An integrated fuzzy fault tree model with Bayesian network-based maintenance optimization of complex equipment in automotive manufacturing

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Abstract

Knowledge-based approaches are useful alternatives to predict the Failure Probability (FP) coping with the insufficient data, process integrity and complexity issue in manufacturing systems. This study proposes a Fault Tree Analysis (FTA) approach as proactive knowledgebased technique to estimate the FP based maintenance planning with subjective information from domain experts. However, the classical-FTA still suffers from the uncertainty and static structure limitations which poses a substantial dilemma in predicting FP. To deal with the uncertainty issues, a Fuzzy-FTA (FFTA) model was developed by statistical analysing the effective attributes such as experts' trait impacts, scales variation and, assorted membership and defuzzification functions. Besides, a Bayesian Network (BN) theory was conducted to overcome the static limitation of classical-FTA. The results of FFTA model revealed that the changes in decision attributes were not statistically significant on FP variation while BN model considering conditional rules to reflect the dynamic relationship between events had more impact on predicting FP. After all, the integrated FFTA-BN model was used in optimization model to find the optimal maintenance intervals according to estimated FP and total expected cost. As a practical example, the proposed model was implemented in a semi-automatic filling system in an automotive production line. The outcomes could be useful for upgrading the availability and safety of complex equipment in manufacturing systems.

Keywords: Automotive industry, Bayesian network, Fault tree analysis, Fuzzy set theory, Maintenance optimization, Uncertainty.

Abbreviation list

Abbreviation	Description	Abbreviation	Description
FTA	Fault Tree Analysis	TE	Top Event
BNs	Bayesian Networks	BEs	Basic Events
IFS	Intuitionistic Fuzzy Set	IEs	Intermediate Events
FFTA	Fuzzy Fault Tree Analysis	ETA	Event Tree Analysis
FPS	Fuzzy Possibility Score	НАССР	Hazard Analysis Critical Control Points
CPTs	Conditional Probability Tables	HAZOP	Hazard and Operability Study
FMEA	Failure Mode and Effect Analysis	MCS	Minimal Cut Set
ABS	Anti-lock Braking System	PLC	Programmable Logic Controller
PCS	Pressure Control Set	END	Event Not Developed
MF	Membership Function	LE	Linguistic Expression
DAG	Directed Acyclic Graph	CPTs	Conditional Probability Tables
FP	Failure Probability	RA	Relative Agreement

1. Introduction

With the advent of new technologies and increasing systems' complexity in modern manufacturing industries, the reliable and effective maintenance programs are required to ensure the high level of productivity and availability at the lowest cost and less number of unexpected shutdowns (Ayvaz and Alpay, 2021; Holgado *et al.*, 2020). In this context, the risk and reliability-based approaches have received the most attention from researchers to support maintenance activity decisions within process-oriented systems (Soltanali *et al.*, 2021: Chemweno *et al.*, 2018; Alizadeh and Sriramula, 2017; Kiran *et al.*, 2016). Moreover, such approaches have been widely used in diagnosing critical hotspots, troubleshooting and continues monitoring of systems with regard to data-driven and knowledge-based methods (Garmabaki *et al.*, 2020; Alzghoul *et al.*, 2014).

Knowledge-based approaches are recognized as very useful techniques with that of data drivenbased methods for evaluating risk and reliability, fault detection, and maintenance decision making face the imprecise and insufficient data related to equipment failures, environmental factors, and human activities (Leimeister and Kolios, 2018; Yazdi and Soltanali, 2018; Kumar, 2014). There are many types of knowledge-based techniques that chiefly refer to risk and reliability analysis such as Failure Mode and Effect Analysis (FMEA), Hazard Analysis Critical Control Points (HACCP), Hazard and Operability Study (HAZOP), Event Tree Analysis (ETA), Fault Tree Analysis (FTA), etc. (Jin *et al.*, 2021; Soltanali *et al.*, 2020a; Leimeister and Kolios, 2018; Zhang *et al.*, 2018; Yildiz *et al.*, 2014; Venkatasubramanian *et al.*, 2003).

