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Article

Influence of Placing Positions of PZT Transducers in Thick Composites on Ultrasonic Guided Waves

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Abstract: The main objective of the paper is to investigate the wave propagation behaviour in composites using numerical and experimental methods. Specifically, the study focuses on the actuation of waves by two PZT transducers placed on the surface and embedded at different positions within the composites, namely the quarter and middle positions. The numerical analysis provides simulated results, while the experimental analysis involves practical testing. The paper demonstrates that the numerical results are consistent with the experimental findings. It is observed that when the PZT transducers are placed at deeper positions within the composites, the peak amplitude of the first wave packet for the A₀ mode decreases. Overall, the paper contributes to the understanding of wave propagation in composites by comparing the effects of different positions of PZT transducers, both on the surface and embedded within the material. The findings highlight the influence of transducer placement on wave characteristics, particularly the reduction in peak amplitude with deeper transducer positioning.

Keywords: structural health monitoring (SHM); lead zirconate titanate (PZT) transducers; embedded positions; thick composites; finite element modelling (FEM)

1. Introduction

There is a great interest in the usage of ultrasonic guided waves (UGW)-based Structural Health Monitoring (SHM) techniques in the aeronautics industry for detecting, locating, and evaluating damages in composite structures [1-3]. These SHM techniques offer real-time monitoring capabilities, improving safety, accuracy, and significantly reducing maintenance time and costs compared to traditional non-destructive techniques (NDT) such as visual inspection, ultrasonic A-/C-scans, X-ray, thermography, and infrared techniques [4-6].

UGW propagation is advantageous for SHM due to its ability to travel long distances with minimal attenuation and its sensitivity to small structural defects [7, 8]. Lead zirconate titanate (PZT) transducers are commonly used in active sensing SHM techniques because of their durability, lightweight nature, relatively low cost, and low power consumption [9]. These PZT transducers can be surface-mounted or embedded within composite structures [10]. However, surface-mounted transducers may be susceptible to damage from external loading, and the thickness and external environments can affect measurement results [11, 12]. Additionally, the anisotropic properties of composite structures make it challenging to predict their structural behaviour under complex multi-directional loading conditions using surface-mounted PZT transducers [13]. Embedded PZT transducers offer improved durability and reliability, especially in thick composite structures [14].

Various methods have been proposed for embedding PZT transducers, including conventional insertion and cut-out techniques [15, 16], as well as the use of SMART LayersTM [17, 18] and circuit-printing techniques [19-21]. However, limited research has focused on studying the effects of embedded PZT transducers within different layers of thick composites.

Some studies have investigated the detection of low-energy impact damage using surface-mounted or embedded PZT transducers, showing that closer proximity to the surface improves the sensitivity [22]. Analytical approaches have also been proposed to investigate the deformation of composite laminates actuated by surface-mounted and embedded PZT transducers, demonstrating

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reduced deflection with increased embedded depth of the transducers [23]. Additionally, the deformation induced by surface-mounted transducers was found to be larger than that of embedded transducers.

The objective of this paper is to study guided waves through different layers of composites using surface-mounted and embedded PZT transducers. Numerical simulations will be conducted to study the guided wave behaviour first. The peak amplitude of the first wave packet and the time-of-flight (ToF) activated/received by PZT transducers at different placing positions will be investigated. After that, UGW propagation through different layers of composite coupons will be experimentally studied.

2. Finite-element Modelling

2.1. Numerical Simulation

To investigate the thickness effect of different embedded positions on ultrasonic guided waves (UGW), numerical simulations were conducted. The focus was on understanding the relationship between the peak amplitude of the first wave packet and the time-of-flight (ToF) of UGW for composites with different thicknesses (2 mm, 4 mm, and 9 mm). In numerical calculations, direct time-integration methods employing explicit and implicit algorithms were utilized [24]. The explicit algorithm, which is conditionally stable, relies entirely on the results of the previous time step (t) to determine the equilibrium state at the subsequent time step (t + Δ t) [24]. It should be noted that the explicit algorithm is more computationally efficient for larger models compared to the implicit algorithm [25].

However, the explicit time integration algorithm described in [26] is specifically designed for surface-mounted PZT transducers, and there is no analytical solution available for embedded PZT transducers using the explicit algorithm within the context of Abaqus/Explicit dynamic analysis. Additionally, the Abaqus/Explicit dynamic analysis lacks a piezoelectric element, further limiting its applicability for simulating UGW propagation in composite laminates with embedded PZT transducers. Consequently, the implicit dynamic analysis (Abaqus/Standard) becomes the sole viable approach for simulating UGW propagation in composite laminates with embedded PZT transducers. To utilize this approach effectively, the piezoelectric matrix and the dielectric parameters (permittivity) for the PZT transducer need to be validated in advance.

