
sscnnFigure01

```
In[*]:= SmainDir = SetDirectory[NotebookDirectory[]];
Get["SchematicSolver`"]
<< SSknowledgeImp00`

In[*]:= SetOptions[DrawElement, {BaseStyle → {FontFamily → "Times", FontSize → 16}}];
plotStyleDD = {{Dashing[.01], GrayLevel[.5]}, {Dashing[.01], GrayLevel[.5]}};
SetOptions[DrawElement, {ElementSize → {1, 1},
  PlotStyle → {{RGBColor[0, 0, 0.7], Thickness[0.004], PointSize[0.01]},
    {RGBColor[0, 0, 1], Thickness[0.0025], PointSize[0.01]}},
  ShowArrowTail → True, ShowNodes → True, TextOffset → Automatic,
  BaseStyle → {FontFamily → "Times", FontSize → 16}}];

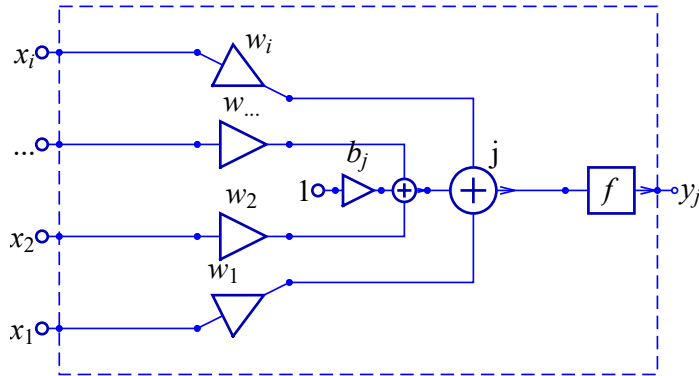
In[*]:= artNeuronInp04 = {
  {"Input", {0, 0}, XX1, " ", TextOffset → {1, 0}},
  {"Input", {0, 2}, XX2, " ", TextOffset → {1, 0}}, {"Input", {0, 4}, XX3, " ",
    TextOffset → {1, 0}}, {"Input", {0, 6}, XX4, " ", TextOffset → {1, 0}}};
artNeuronOut04 = {
  {"Output", {13, 3}, YY1, " ", TextOffset → {-1, 0}}};
artNeuronBody04 = {
  {"Adder", {{7, 3}, {5, 2}, {8, 3}, {5, 4}}, {1, 1, 2, 1}, " "},
  {"Adder", {{8, 3}, {5, 1}, {11, 3}, {5, 5}}, {1, 1, 2, 1}, "j"},
  {"Function", {{11, 3}, {13, 3}}, f, " "},
  {"Input", {6, 3}, 1, " ", TextOffset → {1, 0}},
  {"Line", {{0, 0}, {3, 0}}, {"Line", {{0, 2}, {3, 2}}},
  {"Line", {{0, 4}, {3, 4}}, {"Line", {{0, 6}, {3, 6}}},
  {"Multiplier", {{3, 0}, {5, 1}}, W11, " ", ElementSize → {1, 1}},
  {"Multiplier", {{3, 2}, {5, 2}}, W21, " ", ElementSize → {1, 1}},
  {"Multiplier", {{3, 4}, {5, 4}}, W31, " ", ElementSize → {1, 1}},
  {"Multiplier", {{3, 6}, {5, 5}}, W41, " ", ElementSize → {1, 1}},
  {"Multiplier", {{6, 3}, {7, 3}}, b01, " "},
  {"Polyline", {{0, -1}, {13, -1}, {13, 7}, {0, 7}, {0, -1}}};
```

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In[*]:= subsSymbW = {W11 → w1, W21 → w2, W31 → w..., W41 → w1};
subsSymbB = {b01 → bj};
subsSymbX = {XX1 → x1, XX2 → x2, XX3 → "...", XX4 → xi, YY1 → yj};
mySchematic = artNeuronInp04 ~ Join ~ artNeuronBody04 ~ Join ~ artNeuronOut04;
figure001 = Show[
  {DrawElement /@ (mySchematic /. subsSymbX /. subsSymbB /. subsSymbW)}, Frame → False]

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Out[*]=



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In[*]:= (* Export["figure001.tif",figure001,ImageResolution→300] *)

```

sscnFigure02

```

In[*]:= mainDir = SetDirectory[NotebookDirectory[]];

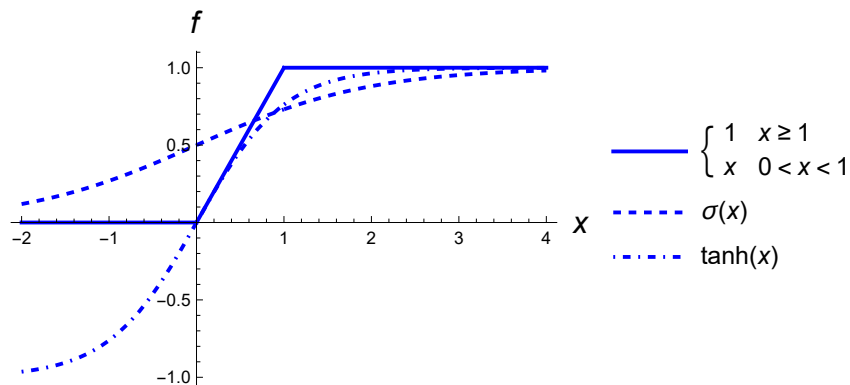
```

```

In[*]:= Clear[b, softmax, W, x, yRamp]
Piecewise[{{Piecewise[{{x, x < 1}}, 1], x > 0}}, 0];
yRamp = PiecewiseExpand[%];
figure002 = Plot[{yRamp, LogisticSigmoid[x], Tanh[x]}, {x, -2, 4},
  ImageSize → {Automatic, 200},
  PlotStyle → {{Thick, Blue}, {Thick, Dashed, Blue}, {Thick, DotDashed, Blue},
    {Thick, DotDashed, Orange}}, PlotLegends → {PiecewiseExpand[
    Piecewise[{{Piecewise[{{x, x < 1}}, 1], x > 0}}, 0]] // TraditionalForm,
    LogisticSigmoid[x] // TraditionalForm, Tanh[x] // TraditionalForm},
  AxesLabel → {Style["x", Italic, FontFamily → "Arial", FontSize → 16],
    Style["f", Italic, FontFamily → "Arial", FontSize → 16]}}

```

Out[*]=



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In[*]:= (* Export["figure002.tif",figure002,ImageResolution→300] *)

```

sscnFigure03

```

In[*]:= SmainDir = SetDirectory[NotebookDirectory[]];
Get["SchematicSolver`"]
<< SSKnowledgeImp00`

In[*]:= SetOptions[DrawElement, {BaseStyle → {FontFamily → "Times", FontSize → 16}}];
plotStyleDD = {{Dashing[.01], GrayLevel[.5]}, {Dashing[.01], GrayLevel[.5]}};
SetOptions[DrawElement, {ElementSize → {1, 1},
  PlotStyle → {{RGBColor[0, 0, 0.7], Thickness[0.004], PointSize[0.01]},
    {RGBColor[0, 0, 1], Thickness[0.0025], PointSize[0.01]}},
  ShowArrowTail → True, ShowNodes → True, TextOffset → Automatic,
  BaseStyle → {FontFamily → "Times", FontSize → 16}}];

In[*]:= artNeuronInp04 = {
  {"Input", {0, 0}, XX1, " ", TextOffset → {1, 0}},
  {"Input", {0, 2}, XX2, " ", TextOffset → {1, 0}}, {"Input", {0, 4}, XX3, " ",
    TextOffset → {1, 0}}, {"Input", {0, 6}, XX4, " ", TextOffset → {1, 0}}};
artNeuronOut04 = {
  {"Output", {13, 3}, YY1, " ", TextOffset → {-1, 0}}};
artNeuronBody04 = {
  {"Adder", {{7, 3}, {5, 2}, {8, 3}, {7, 5}}, {1, 1, 2, 1}, " "},
  {"Adder", {{8, 3}, {5, 0}, {11, 3}, {12, 5}}, {1, 1, 2, 1}, "j"},
  {"Function", {{11, 3}, {13, 3}}, f, " "},
  {"Line", {{0, 0}, {3, 0}}},
  {"Line", {{0, 2}, {3, 2}}},
  {"Line", {{0, 4}, {3, 4}}},
  {"Line", {{0, 6}, {3, 6}}},
  {"Line", {{5, 6}, {7, 5}}},

  {"Line", {{5, 5}, {6, 8}}},
  {"Line", {{5, 4}, {7, 3}}},

  {"Line", {{5, 3}, {8, 8}}},
  {"Line", {{5, 1}, {10, 8}}},
  {"Modulator", {{3, 0}, {4, -1}, {5, 0}, {5, 1}},
    {1, 0, 2, 1}, W11, TextOffset → {1, -1}},
  {"Modulator", {{3, 2}, {4, -1}, {5, 2}, {5, 3}},
    {1, 0, 2, 1}, W21, TextOffset → {1, -1}},
  {"Modulator", {{3, 4}, {4, -1}, {5, 4}, {5, 5}},
    {1, 0, 2, 1}, W31, TextOffset → {1, -1}},
  {"Modulator", {{3, 6}, {4, 5}, {5, 6}, {4, 8}},
    {1, 0, 2, 1}, W41, TextOffset → {1, -1}},
  {"Polyline", {{0, -2}, {13, -2}, {13, 10}, {0, 10}, {0, -2}}};

```

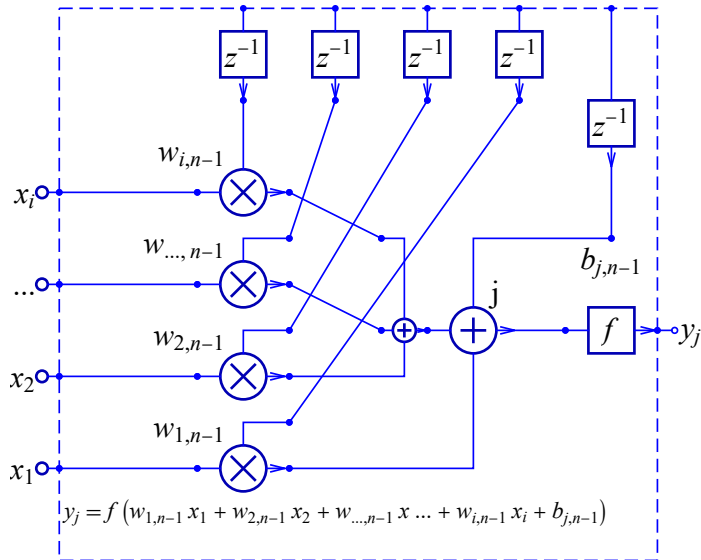
```

In[*]:= artNeuronDelay04 = {
  {"Text", {6, -1}, "yj = f (w1,n-1 x1 + w2,n-1 x2 + w...,n-1 x ... + wi,n-1 xi + bj,n-1)",
   BaseStyle → {FontFamily → "Times", FontSize → 12}},
  {"Text", {12, 4.5}, bj,n-1},
  {"Delay", {{4, 10}, {4, 8}}, 1, " "},
  {"Delay", {{6, 10}, {6, 8}}, 1, " "},
  {"Delay", {{8, 10}, {8, 8}}, 1, " "},
  {"Delay", {{10, 10}, {10, 8}}, 1, " "},
  {"Delay", {{12, 10}, {12, 5}}, 1, " "}};

In[*]:= subsSymbW = {W11 → w1,n-1, W21 → w2,n-1, W31 → w...,n-1, W41 → wi,n-1};
subsSymbB = {b01 → bj,n-1};
subsSymbX = {XX1 → x1, XX2 → x2, XX3 → "...", XX4 → xi, YY1 → yj};
mySchematic =
  artNeuronInp04 ~ Join ~ artNeuronBody04 ~ Join ~ artNeuronOut04 ~ Join ~ artNeuronDelay04;
figure003a = Show[
  {DrawElement /@ (mySchematic /. subsSymbX /. subsSymbB /. subsSymbW)}, Frame → False]

```

Out[*]=



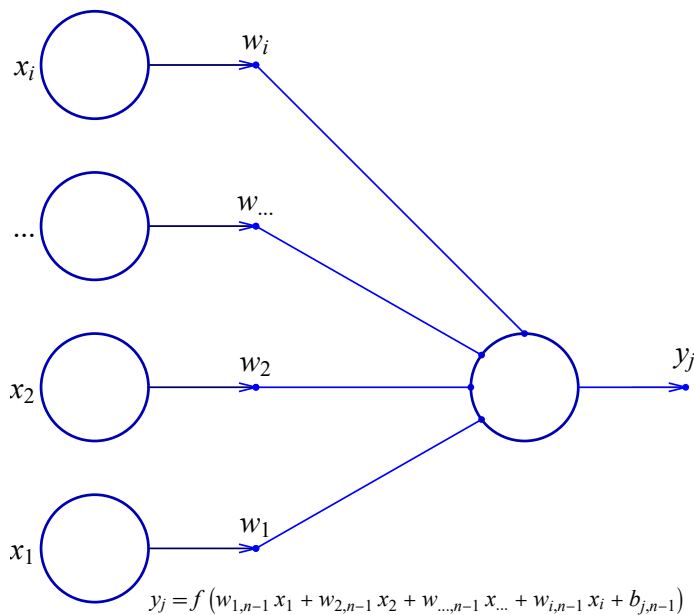
```

In[*]:= artNeuronLin004 = {
  {"Input", {2, 12}, XX4, "", ElementSize → 8, TextOffset → {1, 0}},
  {"Input", {2, 9}, XX3, "", ElementSize → 8, TextOffset → {1, 0}},
  {"Input", {2, 6}, XX2, "", ElementSize → 8, TextOffset → {1, 0}},
  {"Input", {2, 3}, XX1, "", ElementSize → 8, TextOffset → {1, 0}},
  {"Line", {{2, 12}, {7, 7}}},
  {"Line", {{2, 6}, {6, 6}}},
  {"Line", {{2, 9}, {6.2, 6.6}}},
  {"Line", {{2, 3}, {6.2, 5.4}}},
  {"Text", {5, 2}, "yj = f (w1,n-1 x1 + w2,n-1 x2 + w...,n-1 x... + wi,n-1 xi + bj,n-1)",
   BaseStyle → {FontFamily → "Times", FontSize → 12}},
  {"Text", {10, 6.6}, "yj"},
  {"Text", {2, 12.5}, "wi"},
  {"Text", {2, 9.5}, "w..."},
  {"Text", {2, 6.5}, "w2"},
  {"Text", {2, 3.5}, "w1"},
  {"Arrow", {{2, 12}, {0, 12}}},
  {"Arrow", {{2, 9}, {0, 9}}},
  {"Arrow", {{2, 6}, {0, 6}}},
  {"Arrow", {{2, 3}, {0, 3}}},
  {"Arrow", {{10, 6}, {9, 6}}},
  {"Input", {10, 6}, "", "", ElementSize → 8, TextOffset → {1, 0}}};

figure003b =
  Show[{DrawElement /@ (artNeuronLin004 /. subsSymbX /. subsSymbB /. subsSymbW)},
    Frame → False]

