy removal of molding parts, but did not allow plastic to penetrate the gaps between the embedded elements and the mold.

The embedded elements are divided into three groups according to the degree of roughness - the first part of the elements is left with the roughness obtained in the SLM process, the second part is subjected to sandblasting, and the third part is vibratory finishing (see Figure 6).

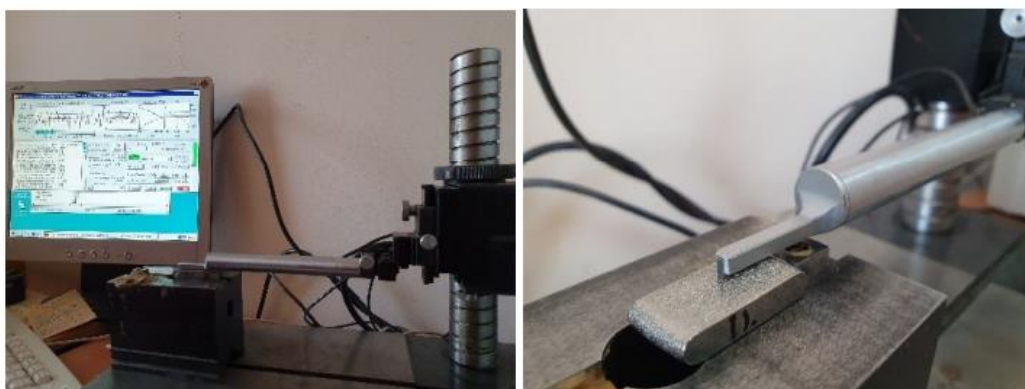


**Figure 6.** The roughness: (a) sandblasting, (b) vibratory finishing.

Because the results of the parametric study revealed a high role of the shear strength of the contact, it was selected to additionally manufacture bushings with ribs. More than 50 embedded bushings were manufactured - from 5 to 7 of each roughness (vibratory finishing, sandblasting, initial SLM process, ribs) for each of the two standard types of the lug and more than 40 flat samples of two types of embedded elements (14 flat samples for each degree of roughness).

#### 2.2.4. Measuring the Roughness of Samples

After surface treatment, the roughness of flat samples was studied using a profilometer (see Figure 7).



**Figure 7.** Roughness measurement.

#### 2.2.5. Manufacturing of Samples of Lugs

The lug molding tool was made of steel by milling on a computer numerically controlled (CNC) machine. The heating of the tool was performed using air heating elements. Tool cooling is not required because of the small series and long molding cycles. Injection molding of designs with embedded elements and samples made of short-reinforced composite material was performed on a



Negri Bosi VE1700-210 electric injection molding machine (see Figure 8). A preliminary simulation of the injection molding process was performed using Moldflow.

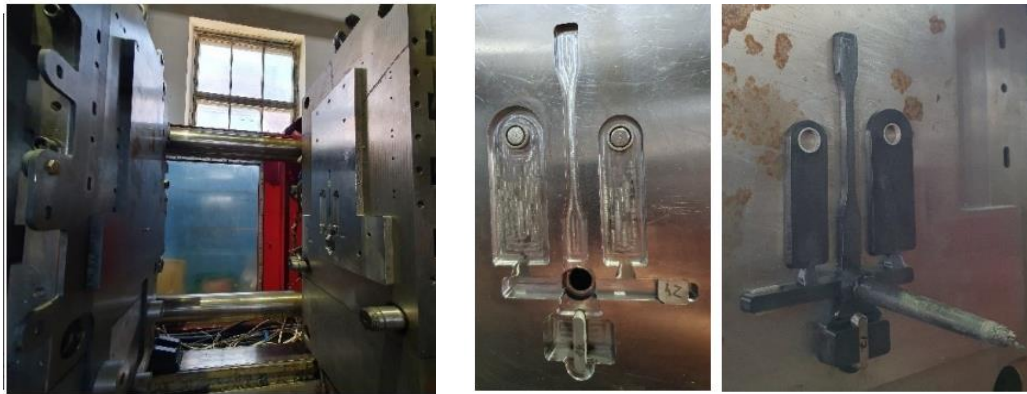


Figure 8. Injection molding process.