Figure 1 illustrates the assembly relationships of the composite structures with embedded PZT transducers using the commercial software ABAQUS. In each model, two PZT transducers were either surface-mounted or embedded into the composite panels, positioned from the first layer to the middle layer.

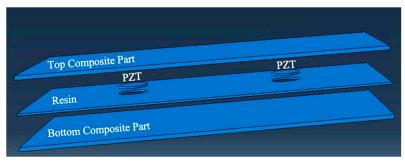


Figure 1. Schematics of assembly for ABAQUS simulation.

To achieve different thicknesses in the composite parts, the overall size of the part was set to 0.22 m \times 0.17 m. The depths of each model were defined as 0.002 m, 0.004 m, and 0.009 m, respectively. The PZT transducer had a diameter of 0.01 m and a thickness of 0.0002 m. To fill the gap in the middle section, a resin part with the same dimensions as the composite part was included. The thickness of the resin part was set to 0.0002 m. The distance between the two PZT transducers was 0.11 m, and their distances from the centre to the edges were 0.055 m in the x-direction and 0.085 m in the y-direction. For the definition of the composite lay-up, the element type was chosen as continuum shell.

The stacking sequences and the single thickness of each ply were $[(0^{\circ}/+45^{\circ}/-45^{\circ}/+90^{\circ})n]s$, where n represents the number of plies (2, 4, or 9), and the single ply thickness was set to 0.000125 m.

In summary, due to limitations in the explicit algorithm and the absence of piezoelectric elements in Abaqus/Explicit, the implicit dynamic analysis (Abaqus/Standard) is the preferred numerical method for simulating UGW propagation in composite laminates with embedded PZT transducers. The assembly relationships of the composite structures with embedded PZT transducers were defined in ABAQUS, including the sizes and positions of the transducers, the thicknesses of the composite and resin parts, and the stacking sequences and thicknesses of the plies. These parameters provide the basis for further analysis and simulation of the UGW behaviour in the composite structures.

Material properties for unidirectional carbon fibre prepregs, the PZT actuator and the resin are listed in Error! Reference source not found.. The piezoelectric and the dielectric parameters used for the implicit dynamic analysis can be found in Error! Reference source not found. For meshing the composite part, an element size of 0.001 m was used in the x-y plane, and only one element was employed in the z-direction. The family type was set as a continuum shell, and the element type chosen was SC8R in the mesh control. The diameter of the PZT transducer was 0.01 m, and the thickness was 0.0002 m. For meshing the PZT actuator, an element size of 0.0005 m was used in all directions. The family type was set as piezoelectric, and the element type chosen was an 8-node linear piezoelectric brick (C3D8E). For meshing the resin, the setups for the element size and mesh control were the same as those used for the composite part and 3D stress, C3D8R.

Uni-directional Carbon Fibre Prepregs IM7/8552 E22 (MPa) G23 (MPa) E₁₁ (MPa) G₁₂ (MPa) G₁₃ (MPa) ν 12 ρ (kg/m³) 161,000 11,380 0.32 5170 5170 3980 1570 **DuraAct PZT (PIC255)** d31 (C/N) d33 (C/N) ρ (kg/m³) d15 (C/N) $\varepsilon_{33}^{T}/\varepsilon_{0}$ $\varepsilon_{11}^{T}/\varepsilon_{0}$ S_{11}^{E} (m²/N) S_{33}^{E} (m²/N) 7800 -180×10^{-12} 400×10^{-12} 550×10^{-12} 1750 1650 16.1×10^{-12} 20.7×10^{-12} Resin (M56) ρ (kg/m³) E (MPa) ν 1300 4130 0.27

Table 1. Material Properties for ABAQUS simulation.

To verify the time step of the signal, the increment size of the period was set to 2e-8 by selecting the "fixed" type and "unlimited" by choosing the "automatic" type under the incrementation window in the STEP procedure. It was observed that there was no difference in the results between these two different settings. For the implicit dynamic procedure, the frequency was set to every n increments (n=10). This means that the analysis would capture data and update the results every 10 time steps. The input signal of the electrical potential used for the implicit dynamic analysis (Abaqus/Standard) was a chirp signal, which is a signal that sweeps through a frequency range [27]. The frequency range of the chirp signal was set from 25 kHz to 500 kHz. The time duration of the signal was 200 μ s, and the input amplitude was 6 V.