```

Out[*]=



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In[*]:= (*
Export["figure003a.tif",figure003a,ImageResolution→300];
Export["figure003b.tif",figure003b,ImageResolution→300];
*)

```

sscnnFigure04 and sscnnFigure05

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In[*]:= SmainDir = SetDirectory[NotebookDirectory[]];
Get["SchematicSolver`"]
<< SSknowledgeImp00`

In[*]:= subsSymb1 = {XX1 → x1, XX2 → x2, XX3 → x3, XX4 → x4, YY1 → y1, YY2 → y2, YY3 → y3, YY4 → y4};
subsSymb2 =
  {W11 → w11, W12 → w12, W13 → w13, W14 → w14, W21 → w21, W22 → w22, W23 → w23, W24 → w24,
   W31 → w31, W32 → w32, W33 → w33, W34 → w34, W41 → w41, W42 → w42, W43 → w43, W44 → w44};
subsSymb3 = {b01 → b01, b02 → b02, b03 → b03, b04 → b04, b11 → b11,
  b12 → b12, b13 → b13, b14 → b14, b21 → b21, b22 → b22, b23 → b23, b24 → b24};
SetOptions[DrawElement, {BaseStyle → {FontFamily → "Times", FontSize → 8}}];
SetOptions[DrawElement, {ElementSize → {1, 1}}];
plotStyleDD = {{Dashing[.01], GrayLevel[.5]}, {Dashing[.01], GrayLevel[.5]}};
SetOptions[DrawElement, {ElementSize → {1, 1},
  PlotStyle → {{RGBColor[0, 0, 0.7], Thickness[0.004], PointSize[0.0025]},
    {RGBColor[0, 0, 1], Thickness[0.0025], PointSize[0.003]}},
  ShowArrowTail → True, ShowNodes → True, TextOffset → Automatic,
  BaseStyle → {FontFamily → "Times", FontSize → 8}}];

In[*]:= artNeuronInp04 = {
  {"Input", {0, 3}, XX1, " ", TextOffset → {1, 0}},
  {"Input", {0, 10}, XX2, " ", TextOffset → {1, 0}}, {"Input", {0, 17}, XX3, " ",
    TextOffset → {1, 0}}, {"Input", {0, 24}, XX4, " ", TextOffset → {1, 0}}};
Show[{DrawElement /@ (artNeuronInp04 /. subsSymb1 /. subsSymb2)}, Frame → False];
artNeuronOut04 = {
  {"Output", {13, 3}, YY1, " ", TextOffset → {-1, 0}},
  {"Output", {13, 10}, YY2, " ", TextOffset → {-1, 0}},
  {"Output", {13, 17}, YY3, " ", TextOffset → {-1, 0}},
  {"Output", {13, 24}, YY4, " ", TextOffset → {-1, 0}}};
artNeuronBody04 = {
  {"Adder", {{7, 3}, {5, 2}, {8, 3}, {5, 4}}, {1, 1, 2, 1}, " "},
  {"Adder", {{8, 3}, {5, 1}, {11, 3}, {5, 5}}, {1, 1, 2, 1}, "1"},
  {"Adder", {{7, 10}, {5, 9}, {8, 10}, {5, 11}}, {1, 1, 2, 1}, " "},
  {"Adder", {{8, 10}, {5, 8}, {11, 10}, {5, 12}}, {1, 1, 2, 1}, "2"},
  {"Adder", {{7, 17}, {5, 16}, {8, 17}, {5, 18}}, {1, 1, 2, 1}, " "},
  {"Adder", {{8, 17}, {5, 15}, {11, 17}, {5, 19}}, {1, 1, 2, 1}, "3"},
  {"Adder", {{7, 24}, {5, 23}, {8, 24}, {5, 25}}, {1, 1, 2, 1}, " "},
  {"Adder", {{8, 24}, {5, 22}, {11, 24}, {5, 26}}, {1, 1, 2, 1}, "4"},
  {"Function", {{11, 24}, {13, 24}}, f, " "}, {"Function", {{11, 17}, {13, 17}}, f, " "},
  {"Function", {{11, 10}, {13, 10}}, f, " "}, {"Function", {{11, 3}, {13, 3}}, f, " "},
  {"Input", {6, 24}, 1, " ", TextOffset → {1, 0}},
  {"Input", {6, 17}, 1, " ", TextOffset → {1, 0}},
  {"Input", {6, 10}, 1, " ", TextOffset → {1, 0}},
  {"Input", {6, 3}, 1, " ", TextOffset → {1, 0}},
  {"Line", {{0, 3}, {3, 0}}, {"Line", {{0, 10}, {3, 2}}},
  {"Line", {{0, 3}, {3, 7}}, {"Line", {{0, 3}, {3, 14}}, {"Line", {{0, 3}, {3, 21}}},
  {"Line", {{0, 17}, {3, 4}}, {"Line", {{0, 10}, {3, 9}}, {"Line", {{0, 10}, {3, 16}}},
  {"Line", {{0, 10}, {3, 23}}, {"Line", {{0, 17}, {3, 11}}},

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{"Line", {{0, 17}, {3, 18}}}, {"Line", {{0, 17}, {3, 25}}},
{"Line", {{0, 24}, {3, 27}}}, {"Line", {{0, 24}, {3, 20}}},
{"Line", {{0, 24}, {3, 13}}}, {"Line", {{0, 24}, {3, 6}}},
{"Multiplier", {{3, 0}, {5, 1}}, W11, " ", ElementSize → {1, 1}},
{"Multiplier", {{3, 2}, {5, 2}}, W21, " ", ElementSize → {1, 1}},
{"Multiplier", {{3, 4}, {5, 4}}, W31, " ", ElementSize → {1, 1}},
{"Multiplier", {{3, 6}, {5, 5}}, W41, " ", ElementSize → {1, 1}},
{"Multiplier", {{3, 7}, {5, 8}}, W12, " ", ElementSize → {1, 1}},
{"Multiplier", {{3, 14}, {5, 15}}, W13, " ", ElementSize → {1, 1}},
{"Multiplier", {{3, 21}, {5, 22}}, W14, " ", ElementSize → {1, 1}},
{"Multiplier", {{3, 9}, {5, 9}}, W22, " "}, {"Multiplier",
  {{3, 11}, {5, 11}}, W32, " "}, {"Multiplier", {{3, 16}, {5, 16}}, W23, " "},
{"Multiplier", {{3, 18}, {5, 18}}, W33, " "}, {"Multiplier", {{3, 13}, {5, 12}},
  W42, " "}, {"Multiplier", {{3, 20}, {5, 19}}, W43, " "}, {"Multiplier",
  {{3, 23}, {5, 23}}, W24, " "}, {"Multiplier", {{3, 25}, {5, 25}}, W34, " "},
{"Multiplier", {{3, 27}, {5, 26}}, W44, " "}, {"Multiplier", {{6, 3}, {7, 3}},
  b01, " "}, {"Multiplier", {{6, 10}, {7, 10}}, b02, " "},
{"Multiplier", {{6, 17}, {7, 17}}, b03, " "}, {"Multiplier", {{6, 24}, {7, 24}},
  b04, " "}, {"Polyline", {{4.7, 0}, {10, 0}, {10, 6}, {4.7, 6}, {4.7, 0}}},
{"Polyline", {{4.7, 7}, {10, 7}, {10, 13}, {4.7, 13}, {4.7, 7}}},
{"Polyline", {{4.7, 14}, {10, 14}, {10, 20}, {4.7, 20}, {4.7, 14}}},
{"Polyline", {{4.7, 21}, {10, 21}, {10, 27}, {4.7, 27}, {4.7, 21}}};

```

```

In[*]:= subsSymbW0 = {W011 → w1,1, W021 → w1,2, W031 → w1,3, W041 → w1,4,
  W012 → w1,5, W022 → w1,6, W032 → w1,7, W042 → w1,8, W013 → w1,9, W023 → w1,10,
  W033 → w1,11, W043 → w1,12, W014 → w1,13, W024 → w1,14, W034 → w1,15, W044 → w1,16};
subsSymbW1 = {W111 → w2,1, W121 → w2,2, W131 → w2,3, W141 → w2,4,
  W112 → w2,5, W122 → w2,6, W132 → w2,7, W142 → w2,8, W113 → w2,9, W123 → w2,10,
  W133 → w2,11, W143 → w2,12, W114 → w2,13, W124 → w2,14, W134 → w2,15, W144 → w2,16};
subsSymbW2 = {W211 → w3,1, W221 → w3,2, W231 → w3,3, W241 → w3,4,
  W212 → w3,5, W222 → w3,6, W232 → w3,7, W242 → w3,8, W213 → w3,9, W223 → w3,10,
  W233 → w3,11, W243 → w3,12, W214 → w3,13, W224 → w3,14, W234 → w3,15, W244 → w3,16};
subsSymbB = {b01 → b1,1, b02 → b1,2, b03 → b1,3, b04 → b1,4, b11 → b2,1,
  b12 → b2,2, b13 → b2,3, b14 → b2,4, b21 → b3,1, b22 → b3,2, b23 → b3,3, b24 → b3,4};
subsSymbX = {XX1 → x1, XX2 → x2, XX3 → x3, XX4 → x4, YY1 → y1, YY2 → y2, YY3 → y3, YY4 → y4};
subsALL1 = (subsSymb1 ~ Join ~ subsSymbW0 ~ Join ~ subsSymbW2 ~
  Join ~ subsSymbW1 ~ Join ~ subsSymbW2 ~ Join ~ subsSymbB ~ Join ~ subsSymbX);

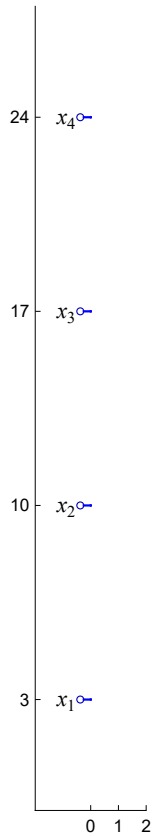
```

```

In[ ]:= SetOptions[DrawElement, {ElementSize → {1, 1},
  PlotStyle → {{RGBColor[0, 0, 0.7], Thickness[0.01], PointSize[0.02]},
    {RGBColor[0, 0, 1], Thickness[0.02], PointSize[0.007]}},
  ShowArrowTail → True, ShowNodes → True, TextOffset → Automatic,
  BaseStyle → {FontFamily → "Times", FontSize → 12}}];
figure004a = Show[{DrawElement /@ (artNeuronInp04 /. subsALL1)},
  Frame → {{True, False}, {True, False}},
  FrameTicks → {{0, 1, 2}, {3, 10, 17, 24}}, PlotRange → {{-2, 2}, {-1, 28}}]

```

Out[]=

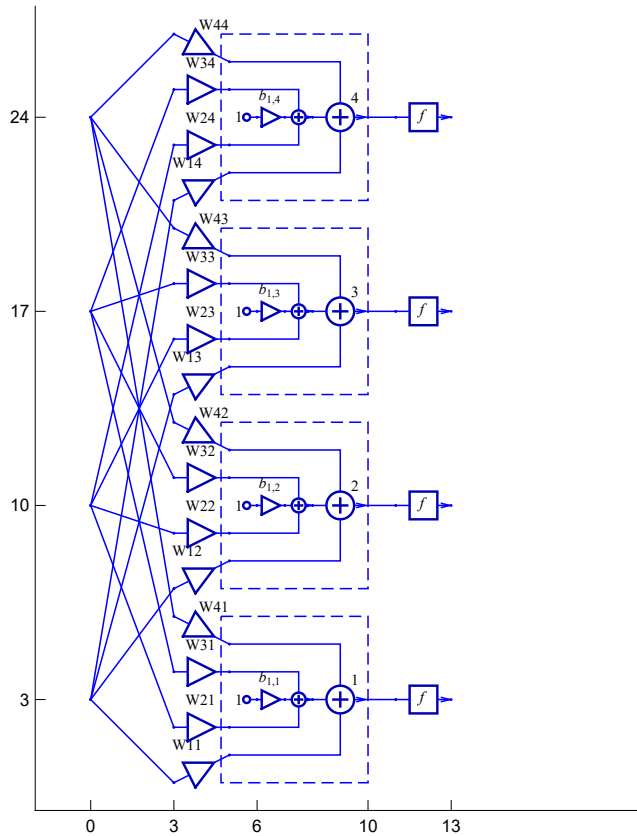



```

In[*]:= SetOptions[DrawElement, {ElementSize → {1, 1},
  PlotStyle → {{RGBColor[0, 0, 0.7], Thickness[0.004], PointSize[0.0025]}},
  {RGBColor[0, 0, 1], Thickness[0.0025`], PointSize[0.003]}},
  ShowArrowTail → True, ShowNodes → True, TextOffset → Automatic,
  BaseStyle → {FontFamily → "Times", FontSize → 8}]];
figure004b = Show[{DrawElement /@ (artNeuronBody04 /. subsALL1)},
  Frame → {{True, False}, {True, False}},
  FrameTicks → {{0, 3, 6, 10, 13}, {3, 10, 17, 24}}, PlotRange → {{-2, 20}, {-1, 28}}]

```

Out[*]=

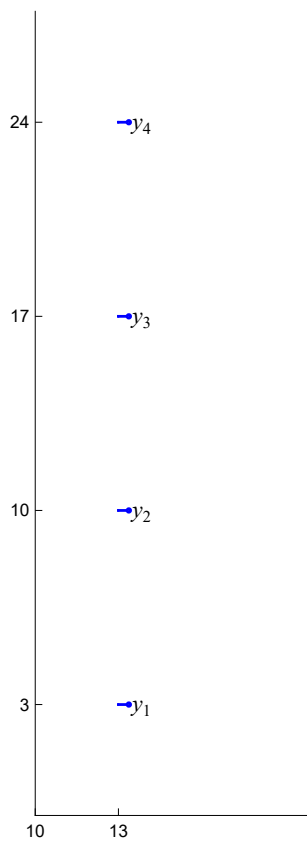


```

In[ ]:= SetOptions[DrawElement, {ElementSize → {1, 1},
    PlotStyle → {{RGBColor[0, 0, 0.7], Thickness[0.01], PointSize[0.01]},
    {RGBColor[0, 0, 1], Thickness[0.01], PointSize[0.007]}},
    ShowArrowTail → True, ShowNodes → True, TextOffset → Automatic,
    BaseStyle → {FontFamily → "Times", FontSize → 12}}];
figure004c = Show[{DrawElement /@ (artNeuronOut04 /. subsALL1)},
    Frame → {{True, False}, {True, False}},
    FrameTicks → {{10, 13}, {3, 10, 17, 24}}, PlotRange → {{10, 20}, {-1, 28}}]

```

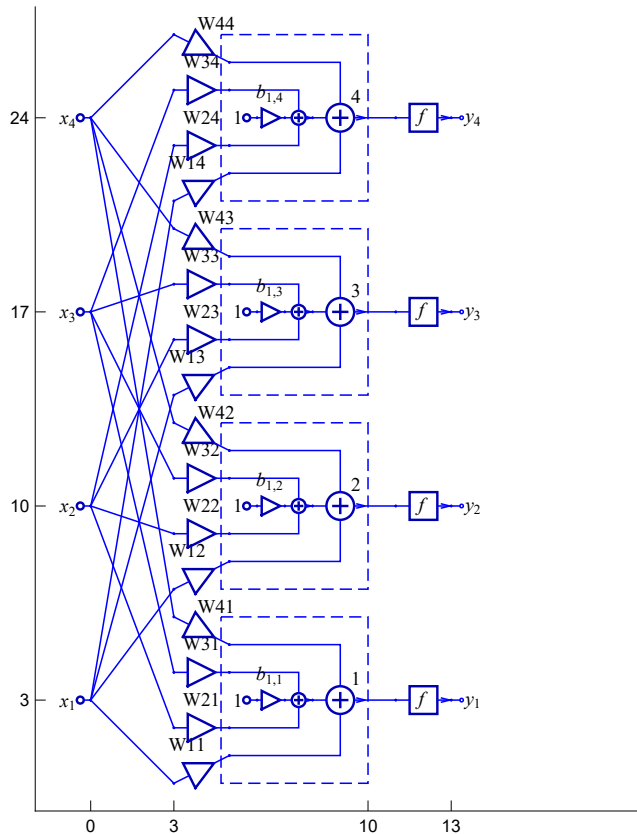
Out[]=



```

In[*]:= SetOptions[DrawElement, {ElementSize → {1, 1},
  PlotStyle → {{RGBColor[0, 0, 0.7], Thickness[0.004], PointSize[0.0025]}},
  {RGBColor[0, 0, 1], Thickness[0.0025], PointSize[0.003]}},
  ShowArrowTail → True, ShowNodes → True, TextOffset → Automatic,
  BaseStyle → {FontFamily → "Times", FontSize → 10}}];
mySchematic = artNeuronInp04 ~ Join ~ artNeuronOut04 ~ Join ~ artNeuronBody04;
figure004d =
  Show[{DrawElement /@ (mySchematic /. subsALL1)}, Frame → {{True, False}, {True, False}},
  FrameTicks → {{0, 3, 10, 13}, {3, 10, 17, 24}}, PlotRange → {{-2, 20}, {-1, 28}}]
Out[*]=

```



```

(*)
Export["figure004a.tif", figure004a, ImageResolution → 300];
Export["figure004b.tif", figure004b, ImageResolution → 300];
Export["figure004c.tif", figure004c, ImageResolution → 300];
Export["figure004d.tif", figure004d, ImageResolution → 300];
*)

```

Figure 5

```

In[*]:= mySchematic = artNeuronInp04 ~ Join ~ artNeuronOut04 ~ Join ~ artNeuronBody04;
SetOptions[DrawElement, {ElementSize → {1, 1},
  PlotStyle → {{RGBColor[0, 0, 0.7], Thickness[0.002], PointSize[0.0012]}},
  {RGBColor[0, 0, 1], Thickness[0.0012], PointSize[0.0014]}},
  ShowArrowTail → True, ShowNodes → True, TextOffset → Automatic,
  BaseStyle → {FontFamily → "Times", FontSize → 8}}];

```

```

In[*]:= numberOfStages = 3;
widthOfStages = 13;
systemBody = artNeuronBody04;
b1TOb1 = Thread[Flatten[{b01, b02, b03, b04}] → Flatten[{b01, b02, b03, b04}]];
b1TOb2 = Thread[Flatten[{b01, b02, b03, b04}] → Flatten[{b11, b12, b13, b14}]];
b1TOb3 = Thread[Flatten[{b01, b02, b03, b04}] → Flatten[{b21, b22, b23, b24}]];
b1TOb4 = Thread[Flatten[{b01, b02, b03, b04}] → Flatten[{b31, b32, b33, b34}]];
w1TOw1 =
  Thread[{W11, W12, W13, W14, W21, W22, W23, W24, W31, W32, W33, W34, W41, W42, W43, W44} →
    {W011, W012, W013, W014, W021, W022, W023, W024,
     W031, W032, W033, W034, W041, W042, W043, W044}];
w1TOw2 =
  Thread[{W11, W12, W13, W14, W21, W22, W23, W24, W31, W32, W33, W34, W41, W42, W43, W44} →
    {W111, W112, W113, W114, W121, W122, W123, W124,
     W131, W132, W133, W134, W141, W142, W143, W144}];
w1TOw3 =
  Thread[{W11, W12, W13, W14, W21, W22, W23, W24, W31, W32, W33, W34, W41, W42, W43, W44} →
    {W211, W212, W213, W214, W221, W222, W223, W224,
     W231, W232, W233, W234, W241, W242, W243, W244}];
w1TOw4 =
  Thread[{W11, W12, W13, W14, W21, W22, W23, W24, W31, W32, W33, W34, W41, W42, W43, W44} →
    {W311, W312, W313, W314, W321, W322, W323, W324,
     W331, W332, W333, W334, W341, W342, W343, W344}];
B1TObK = {b1TOb2, b1TOb3, b1TOb4};
W1TOWK = {w1TOw2, w1TOw3, w1TOw4};
f1TOfK = {f → f, f → f, f → g};
f1TOfK = {f → f, f → g, f → G};
Do[systemBody =
  Join[systemBody, (TranslateSchematic[artNeuronBody04, {k * widthOfStages, 0}] /.
    B1TObK[[k]] /. W1TOWK[[k]] /. f1TOfK[[k]])],
  {k, numberOfStages - 1}];

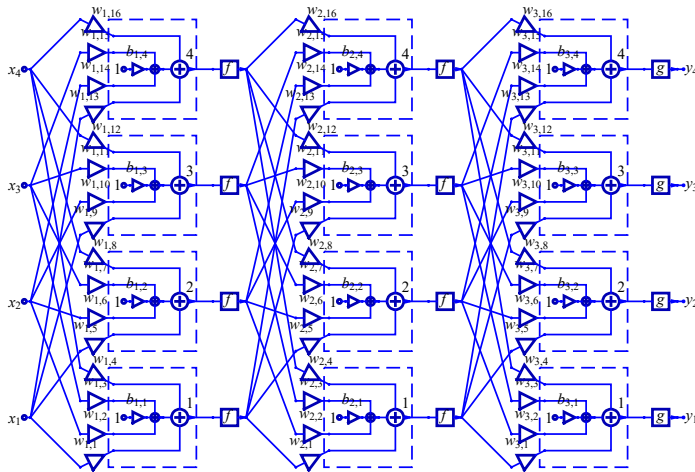
In[*]:= systemInBodyOut = artNeuronInp04 ~ Join ~ systemBody ~ Join ~
  (TranslateSchematic[artNeuronOut04, {(numberOfStages - 1) * widthOfStages, 0}]);