### 3. Results

#### 3.1. Manufacturing of Samples of Embedded Elements and Lugs

To prepare embedded elements for 3D printing, finite element modeling of the SLM process was performed using the Simufact Additive CAE system. According to the calculation, the deformation due to thermal stresses is 0.03-0.06 mm, which indicates the correctness of the selected technological modes (see Figure 9).

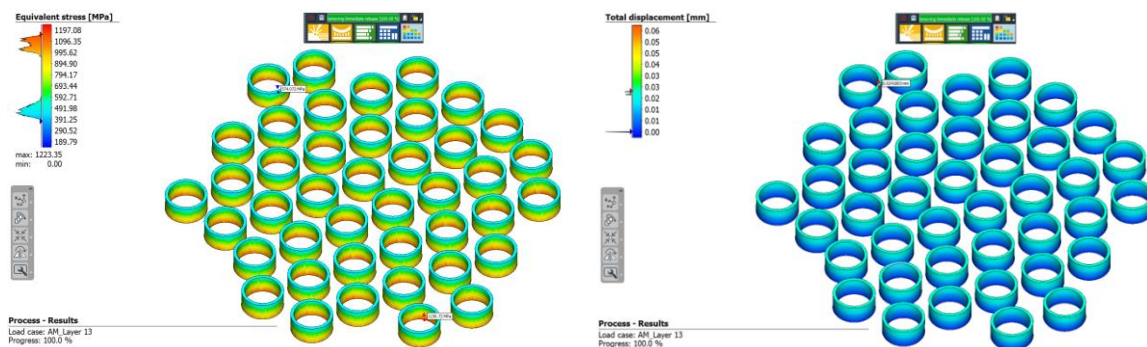
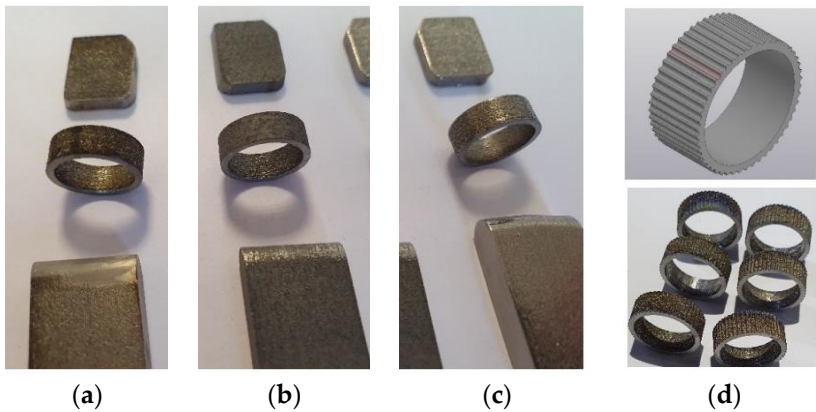


Figure 9. Stress-strain analysis.

The production of titanium embedded elements was carried out using a 3DLAM Mid additive machine. Process parameters are controlled using the 3DLAM Slicer software. More than 50 embedded bushings and more than 40 flat samples of three roughnesses were manufactured using the SLM method. Three types of roughness are provided by the SLM process, sandblasting, and vibratory finishing (see Figure 10).



**Figure 10.** The roughness: (a) SLM process; (b) sandblasting; (c) vibratory finishing; (d) ribbing.

Measurements of the surface roughness of samples of each type showed that the used additive technology produces a surface with a roughness of  $R_a = 10\text{ }\mu\text{m}$ , sandblasting reduces the roughness to  $8.8\text{ }\mu\text{m}$ , and vibratory finishing provides a surface with a roughness of  $2.7\text{ }\mu\text{m}$  (see Table 2).

**Table 2.** Measurement results.

Surface	$R_a,\text{ }\mu\text{m}$	CV, %
Vibratory finishing	2,66	24,6
Sandblasting	8,79	24,9
SLM	10,02	17,9

More than 35 molded parts were made, each of which contained lugs of two standard types and samples (see Figure 11).