2.2. Results

2.2.1. Envelop Signals

The chirp signals obtained were reconstructed into five-cycle Hanning-windowed toneburst signals at 50 kHz and 250 kHz. These toneburst signals were used to analyze the envelope signals of the ultrasonic guided waves (UGW) through the composite panels. The envelope signals were

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computed using the Hilbert transform, a mathematical tool commonly used for signal processing and envelope detection.

Figure 2 provides a summary of the numerical envelope signals of UGW for the composite panels with thicknesses of 2 mm, 4 mm, and 9 mm, placed in different positions. The envelope signals were generated at 50 kHz and 250 kHz. From these signals, the time-of-flight (ToF) and the peak amplitude of the envelope signals (corresponding to the first wave packet of UGW) were calculated for each signal. The results presented in Figure 2 offer insights into the behaviour of the UGW through the composite panels of varying thicknesses and different placements. The ToF provides information about the time it takes for the UGW to travel through the panel, while the peak amplitude of the envelope signals indicates the strength or intensity of the UGW at the first wave packet.

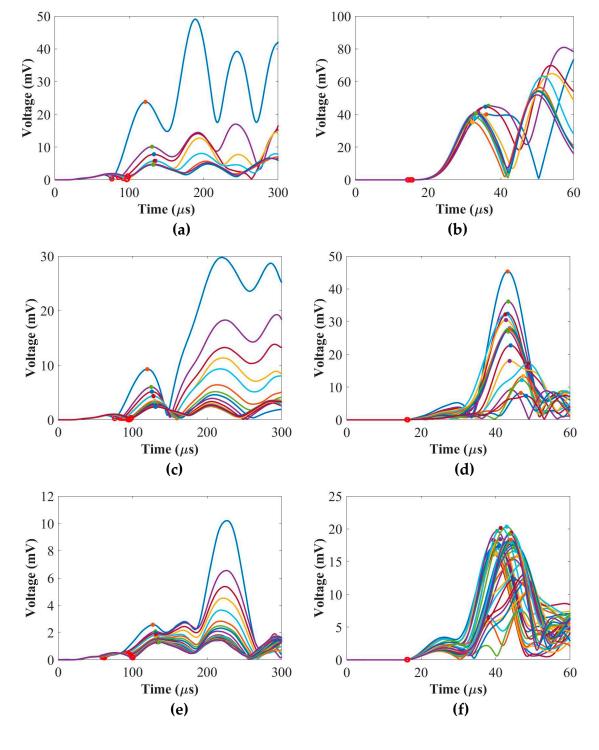


Figure 2. Summary of the numerical envelope signals for the 2 mm panel at **(a)** 50 kHz and **(b)** 250 kHz; for the 4 mm panel at **(c)** 50 kHz and **(d)** 250 kHz; and for the 9 mm panel at **(e)** 50 kHz and **(f)** 250 kHz.

2.2.2. Time-of-Flight (ToF)

Figure 3 displays the relationship between the time-of-flight (ToF) and different placing positions for the thicknesses of 2 mm, 4 mm, and 9 mm panels at 50 kHz and 250 kHz. In the context of the composite stacking sequences during modeling, position 0 on the x-axis in Figure 3 corresponds to the scenario where the PZT transducers are surface-mounted on top of the composite panel. Moving along the x-axis from position 1 to the end position (e.g., from the 1st to 8th layer for the 2 mm panel in Figure 3) represents the embedding of PZT transducers from the 1st layer to the middle layer of the composite panel.

Observing Figure 3, it can be seen that the ToF values appear random or show no clear trend with the increase in placing positions of the PZT transducers. This indicates that the placing positions of the PZT transducers have no significant effect on the ToF of the ultrasonic guided waves. Based on these findings, it can be concluded that the placement of the PZT transducers in different layers of the composite panels does not significantly impact the time it takes for the ultrasonic guided waves to propagate through the material, as indicated by the ToF results.

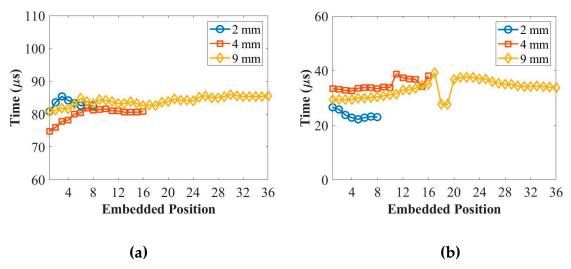


Figure 3. Summary of the ToF for all panels at (a) 50 kHz and (b) 250 kHz.