In such direction, the FTA technique is recognized as a powerful diagnosis tool which has been one of the most important knowledge-based methods since twentieth century. It is known as a deductive procedure in which the combinations of both system faults and human errors can be determined (Kumar and Kaushik, 2020; Yazdi et al., 2019). In general, the FTA analyses are classified into qualitative and quantitative levels. In qualitative analysis, the tree networks are transferred into Minimal Cut Sets (MCSs) consisting of the smallest combinations of Basic Events (BEs) to cause the Top Event (TE). In quantitative analysis, the probability of the occurrence for the TE and other indicators with like importance measures are mathematically computed (Bobbio et al., 2001; Summers, 2000). After designing the FTA structure, the outcomes could give some indications about system reliability and enable the analysist to determine which unit of a system are in urgent risk, so that the corrective actions may adapt for such critical units. In fact, the analysis procedure reflects how failures of units, human error or environmental factors could result in system failure (Kabir et al., 2019; Berrouane and Lounis, 2013). Furthermore, FTA are regularly being performed for improving product quality and availability through prevention of unexpected failures using the convenient maintenance activities in various industrial systems (Liu et al., 2017; Rusin and Wojaczek, 2012; Rice, 2007; Lapp, 2005).

In particular, automotive manufacturer industries are required to improve their productivity, process safety and availability at the less number of showdowns. Accordingly, a reliable

maintenance program could provide a beneficial service to fulfil such objectives. Besides, they still suffer from some aleatory uncertainties derived by integrity and complexity of new equipment, dependency issue between failures, as well as epistemic uncertainties due to the lack of precise and sufficient data to acquire a well-structured maintenance program (Soltanali *et al.*, 2020b; Soltanali *et al.*, 2019).

To handle such deals, the present study contributes by proposing a new framework of maintenance optimization using an improved FTA technique. Moreover, this paper focuses on computational intelligence and decision tree networks techniques intervening main attributes to deal with the epistemic uncertainty and static limitations of classical-FTA. As a consequence, the proposed framework of maintenance optimization could help engineers to make better decisions on how to improve the availability and safety of complex equipment within the automotive production lines.

The remaining of this paper is structured as follows: Section "Literature review" deals with a summary of literature related to FTA concept and its diverse applications and drawbacks. Section "Research methodology" consists of a new framework of maintenance optimization using an improved FTA intervening the computational intelligence and graphical techniques. Section "Results and discussion" entails the main results of proposed framework by mean of an empirical case study and, finally, section "Conclusion" summarizes the concluding remarks and future directions.

2. Literature review

FTA technique has been extensively used within numerous industrial systems aimed at diverse applications; for instance, assessment of system safety in nuclear reactor and gas distribution systems (Purba *et al.*, 2011; Berrouane and Lounis, Z, 2016), analysis of risk and reliability in automotive, chemical and petrochemical sectors (Baig *et al.*, 2013; Lambert, 2004; Kim *et al.*, 2005), diagnosis and prognosis of faults/failures in electric power, electronic components,

pipelines, aerospace (Volkanovski et al., 2009; Yuhua and Datao, 2005), maintenance tasks implication in medical device, mining, chemical processes, mechanical systems, etc. (Rusin and Wojaczek, 2012; Rice, 2007; Gupta et al., 2006; Khan and Haddara, 2004), and so on. Despite many advantages and successful feedback of the classical-FTA technique, it has been criticized for a number of shortcomings and limitations such as, simplifying the model owing to the system' complexity and lack of knowledge about system behaviour, assuming the independence of events, possibility of human error while specifying the logical structure of fault trees and presence of the redundant or common cause failures (Yazdi et al., 2019; Kumar and Kaushik, 2020). Such fluctuations not only may affect the accuracy of expected analysis results, but also implementing proper corrective decisions and solutions. Therefore, to improve the credibility of the results of FTA, the uncertainties are required to be handled. The computational intelligence and decision tree network techniques/theories have been commonly addressed to take the uncertainties into account and supplement the classical-FTA calculations. In that direction, fuzzy set theory has been widely referred to handle uncertainty issues of FTA. Recently, Aghaei et al., (2021) developed a Fuzzy-FTA (FFTA) model for the risk assessment of functional safety in shopping centre construction projects to identify the origin of the risks and to offer suitable management responses to such risks. In another research, Yazdi et al., (2020) established a FFTA using expert opinion to compute the probability of an event. In order to reduce the probability of the TEs in terms of three parameters (safety consequences, cost, and benefit), an importance measurement technique was employed. Akhtar and Kirmani, (2020) applied a FFTA framework for reliability evaluation of a wind energy system. The outcomes showed that the fuzzy-based technique can combine the probabilities imprecision and inaccuracy in reliability engineering. Zhou and Ren, (2020) conducted a novel FFTA method in the assumption of the values of probability of BEs expressed with triangular intuitionistic fuzzy numbers. An example of weapon system is employed to reflect the