**Figure 11.** Manufactured lugs.

3.1. Experimental Determination of Mechanical Characteristics of Contact

A tool was designed and manufactured that allows extruding the lug bushing using clamps to compress the samples (Figure 3) on a universal testing machine Zwick/Roell Z050 TE. 10 lugs of M type were tested for extrusion, 3 samples each with bushings after vibratory finishing and sandblasting, and 4 samples with the original surface after the SLM process (see Figures 12 and 13).

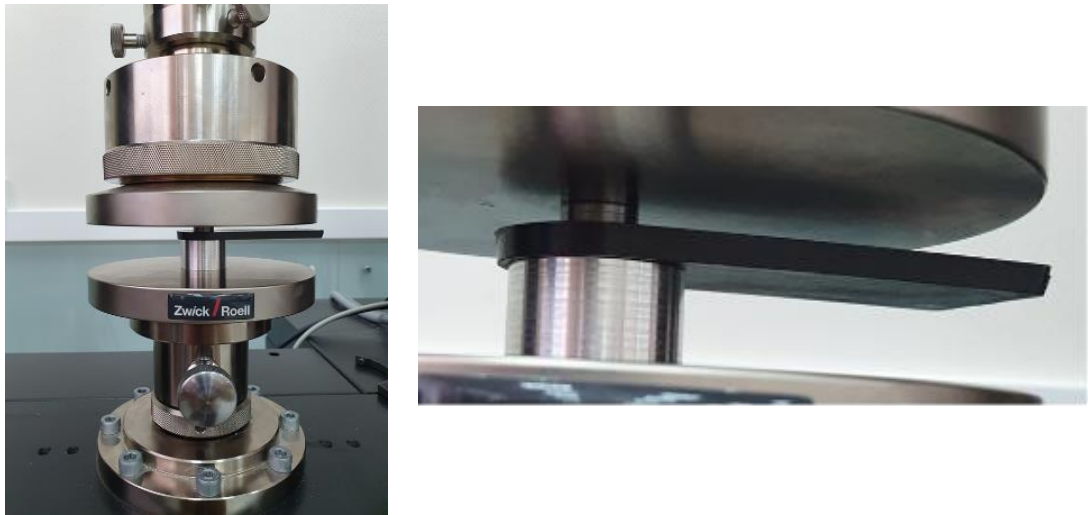


Figure 12. Tests for extrusion of the bushing along the axis.

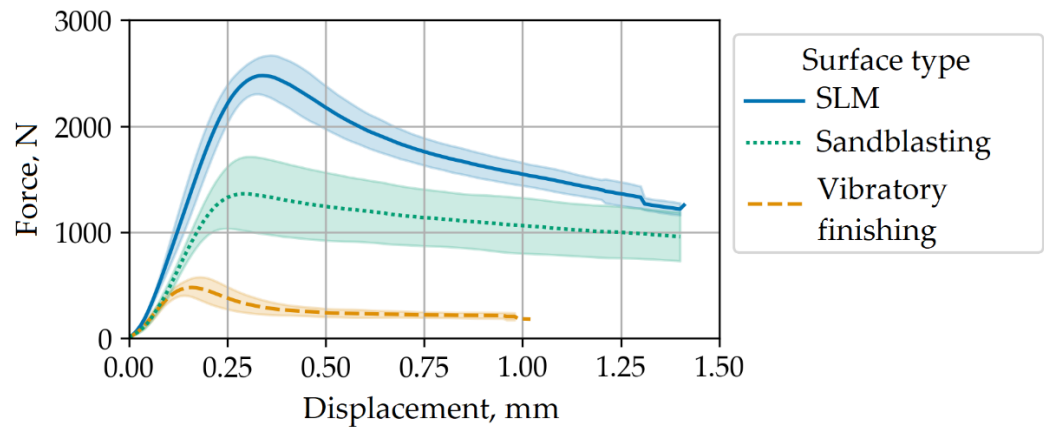
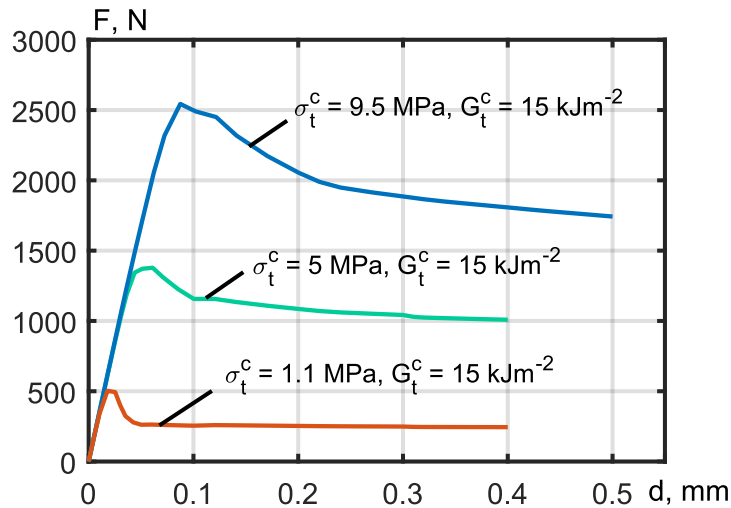