2.2.3. Peak Amplitude

Figure 4 illustrates the relationship between the peak amplitude of the first wave packet and different placing positions for the thicknesses of 2 mm, 4 mm, and 9 mm panels at 50 kHz and 250 kHz. According to Figure 4, it is observed that the peak amplitude of the first wave packet decreases as the transducers are placed in a deeper position within the composite panels. This behaviour is observed for the thicknesses of 2 mm, 4 mm, and 9 mm panels at 50 kHz. However, for the So mode at 250 kHz, there is no significant change in the peak amplitude of the first wave packet with respect to the placing positions. Therefore, based on the findings from Figure 4, it can be stated that the peak amplitude of the first wave packet for the Ao mode at 50 kHz reduces as the placing positions of the transducers are moved to deeper positions within the composite panels. On the other hand, the peak amplitude of the first wave packet for the So mode at 250 kHz does not exhibit a significant variation with the changing placing positions.

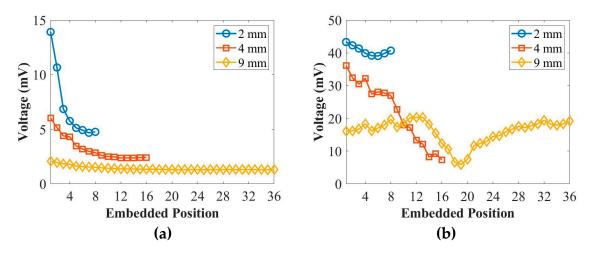


Figure 4. Summary of the peak amplitude of the first wave packet for all panels at **(a)** 50 kHz and **(b)** 250 kHz.

3. Experimental Setup

The coupons consisted of unidirectional carbon fibre prepregs, specifically Hexply® IM7/8552, with stacking sequences of $[(0^{\circ}/+45^{\circ}/-45^{\circ}/+90^{\circ})n]$ s, where n represented the number of plies (2, 4, or 9) corresponding to the thicknesses of 2 mm, 4 mm, and 9 mm panels, respectively. The size of the composite coupon was 260 mm × 45 mm, and the distance between the two PZT transducers was set to 180 mm to avoid any overlap between crosstalk and the first wave packet of the embedded signals at 50 kHz. The distances from the centre of the PZT transducers to the edges were 40 mm in the x-direction and 22.5 mm in the y-direction. For embedding and surface-mounting, DuraActTM (P-876.K025) PZT transducers were used during the manufacturing process. The preparation of the diagnostic film, which connected to the PZT transducers using a Dimatix material printer (DMP-2580), and the embedding and surface-mounting techniques can be referred to in the author's previous work [10].

Figure 5 provides a schematic of a cut-out embedding technique that allowed for edge trimming after curing. Figure 6 shows the schematic of the placing positions of the PZT transducers within the composite coupons. Figure 7 displays examples of the lay-up for middle embedding, as well as a trimming coupon after curing, with middle-embedded ending terminals and connectors. Lastly, Figure 8 shows all three composite coupons with surface-mounted diagnostic films and PZT transducers, as well as the quarter-embedded ending terminals and connectors for the thicknesses of 2 mm, 4 mm, and 9 mm, respectively. These figures provide visual representations of the experimental setup, including the composite coupons with their respective embedded and surface-mounted PZT transducers, the diagnostic films, and the placing positions of the transducers within the coupons.

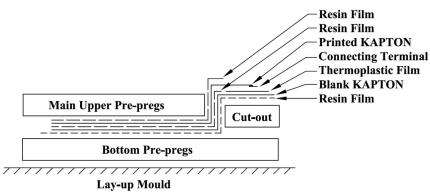


Figure 5. Schematic of lay-up producer with embedded diagnostic films.

Figure 6. Schematic of the PZT transducers placed on the surface, embedded in the quarter and middle layers of the composite coupon.



Figure 7. Examples of **a**) a lay-up procedure with embedded diagnostic film and **b**) a trimmed coupon with middle embedded ending terminals and connector.

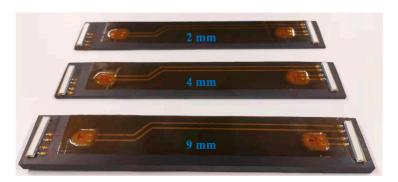


Figure 8. Coupons with surface-mounted diagnostic films and quarter-embedded ending terminals and connectors for the thickness of 2 mm, 4 mm and 9 mm panels.