effectiveness of proposed FFTA method. In another study, a novel approach to evaluate system Failure Probability (FP) was developed using FFTA with qualitative failure data. In this study, the linguistic terms are quantified by triangular intuitionistic fuzzy numbers (Kuzu et al., 2019). Due to the lack of historical data for calculating the failure rate of oil and natural gas pipelines, a FFTA framework with expert elicitation was carried out. The results could help safety professionals while making decisions related to the risk management of oil and gas pipelines (Badida et al., 2019). Moreover, a remarkable number of studies have been made for fault diagnosis, probability of failures, and risk and reliability analysis in process industries using FFTA model (Yazdi, and Zarei, 2018; Yazdi and Darvishmotevali, 2018; Yazdi et al., 2017; Yazdi, 2017). Prior to such studies, Rajakarunakaran et al., (2015) proposed a FFTA model to quantify the fault tree of LPG refuelling facility in the absence or existence of data. The results revealed that the approach is very beneficial for the probabilistic reliability estimation. Meanwhile, Kumar and Yaday, (2012) applied the weakest t-norm based intuitionistic FFTA to evaluate system reliability by finding the most critical units that affects the system reliability. In the other hand, the decision tree networks in particular Bayesian Networks (BNs) have been very prevalent to overcome the static structure limitation of FTA. In fact, BNs as the wellknown graphical model tend to create a causal relationship between key factors (causes) and one or more final outcomes in a system (Zheng et al., 2019; Yazdi and Soltanali, 2019; Rausand, 2013; Jong and Leu, 2013). BN analysis may be qualitative, quantitative, or both, depending on the scope of the analysis and also, they are very popular in statistics, machine learning, artificial intelligence as well as risk and reliability analyses (Bouejla et al., 2014; Hänninen et al., 2014; Huang et al., 2006; Khakzad et al., 2013). In recent years, the integrated FTTA-BN model has been very effective to handle the major subjective uncertainties of classical template of FTA aimed at usability for the risk and reliability assessment, fault analysis and failure diagnosis and prognosis (Aydin *et al.*, 2021; Kabir *et al.*, 2019; Yazdi and Kabir, 2017; Smith *et al.*, 2017; Chiremsel and Chiremsel, 2016).

Based on literature, in order to build up such models, often the Triangular (Trimf) or Trapezoidal (Trapmf) as the core Membership Function (MF), the centre of gravity (Centroid) technique as main defuzzification algorithm and three or five-linguistic scale as main fuzzy numbers are assumed as basis of FTA analyses. However, to the best of authors knowledge, the accuracy and capability of other type of functions and algorithms have not yet been investigated by researchers. As main motivation, this study contributes to make a comprehensive survey on the effect of various membership functions, linguistic scale of fuzzy numbers and defuzzification algorithms to ensure a well-established FTTA-BN model. Besides, the effect of experts' traits was addressed to obtain a more reliable estimation of reliability function so that it could be included into the maintenance optimization model in the next step. Additionally, the most FTTA-BN models have focused mainly on the risk and reliability analysis as well as maintenance tasks implication, while less attention using the outcomes in the scheduled-based maintenance tasks. Hence, another objective of this study is to obtain an optimal maintenance plan by solving an optimization problem under the developed FTTA-BN model. As a consequence, due to the process integrity and complexity issue of new equipment, dependency between units' failures, as well as the importance of the safety guarantee and process availability in manufacturing systems, the proposed framework was implemented in a complex semi-automatic filling system in the automotive production line aimed at helping the engineers to be able to manage the operation and maintenance tasks, effectively.