```

```

In[ ]:= mySchematic = systemInBodyOut;
subsALL1 = (subsSymb1 ~ Join ~ subsSymbW0 ~ Join ~ subsSymbW2 ~
  Join ~ subsSymbW1 ~ Join ~ subsSymbW2 ~ Join ~ subsSymbB ~ Join ~ subsSymbX);
SetOptions[DrawElement, {ElementSize → {1, 1},
  PlotStyle → {{RGBColor[0, 0, 0.7], Thickness[0.004], PointSize[0.0025]},
    {RGBColor[0, 0, 1], Thickness[0.0025], PointSize[0.003]}},
  ShowArrowTail → True, ShowNodes → True, TextOffset → Automatic,
  BaseStyle → {FontFamily → "Times", FontSize → 8}}];
figure005 = Show[{DrawElement /@ (mySchematic /. w1T0w1 /. subsALL1)}, Frame → False]
Out[ ]:=

```



```
(* Export["figure005.tif", figure005, ImageResolution → 300] *)
```

sscnFigure06

```

In[ ]:= SmainDir = SetDirectory[NotebookDirectory[]];
Get["SchematicSolver`"]
<< SSknowledgeImp00`

In[ ]:= subsSymb1 = {XX1 → x1, XX2 → x2, XX3 → x3, XX4 → x4, YY1 → y1, YY2 → y2, YY3 → y3, YY4 → y4};
subsSymb2 =
  {W11 → w11, W12 → w12, W13 → w13, W14 → w14, W21 → w21, W22 → w22, W23 → w23, W24 → w24,
    W31 → w31, W32 → w32, W33 → w33, W34 → w34, W41 → w41, W42 → w42, W43 → w43, W44 → w44};
subsSymb3 = {b01 → b01, b02 → b02, b03 → b03, b04 → b04, b11 → b11,
  b12 → b12, b13 → b13, b14 → b14, b21 → b21, b22 → b22, b23 → b23, b24 → b24};
SetOptions[DrawElement, {BaseStyle → {FontFamily → "Times", FontSize → 8}}];
SetOptions[DrawElement, {ElementSize → {1, 1}}];
plotStyleDD = {{Dashing[.01], GrayLevel[.5]}, {Dashing[.01], GrayLevel[.5]}};
SetOptions[DrawElement, {ElementSize → {1, 1},
  PlotStyle → {{RGBColor[0, 0, 0.7], Thickness[0.004], PointSize[0.0025]},
    {RGBColor[0, 0, 1], Thickness[0.0025], PointSize[0.003]}},
  ShowArrowTail → True, ShowNodes → True, TextOffset → Automatic,
  BaseStyle → {FontFamily → "Times", FontSize → 8}}];

In[ ]:= artNeuronInp04 = {
  {"Input", {0, 3}, XX1, " ", TextOffset → {1, 0}},
  {"Input", {0, 10}, XX2, " ", TextOffset → {1, 0}}, {"Input", {0, 17}, XX3, " ",

```

```

TextOffset → {1, 0}}, {"Input", {0, 24}, XX4, " ", TextOffset → {1, 0}}};
Show[DrawElement /@ (artNeuronInp04 /. subsSymb1 /. subsSymb2), Frame → False];
artNeuronOut04 = {
  {"Output", {13, 3}, YY1, " ", TextOffset → {-1, 0}},
  {"Output", {13, 10}, YY2, " ", TextOffset → {-1, 0}},
  {"Output", {13, 17}, YY3, " ", TextOffset → {-1, 0}},
  {"Output", {13, 24}, YY4, " ", TextOffset → {-1, 0}}};
artNeuronBody04 = {
  {"Adder", {{7, 3}, {5, 2}, {8, 3}, {5, 4}}, {1, 1, 2, 1}, " "},
  {"Adder", {{8, 3}, {5, 1}, {11, 3}, {5, 5}}, {1, 1, 2, 1}, "1"},
  {"Adder", {{7, 10}, {5, 9}, {8, 10}, {5, 11}}, {1, 1, 2, 1}, " "},
  {"Adder", {{8, 10}, {5, 8}, {11, 10}, {5, 12}}, {1, 1, 2, 1}, "2"},
  {"Adder", {{7, 17}, {5, 16}, {8, 17}, {5, 18}}, {1, 1, 2, 1}, " "},
  {"Adder", {{8, 17}, {5, 15}, {11, 17}, {5, 19}}, {1, 1, 2, 1}, "3"},
  {"Adder", {{7, 24}, {5, 23}, {8, 24}, {5, 25}}, {1, 1, 2, 1}, " "},
  {"Adder", {{8, 24}, {5, 22}, {11, 24}, {5, 26}}, {1, 1, 2, 1}, "4"},
  {"Function", {{11, 24}, {13, 24}}, f, " "}, {"Function", {{11, 17}, {13, 17}}, f, " "},
  {"Function", {{11, 10}, {13, 10}}, f, " "}, {"Function", {{11, 3}, {13, 3}}, f, " "},
  {"Input", {6, 24}, 1, " ", TextOffset → {1, 0}},
  {"Input", {6, 17}, 1, " ", TextOffset → {1, 0}},
  {"Input", {6, 10}, 1, " ", TextOffset → {1, 0}},
  {"Input", {6, 3}, 1, " ", TextOffset → {1, 0}},
  {"Line", {{0, 3}, {3, 0}}, {"Line", {{0, 10}, {3, 2}},
  {"Line", {{0, 3}, {3, 7}}, {"Line", {{0, 3}, {3, 14}}, {"Line", {{0, 3}, {3, 21}},
  {"Line", {{0, 17}, {3, 4}}, {"Line", {{0, 10}, {3, 9}}, {"Line", {{0, 10}, {3, 16}},
  {"Line", {{0, 10}, {3, 23}}, {"Line", {{0, 17}, {3, 11}},
  {"Line", {{0, 17}, {3, 18}}, {"Line", {{0, 17}, {3, 25}},
  {"Line", {{0, 24}, {3, 27}}, {"Line", {{0, 24}, {3, 20}},
  {"Line", {{0, 24}, {3, 13}}, {"Line", {{0, 24}, {3, 6}},
  {"Multiplier", {{3, 0}, {5, 1}}, W11, " ", ElementSize → {1, 1}},
  {"Multiplier", {{3, 2}, {5, 2}}, W21, " ", ElementSize → {1, 1}},
  {"Multiplier", {{3, 4}, {5, 4}}, W31, " ", ElementSize → {1, 1}},
  {"Multiplier", {{3, 6}, {5, 5}}, W41, " ", ElementSize → {1, 1}},
  {"Multiplier", {{3, 7}, {5, 8}}, W12, " ", ElementSize → {1, 1}},
  {"Multiplier", {{3, 14}, {5, 15}}, W13, " ", ElementSize → {1, 1}},
  {"Multiplier", {{3, 21}, {5, 22}}, W14, " ", ElementSize → {1, 1}},
  {"Multiplier", {{3, 9}, {5, 9}}, W22, " "}, {"Multiplier",
  {{3, 11}, {5, 11}}, W32, " "}, {"Multiplier", {{3, 16}, {5, 16}}, W23, " "},
  {"Multiplier", {{3, 18}, {5, 18}}, W33, " "}, {"Multiplier", {{3, 13}, {5, 12}},
  W42, " "}, {"Multiplier", {{3, 20}, {5, 19}}, W43, " "}, {"Multiplier",
  {{3, 23}, {5, 23}}, W24, " "}, {"Multiplier", {{3, 25}, {5, 25}}, W34, " "},
  {"Multiplier", {{3, 27}, {5, 26}}, W44, " "}, {"Multiplier", {{6, 3}, {7, 3}},
  b01, " "}, {"Multiplier", {{6, 10}, {7, 10}}, b02, " "},
  {"Multiplier", {{6, 17}, {7, 17}}, b03, " "}, {"Multiplier", {{6, 24}, {7, 24}},
  b04, " "}, {"Polyline", {{4.7`, 0}, {10, 0}, {10, 6}, {4.7`, 6}, {4.7`, 0}}},
  {"Polyline", {{4.7`, 7}, {10, 7}, {10, 13}, {4.7`, 13}, {4.7`, 7}}},
  {"Polyline", {{4.7`, 14}, {10, 14}, {10, 20}, {4.7`, 20}, {4.7`, 14}}},
  {"Polyline", {{4.7`, 21}, {10, 21}, {10, 27}, {4.7`, 27}, {4.7`, 21}}};
mySchematic = artNeuronInp04 ~ Join ~ artNeuronOut04 ~ Join ~ artNeuronBody04;

```

```

In[*]:= SetOptions[DrawElement, {ElementSize → {1, 1},
    PlotStyle → {{RGBColor[0, 0, 0.7], Thickness[0.002], PointSize[0.0012]}},
    {RGBColor[0, 0, 1], Thickness[0.0012], PointSize[0.0014]}},
    ShowArrowTail → True, ShowNodes → True, TextOffset → Automatic,
    BaseStyle → {FontFamily → "Times", FontSize → 8}]];

In[*]:= numberOfStages = 4;
widthOfStages = 13;
systemBody = artNeuronBody04;
b1TOb1 = Thread[Flatten[{b01, b02, b03, b04}] → Flatten[{b01, b02, b03, b04}]];
b1TOb2 = Thread[Flatten[{b01, b02, b03, b04}] → Flatten[{b11, b12, b13, b14}]];
b1TOb3 = Thread[Flatten[{b01, b02, b03, b04}] → Flatten[{b21, b22, b23, b24}]];
b1TOb4 = Thread[Flatten[{b01, b02, b03, b04}] → Flatten[{b31, b32, b33, b34}]];
w1TOw1 =
    Thread[{W11, W12, W13, W14, W21, W22, W23, W24, W31, W32, W33, W34, W41, W42, W43, W44} →
        {W011, W012, W013, W014, W021, W022, W023, W024,
        W031, W032, W033, W034, W041, W042, W043, W044}];
w1TOw2 =
    Thread[{W11, W12, W13, W14, W21, W22, W23, W24, W31, W32, W33, W34, W41, W42, W43, W44} →
        {W111, W112, W113, W114, W121, W122, W123, W124,
        W131, W132, W133, W134, W141, W142, W143, W144}];
w1TOw3 =
    Thread[{W11, W12, W13, W14, W21, W22, W23, W24, W31, W32, W33, W34, W41, W42, W43, W44} →
        {W211, W212, W213, W214, W221, W222, W223, W224,
        W231, W232, W233, W234, W241, W242, W243, W244}];
w1TOw4 =
    Thread[{W11, W12, W13, W14, W21, W22, W23, W24, W31, W32, W33, W34, W41, W42, W43, W44} →
        {W311, W312, W313, W314, W321, W322, W323, W324,
        W331, W332, W333, W334, W341, W342, W343, W344}];
B1TObK = {b1TOb2, b1TOb3, b1TOb4};
w1TOWK = {w1TOw2, w1TOw3, w1TOw4};
f1TOFK = {f → f, f → f, f → g};
Do[systemBody =
    Join[systemBody, (TranslateSchematic[artNeuronBody04, {k * widthOfStages, 0}] /.
        B1TObK[[k]] /. w1TOWK[[k]] /. f1TOFK[[k]])],
    {k, numberOfStages - 1}];

In[*]:= systemInBodyOut = artNeuronInp04 ~ Join ~ systemBody ~ Join ~
    (TranslateSchematic[artNeuronOut04, {(numberOfStages - 1) * widthOfStages, 0}]);

```

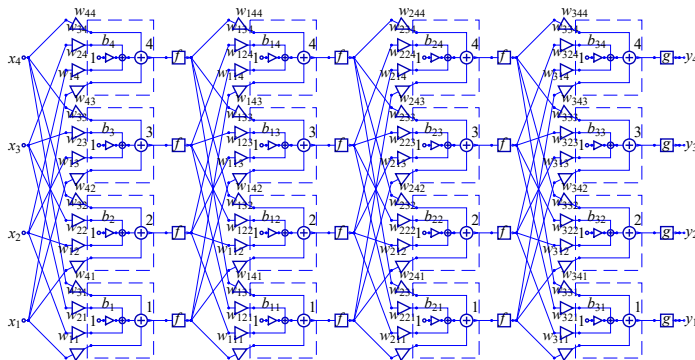
```

In[ ]:= subsSymbW0 = {W011 → w011, W012 → w012, W013 → w013, W014 → w014,
  W021 → w021, W022 → w022, W023 → w023, W024 → w024, W031 → w031, W032 → w032,
  W033 → w033, W034 → w034, W041 → w041, W042 → w042, W043 → w043, W044 → w044};
subsSymbW1 = {W111 → w111, W112 → w112, W113 → w113, W114 → w114,
  W121 → w121, W122 → w122, W123 → w123, W124 → w124, W131 → w131, W132 → w132,
  W133 → w133, W134 → w134, W141 → w141, W142 → w142, W143 → w143, W144 → w144};
subsSymbW2 = {W211 → w211, W212 → w212, W213 → w213, W214 → w214,
  W221 → w221, W222 → w222, W223 → w223, W224 → w224, W231 → w231, W232 → w232,
  W233 → w233, W234 → w234, W241 → w241, W242 → w242, W243 → w243, W244 → w244};
subsSymbW3 = {W311 → w311, W312 → w312, W313 → w313, W314 → w314,
  W321 → w321, W322 → w322, W323 → w323, W324 → w324, W331 → w331, W332 → w332,
  W333 → w333, W334 → w334, W341 → w341, W342 → w342, W343 → w343, W344 → w344};
subsSymbB =
  {b01 → b01, b02 → b02, b03 → b03, b04 → b04, b11 → b11, b12 → b12, b13 → b13, b14 → b14,
  b21 → b21, b22 → b22, b23 → b23, b24 → b24, b31 → b31, b32 → b32, b33 → b33, b34 → b34};
subsSymbX = {XX1 → x1, XX2 → x2, XX3 → x3, XX4 → x4, YY1 → y1, YY2 → y2, YY3 → y3, YY4 → y4};

In[ ]:= mySchematic = systemInBodyOut;
subsALL1 = (subsSymb1 ~ Join ~ subsSymbW0 ~ Join ~ subsSymbW2 ~ Join ~ subsSymbW3 ~
  Join ~ subsSymbW1 ~ Join ~ subsSymbW2 ~ Join ~ subsSymbB ~ Join ~ subsSymbX);
Show[ {DrawElement /@ (mySchematic /. w1T0w1 /. subsALL1)}, Frame → False]

```

Out[]:=



```

In[ ]:= procedureName = implementationProcedure;
DiscreteSystemImplementation2[mySchematic, ToString[procedureName]];
(* DiscreteSystemImplementationSummary2[mySchematic, Verbose → False]; *)
eqns = DiscreteSystemImplementationEquations2[mySchematic, Verbose → False];
numberOfInputs = Length[eqns[[1]]];
inputSequence =
  MultiplexSequence @@ Table[UnitImpulseSequence[], {numberOfInputs}];
inputSequence = {{XX1, XX2, XX3, XX4, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1}};
initialConditions = 0 * eqns[[2]];
systemParameters = eqns[[3]];
{outputSequence, finalConditions} = DiscreteSystemImplementationProcessing2[
  inputSequence, initialConditions, systemParameters, procedureName];
y1st = outputSequence[[1]];

y1stIND = y1st /. subsSymb1 /. w1T0w1 /. subsALL1;
% // StandardForm

```



```
Implementation procedure name: implementationProcedure
```

Implementation procedure usage:

Out[•]=

$$\{\{XX1, XX2, XX3, XX4, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1\}\}$$

`Out[•]//StandardForm=`

[illegible]