4. Results and Discussions

In this section, the amplitude of ultrasonic guided waves (UGW) based on active sensing will be investigated to compare the actuation behaviours using different placing positions of PZT transducers across the different thicknesses of composites.

Figures 9 and 10 present the peak amplitude and time-of-flight (ToF) of the first wave packet of UGW actuated by PZT transducers in different placing positions for the 2 mm, 4 mm, and 9 mm thick coupons at 50 kHz and 250 kHz, respectively. In Figure 9, it can be observed that the peak amplitude of the first wave packet for the surface-mounted signal is higher compared to the quarter- and middle-embedded signals at 50 kHz. However, the placing positions do not significantly affect the peak amplitude at 250 kHz. Figure 10 demonstrates that the ToF of the UGW is not influenced by the placing positions of the PZT transducers at both 50 kHz and 250 kHz.

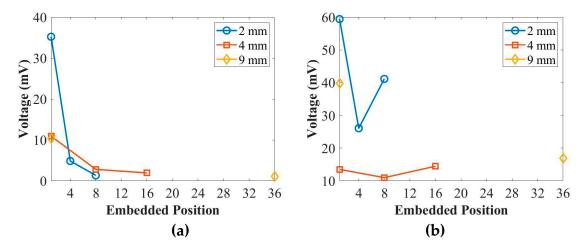


Figure 9. The peak amplitude of the first wave packet actuated by PZT transducers placed in different positions at **(a)** 50 kHz and **(b)** 250 kHz for the 2 mm, 4 mm and 9 mm thick coupons.

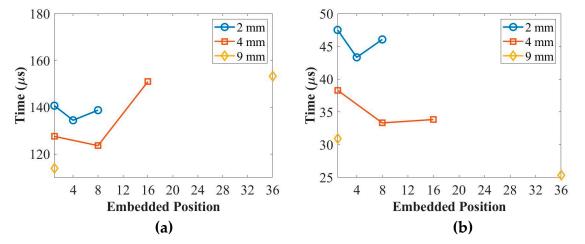


Figure 10. The time-of-flight (ToF) of the first wave packet actuated by PZT transducers placed in different positions at **(a)** 50 kHz and **(b)** 250 kHz for the 2 mm, 4 mm and 9 mm thick coupons.

As it can be seen the experimental and numerical simulations results are in good agreement. These experimental results provide insights into the actuation behaviours of UGW using different placing positions of PZT transducers across various thicknesses of composites. The peak amplitude of the first wave packet is influenced by the placing positions at 50 kHz but remains unaffected at 250 kHz. Meanwhile, the ToF of the UGW is independent of the placing positions at both frequencies.

5. Conclusions

In this paper, the effect of ultrasonic guided waves (UGW) through different layers of composite plates was investigated using both numerical and experimental approaches.

The numerical analysis involved finite-element modeling to simulate the UGW actuated by PZT transducers placed at different positions, ranging from the surface to the middle layers of the composite plates. The time-of-flight (ToF) and peak amplitude of the first wave packet of UGW through different layers were studied. The numerical results revealed that the ToF did not exhibit significant changes at 250 kHz. However, at 50 kHz, the peak amplitude of the first wave packet decreased with deeper embedding positions for the 2 mm, 4 mm, and 9 mm composite plates. This suggests that the depth of the embedding position has an influence on the peak amplitude of the UGW, particularly at lower frequencies.

The experimental studies involved the fabrication of composite coupons with different thicknesses (2 mm, 4 mm, and 9 mm). PZT transducers were mounted on the surface and embedded

in the quarter and middle positions of each composite coupon. UGW actuated by PZT transducers in different placing positions were compared. It was observed that at $50 \, \text{kHz}$, the peak amplitude of the first wave packet for the surface-mounted signal was higher than that of the quarter- and middle-embedded signals. This indicates that the A_0 mode, which dominates at $50 \, \text{kHz}$, is affected by the placing positions of the PZT transducers. These experimental results were found to be in agreement with the numerical simulation results.

In summary, both the numerical and experimental investigations provided insights into the behaviour of UGW through different layers of composite plates. The results demonstrated that the peak amplitude of the UGW is influenced by the depth of embedding position and the A_0 mode is particularly sensitive to the placing positions of the PZT transducers.

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