3. Research methodology

The proposed framework of maintenance optimization based on FFTA-BN model is shown in Fig.1. FTA and BN models construction, expert judgment process, and maintenance optimization are three key factors in the proposed framework. First, the TE is identified as the main problem. After that, the computations need to be classified into qualitative and quantitative levels. For qualitative analysis, the FTA structure is constructed to determine the root cause of the TE affected by Intermediate Events (IEs) and BEs, as well as to clarify the relationship of events statically with the aid of logic gates at the level of system's components. Followed by, in quantitative analysis, the experts' knowledge and fuzzy set theory are utilized to calculate the probability of failure and system reliability in terms of each Minimal Cut Set (MCS) in FFTA model. The results of FFTA are employed as input factors in the BN structure, so that the reliability function is predicted under dynamic relationship between events. Finally, the results of combined FFTA-BN model is applied into optimization model to predict the optimal maintenance intervals. The details of each step are provided as follows:

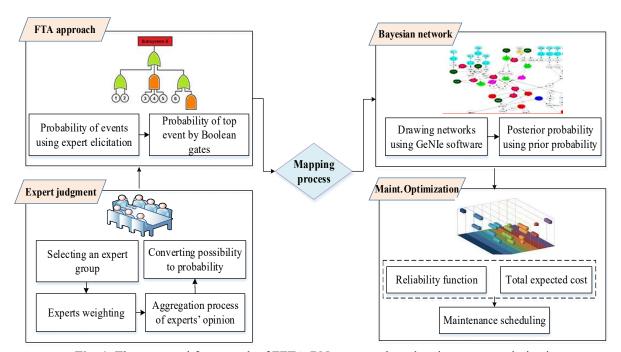


Fig. 1. The proposed framework of FFTA-BN structure-based maintenance optimization

3.1. Theory of FTA approach

FTA belongs to the deductive methods used for identifying the occurrences in equipment or systems that could result in system failure. It provides interrelations between occurrences through graphical representation that can result in system failure. (Farinha, 2018). FTA is started with a specified potential critical event in the system, named as *TE*. In qualitative analysis, *TE* can be initiated from the *BEs* or in combination with Intermediate Event (*IEs*) towards *TE* which are linked through the logical *AND/OR* gates. All *BEs*, from the *TE* to the down are supposed to be binary events that either occur or do not occur, which means that FTA is also a deterministic method. Table 1 shows the graphical symbols commonly used in FTA structure. For instance, from the logic gates, *OR* gate, indicates that there is an occurrence at the output, since there is at least one entry. Besides, *AND* gate implies that there is an occurrence at the output only when there are simultaneous occurrences in all entries (Farinha, 2018; Yazdi and Soltanali, 2018).

Table 1. Main symbols and construction of a fault tree adapted from (Farinha, 2018)

Item	Symbol	Construction
Logic gates:		
-OR gate (OR)		
-AND gate (AND)		
Events:		
-Basic Event (BE)		
-External Event (EE)		7 7 7
-Event Not Developed (END)		
-Intermediate Event (IE)		
Transfer format:		

In quantitative analysis level, the FP of TE or P(T) by estimating the FP of BEs or $P(X_i)$ under AND/OR gates, can be computed as follows (Cheliyan and Bhattacharyya, 2018).

$$P(T) = \begin{cases} \prod_{i=1}^{N} P(X_i) & \text{for } AND \text{ gate} \\ 1 - \prod_{i=1}^{N} (1 - P(X_i)) & \text{for } Or \text{ gate} \end{cases}$$
 (1)

where N is the number of BEs. $P(X_i)$ is the FP of the event X_i . P(T) is the probability of failure of TE. The FP of the TE is evaluated by obtaining its Minimal Cut Sets (MCS). Once all the MCSs, denoted C_i ($i = 1, 2, ..., N_c$) where N_c is the number of MCS, are determined, the FP of the TE, denoted P(T), is given by

$$P(T) = 1 - \prod_{i=1}^{N_c} \left(1 - P(C_i) \right)$$
 (2)

where $P(C_i)$ is the FP of C_i . As long as the failure probabilities of the BEs are small, (i.e., $P(X_i)$ ≤ 1), the above estimate of P(T) can be approximated well by