[illegible]

$$\ln[\bullet] := \mathbf{XXX} =$$

$$\begin{aligned} & \{g[b_{31} + f[b_{21} + f[b_{11} + f[b_1 + w_{11}x_1 + w_{21}x_2 + w_{31}x_3 + w_{41}x_4]w_{111} + f[b_2 + w_{12}x_1 + w_{22}x_2 + w_{32}x_3 + \\ & \quad w_{42}x_4]w_{121} + f[b_3 + w_{13}x_1 + w_{23}x_2 + w_{33}x_3 + w_{43}x_4]w_{131} + \\ & \quad f[b_4 + w_{14}x_1 + w_{24}x_2 + w_{34}x_3 + w_{44}x_4]w_{141}]w_{211} + f[b_{12} + \\ & \quad f[b_1 + w_{11}x_1 + w_{21}x_2 + w_{31}x_3 + w_{41}x_4]w_{112} + f[b_2 + w_{12}x_1 + w_{22}x_2 + w_{32}x_3 + w_{42}x_4]w_{122} + \\ & \quad f[b_3 + w_{13}x_1 + w_{23}x_2 + w_{33}x_3 + w_{43}x_4]w_{132} + f[b_4 + w_{14}x_1 + w_{24}x_2 + w_{34}x_3 + w_{44}x_4]w_{142}] \\ & \quad w_{221} + f[b_{13} + f[b_1 + w_{11}x_1 + w_{21}x_2 + w_{31}x_3 + w_{41}x_4]w_{113} + \\ & \quad f[b_2 + w_{12}x_1 + w_{22}x_2 + w_{32}x_3 + w_{42}x_4]w_{123} + f[b_3 + w_{13}x_1 + w_{23}x_2 + w_{33}x_3 + w_{43}x_4]w_{133} + \\ & \quad f[b_4 + w_{14}x_1 + w_{24}x_2 + w_{34}x_3 + w_{44}x_4]w_{143}]w_{231} + \\ & \quad f[b_{14} + f[b_1 + w_{11}x_1 + w_{21}x_2 + w_{31}x_3 + w_{41}x_4]w_{114} + f[b_2 + w_{12}x_1 + w_{22}x_2 + w_{32}x_3 + w_{42}x_4] \\ & \quad w_{124} + f[b_3 + w_{13}x_1 + w_{23}x_2 + w_{33}x_3 + w_{43}x_4]w_{134} + \\ & \quad f[b_4 + w_{14}x_1 + w_{24}x_2 + w_{34}x_3 + w_{44}x_4]w_{144}]w_{241}]w_{311} + \\ & \quad f[b_{22} + f[b_{11} + f[b_1 + w_{11}x_1 + w_{21}x_2 + w_{31}x_3 + w_{41}x_4]w_{111} + \\ & \quad f[b_2 + w_{12}x_1 + w_{22}x_2 + w_{32}x_3 + w_{42}x_4]w_{121} + f[b_3 + w_{13}x_1 + w_{23}x_2 + w_{33}x_3 + w_{43}x_4]w_{131} + \\ & \quad f[b_4 + w_{14}x_1 + w_{24}x_2 + w_{34}x_3 + w_{44}x_4]w_{141}]w_{212} + f[b_{12} + \\ & \quad f[b_1 + w_{11}x_1 + w_{21}x_2 + w_{31}x_3 + w_{41}x_4]w_{112} + f[b_2 + w_{12}x_1 + w_{22}x_2 + w_{32}x_3 + w_{42}x_4]w_{122} + \\ & \quad f[b_3 + w_{13}x_1 + w_{23}x_2 + w_{33}x_3 + w_{43}x_4]w_{132} + f[b_4 + w_{14}x_1 + w_{24}x_2 + w_{34}x_3 + w_{44}x_4]w_{142}] \\ & \quad w_{222} + f[b_{13} + f[b_1 + w_{11}x_1 + w_{21}x_2 + w_{31}x_3 + w_{41}x_4]w_{113} + \\ & \quad f[b_2 + w_{12}x_1 + w_{22}x_2 + w_{32}x_3 + w_{42}x_4]w_{123} + f[b_3 + w_{13}x_1 + w_{23}x_2 + w_{33}x_3 + w_{43}x_4]w_{133} + \end{aligned}$$

[illegible]

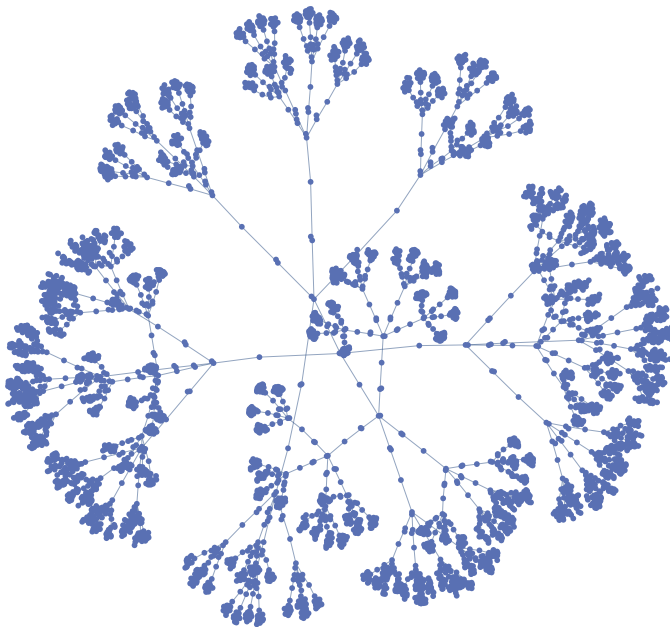
$$\begin{aligned}
& f[b_1 + w_{11} x_1 + w_{21} x_2 + w_{31} x_3 + w_{41} x_4] w_{112} + f[b_2 + w_{12} x_1 + w_{22} x_2 + w_{32} x_3 + w_{42} x_4] w_{122} + \\
& f[b_3 + w_{13} x_1 + w_{23} x_2 + w_{33} x_3 + w_{43} x_4] w_{132} + f[b_4 + w_{14} x_1 + w_{24} x_2 + w_{34} x_3 + w_{44} x_4] w_{142}] \\
& w_{224} + f[b_{13} + f[b_1 + w_{11} x_1 + w_{21} x_2 + w_{31} x_3 + w_{41} x_4] w_{113} + \\
& f[b_2 + w_{12} x_1 + w_{22} x_2 + w_{32} x_3 + w_{42} x_4] w_{123} + f[b_3 + w_{13} x_1 + w_{23} x_2 + w_{33} x_3 + w_{43} x_4] w_{133} + \\
& f[b_4 + w_{14} x_1 + w_{24} x_2 + w_{34} x_3 + w_{44} x_4] w_{143}] w_{234} + \\
& f[b_{14} + f[b_1 + w_{11} x_1 + w_{21} x_2 + w_{31} x_3 + w_{41} x_4] w_{114} + f[b_2 + w_{12} x_1 + w_{22} x_2 + w_{32} x_3 + w_{42} x_4] \\
& w_{124} + f[b_3 + w_{13} x_1 + w_{23} x_2 + w_{33} x_3 + w_{43} x_4] w_{134} + \\
& f[b_4 + w_{14} x_1 + w_{24} x_2 + w_{34} x_3 + w_{44} x_4] w_{144}] w_{244}] w_{344}];
\end{aligned}$$

In[*]:= y1stS = { ... };

Head: Sequence
Length: 4
Byte count: 315880
Uniconize

In[*]:= ExpressionGraph[y1st]

Out[*]=



Implementation

```

In[*]:= SeedRandom[123];
W1m = Round[1000 RandomReal[{-1, 1}, {4, 2}]] / 1000.;
b1m = Round[1000 RandomReal[{-1, 1}, 4]] / 1000.;
W2m = Round[1000 RandomReal[{-1, 1}, {4, 4}]] / 1000.;
b2m = Round[1000 RandomReal[{-1, 1}, 4]] / 1000.;
W3m = Round[1000 RandomReal[{-1, 1}, {4, 4}]] / 1000.;
b3m = Round[1000 RandomReal[{-1, 1}, 4]] / 1000.;
W4m = Round[1000 RandomReal[{-1, 1}, {4, 4}]] / 1000.;
b4m = Round[1000 RandomReal[{-1, 1}, 4]] / 1000.;
W1m4 = PadRight[W1m, {4, 4}]; x1m = {1.2, 4.5, 0, 0};
subsSymbZ = {XX1 → x1, XX2 → x2, XX3 → x3, XX4 → x4, YY1 → y1, YY2 → y2, YY3 → y3, YY4 → y4};
inputSequence /. subsSymbZ
subsInp = {x1, x2, x3, x4} /. {x1 → 1.2, x2 → 4.5, x3 → 0, x4 → 0}

Out[*]=
{{x1, x2, x3, x4, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1}}

Out[*]=
{1.2, 4.5, 0, 0}

In[*]:= Clear[W11, W21, W31, W41, W12, W22, W32, W42, W13, W23, W33, W43, W14, W24, W34, W44]
Wsubs =
  {{W11, W21, W31, W41}, {W12, W22, W32, W42}, {W13, W23, W33, W43}, {W14, W24, W34, W44}};
subsW = Thread[Flatten[Wsubs] → Flatten[W1m4]]
Bsubs = {b01, b02, b03, b04};
subsB = Thread[Flatten[Bsubs] → Flatten[b1m]]
subsW = Thread[Flatten[Wsubs] → Flatten[W1m4]]
subsInp = Thread[Flatten[inputSequence][[1 ;; 4]] → Flatten[{1.2, 4.5, 0, 0}]]
y1stN = N[y1st /. subsW /. subsB /. subsInp /. f → Tanh];

Out[*]=
{W11 → -0.089, W21 → 0.956, W31 → 0, W41 → 0, W12 → 0.886, W22 → 0.924, W32 → 0, W42 → 0,
 W13 → -0.395, W23 → -0.067, W33 → 0, W43 → 0, W14 → -0.877, W24 → -0.229, W34 → 0, W44 → 0}

Out[*]=
{b01 → -0.14, b02 → 0.557, b03 → -0.903, b04 → 0.257}

Out[*]=
{W11 → -0.089, W21 → 0.956, W31 → 0, W41 → 0, W12 → 0.886, W22 → 0.924, W32 → 0, W42 → 0,
 W13 → -0.395, W23 → -0.067, W33 → 0, W43 → 0, W14 → -0.877, W24 → -0.229, W34 → 0, W44 → 0}

Out[*]=
{XX1 → 1.2, XX2 → 4.5, XX3 → 0, XX4 → 0}

```

```

In[*]:= Wsubs1 = {{W111, W121, W131, W141}, {W112, W122, W132, W142},
                 {W113, W123, W133, W143}, {W114, W124, W134, W144}};
subsW1 = Thread[Flatten[Wsubs1] → Flatten[W2m]]
Bsubs1 = {b11, b12, b13, b14};
subsB1 = Thread[Flatten[Bsubs1] → Flatten[b2m]]
y1stN = y1st /. subsW /. subsW1 /. subsB /. subsB1 /. subsInp /. f → Tanh;

Out[*]=
{W111 → -0.444, W121 → -0.82, W131 → 0.753, W141 → -0.782, W112 → -0.468, W122 → 0.837,
 W132 → -0.66, W142 → -0.801, W113 → -0.06, W123 → -0.194, W133 → 0.943,
 W143 → -0.37, W114 → -0.748, W124 → -0.455, W134 → 0.211, W144 → 0.344}

Out[*]=
{b11 → -0.515, b12 → -0.016, b13 → 0.126, b14 → 0.098}

In[*]:= Wsubs2 = {{W211, W221, W231, W241}, {W212, W222, W232, W242},
                 {W213, W223, W233, W243}, {W214, W224, W234, W244}};
subsW2 = Thread[Flatten[Wsubs2] → Flatten[W3m]]
Bsubs2 = {b21, b22, b23, b24};
subsB2 = Thread[Flatten[Bsubs2] → Flatten[b3m]]

Out[*]=
{W211 → -0.037, W221 → 0.289, W231 → -0.165, W241 → 0.409, W212 → 0.923, W222 → 0.808,
 W232 → 0.741, W242 → 0.263, W213 → -0.215, W223 → -0.127, W233 → 0.137,
 W243 → -0.034, W214 → -0.679, W224 → 0.927, W234 → -0.908, W244 → -0.007}

Out[*]=
{b21 → -0.008, b22 → -0.975, b23 → -0.023, b24 → -0.843}

In[*]:= Wsubs3 = {{W311, W321, W331, W341}, {W312, W322, W332, W342},
                 {W313, W323, W333, W343}, {W314, W324, W334, W344}};
subsW3 = Thread[Flatten[Wsubs3] → Flatten[W4m]]
Bsubs3 = {b31, b32, b33, b34};
subsB3 = Thread[Flatten[Bsubs3] → Flatten[b4m]]
y1stN =
  y1st /. subsW /. subsW1 /. subsW2 /. subsW3 /. subsB /. subsB1 /. subsB2 /. subsB3 /.
    subsInp /. f → Tanh /. g → Exp

Out[*]=
{W311 → -0.086, W321 → 0.266, W331 → 0.035, W341 → 0.334, W312 → 0.289,
 W322 → -0.174, W332 → 0.989, W342 → 0.578, W313 → -0.584, W323 → -0.469,
 W333 → 0.03, W343 → -0.275, W314 → 0.203, W324 → 0.009, W334 → 0.159, W344 → -0.213}

Out[*]=
{b31 → 0.01, b32 → 0.891, b33 → -0.337, b34 → -0.087}

Out[*]=
{1.03727, 4.72264, 0.876151, 0.765064}

```

```

In[*]:= yFinalN = y1stN / Total[y1stN]
        yMax = Max[yFinalN]
        yPos = (Position[yFinalN, yMax] // Flatten) [[1]]

Out[*]=
{0.14015, 0.638097, 0.118381, 0.103371}

Out[*]=
0.638097

Out[*]=
2

```

Implementation symbolic

```

In[*]:= yFinalN =
        y1st / Total[y1st] /. subsW /. subsW1 /. subsW2 /. subsW3 /. subsB /. subsB1 /. subsB2 /.
        subsB3 /. subsInp /. f -> Tanh /. g -> Exp

Out[*]=
{0.14015, 0.638097, 0.118381, 0.103371}

```

sscnFigure07

```

In[*]:= SmainDir = SetDirectory[NotebookDirectory[]];
        Get["SchematicSolver`"]
        << SSknowledgeImp00`

In[*]:= subsSymb1 = {XX1 -> x1, XX2 -> x2, XX3 -> x3, XX4 -> x4, YY1 -> y1, YY2 -> y2, YY3 -> y3, YY4 -> y4};
        subsSymb2 =
        {W11 -> w11, W12 -> w12, W13 -> w13, W14 -> w14, W21 -> w21, W22 -> w22, W23 -> w23, W24 -> w24,
        W31 -> w31, W32 -> w32, W33 -> w33, W34 -> w34, W41 -> w41, W42 -> w42, W43 -> w43, W44 -> w44};
        subsSymb3 = {b01 -> b01, b02 -> b02, b03 -> b03, b04 -> b04, b11 -> b11,
        b12 -> b12, b13 -> b13, b14 -> b14, b21 -> b21, b22 -> b22, b23 -> b23, b24 -> b24};
        SetOptions[DrawElement, {BaseStyle -> {FontFamily -> "Times", FontSize -> 8}}];
        SetOptions[DrawElement, {ElementSize -> {1, 1}}];
        plotStyleDD = {{Dashing[.01], GrayLevel[.5]}, {Dashing[.01], GrayLevel[.5]}};
        SetOptions[DrawElement, {ElementSize -> {1, 1},
        PlotStyle -> {{RGBColor[0, 0, 0.7], Thickness[0.004], PointSize[0.0025]},
        {RGBColor[0, 0, 1], Thickness[0.0025], PointSize[0.003]}},
        ShowArrowTail -> True, ShowNodes -> True, TextOffset -> Automatic,
        BaseStyle -> {FontFamily -> "Times", FontSize -> 8}}];

In[*]:= artNeuronInp04 = {
        {"Input", {0, 3}, XX1, " ", TextOffset -> {1, 0}},
        {"Input", {0, 10}, XX2, " ", TextOffset -> {1, 0}}, {"Input", {0, 17}, XX3, " ",
        TextOffset -> {1, 0}}, {"Input", {0, 24}, XX4, " ", TextOffset -> {1, 0}}};
        Show[DrawElement/@(artNeuronInp04 /. subsSymb1 /. subsSymb2), Frame -> False];
        artNeuronOut04 = {
        {"Output", {13, 3}, YY1, " ", TextOffset -> {-1, 0}},
        {"Output", {13, 10}, YY2, " ", TextOffset -> {-1, 0}},
        {"Output", {13, 17}, YY3, " ", TextOffset -> {-1, 0}},
        {"Output", {13, 24}, YY4, " ", TextOffset -> {-1, 0}}};
        artNeuronBody04 = {

```

```

{"Adder", {{7, 3}, {5, 2}, {8, 3}, {5, 4}}, {1, 1, 2, 1}, " "},
{"Adder", {{8, 3}, {5, 1}, {11, 3}, {5, 5}}, {1, 1, 2, 1}, "1"},
{"Adder", {{7, 10}, {5, 9}, {8, 10}, {5, 11}}, {1, 1, 2, 1}, " "},
{"Adder", {{8, 10}, {5, 8}, {11, 10}, {5, 12}}, {1, 1, 2, 1}, "2"},
{"Adder", {{7, 17}, {5, 16}, {8, 17}, {5, 18}}, {1, 1, 2, 1}, " "},
{"Adder", {{8, 17}, {5, 15}, {11, 17}, {5, 19}}, {1, 1, 2, 1}, "3"},
{"Adder", {{7, 24}, {5, 23}, {8, 24}, {5, 25}}, {1, 1, 2, 1}, " "},
{"Adder", {{8, 24}, {5, 22}, {11, 24}, {5, 26}}, {1, 1, 2, 1}, "4"},
{"Function", {{11, 24}, {13, 24}}, f, " "}, {"Function", {{11, 17}, {13, 17}}, f, " "},
{"Function", {{11, 10}, {13, 10}}, f, " "}, {"Function", {{11, 3}, {13, 3}}, f, " "},
{"Input", {6, 24}, 1, " ", TextOffset → {1, 0}},
{"Input", {6, 17}, 1, " ", TextOffset → {1, 0}},
{"Input", {6, 10}, 1, " ", TextOffset → {1, 0}},
{"Input", {6, 3}, 1, " ", TextOffset → {1, 0}},
{"Line", {{0, 3}, {3, 0}}, {"Line", {{0, 10}, {3, 2}},
{"Line", {{0, 3}, {3, 7}}, {"Line", {{0, 3}, {3, 14}}, {"Line", {{0, 3}, {3, 21}},
{"Line", {{0, 17}, {3, 4}}, {"Line", {{0, 10}, {3, 9}}, {"Line", {{0, 10}, {3, 16}},
{"Line", {{0, 10}, {3, 23}}, {"Line", {{0, 17}, {3, 11}},
{"Line", {{0, 17}, {3, 18}}, {"Line", {{0, 17}, {3, 25}},
{"Line", {{0, 24}, {3, 27}}, {"Line", {{0, 24}, {3, 20}},
{"Line", {{0, 24}, {3, 13}}, {"Line", {{0, 24}, {3, 6}},
{"Multiplier", {{3, 0}, {5, 1}}, W11, " ", ElementSize → {1, 1}},
{"Multiplier", {{3, 2}, {5, 2}}, W21, " ", ElementSize → {1, 1}},
{"Multiplier", {{3, 4}, {5, 4}}, W31, " ", ElementSize → {1, 1}},
{"Multiplier", {{3, 6}, {5, 5}}, W41, " ", ElementSize → {1, 1}},
{"Multiplier", {{3, 7}, {5, 8}}, W12, " ", ElementSize → {1, 1}},
{"Multiplier", {{3, 14}, {5, 15}}, W13, " ", ElementSize → {1, 1}},
{"Multiplier", {{3, 21}, {5, 22}}, W14, " ", ElementSize → {1, 1}},
{"Multiplier", {{3, 9}, {5, 9}}, W22, " "}, {"Multiplier",
  {{3, 11}, {5, 11}}, W32, " "}, {"Multiplier", {{3, 16}, {5, 16}}, W23, " "},
{"Multiplier", {{3, 18}, {5, 18}}, W33, " "}, {"Multiplier", {{3, 13}, {5, 12}},
  W42, " "}, {"Multiplier", {{3, 20}, {5, 19}}, W43, " "}, {"Multiplier",
  {{3, 23}, {5, 23}}, W24, " "}, {"Multiplier", {{3, 25}, {5, 25}}, W34, " "},
{"Multiplier", {{3, 27}, {5, 26}}, W44, " "}, {"Multiplier", {{6, 3}, {7, 3}},
  b01, " "}, {"Multiplier", {{6, 10}, {7, 10}}, b02, " "},
{"Multiplier", {{6, 17}, {7, 17}}, b03, " "}, {"Multiplier", {{6, 24}, {7, 24}},
  b04, " "}, {"Polyline", {{4.7, 0}, {10, 0}, {10, 6}, {4.7, 6}, {4.7, 0}},
{"Polyline", {{4.7, 7}, {10, 7}, {10, 13}, {4.7, 13}, {4.7, 7}},
{"Polyline", {{4.7, 14}, {10, 14}, {10, 20}, {4.7, 20}, {4.7, 14}},
{"Polyline", {{4.7, 21}, {10, 21}, {10, 27}, {4.7, 27}, {4.7, 21}}};

