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Analysis of Accuracy in Clinical Identification of the Implant Site: Pilot Study with Thermo-Printed Templates

Enzo Cumbo, Giuseppe Gallina, Pietro Messina and Giuseppe Alessandro Scardina

Abstract: In implantology, among the key choices, to obtain predictable results, it is essential to establish, on the basis of radiographic examinations, the bone site where to insert the implants; these selected locations must be identified first on the mucosa and then on the cortical bone. Surgical guides represent a valid aid especially in complex cases with more than 3 or 4 implants, whereas in single implant cases they are rarely used. This study evaluates the clinical precision with which the implant sites, on the patient's mucosa, are identified in surgical procedures planned without any templates. The verification of this precision is carried out through thermoprinted templates with radiopaque references which could however help the clinician to identify these sites in a simple, rapid and economical way.

Keywords: Implantology; implant site; thermo-printed templates

INTRODUCTION:

The introduction of 3D radiographic examinations into dentistry has allowed, through computerized image processing, an increasingly simplified and precise organization of surgical procedures. (1,2) In implantology it's a priority to establish where to place the implants and what angle to give them. The 3D exam allows the clinician to evaluate sections of the upper jaw or mandible to decide with extreme precision where to insert the fixtures. The volumetric RX investigation, also, allows the use of computer data in order to develop three-dimensional objects, thanks to the 3D printers widely used today. (3,4,5) The computerized management of clinical procedures can be carried out by surgical guides which give the dentist the possibility of inserting the implants with extreme precision guaranteeing predictable results (6,7,8). On the other hand, the creation of those guides, in some cases, could be an excessively complex and onerous solution when compared with the size of the edentulous site and the number of implants to be inserted. (9,10,11)

In the case of surgical interventions based on the freehand insertion technique, it is essential to interface and correlate the 3D radiographic investigations with the patient's clinical conditions in order to identify with certainty where to insert the fixtures; in the absence of adequate clinical reference points, such as the remaining teeth in the arch, this identification could turn out to be incorrect and therefore nullify the precision with which the implant sites were instead located on the 3D exam.

This risk of error is minimal in the case of monoedentulous sites thanks to the presence of the mesial and distal teeth close to the implant area and becomes increasingly greater as these dental references become distant. (12,13,14,15)

This study evaluated the precision with which the implant sites, on the patient's mucosa, are identified in different clinical conditions using a thermo-printed device that is easy and cheap to make and can also be used as a guide in identifying these areas.

MATERIALS AND METHODS.

This study is based on an experimental protocol, based on surgical templates to be built on diagnostic dental cast, to be worn by the patient during the 3D exam, in order to verify the accuracy of the clinical identification of the implant site on the mucosa in procedures without surgical guides.

Twenty-two patients with partial edentulism were selected for which prosthetic rehabilitations with single or multiple implants were planned. Alginate impressions were taken on all patients, in order to obtain cast models, as well as preliminary orthopantomographic x-ray examinations.

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By interfacing clinical and orthopantomographic data, a preliminary decision was made where the implants could potentially be located. This preliminary decision made it possible to mark on the cast model, using a felt-tip pen, the site where to locate any single fixture.

For each patient, on the cast models, exactly in the points marked by the marker, steel spheres with a diameter of 2 millimeters were glued using cyanoacrylate. On those cast models thus modified, thermo-printed templates were made with 0.5 mm thick sheets of soft consistency. These templates, during the hot thermoforming, detached and incorporated the tiny spheres previously placed, so as to represent precise radio-opaque landmarks integral with the devices themselves.



Fig 1



Fig 2

All templates have been finished and regularized at the edges so that they can be comfortably worn by the patient during the 3D RX exam without causing obstacles to correct execution.

On the RX images, the metal spheres appear clearly visible in the hypothetical points where the fixtures could be inserted and given their very small size, the unwanted scatter effects in the RX images, normally caused by metal objects, were completely negligible and not have reduced the minimum quality and legibility of the exams.

By scrolling through the various sections of the 3D exam, the hypothetical positions where to place the implants were verified.

All 22 patients were further divided into 3 groups: 1) patients with monoedentulous intercalated sites (type III or IV Kennedy class); 2) patients with distal edentulism of 3 teeth and planning of 2 implant fixtures (type I or II class Kennedy). 3) patients with distal edentulism where more than 3 teeth were missing and planning of 3 or more implant fixtures (type I or II Kennedy class).

A total of 22 templates were thermoformed as follows: n. 12 templates relating to group 1 (with a single sphere), n. 6 templates for group 2 (with 2 spheres per template) and n. 4 templates for group 3 (with 3 or more spheres).