$$P(T) \approx \sum_{i=1}^{N_c} P(C_i) \tag{3}$$

A typical MCS is a collection of the BEs and may be denoted as

$$C_i = \overline{X_1}, \overline{X_2}, ..., \overline{X_{N_i-1}}, \overline{X_{N_i}} \quad where \overline{X_i} \in (X_1, X_2, ..., X_N)$$

$$\tag{4}$$

where N_j is the number of BEs in C_j , also called the order of the MCS. On the other hand, there are several ways to compute the probability of all BEs such as expert judgment, extrapolation, and statistical-based methods. In this study, the experts' knowledge is utilized to calculate the probability of failures. Due to the various opinion, information, experience, and intellectual attributes of experts, it may lead to a number of uncertainties in the probability of failure values. Therefore, a combination of expert opinions should be used for this purpose. On the other hand, the FTA team in terms of age, expertise, skill, experience, knowledge level, etc. are almost heterogeneous that needs to be handled. The main experts' attributes and their weights are described in Table 2 (Yazdi and Soltanali, 2018).

Categorize weight weight Item Categorize Item Higher-ranking PhD 5 5 academic 4 4 Master Low-ranking academic Profession Education Bachelor 3 Engineer 3 position Associate 2 Technician 2 Diploma Worker 1 1 More than More than 20 years 5 40 4 36-39 16 - 20Age Job Tenure 30-35 2 10-15 3 2 1 6-9 Less than 30 ≤5

Table 2. Weight rating according to experts' attributes

The weighting score of an expert is the summation of these weights for attributes. The weighting factor for each expert is then computed by (Cheliyan and Bhattacharyya, 2018).

Weighting factor of the expert=
$$\frac{\text{Weighting score of the expert}}{\text{Sum of weighting scores of all experts}}$$
 (5)

Table 3 shows the experts' weights and their characteristic to accomplish the process judgments in the FTA approach in the present study.

Table 3. Expert weighting of group decision-making for the present study

Expert	Education	Age	Profession position	Job Tenure	Weighting score (w)
Expert 1:	Bachelor (3)	36 (2)	Process Engineer (3)	15 (3)	0.234
Expert 2:	Master (4)	38 (3)	Mechanical Engineer (3)	13 (3)	0.276
Expert 3:	Bachelor (3)	46 (2)	Electrical Engineer (3)	16 (4)	0.255
Expert 4:	Bachelor (3)	42 (2)	Safety Engineer (3)	14 (3)	0.234
Total	13	9	12	13	47/47=1

Besides, linguistic expressions were used to fulfil the experts' opinions about probability of the BEs. Moreover, the fuzzy numbers are adapted to handle such linguistic expressions. In this study, three modes of 3-scale, 5-scale, and 10-scale of fuzzy linguistic expressions were evaluated along with four types of Membership Functions (*MFs*) including: Triangular-shaped (*Trimf*), Trapezoidal-shaped (*Trapmf*), Π-shaped (*Pimf*) and Gaussian (*Gaussmf*) (Table 4, 5 and 6) (Soltanali *et al.*, 2020a; Hsu and Chen, 1992; Yazd *et al.*, 2017).

Table 4. 3-scale fuzzy with 4 membership function

Rank	Linguistic expression	MF function	Fuzzy number
		Trapmf	(0.0, 0.0, 0.02, 0.04)
1 2 2	Emgastic expression	(0.0, 0.02, 0.04)	
1, 2, 3	Low (L)	Gaussmf	(0, 0, 0.07, 0.22)
		Pimf	(0.0, 0.0, 0.22, 0.38)
		Trapmf	(0.23, 0.47, 0.53, 0.77)
4.5.6.7	M.T. AO	Trimf	(0.2, 0.5, 0.8)
4, 5, 6, /	1, 2, 3 Low (L) 4, 5, 6, 7 Medium (M)	Gaussmf	(0.10, 0.47, 0.50, 0.53)
		Pimf	(0.23, 0.47, 0.53, 0.77)
		Trapmf	(0.6, 0.8, 1.0, 1.0)
1, 2, 3		Trimf	(0.6, 0.8, 1.0)
8, 9, 10	High (H)	Gaussmf	(0.7, 0.8, 0.9, 1.0)
	Gaussmf Pimf	Pimf	(0.62, 0.78, 1.0, 1.0)