```

```
In[*]:= mySchematic = artNeuronInp04 ~ Join ~ artNeuronOut04 ~ Join ~ artNeuronBody04;
```

```
In[*]:= SetOptions[DrawElement, {ElementSize → {1, 1},
  PlotStyle → {{RGBColor[0, 0, 0.7], Thickness[0.002], PointSize[0.0012]},
    {RGBColor[0, 0, 1], Thickness[0.0012], PointSize[0.0014]}},
  ShowArrowTail → True, ShowNodes → True, TextOffset → Automatic,
  BaseStyle → {FontFamily → "Times", FontSize → 8}}];
```

```

In[*]:= numberOfStages = 4;
widthOfStages = 13;
systemBody = artNeuronBody04;
b1TOb1 = Thread[Flatten[{b01, b02, b03, b04}] → Flatten[{b01, b02, b03, b04}]];
b1TOb2 = Thread[Flatten[{b01, b02, b03, b04}] → Flatten[{b11, b12, b13, b14}]];
b1TOb3 = Thread[Flatten[{b01, b02, b03, b04}] → Flatten[{b21, b22, b23, b24}]];
b1TOb4 = Thread[Flatten[{b01, b02, b03, b04}] → Flatten[{b31, b32, b33, b34}]];
w1TOw1 =
  Thread[{W11, W12, W13, W14, W21, W22, W23, W24, W31, W32, W33, W34, W41, W42, W43, W44} →
    {W011, W012, W013, W014, W021, W022, W023, W024,
     W031, W032, W033, W034, W041, W042, W043, W044}];
w1TOw2 =
  Thread[{W11, W12, W13, W14, W21, W22, W23, W24, W31, W32, W33, W34, W41, W42, W43, W44} →
    {W111, W112, W113, W114, W121, W122, W123, W124,
     W131, W132, W133, W134, W141, W142, W143, W144}];
w1TOw3 =
  Thread[{W11, W12, W13, W14, W21, W22, W23, W24, W31, W32, W33, W34, W41, W42, W43, W44} →
    {W211, W212, W213, W214, W221, W222, W223, W224,
     W231, W232, W233, W234, W241, W242, W243, W244}];
w1TOw4 =
  Thread[{W11, W12, W13, W14, W21, W22, W23, W24, W31, W32, W33, W34, W41, W42, W43, W44} →
    {W311, W312, W313, W314, W321, W322, W323, W324,
     W331, W332, W333, W334, W341, W342, W343, W344}];
B1TObK = {b1TOb2, b1TOb3, b1TOb4};
W1TOWK = {w1TOw2, w1TOw3, w1TOw4};
f1TOfK = {f → f, f → f, f → g};
Do[systemBody =
  Join[systemBody, (TranslateSchematic[artNeuronBody04, {k * widthOfStages, 0}] /.
    B1TObK[[k]] /. W1TOWK[[k]] /. f1TOfK[[k]])];
, {k, numberOfStages - 1}];

In[*]:= systemInBodyOut = artNeuronInp04 ~ Join ~ systemBody ~ Join ~
  (TranslateSchematic[artNeuronOut04, {(numberOfStages - 1) * widthOfStages, 0}]);

In[*]:= subsSymbW0 = {W011 → w011, W012 → w012, W013 → w013, W014 → w014,
  W021 → w021, W022 → w022, W023 → w023, W024 → w024, W031 → w031, W032 → w032,
  W033 → w033, W034 → w034, W041 → w041, W042 → w042, W043 → w043, W044 → w044};
subsSymbW1 = {W111 → w111, W112 → w112, W113 → w113, W114 → w114,
  W121 → w121, W122 → w122, W123 → w123, W124 → w124, W131 → w131, W132 → w132,
  W133 → w133, W134 → w134, W141 → w141, W142 → w142, W143 → w143, W144 → w144};
subsSymbW2 = {W211 → w211, W212 → w212, W213 → w213, W214 → w214,
  W221 → w221, W222 → w222, W223 → w223, W224 → w224, W231 → w231, W232 → w232,
  W233 → w233, W234 → w234, W241 → w241, W242 → w242, W243 → w243, W244 → w244};
subsSymbW3 = {W311 → w311, W312 → w312, W313 → w313, W314 → w314,
  W321 → w321, W322 → w322, W323 → w323, W324 → w324, W331 → w331, W332 → w332,
  W333 → w333, W334 → w334, W341 → w341, W342 → w342, W343 → w343, W344 → w344};
subsSymbB =
  {b01 → b01, b02 → b02, b03 → b03, b04 → b04, b11 → b11, b12 → b12, b13 → b13, b14 → b14,
   b21 → b21, b22 → b22, b23 → b23, b24 → b24, b31 → b31, b32 → b32, b33 → b33, b34 → b34};
subsSymbX = {XX1 → x1, XX2 → x2, XX3 → x3, XX4 → x4, YY1 → y1, YY2 → y2, YY3 → y3, YY4 → y4};

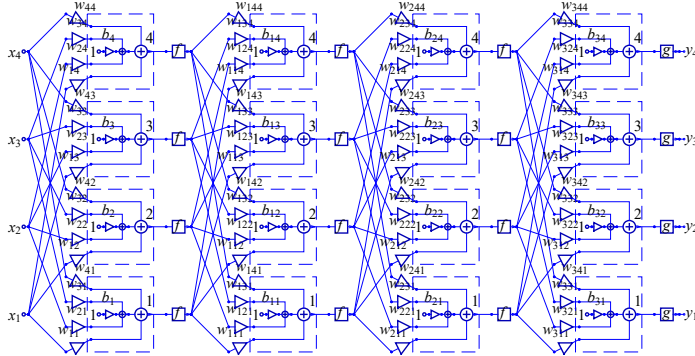
```

```

In[ ]:= mySchematic = systemInBodyOut;
subsALL1 = (subsSymb1 ~ Join ~ subsSymbW0 ~ Join ~ subsSymbW2 ~ Join ~ subsSymbW3 ~
Join ~ subsSymbW1 ~ Join ~ subsSymbW2 ~ Join ~ subsSymbB ~ Join ~ subsSymbX);
Show[{DrawElement /@ (mySchematic /. w1Tow1 /. subsALL1)}, Frame → False]

```

Out[]=



```

In[ ]:= procedureName = implementationProcedure;
DiscreteSystemImplementation2[mySchematic, ToString[procedureName]];
(* DiscreteSystemImplementationSummary2[mySchematic, Verbose→False]; *)
eqns = DiscreteSystemImplementationEquations2[mySchematic, Verbose → False];
numberOfInputs = Length[eqns[[1]];
inputSequence =
  MultiplexSequence @@ Table[UnitImpulseSequence[], {numberOfInputs}];
inputSequence = {{XX1, XX2, XX3, XX4, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1}};
initialConditions = 0 * eqns[[2]];
systemParameters = eqns[[3]];
{outputSequence, finalConditions} = DiscreteSystemImplementationProcessing2[
  inputSequence, initialConditions, systemParameters, procedureName];
y1st = outputSequence[[1]];

y1stIND = y1st /. subsSymb1 /. w1Tow1 /. subsALL1;
% // StandardForm

Implementation procedure name: implementationProcedure
Implementation procedure usage:

```

Out[]=

```
{XX1, XX2, XX3, XX4, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1, 1}
```

Out[]//StandardForm=

```

{g[b31 + f[b21 +
  f[b11 + f[b1 + w11 x1 + w21 x2 + w31 x3 + w41 x4] w111 + f[b2 + w12 x1 + w22 x2 + w32 x3 + w42 x4] w121 +
  f[b3 + w13 x1 + w23 x2 + w33 x3 + w43 x4] w131 + f[b4 + w14 x1 + w24 x2 + w34 x3 + w44 x4] w141]
  w211 + f[b12 + f[b1 + w11 x1 + w21 x2 + w31 x3 + w41 x4] w112 +
  f[b2 + w12 x1 + w22 x2 + w32 x3 + w42 x4] w122 + f[b3 + w13 x1 + w23 x2 + w33 x3 + w43 x4] w132 +
  f[b4 + w14 x1 + w24 x2 + w34 x3 + w44 x4] w142] w221 +
  f[b13 + f[b1 + w11 x1 + w21 x2 + w31 x3 + w41 x4] w113 + f[b2 + w12 x1 + w22 x2 + w32 x3 + w42 x4] w123 +
  f[b3 + w13 x1 + w23 x2 + w33 x3 + w43 x4] w133 + f[b4 + w14 x1 + w24 x2 + w34 x3 + w44 x4] w143]
  w231 + f[b14 + f[b1 + w11 x1 + w21 x2 + w31 x3 + w41 x4] w114 +
  f[b2 + w12 x1 + w22 x2 + w32 x3 + w42 x4] w124 + f[b3 + w13 x1 + w23 x2 + w33 x3 + w43 x4] w134 +
  f[b4 + w14 x1 + w24 x2 + w34 x3 + w44 x4] w144] w241] w311 +
  f[b22 + f[b11 + f[b1 + w11 x1 + w21 x2 + w31 x3 + w41 x4] w111 +

```


[illegible]

[illegible]

$$\begin{aligned} & w_{233} + f[b_{14} + f[b_1 + w_{11} x_1 + w_{21} x_2 + w_{31} x_3 + w_{41} x_4] w_{114} + \\ & \quad f[b_2 + w_{12} x_1 + w_{22} x_2 + w_{32} x_3 + w_{42} x_4] w_{124} + f[b_3 + w_{13} x_1 + w_{23} x_2 + w_{33} x_3 + w_{43} x_4] w_{134} + \\ & \quad f[b_4 + w_{14} x_1 + w_{24} x_2 + w_{34} x_3 + w_{44} x_4] w_{144}] w_{243}] w_{334} + \\ f[b_{24} + & f[b_{11} + f[b_1 + w_{11} x_1 + w_{21} x_2 + w_{31} x_3 + w_{41} x_4] w_{111} + \\ & \quad f[b_2 + w_{12} x_1 + w_{22} x_2 + w_{32} x_3 + w_{42} x_4] w_{121} + f[b_3 + w_{13} x_1 + w_{23} x_2 + w_{33} x_3 + w_{43} x_4] w_{131} + \\ & \quad f[b_4 + w_{14} x_1 + w_{24} x_2 + w_{34} x_3 + w_{44} x_4] w_{141}] w_{214} + \\ f[b_{12} + & f[b_1 + w_{11} x_1 + w_{21} x_2 + w_{31} x_3 + w_{41} x_4] w_{112} + f[b_2 + w_{12} x_1 + w_{22} x_2 + w_{32} x_3 + w_{42} x_4] w_{122} + \\ & \quad f[b_3 + w_{13} x_1 + w_{23} x_2 + w_{33} x_3 + w_{43} x_4] w_{132} + \\ & \quad f[b_4 + w_{14} x_1 + w_{24} x_2 + w_{34} x_3 + w_{44} x_4] w_{142}] w_{224} + \\ f[b_{13} + & f[b_1 + w_{11} x_1 + w_{21} x_2 + w_{31} x_3 + w_{41} x_4] w_{113} + f[b_2 + w_{12} x_1 + w_{22} x_2 + w_{32} x_3 + w_{42} x_4] w_{123} + \\ & \quad f[b_3 + w_{13} x_1 + w_{23} x_2 + w_{33} x_3 + w_{43} x_4] w_{133} + f[b_4 + w_{14} x_1 + w_{24} x_2 + w_{34} x_3 + w_{44} x_4] w_{143}] \\ & w_{234} + f[b_{14} + f[b_1 + w_{11} x_1 + w_{21} x_2 + w_{31} x_3 + w_{41} x_4] w_{114} + \\ & \quad f[b_2 + w_{12} x_1 + w_{22} x_2 + w_{32} x_3 + w_{42} x_4] w_{124} + f[b_3 + w_{13} x_1 + w_{23} x_2 + w_{33} x_3 + w_{43} x_4] w_{134} + \\ & \quad f[b_4 + w_{14} x_1 + w_{24} x_2 + w_{34} x_3 + w_{44} x_4] w_{144}] w_{244}] w_{344}] \} \end{aligned}$$

$$\ln[\bullet] := \mathbf{XXX} =$$

[illegible]

[illegible]

[illegible]

```
In[ ]:= slika007b = ExpressionGraph[y1st]
```



```

In[*]:= Clear[W11, W21, W31, W41, W12, W22, W32, W42, W13, W23, W33, W43, W14, W24, W34, W44]
Wsubs =
  {{W11, W21, W31, W41}, {W12, W22, W32, W42}, {W13, W23, W33, W43}, {W14, W24, W34, W44}};
subsW = Thread[Flatten[Wsubs] → Flatten[W1m4]]
Bsubs = {b01, b02, b03, b04};
subsB = Thread[Flatten[Bsubs] → Flatten[b1m]]
subsW = Thread[Flatten[Wsubs] → Flatten[W1m4]]
subsInp = Thread[Flatten[inputSequence][[1 ;; 4]] → Flatten[{1.2, 4.5, 0, 0}]]
y1stN = N[y1st /. subsW /. subsB /. subsInp /. f → Tanh];

Out[*]=
{W11 → -0.089, W21 → 0.956, W31 → 0, W41 → 0, W12 → 0.886, W22 → 0.924, W32 → 0, W42 → 0,
 W13 → -0.395, W23 → -0.067, W33 → 0, W43 → 0, W14 → -0.877, W24 → -0.229, W34 → 0, W44 → 0}

Out[*]=
{b01 → -0.14, b02 → 0.557, b03 → -0.903, b04 → 0.257}

Out[*]=
{W11 → -0.089, W21 → 0.956, W31 → 0, W41 → 0, W12 → 0.886, W22 → 0.924, W32 → 0, W42 → 0,
 W13 → -0.395, W23 → -0.067, W33 → 0, W43 → 0, W14 → -0.877, W24 → -0.229, W34 → 0, W44 → 0}

Out[*]=
{XX1 → 1.2, XX2 → 4.5, XX3 → 0, XX4 → 0}

In[*]:= Wsubs1 = {{W111, W121, W131, W141}, {W112, W122, W132, W142},
  {W113, W123, W133, W143}, {W114, W124, W134, W144}};
subsW1 = Thread[Flatten[Wsubs1] → Flatten[W2m]]
Bsubs1 = {b11, b12, b13, b14};
subsB1 = Thread[Flatten[Bsubs1] → Flatten[b2m]]
y1stN = y1st /. subsW /. subsW1 /. subsB /. subsB1 /. subsInp /. f → Tanh;

Out[*]=
{W111 → -0.444, W121 → -0.82, W131 → 0.753, W141 → -0.782, W112 → -0.468, W122 → 0.837,
 W132 → -0.66, W142 → -0.801, W113 → -0.06, W123 → -0.194, W133 → 0.943,
 W143 → -0.37, W114 → -0.748, W124 → -0.455, W134 → 0.211, W144 → 0.344}

Out[*]=
{b11 → -0.515, b12 → -0.016, b13 → 0.126, b14 → 0.098}

In[*]:= Wsubs2 = {{W211, W221, W231, W241}, {W212, W222, W232, W242},
  {W213, W223, W233, W243}, {W214, W224, W234, W244}};
subsW2 = Thread[Flatten[Wsubs2] → Flatten[W3m]]
Bsubs2 = {b21, b22, b23, b24};
subsB2 = Thread[Flatten[Bsubs2] → Flatten[b3m]]

Out[*]=
{W211 → -0.037, W221 → 0.289, W231 → -0.165, W241 → 0.409, W212 → 0.923, W222 → 0.808,
 W232 → 0.741, W242 → 0.263, W213 → -0.215, W223 → -0.127, W233 → 0.137,
 W243 → -0.034, W214 → -0.679, W224 → 0.927, W234 → -0.908, W244 → -0.007}

Out[*]=
{b21 → -0.008, b22 → -0.975, b23 → -0.023, b24 → -0.843}