For each individual clinical case, the implantologist was asked to examine the 3D exam, identify the sections with the radiopaque spheres and then visit the patient to mark on the mucosa with an indelible marker (2 mm tip) where the sites had been selected for implant placement. Subsequently, the mask with the spheres was inserted on the single patient to compare its position with the points marked with the marker.

In case of mismatch, the distance between the metal ball and the dot on the mucosa was measured to quantify the error made by the implantologist.

In total, distributed among the various patients, the correspondences between the positions of 40 metal spheres and as many hypothetical implant sites identified with the marker on the mucosa were analysed.

The result of the measurements was coded in three possibilities: 0 error (precise correspondence between metal sphere and dot on the mucosa), minimum error (distance between metal sphere and dot <2mm), maximum error (distance between metal sphere and dot >2mm).

RISULTS

In **group 1** (monoedentulism) in 8 locations there was a perfect correspondence between the metal sphere incorporated in the mask made to be worn by the patient and the sign on the mucosa indicated by the implantologist as the area of the future implant. A minimum error (<2mm) was found in 3 sites and a maximum error (>2mm) was recorded only in one case.

In **group 2** (poliedentulism/2 implants) in 6 locations there was perfect correspondence between the sphere and the sign on the mucosa indicated by the implantologist as the area of the future implant. In 4 sites there was a minimum error (<2mm) and in 2 cases there was a maximum error (>2mm).

In **group 3** (poliedentulism/>2 implants) in 6 locations there was perfect correspondence between the sphere and the sign on the mucosa. In 4 sites there was a minimum error (<2mm) and in 6 sites there was a maximum error (>2mm).

Table 1										
	GROUP 1		GROUP 2		GROUP 3					
	(III-IV	Kennedy class)	(I-II Kennedy class)		(I-II Kennedy class)					
	MONO EDENTULOUS MULTIPLE EDENTULOUS MULTIPLE EDENULO									
			SITES	TOT						
	SITES	(1 implant)	SITES	SITES (2 implants)	(>2 implants)					
Patients		12	6		4	22				
Spheres		12	12		16	40				
Perfect match	<u> </u>	8	6		6	20				
Distance <2mm		3		4	4	11				
Distance >2m	l	1		2	6	9				
m										
Total		12		12	16	40				

Within the single group, it was also assessed how much the distance between the presumed implant site and the neighboring teeth (which serve as the anatomical reference point for the clinical calculation of the correct position of the fixture) influenced the choices of the implantologist in marking the point on the mucosa. In groups 2 and 3 the mesial implant site (closest to the remaining natural tooth) was defined as the <u>1st implant site</u>. The subsequent implant site (distal to the first) was defined as the <u>2nd implant site</u> and so on for the 3rd and 4th implant site studied in this research.

In **group 1**, given that these are single fixture sites, the data are those already reported above.

In **group 2**, for the first implant site, in 5 cases there was a perfect correspondence between the metal sphere incorporated in the mask made to be worn by the patient and the mark on the mucosa indicated by the implantologist as the site of the future implant. In one case there was a minimum error (<2mm) and in no case was there a maximum error (>2mm). For the second implant site, in one case there was a perfect correspondence between the metal sphere incorporated in the mask made to be worn by the patient and the mark on the mucosa indicated by the implantologist as the site of the future implant. In 3 cases there was a minimum error (<2mm) and in 2 cases there was a maximum error (>2mm).

In **group 3**, for the first implant site, in 4 cases there was a perfect correspondence between the metal ball incorporated in the mask made to be worn by the patient and the mark on the mucosa. In no case was there a minimum error (<2mm) and in no case was there a maximum error (>2mm). For the second implant site, in 2 cases there was a perfect correspondence between the metal sphere

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incorporated in the mask made to be worn by the patient and the mark on the mucosa indicated by the implantologist as the site of the future implant. In 2 cases there was a minimum error (<2mm) and in no case was there a maximum error (>2mm). For the third implant site, in 0 cases there was a perfect correspondence between the metal sphere incorporated in the mask made to be worn by the patient and the mark on the mucosa indicated by the implantologist as the site of the future implant. In 2 cases there was a minimum error (<2mm) and in 2 cases there was a maximum error (>2mm). For the fourth implant site, in 0 cases there was a perfect correspondence between the metal sphere incorporated in the mask made to be worn by the patient and the mark on the mucosa indicated by the implantologist as the site of the future implant. In 0 cases there was a minimum error (<2mm) and in 3 cases there was a maximum error (>2mm). All data were subjected to statistical analysis.