Figure 13. Experimentally obtained force from displacement for extrusion of the bushing along the axis with different embedded elements surface types.

The parameters of the adhesion interaction model for mode II were fitted based on studies on extrusion of bushings along the axis. It is shown that vibratory finishing corresponds to a maximum equivalent tangential contact stress of 1.1 MPa, sandblasting corresponds to 5 MPa, and the original SLM technology provides a contact shear strength of 9.5 MPa. The rate of energy release in this case is 15 N/mm (see Figure 14).



**Figure 14.** Calculation of extrusion of the bushing along the axis of the lug with different parameters of CZM Mode II model.

3.2. Verification of Molding Models

A comparison was made of the strength and rigidity of designs with embedded elements made of short-reinforced composite materials, obtained experimentally (partially filled) and by calculation, considering the anisotropy of the material model. To consider the anisotropy of the lud, a thermoplastic molding calculation was performed using the Autodesk Moldflow system, including the calculation of the orientation of the reinforcing fibers. The calculation was verified by determining the correspondence between the calculated (colored) and experimentally observed ( black) molding fronts (see Figure 15).



**Figure 15.** Comparison of calculated and experimentally obtained molding fronts.

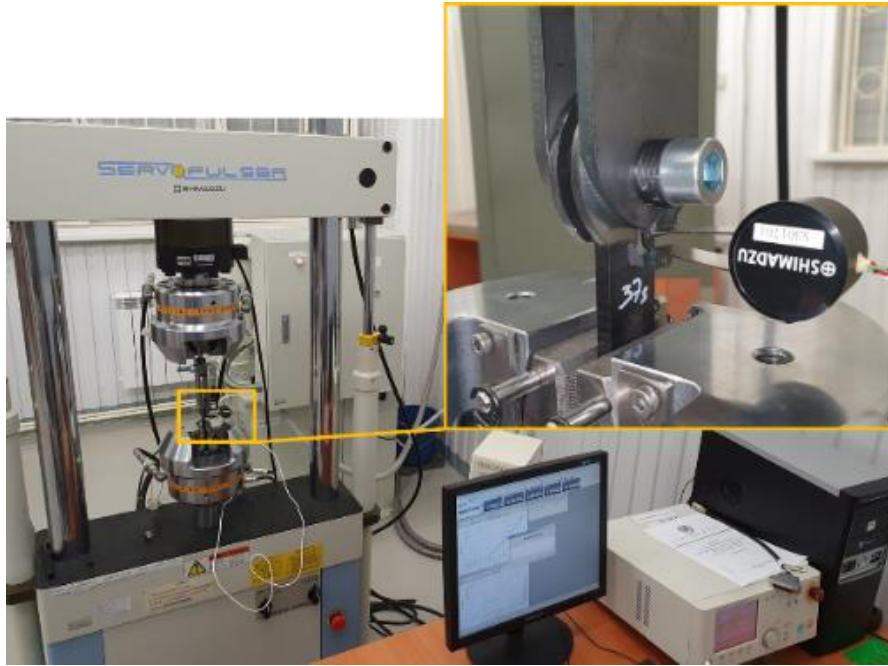
3.2. Experimental Determination of the Load-Bearing Capacity of Lugs with Bushings

60 samples of lugs were tested - two standard types S and M with 5 surface options for embedded elements (vibratory finishing; sandblasting; SLM, bushing with ribs, with the original roughness of SLM process; lugs without bushing) (see Figure 16, Table 3).