```

```

In[ ]:= Wsubs3 = {{W311, W321, W331, W341}, {W312, W322, W332, W342},
                 {W313, W323, W333, W343}, {W314, W324, W334, W344}};
subsW3 = Thread[Flatten[Wsubs3] → Flatten[W4m]]
Bsubs3 = {b31, b32, b33, b34};
subsB3 = Thread[Flatten[Bsubs3] → Flatten[b4m]]
y1stN =
  y1st /. subsW /. subsW1 /. subsW2 /. subsW3 /. subsB /. subsB1 /. subsB2 /. subsB3 /.
    subsInp /. f → Tanh /. g → Exp

Out[ ]:=
{W311 → -0.086, W321 → 0.266, W331 → 0.035, W341 → 0.334, W312 → 0.289,
 W322 → -0.174, W332 → 0.989, W342 → 0.578, W313 → -0.584, W323 → -0.469,
 W333 → 0.03, W343 → -0.275, W314 → 0.203, W324 → 0.009, W334 → 0.159, W344 → -0.213}

Out[ ]:=
{b31 → 0.01, b32 → 0.891, b33 → -0.337, b34 → -0.087}

Out[ ]:=
{1.03727, 4.72264, 0.876151, 0.765064}

In[ ]:= yFinalN = y1stN / Total[y1stN]
yMax = Max[yFinalN]
yPos = (Position[yFinalN, yMax] // Flatten) [[1]]

Out[ ]:=
{0.14015, 0.638097, 0.118381, 0.103371}

Out[ ]:=
0.638097

Out[ ]:=
2

```

Implementation symbolic

```

In[ ]:= yFinalN =
  y1st / Total[y1st] /. subsW /. subsW1 /. subsW2 /. subsW3 /. subsB /. subsB1 /. subsB2 /.
    subsB3 /. subsInp /. f → Tanh /. g → Exp

Out[ ]:=
{0.14015, 0.638097, 0.118381, 0.103371}

In[ ]:= yFinalN // MatrixForm

Out[ ]//MatrixForm=

$$\begin{pmatrix} 0.14015 \\ 0.638097 \\ 0.118381 \\ 0.103371 \end{pmatrix}$$


```

sscnFigure08

```

In[ ]:= SmainDir = SetDirectory[NotebookDirectory[]];
Clear[t0, t1, t2, t3, t4, x, y]

In[ ]:= t0 = {{0.25`, 1.75`}, {0.26`, 10.5`}, {0.27`, 42.25`}, {0.28`, 87.75`}, {0.29`, 137.25`},
             {0.3`, 209.75`}, {0.31`, 295.75`}, {0.32`, 384.5`}, {0.33`, 474.75`},
             {0.34`, 535.5`}, {0.35`, 619.75`}, {0.36`, 652.75`}, {0.37`, 720.25`},

```



```

{0.38`, 763.25`}, {0.39`, 772.75`}, {0.4`, 783.25`}, {0.41`, 806.`}, {0.42`, 800.5`},
{0.43`, 792.75`}, {0.44`, 813.5`}, {0.45`, 794.`}, {0.46`, 788.25`},
{0.47`, 729.5`}, {0.48`, 738.25`}, {0.49`, 696.`}, {0.5`, 698.25`}, {0.51`, 631.`},
{0.52`, 623.`}, {0.53`, 602.25`}, {0.54`, 565.`}, {0.55`, 553.5`}, {0.56`, 519.75`},
{0.57`, 479.5`}, {0.58`, 474.`}, {0.59`, 450.75`}, {0.6`, 427.`}, {0.61`, 411.75`},
{0.62`, 393.`}, {0.63`, 382.5`}, {0.64`, 351.`}, {0.65`, 317.`}, {0.66`, 312.`},
{0.67`, 289.5`}, {0.68`, 280.75`}, {0.69`, 257.75`}, {0.7`, 266.25`},
{0.71`, 215.5`}, {0.72`, 209.25`}, {0.73`, 199.5`}, {0.74`, 185.`}, {0.75`, 171.`},
{0.76`, 154.75`}, {0.77`, 148.25`}, {0.78`, 138.25`}, {0.79`, 123.5`},
{0.8`, 94.75`}, {0.81`, 101.`}, {0.82`, 84.75`}, {0.83`, 71.`}, {0.84`, 62.`},
{0.85`, 64.5`}, {0.86`, 54.75`}, {0.87`, 41.75`}, {0.88`, 38.5`}, {0.89`, 27.5`},
{0.9`, 17.75`}, {0.91`, 19.75`}, {0.92`, 14.5`}, {0.93`, 12.25`}, {0.94`, 7.25`},
{0.95`, 3.75`}, {0.96`, 2.5`}, {0.97`, 0.75`}, {0.98`, 0.`}, {0.99`, 0.`}};
t1 = {{0.25`, 1}, {0.26`, 10}, {0.27`, 39}, {0.28`, 87}, {0.29`, 144}, {0.3`, 231},
{0.31`, 296}, {0.32`, 394}, {0.33`, 472}, {0.34`, 490}, {0.35`, 659}, {0.36`, 652},
{0.37`, 711}, {0.38`, 737}, {0.39`, 785}, {0.4`, 784}, {0.41`, 782}, {0.42`, 793},
{0.43`, 779}, {0.44`, 791}, {0.45`, 790}, {0.46`, 776}, {0.47`, 745},
{0.48`, 690}, {0.49`, 713}, {0.5`, 724}, {0.51`, 632}, {0.52`, 599}, {0.53`, 591},
{0.54`, 551}, {0.55`, 555}, {0.56`, 507}, {0.57`, 471}, {0.58`, 467},
{0.59`, 463}, {0.6`, 416}, {0.61`, 357}, {0.62`, 395}, {0.63`, 381}, {0.64`, 334},
{0.65`, 317}, {0.66`, 308}, {0.67`, 291}, {0.68`, 279}, {0.69`, 286}, {0.7`, 271},
{0.71`, 207}, {0.72`, 201}, {0.73`, 187}, {0.74`, 170}, {0.75`, 187},
{0.76`, 145}, {0.77`, 146}, {0.78`, 122}, {0.79`, 122}, {0.8`, 103}, {0.81`, 98},
{0.82`, 96}, {0.83`, 69}, {0.84`, 59}, {0.85`, 53}, {0.86`, 59}, {0.87`, 46},
{0.88`, 33}, {0.89`, 19}, {0.9`, 22}, {0.91`, 13}, {0.92`, 11}, {0.93`, 16},
{0.94`, 7}, {0.95`, 4}, {0.96`, 4}, {0.97`, 2}, {0.98`, 0}, {0.99`, 0}};
t2 = {{0.25`, 4}, {0.26`, 10}, {0.27`, 43}, {0.28`, 90}, {0.29`, 121}, {0.3`, 209},
{0.31`, 306}, {0.32`, 372}, {0.33`, 493}, {0.34`, 552}, {0.35`, 600}, {0.36`, 623},
{0.37`, 704}, {0.38`, 807}, {0.39`, 776}, {0.4`, 770}, {0.41`, 849}, {0.42`, 795},
{0.43`, 778}, {0.44`, 838}, {0.45`, 796}, {0.46`, 789}, {0.47`, 711},
{0.48`, 754}, {0.49`, 716}, {0.5`, 667}, {0.51`, 620}, {0.52`, 620}, {0.53`, 620},
{0.54`, 552}, {0.55`, 538}, {0.56`, 499}, {0.57`, 483}, {0.58`, 476},
{0.59`, 455}, {0.6`, 441}, {0.61`, 416}, {0.62`, 381}, {0.63`, 393}, {0.64`, 334},
{0.65`, 318}, {0.66`, 304}, {0.67`, 291}, {0.68`, 265}, {0.69`, 238}, {0.7`, 240},
{0.71`, 225}, {0.72`, 220}, {0.73`, 218}, {0.74`, 182}, {0.75`, 173},
{0.76`, 150}, {0.77`, 153}, {0.78`, 150}, {0.79`, 122}, {0.8`, 102}, {0.81`, 100},
{0.82`, 92}, {0.83`, 71}, {0.84`, 68}, {0.85`, 59}, {0.86`, 61}, {0.87`, 36},
{0.88`, 40}, {0.89`, 19}, {0.9`, 12}, {0.91`, 27}, {0.92`, 18}, {0.93`, 10},
{0.94`, 5}, {0.95`, 3}, {0.96`, 0}, {0.97`, 1}, {0.98`, 0}, {0.99`, 0}};
t3 = {{0.25`, 1}, {0.26`, 13}, {0.27`, 57}, {0.28`, 83}, {0.29`, 146}, {0.3`, 204},
{0.31`, 292}, {0.32`, 378}, {0.33`, 447}, {0.34`, 525}, {0.35`, 580}, {0.36`, 672},
{0.37`, 740}, {0.38`, 779}, {0.39`, 752}, {0.4`, 823}, {0.41`, 817}, {0.42`, 798},
{0.43`, 791}, {0.44`, 829}, {0.45`, 802}, {0.46`, 766}, {0.47`, 746},
{0.48`, 788}, {0.49`, 644}, {0.5`, 719}, {0.51`, 663}, {0.52`, 646}, {0.53`, 588},
{0.54`, 573}, {0.55`, 553}, {0.56`, 568}, {0.57`, 490}, {0.58`, 494},
{0.59`, 449}, {0.6`, 415}, {0.61`, 475}, {0.62`, 389}, {0.63`, 367}, {0.64`, 385},
{0.65`, 318}, {0.66`, 326}, {0.67`, 303}, {0.68`, 301}, {0.69`, 243}, {0.7`, 258},
{0.71`, 207}, {0.72`, 207}, {0.73`, 179}, {0.74`, 198}, {0.75`, 165},
{0.76`, 167}, {0.77`, 147}, {0.78`, 139}, {0.79`, 137}, {0.8`, 91}, {0.81`, 96},
{0.82`, 79}, {0.83`, 79}, {0.84`, 73}, {0.85`, 71}, {0.86`, 51}, {0.87`, 42},

```

```

{0.88`, 44}, {0.89`, 45}, {0.9`, 15}, {0.91`, 22}, {0.92`, 19}, {0.93`, 12},
{0.94`, 8}, {0.95`, 6}, {0.96`, 4}, {0.97`, 0}, {0.98`, 0}, {0.99`, 0}};
t4 = {{0.25`, 1}, {0.26`, 9}, {0.27`, 30}, {0.28`, 91}, {0.29`, 138}, {0.3`, 195},
{0.31`, 289}, {0.32`, 394}, {0.33`, 487}, {0.34`, 575}, {0.35`, 640}, {0.36`, 664},
{0.37`, 726}, {0.38`, 730}, {0.39`, 778}, {0.4`, 756}, {0.41`, 776}, {0.42`, 816},
{0.43`, 823}, {0.44`, 796}, {0.45`, 788}, {0.46`, 822}, {0.47`, 716},
{0.48`, 721}, {0.49`, 711}, {0.5`, 683}, {0.51`, 609}, {0.52`, 627}, {0.53`, 610},
{0.54`, 584}, {0.55`, 568}, {0.56`, 505}, {0.57`, 474}, {0.58`, 459},
{0.59`, 436}, {0.6`, 436}, {0.61`, 399}, {0.62`, 407}, {0.63`, 389}, {0.64`, 351},
{0.65`, 315}, {0.66`, 310}, {0.67`, 273}, {0.68`, 278}, {0.69`, 264}, {0.7`, 296},
{0.71`, 223}, {0.72`, 209}, {0.73`, 214}, {0.74`, 190}, {0.75`, 159},
{0.76`, 157}, {0.77`, 147}, {0.78`, 142}, {0.79`, 113}, {0.8`, 83}, {0.81`, 110},
{0.82`, 72}, {0.83`, 65}, {0.84`, 48}, {0.85`, 75}, {0.86`, 48}, {0.87`, 43},
{0.88`, 37}, {0.89`, 27}, {0.9`, 22}, {0.91`, 17}, {0.92`, 10}, {0.93`, 11},
{0.94`, 9}, {0.95`, 2}, {0.96`, 2}, {0.97`, 0}, {0.98`, 0}, {0.99`, 0}};
sn = 100000;

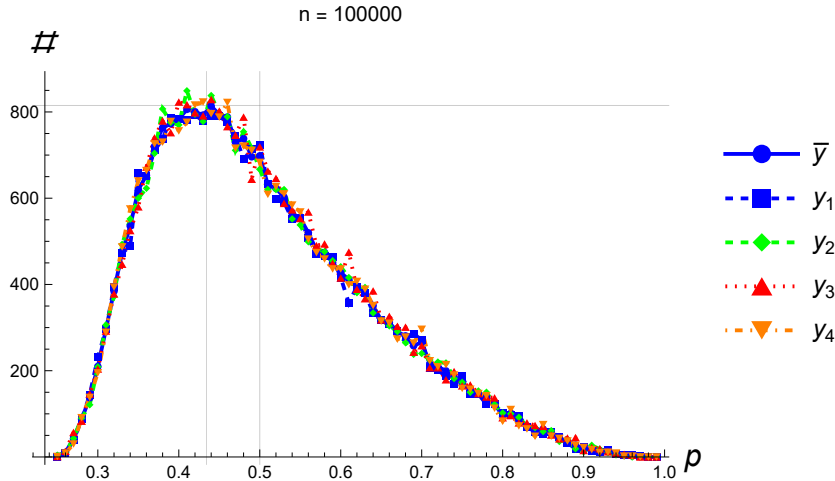
```

```

In[ ]:= yGridLines = {{0.43435463392312135, 0.5}, {815}};
slika008a = ListLinePlot[{t0, t1, t2, t3, t4},
  AxesLabel → {Style["p", Italic, FontFamily → "Arial", FontSize → 16],
    Style["#", Italic, FontFamily → "Arial", FontSize → 16]},
  PlotLabel → "n = " <> ToString[sn], PlotStyle → {{Thick, Blue}, {Thick, Dashed, Blue},
    {Thick, Dashed, Green}, {Thick, Dotted, Red}, {Thick, DotDashed, Orange}},
  PlotMarkers → {Automatic, Scaled[0.02]}, GridLines → yGridLines,
  Ticks → {Automatic, Automatic}, PlotLegends → {"ȳ", "y₁", "y₂", "y₃", "y₄"}]

```

Out[]:=



```

(*
Export["slika008a.tif", slika008a, ImageResolution → 300];
*)

```

In[*]:= t0

Out[*]=

```
{ {0.25, 1.75}, {0.26, 10.5}, {0.27, 42.25}, {0.28, 87.75}, {0.29, 137.25}, {0.3, 209.75},
  {0.31, 295.75}, {0.32, 384.5}, {0.33, 474.75}, {0.34, 535.5}, {0.35, 619.75},
  {0.36, 652.75}, {0.37, 720.25}, {0.38, 763.25}, {0.39, 772.75}, {0.4, 783.25},
  {0.41, 806.}, {0.42, 800.5}, {0.43, 792.75}, {0.44, 813.5}, {0.45, 794.},
  {0.46, 788.25}, {0.47, 729.5}, {0.48, 738.25}, {0.49, 696.}, {0.5, 698.25},
  {0.51, 631.}, {0.52, 623.}, {0.53, 602.25}, {0.54, 565.}, {0.55, 553.5},
  {0.56, 519.75}, {0.57, 479.5}, {0.58, 474.}, {0.59, 450.75}, {0.6, 427.},
  {0.61, 411.75}, {0.62, 393.}, {0.63, 382.5}, {0.64, 351.}, {0.65, 317.}, {0.66, 312.},
  {0.67, 289.5}, {0.68, 280.75}, {0.69, 257.75}, {0.7, 266.25}, {0.71, 215.5},
  {0.72, 209.25}, {0.73, 199.5}, {0.74, 185.}, {0.75, 171.}, {0.76, 154.75},
  {0.77, 148.25}, {0.78, 138.25}, {0.79, 123.5}, {0.8, 94.75}, {0.81, 101.},
  {0.82, 84.75}, {0.83, 71.}, {0.84, 62.}, {0.85, 64.5}, {0.86, 54.75}, {0.87, 41.75},
  {0.88, 38.5}, {0.89, 27.5}, {0.9, 17.75}, {0.91, 19.75}, {0.92, 14.5}, {0.93, 12.25},
  {0.94, 7.25}, {0.95, 3.75}, {0.96, 2.5}, {0.97, 0.75}, {0.98, 0.}, {0.99, 0.}}
```

In[*]:= Clear[x, y]

y = FindFormula[t0, x, PerformanceGoal → "Quality"]

Out[*]=

96.2671 + 86.9355 Cos[16.728 x] - 344.777 Log[x] + 592.718 Log[x] Sin[9.2 x]

In[*]:= y // TraditionalForm

Out[*]//TraditionalForm=

-344.777 log(x) + 86.9355 cos(16.728 x) + 592.718 log(x) sin(9.2 x) + 96.2671

In[*]:= ys = Table[{x, y}, {x, 0.25, .99, 0.01}];

yGridLines = {{0.3472, 0.545357342}, {568}};

slika008b = ListLinePlot[{t0, ys},

AxesLabel → {Style["p", Italic, FontFamily → "Arial", FontSize → 16],

Style["#", Italic, FontFamily → "Arial", FontSize → 16]},

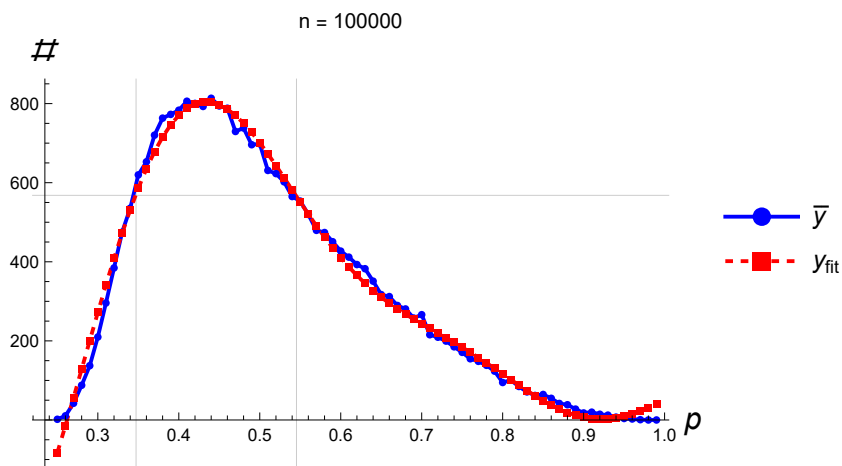
PlotLabel → "n = " <> ToString[sn], PlotStyle → {{Thick, Blue}, {Thick, Dashed, Red},