Table 2

Table 2												
	GROUP 1	GROUP 1	GROUP 1	Spheres								
	1° implant site	2° implant site	3° implant site									
	MONO-	MONO-	MONO-									
GROUP 1	EDENTULOUS	EDENTULOUS	EDENTULOUS									
	SITES	SITES	SITES									
Perfect match 8		not applicable	not applicable									
Distance <2mm 3		not applicable	not applicable									
Distance >2mm	1	not applicable	not applicable									
Total	12	0	0	12								
					T							
	GROUP 2	GROUP 2	GROUP 2	Spheres								
	1° implant site	2° implant site	3° implant site									
GROUP 2	MULTIPLE	MULTIPLE	MULTIPLE									
	EDENTULOUS	EDENTULOUS	EDENTULOUS									
	SITES	SITES 1	SITES									
	Perfect match 5		not applicable									
Distance <2mm	1	3	not applicable									
Distance >2mm	0	2	not applicable									
Total	6	6	0	12								
	GROUP 3	GROUP 3	GROUP 3	GROUP 3	GROU P 3	Spheres						
GROUP 3	1° implant site	2° implant site	3° implant site	4° implant site	5° implan t site							
	MULTIPLE EDENTULOUS SITES	MULTIPLE EDENTULOUS SITES	MULTIPLE EDENTULOUS SITES	MULTIPLE EDENTULOU S SITES	MULTI PLE EDEN TULO US SITES							
Perfect match	4	2	0	0	0							
Distance <2mm	0	2	2	0	0							

DISCUSSION

Distance >2mm

Total

0

From the data examined in this study, it's clear that in certain clinical conditions, such as monoedentulism, it's extremely easy to identify on the mucosa and then on the cortical bone where to position the implant. In these cases, the presence of the two contiguous teeth (mesial and distal) adjacent to the edentulous site offers the implantologist certain landmarks. When the presumed implant site is far from a natural teeth and when the latter are only on one side, as I or II Kennedy classes, precisely identifying the exact point where to start milling the bone could be a problem.

2

3

16

0

Our results show that it's significant that in the 2nd, 3rd and 4th implant site respectively, as the distance from the last natural tooth in the arch increases, the error progressively increases.

In this study, for example, in group 3 (poliedentulism with more than 3 implants) at the level of the 4th implant site, the most distal to the natural tooth remaining in the arch, in 0% of cases there

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was a precise correspondence between the metal sphere and the point marked on the mucosa; similarly, always in group 3, at the level of the 4th implant site, in 100% of cases there was a maximum error (>2mm).

The same conclusion is reached if the data relating to group 2 are analysed, where more specifically the first implant site (the mesial one) presents data which can be superimposed on those relating to the single implant site of group 1; the second implant site (the most distal) instead has a greater margin of error but not as large as that of the third and fourth implant site of group 3.

This imprecision, due to the reduced ability of the human eye to evaluate distances as the reference anatomical landmark becomes more distant, often pushes the implantologist to use surgical templates which also give important indications on the angle to be given to the axis of the fixture. In clinically simple situations, such as monoimplant sites, surgical guides are not normally used because the precision in inserting the implant is easily controllable.

On the other hand, in extreme situations, such as those of group 3 and with the planning of 3 or more implants and in the presence of important anatomical areas, such as the mandibular canal, it seems appropriate to resort to the classic implant templates. (16) In intermediate situations such as those of group 3, which require the identification of two implant sites, the execution of templates with radiopaque references could represent an economic and easy-to-perform solution. Naturally, the type of information given by these thermo-printed guides is reduced only to identifying the point on the mucosa and on the bone where to insert the fixture without the aid of additional information regarding the angle. (17.18)

With regard to these parameters, the clinician must refer to the data acquired through a 3D RX examination as normally occurs in the execution of freehand techniques.

It seems clear that every time the positioning of the implant suggested by the sphere incorporated in the template has to be modified thanks to the information coming from the 3D sections, the same spheres visible both in the volumetric RX and on the mucosa (when the device is worn), can be considered as the residual teeth that are normally used as landmarks; therefore their extreme proximity to the new point where to place the implant greatly reduces the margin of error.

CONCLUSIONS

This research is part of a study that examines a whole series of preliminary assessments that the implantologist carries out during the setting of the surgical intervention. The planning of such a delicate treatment, which has a high biological cost for the patient, requires attention and is aimed at obtaining predictable results. This study shows that sometimes, in particular situations, our visual assessment, especially on distances, may not be accurate with the consequence of making mistakes that could invalidate the entire implant protocol. (19,20,21,22) In some clinical conditions, the packaging of thermo-printed masks with radiopaque references, which can also be done in the studio without the aid of a dental technician and with the help of a few simple equipment, could allow the implantologist to significantly increase the level of accuracy in identifying the implant site. (23)

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