Table 5. 5-scale fuzzy with 4 membership function

Rank	Linguistic expression	MF function	Fuzzy number
		Trapmf	(0.0, 0.0, 0.1, 0.2)
1	Very low (VL)	Trapmf (0.0, 0) Trimf (0.0) Gaussmf (0.0, 0.0) Pimf (0.00, 0.0) Trapmf (0.1, 0) Trimf (0.05, Gaussmf (0.03, 0.1) Pimf (0.11, 0.1) Trapmf (0.20, Gaussmf (0.03, 0.3) Pimf (0.31, 0.3) Trimf (0.31, 0.3) Trimf (0.55, Gaussmf (0.03, 0.3) Pimf (0.6, 0) Trimf (0.55, Gaussmf (0.03, 0.4) Trimf (0.55, Gaussmf (0.03, 0.6) Trimf (0.61, 0.6) Trapmf (0.61, 0.6) Trimf (0.8, 0) Trimf (0.8, 0) Trimf (0.8, 0) Gaussmf (0.03, 0.8)	(0.0, 0.1, 0.2)
1	very low (VL)		(0.0, 0.0, 0.03, 0.11)
		Pimf	(0.00, 0.00, 0.11, 0.19)
		Trapmf	(0.1, 0.2, 0.3, 0.4)
2, 3	Low (L)	Trimf	(0.05, 0.25, 0.45)
2, 3	Low (L)	Gaussmf	(0.03, 0.19, 0.03, 0.31)
		Pimf	(0.11, 0.19, 0.31, 0.39)
		Trapmf	(0.3, 0.4, 0.6, 0.7)
4, 5, 6	Medium (M)	Trimf	(0.20, 0.50, 0.80)
4, 5, 0	Medium (M)	Trapmf (0.0 Trimf (0 Gaussmf (0.0, Pimf (0.00, Trapmf (0.1 Trimf (0.6 Gaussmf (0.03, Pimf (0.11, Trapmf (0.2 Gaussmf (0.03, Pimf (0.31, Trapmf (0.6 Trimf (0.6 Gaussmf (0.03, Pimf (0.61, Trapmf (0.8 Trimf (0.8 Trimf (0.8 Trimf (0.03, Gaussmf (0.03,	(0.03, 0.39, 0.03, 0.61)
		Pimf	(0.31, 0.39, 0.61, 0.69)
		Trapmf	(0.6, 0.7, 0.8, 0.9)
7, 8	High (H)	Trimf	(0.55, 0.75, 0.95)
7, 6	High (H)	Gaussmf	(0.03, 0.69, 0.03, 0.81)
		Pimf	(0.61, 0.69, 0.81, 0.89)
		Trapmf	(0.8, 0.9, 1.0, 1.0)
9, 10	Vary high (VII)	Trimf	(0.8, 0.9, 1.0)
9, 10	Very high (VH)	Trapmf (0.0, 0.0, 0.0, 17 mf (0.0, 0.0, 0.0) Gaussmf (0.0, 0.0, 0.0, 0.0) Pimf (0.00, 0.00, 0.0) Trapmf (0.1, 0.2, 17 mf (0.05, 0.3, 0.19, 19 mf (0.11, 0.19, 19 mf (0.20, 0.3, 0.4, 17 mf (0.20, 0.3, 0.39, 19 mf (0.31, 0.39, 19 mf (0.31, 0.39, 19 mf (0.31, 0.39, 19 mf (0.55, 0.3, 0.69, 19 mf (0.60, 0.7, 18 mf (0.55, 0.3, 0.69, 19 mf (0.61, 0.69, 18 mf (0.8, 0.9, 18 mf (0.03, 0.89, 0.69, 19 mf (0.03, 0.89, 0.69, 19 mf (0.03, 0.89, 0.89, 0.03, 0.89, 0.99, 10 mf (0.03, 0.89, 0.89, 0.90,	(0.03, 0.89, 1.00, 1.00)
		Pimf	(0.81, 0.89, 1.00, 1.00)