**Table 3.** Load-bearing capacity of lugs with different surfaces of embedded elements.

Surface	F max, N	CV, %	F max, N	CV, %
	S type		M type	
Vibratory finishing	4886	6.96	7457	6.54
Sandblasting	5186	3.39	7302	5.10
SLM	5429	1.63	7722	1.73
Ribbing	6029	1.24	8388	2.48
Without bushing	5008	1.72	7551	6.71

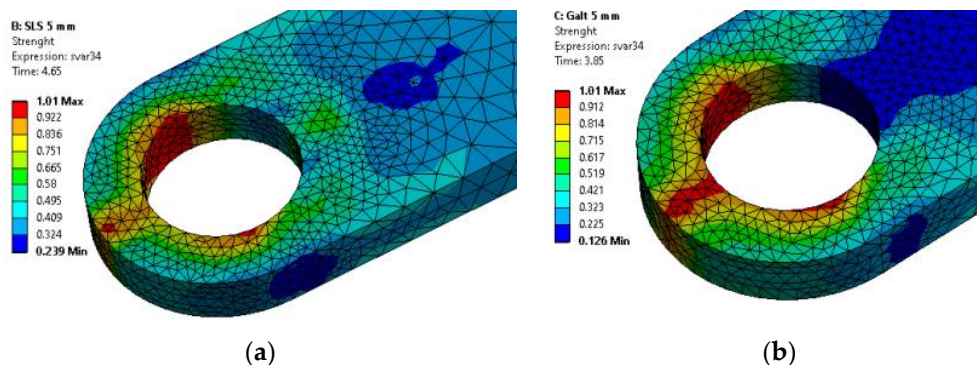




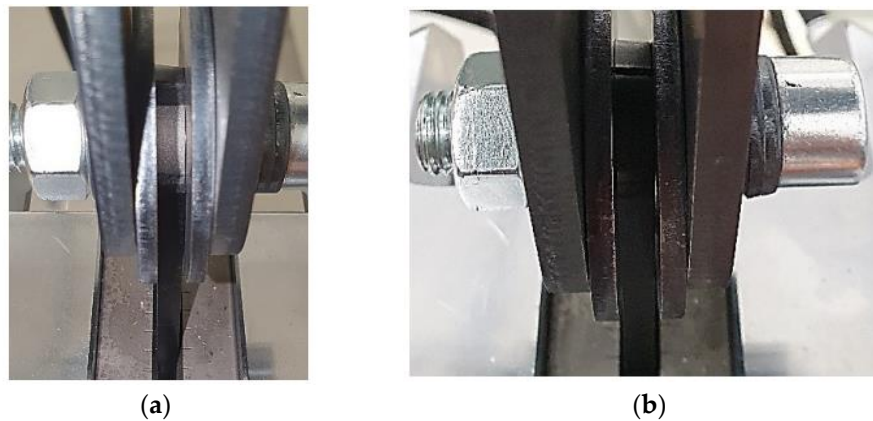
**Figure 16.** Test to determine the load-bearing capacity of lugs.

### 3.3. Verification of the Contact Interaction Model

Considering the orientation of the reinforcing fibers makes it possible to use the anisotropic Tsai-Hill strength criterion in the First pseudo-grain failure (FPGF) formulation, which allows one to correctly predict the strength of short-reinforced composite materials, since the field of equivalent von Mises stresses cannot correctly consider the anisotropic behavior of plastics, for example, destruction in the lug nose of size S caused by the presence of a weld line. A comparison of the fields of the Tsai Hill strength criterion with the places of destruction of the samples shows a correct prediction of the places of initiation of destruction (see Figure 17). Moreover, the fracture locations, both in calculations and in experiments, depend on the contact parameters - S-type lugs with embedded parts processed by vibratory finishing are destroyed along the weld line in the lug nose, whereas lugs with embedded surfaces using SLM process are destroyed from the side, in the place of the highest contact stresses (see Figure 18).



**Figure 17.** Calculation of the strength criterion at the lugs destruction moment: (a) SLM bushing surface, (b) Vibratory finishing bushing surface.



**Figure 18.** Destruction of lugs with bushings of different roughness: **(a)** SLM bushing surface, **(b)** Vibratory finishing bushing surface.