{Thick, Dashed, Green}, {Thick, Dotted, Red}, {Thick, DotDashed, Orange}},

PlotMarkers → {Automatic, Scaled[0.02]}, GridLines → yGridLines,

Ticks → {Automatic, Automatic}, PlotLegends → {" $\bar{y}$ ", " y_{fit} "}

Out[*]=



```

(*
Export["slika008b.tif",slika008b,ImageResolution→300];
*)

In[ ]:= Export["slika008b.tif", slika008b, ImageResolution → 300]
Out[ ]=
slika008b.tif

In[ ]:= 100 Integrate[y, {x, 0.25, 0.99}]
Out[ ]=
25 025.6

In[ ]:= yd1 = D[y, x]
yd2 = D[yd1, x]
Out[ ]=

$$-\frac{344.777}{x} + 5453. \cos[9.2 x] \log[x] + \frac{592.718 \sin[9.2 x]}{x} - 1454.25 \sin[16.728 x]$$

Out[ ]=

$$\frac{344.777}{x^2} + \frac{10906. \cos[9.2 x]}{x} - 24326.7 \cos[16.728 x] -$$


$$\frac{592.718 \sin[9.2 x]}{x^2} - 50167.6 \log[x] \sin[9.2 x]$$


In[ ]:= xZero = FindRoot[yd1, {x, 0.5}]
yMax = y /. xZero
eq = (y == 0.70710 yMax)
x09a = FindRoot[eq, {x, 0.4}];
x09b = FindRoot[eq, {x, 0.6}];
{x09a, x09b}
y /. {x09a, x09b}
100 Integrate[y, {x, (x /. x09a), (x /. x09b)}]
Out[ ]=
{x → 0.433535}

Out[ ]=
804.809

Out[ ]=
96.2671 + 86.9355 Cos[16.728 x] - 344.777 Log[x] + 592.718 Log[x] Sin[9.2 x] == 569.081

Out[ ]=
{{x → 0.346788}, {x → 0.544074}}

Out[ ]=
{569.081, 569.081}

Out[ ]=
14213.

In[ ]:= {Total[t0][[2]], Total[t1][[2]], Total[t2][[2]], Total[t3][[2]], Total[t4][[2]],
Total[t1][[2]] + Total[t2][[2]] + Total[t3][[2]] + Total[t4][[2]]}
Out[ ]=
{25000., 24747, 24974, 25299, 24980, 100000}

```

```
In[*]:= t0[[All, 2]]
Out[*]=
{1.75, 10.5, 42.25, 87.75, 137.25, 209.75, 295.75, 384.5, 474.75, 535.5, 619.75, 652.75,
 720.25, 763.25, 772.75, 783.25, 806., 800.5, 792.75, 813.5, 794., 788.25, 729.5, 738.25,
 696., 698.25, 631., 623., 602.25, 565., 553.5, 519.75, 479.5, 474., 450.75, 427.,
 411.75, 393., 382.5, 351., 317., 312., 289.5, 280.75, 257.75, 266.25, 215.5, 209.25,
 199.5, 185., 171., 154.75, 148.25, 138.25, 123.5, 94.75, 101., 84.75, 71., 62., 64.5,
 54.75, 41.75, 38.5, 27.5, 17.75, 19.75, 14.5, 12.25, 7.25, 3.75, 2.5, 0.75, 0., 0.}
```

sscnFigureMatrix

Classic Neural Networks

```
In[*]:= SeedRandom[123];
W1 = RandomReal[{-1, 1}, {4, 2}]; b1 = RandomReal[{-1, 1}, 4];
W2 = RandomReal[{-1, 1}, {4, 4}]; b2 = RandomReal[{-1, 1}, 4];
W3 = RandomReal[{-1, 1}, {4, 4}]; b3 = RandomReal[{-1, 1}, 4];
(NumberForm[#, 2] &) [MatrixForm /@ Association[W1 → W1, W2 → W2, W3 → W3]]
(NumberForm[#, 2] &) [MatrixForm /@ Association[b1 → b1, b2 → b2, b3 → b3]]
```

Out[*]//NumberForm=

$$\left\langle \begin{array}{c} W_1 \rightarrow \begin{pmatrix} -0.089 & 0.96 \\ 0.89 & 0.92 \\ -0.4 & -0.067 \\ -0.88 & -0.23 \end{pmatrix}, W_2 \rightarrow \begin{pmatrix} -0.44 & -0.82 & 0.75 & -0.78 \\ -0.47 & 0.84 & -0.66 & -0.8 \\ -0.06 & -0.19 & 0.94 & -0.37 \\ -0.75 & -0.46 & 0.21 & 0.34 \end{pmatrix}, \\ W_3 \rightarrow \begin{pmatrix} -0.037 & 0.29 & -0.16 & 0.41 \\ 0.92 & 0.81 & 0.74 & 0.26 \\ -0.22 & -0.13 & 0.14 & -0.034 \\ -0.68 & 0.93 & -0.91 & -0.0075 \end{pmatrix} \right\rangle$$

Out[*]//NumberForm=

$$\left\langle \begin{array}{c} b_1 \rightarrow \begin{pmatrix} -0.14 \\ 0.56 \\ -0.9 \\ 0.26 \end{pmatrix}, b_2 \rightarrow \begin{pmatrix} -0.52 \\ -0.016 \\ 0.13 \\ 0.098 \end{pmatrix}, b_3 \rightarrow \begin{pmatrix} -0.0082 \\ -0.98 \\ -0.023 \\ -0.84 \end{pmatrix} \right\rangle$$

```
In[*]:= Tanh[x] // TraditionalForm
```

Out[*]//TraditionalForm=

tanh(x)

```

In[*]:= X1 = {1.2, 4.5};
% // MatrixForm
W11 = W1;
% // MatrixForm
W11 . X1;
% // MatrixForm
b1 = b1;
% // MatrixForm
W11 . X1 + b1;
% // MatrixForm
X11 = Tanh[W11 . X1 + b1];
% // MatrixForm

Out[*]//MatrixForm=

$$\begin{pmatrix} 1.2 \\ 4.5 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} -0.0885617 & 0.955652 \\ 0.886429 & 0.924431 \\ -0.395304 & -0.0665829 \\ -0.876723 & -0.228711 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} 4.19416 \\ 5.22366 \\ -0.773988 \\ -2.08127 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} -0.140323 \\ 0.557488 \\ -0.902819 \\ 0.256534 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} 4.05384 \\ 5.78114 \\ -1.67681 \\ -1.82473 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} 0.999398 \\ 0.999981 \\ -0.932446 \\ -0.949308 \end{pmatrix}$$


```

```

In[*]:= X1 = X11;
        % // MatrixForm
W21 = W2;
        % // MatrixForm
W21 . X11;
        % // MatrixForm
b2 = b2;
        % // MatrixForm
W21 . X11 + b2;
        % // MatrixForm
X22 = Tanh[W21 . X11 + b2];
        % // MatrixForm

Out[*]//MatrixForm=

$$\begin{pmatrix} 0.999398 \\ 0.999981 \\ -0.932446 \\ -0.949308 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} -0.444026 & -0.819565 & 0.753173 & -0.781786 \\ -0.468485 & 0.837219 & -0.660168 & -0.800843 \\ -0.0596039 & -0.193521 & 0.943171 & -0.370142 \\ -0.74844 & -0.45548 & 0.211495 & 0.343527 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} -1.22345 \\ 1.74482 \\ -0.781161 \\ -1.72678 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} -0.515198 \\ -0.0163946 \\ 0.125886 \\ 0.0983918 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} -1.73864 \\ 1.72842 \\ -0.655275 \\ -1.62839 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} -0.940069 \\ 0.938869 \\ -0.57521 \\ -0.925832 \end{pmatrix}$$


```

```

In[*]:= X1 = X22;
% // MatrixForm
W31 = W3;
% // MatrixForm
W31 . X22;
% // MatrixForm
b3 = b3;
% // MatrixForm
W31 . X22 + b3;
% // MatrixForm
X33 = W31 . X22 + b3;

Out[*]//MatrixForm=

$$\begin{pmatrix} -0.940069 \\ 0.938869 \\ -0.57521 \\ -0.925832 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} -0.036781 & 0.288511 & -0.164898 & 0.409043 \\ 0.922663 & 0.807615 & 0.740989 & 0.263322 \\ -0.215215 & -0.127425 & 0.136959 & -0.0341827 \\ -0.67907 & 0.926666 & -0.907707 & -0.00747479 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} 0.0215967 \\ -0.779139 \\ 0.035548 \\ 2.03743 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} -0.00815844 \\ -0.975298 \\ -0.0227348 \\ -0.842961 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} 0.0134383 \\ -1.75444 \\ 0.0128131 \\ 1.19447 \end{pmatrix}$$


In[*]:= Exp[X33] / Total[Exp[X33]]
% // MatrixForm

Out[*]=
{0.184236, 0.0314483, 0.184121, 0.600195}

Out[*]//MatrixForm=

$$\begin{pmatrix} 0.184236 \\ 0.0314483 \\ 0.184121 \\ 0.600195 \end{pmatrix}$$


In[*]:= softmax[x_] := Exp[x] / Total[Exp[x]];

In[*]:= softmax[W3.Tanh[W2.Tanh[W1.{1.2, 4.5} + b1] + b2] + b3]

Out[*]=
{0.184236, 0.0314483, 0.184121, 0.600195}

```



```
In[*]:= Exp[x] / Total[Exp[x]] // TraditionalForm
```

```
Out[*]//TraditionalForm=
```

$$\frac{e^x}{\text{Total}[e^x]}$$

$$\left\langle \left| b_1 \rightarrow \begin{pmatrix} -0.14 \\ 0.56 \\ -0.9 \\ 0.26 \end{pmatrix}, b_2 \rightarrow \begin{pmatrix} -0.52 \\ -0.016 \\ 0.13 \\ 0.098 \end{pmatrix}, b_3 \rightarrow \begin{pmatrix} -0.0082 \\ -0.98 \\ -0.023 \\ -0.84 \end{pmatrix} \right| \right\rangle$$

```
In[*]:=
```

$$\begin{pmatrix} -0.089 & 0.96 \\ 0.89 & 0.92 \\ -0.4 & -0.067 \\ -0.88 & -0.23 \end{pmatrix} // \text{MatrixForm}$$

```
Out[*]//MatrixForm=
```

$$\begin{pmatrix} -0.0885617 & 0.955652 \\ 0.886429 & 0.924431 \\ -0.395304 & -0.0665829 \\ -0.876723 & -0.228711 \end{pmatrix}$$

```
In[*]:= {1.2, 4.5, 0, 0} // MatrixForm
```

```
Out[*]//MatrixForm=
```

$$\begin{pmatrix} 1.2 \\ 4.5 \\ 0 \\ 0 \end{pmatrix}$$

```
Out[*]//NumberForm=
```

$$\left\langle \left| w_1 \rightarrow \begin{pmatrix} -0.089 & 0.96 \\ 0.89 & 0.92 \\ -0.4 & -0.067 \\ -0.88 & -0.23 \end{pmatrix}, w_2 \rightarrow \begin{pmatrix} -0.44 & -0.82 & 0.75 & -0.78 \\ -0.47 & 0.84 & -0.66 & -0.8 \\ -0.06 & -0.19 & 0.94 & -0.37 \\ -0.75 & -0.46 & 0.21 & 0.34 \end{pmatrix} \right\rangle,$$

$$w_3 \rightarrow \begin{pmatrix} -0.037 & 0.29 & -0.16 & 0.41 \\ 0.92 & 0.81 & 0.74 & 0.26 \\ -0.22 & -0.13 & 0.14 & -0.034 \\ -0.68 & 0.93 & -0.91 & -0.0075 \end{pmatrix} \left| \right\rangle$$

```

In[*]:= W1 // MatrixForm
W2 // MatrixForm
W3 // MatrixForm

Out[*]//MatrixForm=

$$\begin{pmatrix} -0.0885617 & 0.955652 \\ 0.886429 & 0.924431 \\ -0.395304 & -0.0665829 \\ -0.876723 & -0.228711 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} -0.444026 & -0.819565 & 0.753173 & -0.781786 \\ -0.468485 & 0.837219 & -0.660168 & -0.800843 \\ -0.0596039 & -0.193521 & 0.943171 & -0.370142 \\ -0.74844 & -0.45548 & 0.211495 & 0.343527 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} -0.036781 & 0.288511 & -0.164898 & 0.409043 \\ 0.922663 & 0.807615 & 0.740989 & 0.263322 \\ -0.215215 & -0.127425 & 0.136959 & -0.0341827 \\ -0.67907 & 0.926666 & -0.907707 & -0.00747479 \end{pmatrix}$$


In[*]:= b1 // MatrixForm
b2 // MatrixForm
b3 // MatrixForm

Out[*]//MatrixForm=

$$\begin{pmatrix} -0.140323 \\ 0.557488 \\ -0.902819 \\ 0.256534 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} -0.515198 \\ -0.0163946 \\ 0.125886 \\ 0.0983918 \end{pmatrix}$$


Out[*]//MatrixForm=

$$\begin{pmatrix} -0.00815844 \\ -0.975298 \\ -0.0227348 \\ -0.842961 \end{pmatrix}$$


```

sscnnKnowledgeImp00

```

(* SSknowledgeImp00.m *)
(* << SSknowledgeImp00` *)

Clear[DiscreteSystemImplementationEquations2, DiscreteSystemImplementationSummary2, DiscreteSy

(*-----DiscreteSystemImplementationEquations2 -----*)
Options[DiscreteSystemImplementationEquations2] = {PrintFloatingPorts \
→ False, Verbose → False};
DiscreteSystemImplementationEquations2[
  schematicSpec : {{"Adder" | "Arrow" | "Delay" | "Function" |
    "Input" | "Line" | "Modulator" | "Multiplier" | "Node" |

```

```

"Output" | "Polyline" |
"Text", {_?NumberQ, _?
  NumberQ} | {{_?NumberQ, _?
    NumberQ}, {_?NumberQ, _?NumberQ} ..}, ___} ..},
Y_Symbol : Y, opts___?OptionQ] :=
Module[{a, analysisElementList, countImplementationElements,
  duplicateCoords, duplicateFlag, elementDelay, elementDelayCoordsIn,
  elementDelayCoordsOut, elementDelayVectorIn,
  elementDelayVectorOut, elementInput, elementInputCoords,
  elementInputVector, elementOutput, elementOutputCoords,
  elementOutputVector, implementationElementList,
  implementationEquations, implementationVars, implementationVarsRaw,
  k, knownCoords, linePosition, lineRule, nodeCoords, nodeCoordsRaw,
  numberImplementationElements, outputCoords, outputCoordsRaw, pfp,
  q, response, signalCoords, signalVector, systemEquations, t,
  topologyElementList, topologyElementListRaw, v, verb, vGain,
  vInitial, V},
{pfp, verb} = {PrintFloatingPorts, Verbose} /. Flatten[{opts]} /.
  Options[DiscreteSystemImplementationEquations2];
topologyElementListRaw =
  Apply[NonlinearDiscreteElementTopology, schematicSpec, {1}];
topologyElementList =
  Select[topologyElementListRaw, Length[#] ≠ 0 &];
linePosition =
  Position[topologyElementList, {"Line", __}] // Flatten;
Do[lineRule = {topologyElementList[[linePosition[[k]], 2]] →
  topologyElementList[[linePosition[[k]], 3]]};
  t = topologyElementList /. lineRule;
  topologyElementList = t; {k, Length[linePosition]}};
elementInput = Select[topologyElementList, #[[1]] == "Input" &];
elementInputCoords = #[[2]] & /@ elementInput;
elementInputVector = Y /@ elementInputCoords;
elementOutput = Select[topologyElementList, #[[1]] == "Output" &];
elementOutputCoords = #[[2]] & /@ elementOutput;
elementOutputVector = Y /@ elementOutputCoords;
elementDelay = Select[topologyElementList, #[[1]] == "Delay" &];
elementDelayCoordsOut = #[[2]] & /@ elementDelay;
elementDelayVectorOut = Y /@ elementDelayCoordsOut;
elementDelayCoordsIn = #[[3]] & /@ elementDelay;
elementDelayVectorIn = Y /@ elementDelayCoordsIn;
analysisElementList =
  Select[topologyElementList, ((#[[1]] ≠ "Line") && (#[[1]] ≠
    "Output")) &];
If[verb,
  Print["DiscreteSystemImplementationEquations ver. 2007.7.7"];
  Print["Schematic specification = ", schematicSpec];
  Print["Signals at nodes are designated by the symbol ", Y];
  Print["Topology element list (raw) = ", topologyElementListRaw];
  Print["Topology element list = ", topologyElementList];
  Print["Line-element position = ", linePosition];
  Print["Input elements = ", elementInput];
  Print["Input-element coordinates = ", elementInputCoords];
  Print["Input-element vector = ", elementInputVector];
  Print["Output elements = ", elementOutput];
  Print["Output-element coordinates = ", elementOutputCoords];