Table 6. 10-scale fuzzy with 4 membership function

Rank	LE	MF	Fuzzy number	Rank	LE	MF	Fuzzy number	
'	>	Trimf	(0.0, 0.1, 0.2)		٠. ر	Trimf	(0.5, 0.6, 0.7)	
	low L)	Trapmf	(0.01, 0.09, 0.11, 0.19)	6	e or nigh H)	Trapmf	(0.51, 0.59, 0.61, 0.69)	
1	Very (V)	Gaussmf	(0.03, 0.09, 0.03, 0.11)		More or less high (MH)	Gaussmf	(0.03, 0.59, 0.03, 0.61)	
	>	Pimf	(0.01, 0.09, 0.11, 0.19)			Pimf Trimf Trapmf	(0.51, 0.59, 0.61, 0.69)	
	$\overline{\mathbf{x}}$	Trimf	(0.1, 0.2, 0.3)	7		Trimf	(0.6, 0.7, 0.8)	
2	Low (I	Trapmf	(0.11, 0.19, 0.21, 0.29)		Fairly high (FH)	Trapmf	(0.61, 0.69, 0.71, 0.79)	
2		Gaussmf	(0.03, 0.19, 0.03, 0.21)		/	Faj hi (F	Gaussmf	(0.03, 0.69, 0.03, 0.71)
		Pimf	(0.11, 0.19, 0.21, 0.29)			Pimf	(0.61, 0.69, 0.71, 0.79)	
		Trimf	(0.2, 0.3, 0.4)			Trimf	(0.7, 0.8, 0.9)	
2	£ ₹ ₹	Trapmf	(0.21, 0.29, 0.31, 0.39)	8	gh 1)	Trapmf	(0.71, 0.79, 0.81, 0.89)	
3	Fairly low (FL)	Gaussmf	(0.03, 0.29, 0.03, 0.31)		High (H)	Gaussmf	(0.03, 0.79, 0.03, 0.81)	
		Pimf	(0.21, 0.29, 0.31, 0.39)			Pimf	(0.71, 0.79, 0.81, 0.89)	

	More or less low (ML)	Trimf	(0.3, 0.4, 0.5)	9		Trimf	(0.8, 0.9, 1.0)
		Trapmf	(0.31, 0.39, 0.41, 0.49)		high H)	Trapmf	(0.81, 0.89, 0.91, 0.99)
		Gaussmf	(0.03, 0.39, 0.03, 0.41)		/ery	Gaussmf	(0.03, 0.89, 0.03, 0.91)
		Pimf	(0.31, 0.39, 0.41, 0.49)			Pimf	(0.81, 0.89, 0.91, 0.99)
	_	Trimf	(0.4, 0.5, 0.6)	10	>	Trimf Trapmf	(0.9, 1.0, 1.0)
	Medium (M)	Trapmf	(0.41, 0.49, 0.51, 0.59)		nely h 1)		(0.91, 0.99, 1.00, 1.00)
5	edi M	Gaussmf	(0.03, 0.49, 0.03, 0.51)		trem high (VH)	Gaussmf	(0.03, 0.99, 1.00, 1.00)
	Σ	Pimf	(0.41, 0.49, 0.51, 0.59)		Extremon high (VH)	Pimf	(0.91, 0.99, 1.00, 1.00)

LE: Linguistic Expression, MF: Membership Function

In this section, aggregation process of expert judgments was assigned to achieve a reliable decision, because each expert might have a variety of opinions about failure probability. This process is conducted via the five following steps (Yazd *et al.*, 2017):

1. Calculating degree of similarity between opinion of every two experts S (A, B) Eq. (6):

$$S(\tilde{A}, \tilde{B}) = 1 - \frac{1}{J} \sum_{i=1}^{J} |a_i - b_i|$$
 (6)

where J is the parameters of the membership function; a_i and b_i are also the parameters of the membership function.