It is shown that the mathematical models used give a result that corresponds qualitatively - greater roughness gives greater load-bearing capacity and has load-bearing capacity values of the same order, but in the calculations, the influence of roughness on the load-bearing capacity is much stronger (see Table 4). In calculations, the difference between the load-bearing capacity of pin-joints with bushings with surface after SLM and vibratory finishing is 53% for the S type and 44% for the M type, whereas in experiments, this difference is 11% for the S type and 3.5% for the M type.

**Table 4.** Calculated lag load capacity with fitted CZM Mode II parameters.

Surface	F max, N	
	S type	M type
Vibratory finishing	4741	6386
Sandblasting	6344	8052
SLM	7260	9220

#### 4. Discussion

It has been experimentally confirmed that an increase in the roughness of the embedded element leads to an increase in the load-bearing capacity of the lugs. Thus, compared with the surface obtained by vibratory finishing, the original surface after the SLM process gives the load-bearing capacity of the unit 11% higher for standard S type and 3,5% higher for standard M type. For S type, during the design of which the contribution of the adhesive connection was considered, the influence of roughness is more noticeable than for M type, where the main load-bearing capacity lies on the lug body. The weight of the M type lug is 17 g, which is 1.58 times more than the weight of the S type lug (which weighs 10.7 g), and the maximum tensile load is only 1.42 times higher. Therefore, the S-type lug designed with an adhesive connection in mind has a weight efficiency that is 11.7% higher than that of the M-type lug. A comparison of the load-bearing capacity of lugs with a bushing and reference lugs without a bushing with the same internal and external diameters shows that the presence of a bushing with weak adhesion can lead to a decrease in the load-bearing capacity of the pin-joint compared with a pin-joint without an embedded element due to a reduction in the cross-sectional area of the plastic. The assumption about the importance of increasing the maximum equivalent tangential contact stress is confirmed by the fact that lugs with a bushing with ribs have a load-bearing capacity of 11% for S type and 8.6% for M type compared with lugs with a bushing of the same roughness, determined by the SLM process. Compared with lugs without bushings, the use of bushings with ribs increases the load-bearing capacity by 20% for S type and 11% for M type. The weight efficiency of an S-type lug with a bushing with ribs is 27% higher than that of an M-type lug without a bushing, which indicates the possibility of a significant reduction in weight with the development of SLM technology for the manufacture of embedded elements for aerospace designs. To determine the parameters of adhesive interaction in mode II, which determines damage caused

by shear, extrusion tests were performed on bushings with varying degrees of roughness along the lug axis on a universal testing machine Zwick/Roell Z050 TE. The force acting on the bushing along the extrusion axis for surfaces provided by the SLM process, sandblasting, and vibratory finishing are 2500, 1383, and 496 N, respectively. That is, sandblasting can reduce the plastic shear force by 45%, and vibrating finishing can reduce the contact shear force by 80%.

## 5. Conclusion

This article describes the results of a study on the load-bearing capacity of an aerospace design with embedded elements with different surface roughness values. The CZM model of cohesive elements was used as the main model of contact interaction. The dimensions of the embedded elements are determined on the basis of parametric optimization, taking into account the various types of contact interactions. An experimental study was conducted using an example of lugs of two sizes. More than 50 embedded bushings and more than 40 flat samples of three roughnesses provided by the initial SLM process, sandblasting, and vibratory finishing were manufactured using the SLM method. A tool and 35 injection molding parts were made, each of which contained lugs of two types and flat samples. 60 lugs of two types and five types of bushings were tested, the surface of which was obtained by vibratory finishing, sandblasting, the SLM process, bushings with ribs, and lugs without a bushing. The rib height of the lug is 0.2 mm.

It has been shown that the use of sandblasting can reduce the shear force of plastic by 45%, and the use of vibratory finishing can reduce the shear force in contact by 80%. The mathematical models were refined based on the results of sample testing. A comparison was made of the strength of the designs with embedded elements made of short-reinforced composite materials obtained experimentally and by calculation. A comparison of the fields of the Tsai Hill strength criterion with the places of destruction of the samples shows a correct prediction of the places of initiation of destruction.

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