```

```

Print["Output-element vector = ", elementOutputVector];
Print["Delay elements = ", elementDelay];
Print["Delay-element output coordinates = ", elementDelayCoordsOut];
Print["Delay-element output vector = ", elementDelayVectorOut];
Print["Delay-element input coordinates = ", elementDelayCoordsIn];
Print["Delay-element input vector = ", elementDelayVectorIn];
Print["Analysis elements = ", analysisElementList];];
If[analysisElementList == {},
  Message[DiscreteSystemImplementationEquations2::"noelems"];
  Return[{{}}, {}, {}, {}, {}, {}];];
If[elementInput == {},
  Message[DiscreteSystemImplementationEquations2::"noinputs"];
  Return[{{}}, {}, {}, {}, {}, {}];];
If[Length[elementInput] != Length[elementInputCoords // Union],
  Message[DiscreteSystemImplementationEquations2::"duplin"];
  Print["Here are all Input elements: ",
    Sort[elementInput] // Column];
  Return[{{}}, {}, {}, {}, {}, {}];];
If[elementOutput == {},
  Message[DiscreteSystemImplementationEquations2::"nooutputs"];
  Return[{{}}, {}, {}, {}, {}, {}];];
If[Length[elementOutput] != Length[elementOutputCoords // Union],
  Message[DiscreteSystemImplementationEquations2::"duplout"];
  Print["Here are all Output elements: ",
    Sort[elementOutput] // Column];
  Return[{{}}, {}, {}, {}, {}, {}];];
nodeCoordsRaw =
If[#[[1]] == "Adder" || #[[1]] == "Modulator",
  Prepend[#[[3]], #[[2]], {#[[2]], #[[3]]} & /@
    analysisElementList];
nodeCoords = Select[Flatten[nodeCoordsRaw, 1], Length[#] != 0 &];
signalCoords = Sort[Union[nodeCoords]];
signalVector = Y /@ signalCoords;
outputCoordsRaw = #[[2]] & /@ analysisElementList;
outputCoords = Sort[Union[outputCoordsRaw]];
outputVector = Y /@ outputCoords;
duplicateCoords = Count[outputCoordsRaw, #] & /@ outputCoords;
duplicateFlag = (If[#1 > 1,
  Message[DiscreteSystemImplementationEquations2::"outputs",
    outputCoords[[First[Flatten[Position[duplicateCoords, #1]]]]];
  True, False]) & /@ duplicateCoords;
If[verb, (*Print["Node coordinates (raw) = ", nodeCoordsRaw];*)
  Print["Node coordinates = ", nodeCoords];
  Print["Signal coordinates = ", signalCoords];
  Print["Signal vector = ", signalVector];
  Print["Output-port coordinates (raw) = ", outputCoordsRaw];
  Print["Output-port coordinates = ", outputCoords];
  Print["Output-port vector = ", outputVector];
  Print["Duplicate output count = ", duplicateCoords];
  Print["Duplicate output flag = ", duplicateFlag];
  Print["System variables = ", outputVector];];
If[Count[duplicateFlag, True] > 0,
  Message[DiscreteSystemImplementationEquations2::"intercon"];
  Return[{{}}, {}, {}, {}, {}, {}];];
If[Not[signalVector == outputVector],

```

```

Print["Unconnected nodes exist: ",
  Complement[signalVector, outputVector]];
Message[DiscreteSystemImplementationEquations2::"intercon"];
Return[{{}}, {{}}, {{}}, {{}}, {{}}, {{}}];
If[Not[
  Intersection[signalVector, elementOutputVector] ==
    Sort[elementOutputVector]],
  Print["Unconnected system outputs exist: ",
    Complement[elementOutputVector, signalVector]];
  Message[DiscreteSystemImplementationEquations2::"intercon"];
  Return[{{}}, {{}}, {{}}, {{}}, {{}}, {{}}];
systemEquations = {};
Do[a = analysisElementList[[k]]; v = Last[a];
  If[MatchQ[v, {_, _}] === True, {vGain, vInitial} =
    v, {vGain, vInitial} = {v, 0}];
  Switch[First[a], "Adder",
    AppendTo[systemEquations,
      Y[a[[2]]] ==
        Y[a[[3, 1]]]*v[[1]] + Y[a[[3, 2]]]*v[[2]] +
        Y[a[[3, 3]]]*v[[3]]; "Delay",
    AppendTo[systemEquations,
      Y[a[[2]]] == previousSample[Y[a[[3]]]]; "Function",
    AppendTo[systemEquations, Y[a[[2]]] == v[Y[a[[3]]]]; "Input",
    AppendTo[systemEquations, Y[a[[2]]] == v]; "Modulator",
    AppendTo[systemEquations,
      Y[a[[2]]] ==
        If[v[[1]] == 0, 1, Y[a[[3, 1]]]]*
        If[v[[2]] == 0, 1, Y[a[[3, 2]]]]*
        If[v[[3]] == 0, 1, Y[a[[3, 3]]]]; "Multiplier",
    AppendTo[systemEquations, Y[a[[2]]] == Y[a[[3]]]*v]; _,
    Message[DiscreteSystemImplementationEquations2::"unsup",
      a // InputForm];] (*end Switch*), {k,
    Length[analysisElementList]};
If[verb, Print["System equations = ", systemEquations // Column];];
If[pfp || verb,
  If[signalVector == outputVector, Print["No floating ports."],
    Print["Floating ports = ",
      Complement[signalVector, outputVector]];];];
implementationElementList =
  Select[analysisElementList, ((#[[1]] != "Delay") && (#[[1]] !=
    "Input")) &];
implementationVarsRaw =
  Variables[Part[implementationElementList, All, 4]];
(*exclude names of symbols that have been defined*)
t = UndefinedSymbolQ[#] & /@ implementationVarsRaw;
implementationVars = Select[t, (# != False) &];
implementationEquations = {};
Do[a = elementInput[[k]]; v = Last[a];
  AppendTo[implementationEquations, Y[a[[2]]] == v];, {k,
    Length[elementInput]};
Do[a = elementDelay[[k]]; v = Last[a];
  AppendTo[implementationEquations,
    Y[a[[2]]] == previousSample[Y[a[[3]]]]; {k,
    Length[elementDelay]};];
knownCoords = Join[elementInputCoords, elementDelayCoordsOut];

```

```

numberImplementationElements = Length[implementationElementList];
Do[(*body Do*)
countImplementationElements = Length[implementationElementList];
Do[a = implementationElementList[[k]]; v = Last[a];
Switch[First[a], "Adder",
If[Complement[Select[a[[3]], # != {} &],
Intersection[Select[a[[3]], # != {} &],
knownCoords]] == {}, (*then*)
AppendTo[implementationEquations,
Y[a[[2]]] ==
Y[a[[3, 1]]]*v[[1]] + Y[a[[3, 2]]]*v[[2]] +
Y[a[[3, 3]]]*v[[3]]];
AppendTo[knownCoords, a[[2]]];
t = Delete[implementationElementList, k];
implementationElementList = t;
Break[]; (*else*) False];, "Function",
If[Complement[{a[[3]]},
Intersection[{a[[3]]}, knownCoords]] == {}, (*then*)
AppendTo[implementationEquations, Y[a[[2]]] == v[Y[a[[3]]]]];
AppendTo[knownCoords, a[[2]]];
t = Delete[implementationElementList, k];
implementationElementList = t; Break[]; (*else*) False];,
"Modulator",
If[Complement[Select[a[[3]], # != {} &],
Intersection[Select[a[[3]], # != {} &],
knownCoords]] == {}, (*then*)
AppendTo[implementationEquations,
Y[a[[2]]] ==
If[v[[1]] == 0, 1, Y[a[[3, 1]]]]*
If[v[[2]] == 0, 1, Y[a[[3, 2]]]]*
If[v[[3]] == 0, 1, Y[a[[3, 3]]]]];
AppendTo[knownCoords, a[[2]]];
t = Delete[implementationElementList, k];
implementationElementList = t;
Break[]; (*else*) False];, "Multiplier",
If[Complement[{a[[3]]},
Intersection[{a[[3]]}, knownCoords]] == {}, (*then*)
AppendTo[implementationEquations, Y[a[[2]]] == Y[a[[3]]]*v];
AppendTo[knownCoords, a[[2]]];
t = Delete[implementationElementList, k];
implementationElementList = t; Break[]; (*else*) False];, _,
Message[DiscreteSystemImplementationEquations2::"unsup",
a // InputForm];] (*end Switch*), {k,
countImplementationElements}];, \
{numberImplementationElements}]; (*end Do*)
If[verb,
Print["Implementation elements = ", implementationElementList];
Print["Number of implementation elements = ",
numberImplementationElements];
Print["Implementation parameters (raw) = ",
implementationVarsRaw];
Print["Implementation parameters = ", implementationVars];
Print["Known coordinates = ", knownCoords];
Print["Implementation equations = ",
implementationEquations // Column];

```

```

Print["Not-Implemented elements = ",
  implementationElementList // Column];];
If[implementationElementList == {} (*then*),
  response = {elementInputVector, elementDelayVectorOut,
    implementationVars, implementationEquations,
    elementOutputVector, elementDelayVectorIn};, (*else*)
  response = {{}, {}, {}, {}, {}, {}];
Message[DiscreteSystemImplementationEquations2::"alglloop"];];
response]

DiscreteSystemImplementationEquations2[___] :=
  Module[{},
    Message[DiscreteSystemImplementationEquations2::"invargs"];
    {{}, {}, {}, {}, {}, {}];];

(*-----DiscreteSystemImplementationSummary2-----*)
Options[DiscreteSystemImplementationSummary2] = {Verbose → False};
DiscreteSystemImplementationSummary2[schematicSpec_List,
  opts___?OptionQ] :=
  Module[{verb, equations},
    equations = DiscreteSystemImplementationEquations2[schematicSpec];
    If[Flatten[equations] == {}, Return[]];
    verb =
      Verbose /. Flatten[{opts}] /.
        Options[DiscreteSystemImplementationSummary2];
    Print["Input: ", equations // First];
    Print["Initial state: ", equations[[2]]];
    Print["Parameter: ", equations[[3]]];
    If[verb, (*then*) Print["Equations: ", equations[[4]] // Column];];
    Print["Output: ", equations[[5]]];
    Print["Final state: ", equations // Last];];

DiscreteSystemImplementationSummary2[_] :=
  Module[{},
    Message[DiscreteSystemImplementationSummary2::"invargs"];];

DiscreteSystemImplementationSummary2[a___] :=
  Module[{n}, n = Length[{a}];
    Message[DiscreteSystemImplementationSummary2::"argx", n, 1];];

(*-----DiscreteSystemImplementation2-----*)
DiscreteSystemImplementation2[schematicSpec_List,
  procedureName_String : "implementationProcedure"] :=
  Module[{schematicEquations, codeString},
    schematicEquations =
      DiscreteSystemImplementationEquations2[schematicSpec];
    If[Flatten[schematicEquations] == {}, Return[]];
    codeString =
      DiscreteSystemImplementationModule2[schematicEquations,
        procedureName, Verbose → True];];

DiscreteSystemImplementation2[___] :=
  Module[{}, Message[DiscreteSystemImplementation2::"invargs"];];

(*-----DiscreteSystemImplementationModule2-----*)

```

```

Options[DiscreteSystemImplementationModule2] = {Verbose → False};
DiscreteSystemImplementationModule2[
  r : {_List, _List, {_Symbol ...}, {_Equal ..}, _List, _List},
  procedureName_String : "implementationProcedure",
  opts___?OptionQ] :=
Module[{eqnsL, negCoords, x, y, dims, dimsName, verb, signalName,
  signalNameStr, ruleYxpy, dataVars, dataVarsStr, dataEqns,
  initVars, initVarsStr, initEqns, localVars, localVarsStr, params,
  bodyEqns, bodyVars, bodyStr, bodyRepl, outArgs, outVars, outStr,
  inputArguments, comma, quote, usageString,
  implementationString}, (*r is returned by DSIE,
  procedureName is a string*)
If[Not[ValidImplementationModuleNameQ[procedureName]],
  Message[DiscreteSystemImplementationModule2::"invname",
    procedureName];
  Return[""]];
(*check that procedureName is not a built-in function*)
If[Names["System`"~StringJoin~procedureName] == {procedureName},
  Message[DiscreteSystemImplementationModule2::"sysname",
    procedureName];
  Return[""]];
(*check for negative coords*)
eqnsL = Part[r[[4]], All, 1] /. h_[{x_, y_}] → {x, y};
negCoords =
  Select[eqnsL, (Negative[First[#]] || Negative[Last[#]]) &];
If[negCoords ≠ {},
  Message[DiscreteSystemImplementationModule2::"negcoords",
    negCoords];
  Return[""]];
(*dimension info as procName[] call*)dims = Length[#] & /@ r;
dimsName =
  StringJoin[procedureName, "[ ] := ", ToString[dims], "; "];
ToExpression[dimsName];
verb =
  Verbose /. Flatten[{opts}] /.
    Options[DiscreteSystemImplementationModule2];
signalName = First[r] // First // Head;
signalNameStr = signalName // ToString;
ruleYxpy :=
  signalName[{x_, y_}] →
    ToExpression[
      StringJoin[signalNameStr, ToString[x], "p", ToString[y]]];
dataVars = r[[1]];
dataVarsStr = ToString[dataVars /. ruleYxpy];
dataEqns =
  StringJoin[" ", dataVarsStr, " = ", "dataSamples", ";"];
initVars = r[[2]];
initVarsStr = ToString[initVars /. ruleYxpy];
If[r[[2]] == {}, initEqns = " "; (*else*),
  initEqns =
    StringJoin[" ", initVarsStr, " = ", "initialConditions",
      ";"];
localVars = Part[r[[4]], All, 1]~Join~r[[3]];
localVarsStr = ToString[localVars /. ruleYxpy];
If[r[[3]] == {}, params = " "; (*else*),

```



```

params =
  StringJoin[" ", ToString[r[[3]], " = ",
    "systemParameters;"];];
bodyEqns = Drop[r[[4]], Length[r[[1]] + Length[r[[2]]]];
bodyVars = bodyEqns /. ruleYxpy;
bodyStr = ToString[bodyVars // InputForm];
bodyRepl =
  StringReplace[
    bodyStr, {"{" → " ", "==" → "=", "}" → ";", "," → ";"}];
outArgs = r[[{5, 6}]];
outVars = outArgs /. ruleYxpy;
outStr = StringJoin[" ", ToString[outVars]];
inputArguments =
  "[dataSamples_List, initialConditions_List, \
systemParameters_List]";
comma = ",";
quote = "\"";
usageString =
  StringJoin[procedureName, "::usage = ", quote, outStr, " = ",
    procedureName, "[", dataVarsStr, comma, initVarsStr, comma,
    ToString[r[[3]], "]",
    " is the template for calling the procedure. ",
    " The general template is ",
    "{outputSamples, finalConditions} = ",
    "procedureName[inputSamples, initialConditions, \
systemParameters]. ",
    "See also: DiscreteSystemImplementationProcessing2", quote, ";",
    " "];
implementationString =
  StringJoin[procedureName, inputArguments, " := ", "Module", "[ ",
    localVarsStr, comma, params, dataEqns, initEqns, bodyRepl,
    outStr, " ]"];
(*activate implementation code*)
ToExpression[usageString~StringJoin~implementationString];
If[verb, (*then*)
  Print["Implementation procedure name: ", procedureName];
  Print["Implementation procedure usage: "];
  ToExpression["?"~StringJoin~procedureName];];
StringJoin[usageString, dimsName, implementationString];

DiscreteSystemImplementationModule2[x_] :=
  Module[{}, Message[DiscreteSystemImplementationModule2:"invargs"];
  ""];

DiscreteSystemImplementationModule2[x_, y_] :=
  Module[{}, Message[DiscreteSystemImplementationModule2:"invargs"];
  ""];

DiscreteSystemImplementationModule2[a___] :=
  Module[{n}, n = Length[{a}];
  Message[DiscreteSystemImplementationModule2:"argx", n];
  ""];

(*-----DiscreteSystemImplementationProcessing2-----*)
DiscreteSystemImplementationProcessing2[inputSequence_List?MatrixQ,

```

```

initialConditions_List, systemParameters_List?VectorQ,
procedureName_Symbol] :=
Module[{dimsName, dimsValue, finalConditions = initialConditions, n,
  outputSequence = {},
  response}, (*check that procedureName is not a built-in function*)
If[Names[
  "System`"~StringJoin~ToString[procedureName]] == {ToString[
  procedureName]},
  Message[DiscreteSystemImplementationProcessing2::"sysname",
    procedureName];
  Return[{{}, {}}];
dimsName = ToString[procedureName]~StringJoin~"[]";
dimsValue = ToExpression[dimsName];
If[MatchQ[dimsValue, _List?VectorQ] === False,
  Message[DiscreteSystemImplementationProcessing2::"invdims",
    procedureName, dimsValue];
  Return[{{}, {}}];
If[Length[First[inputSequence]] != dimsValue[[1]],
  Message[DiscreteSystemImplementationProcessing2::"invinp",
    Length[First[inputSequence]], dimsValue[[1]];
  Return[{{}, {}}];
If[Length[initialConditions] != dimsValue[[2]],
  Message[DiscreteSystemImplementationProcessing2::"invcond",
    Length[initialConditions], dimsValue[[2]];
  Return[{{}, {}}];
If[Length[systemParameters] != dimsValue[[3]],
  Message[DiscreteSystemImplementationProcessing2::"invparam",
    Length[systemParameters], dimsValue[[3]];
  Return[{{}, {}}];
Do[response =
  procedureName[inputSequence[[n]], finalConditions,
    systemParameters];
AppendTo[outputSequence, First[response]];
finalConditions = Last[response];, {n, Length[inputSequence]};
{outputSequence, finalConditions}];

DiscreteSystemImplementationProcessing2[_ , _ , _ , _] :=
Module[{},
  Message[DiscreteSystemImplementationProcessing2::"invargs"];
  {{}, {}}];

DiscreteSystemImplementationProcessing2[a___] :=
Module[{n, n = Length[{a}];
  Message[DiscreteSystemImplementationProcessing2::"argx", n, 4];
  {{}, {}}];

```