2. Computing the Relative Agreement (RA) degree, (AA (E_u)) of expert's opinion Eq. (7):

$$AA(E_u) = \frac{1}{J-1} \sum_{v=1, u \neq v}^{J} S(\tilde{R}_u, \tilde{R}_v)$$
(6)

3. Computing the Relative Agreement (RA (E_u)) degree, of expert's opinion Eq. (7):

$$RA(E_u) = \frac{AA(E_u)}{\sum_{u=1}^{J} AA(E_u)}$$
(8)

4. Calculating the consensus coefficient degree of expert's opinion ($CC(E_u)$) Eq. (9):

$$CC(E_u) = \beta W(E_u) + (1-\beta).RA(E_u)$$
 (9)
where, W is the weight of each expert, β is relaxation factor $(0 \le \beta \le 1)$ wherever it can be used for sensitivity analysis to determine sensible effect of expert's traits on experts' opinion.

5. Computing the final result of expert's opinions (\widetilde{R}_{AG}) Eq. (10):

$$\tilde{R}_{AG} = CC(E_1) \otimes \tilde{R}_2 \oplus CC(E_2) \otimes \tilde{R}_2 \oplus ... \oplus CC(E_m) \otimes \tilde{R}_M$$
(10)

where \oplus is a fuzzy sum operation and \otimes is a fuzzy scalar multiply operation. \widetilde{R}_{AG} is a fuzzy set in which the defuzzification method must be used to calculate a single point value called Fuzzy Possibility Score (*FPS*) which represents the possibility of the *BEs*. For this purpose,

five algorithms including centroid, bisector, smallest of maximum (som), middle of maximum (mom) and largest of maximum (lom) were applied. Finally, the FPS of all BE_s needs to be converted to their FP or $P(X_i)$ in which the values can be varied between 0 to 1. The FP, as defined by Onisawa (1998), is given by:

$$P(x) = \begin{cases} \frac{1}{10^k} & for \ FPS \neq 0 \\ 0 & for \ FPS = 0 \end{cases} \quad k = 2.301 \left(\frac{1 - FPS}{FPS}\right)^{\frac{1}{3}}$$
 (11)

A computer programming was deployed in MATLAB-vR-2020b (MathworksInc, US) to calculate the $P(X_i)$ in FFTA model.

3.2. Mapping FFTA into BN model

In order to handle the static drawback of FFTA model, a Bayesian updating mechanism was conducted. In fact, a Bayesian network (BN) is a graphical model which provides the causal relationship between causes in a system. It entails a set of random variables represented by root, intermediate and leaf nodes, bounded by oriented arcs or Directed Acyclic Graph (DAG) and accompanied by their conditional dependencies. In BN, a node from which an edge/link is directed to another node is called "parent" while the other node to which the edge is called "child". In other words, a node describes a state or condition, an arc indicates a direct influence, and Conditional Probability Tables (CPTs) implies the conditional independency relationships between parent-child nodes. The probabilities of the root events are assigned to the corresponding root nodes as prior probabilities, while for intermediate nodes as well as the leaf nodes (TEs), CPTs need to be developed (Yazdi and Soltanali, 2018). In this study, the results of FP are considered as prior probability for estimating posterior probability in BN. Given the conditional dependency of variables and the chain rule, BN represents the joint probability distribution of a set of variables $T = \{X_1, ..., X_n\}$ as follows:

$$P(T) = \prod_{i=1}^{n} (P(X_i | P_a(X_i)))$$
(12)

Where $P_a(X_i)$ is the parent set of variables, X_i . Accordingly, the probability of X_i is calculated as:

$$P(X_i) = \sum_{i} x_{i \neq i} P(T) \tag{13}$$

During BN analysis, a series of evidence (E) is examined, and the posterior or updated probability distribution of X_i can be calculated using Bayes' theorem as follows:

$$P(X_i \mid E) = \frac{P(X_i, E)}{P(E)} = \frac{P(E \mid X_i) \cdot P(X_i)}{\sum_{V} P(X_i \mid E) \cdot P(X_i)}$$
(14)

where, P(Xi|E) is the posterior probability under a given evidence E, P(Xi) is the prior probability of event Xi, P(E|Xi) is the evidence likelihood of the given event Xi, P(E) is the pre-defined posterior probability of evidence, and $\sum_{V} P(X_i | E) . P(X_i)$ is the joint probability distribution of E. The Bayesian network mapping process as well as related calculations was made in GeNIe 3.0 academic software.

3.3. Maintenance optimization model

In this subsection, the outcomes of developed FFTA-BN model specifically the probability of failures and reliability indexes were employed within maintenance optimization model. The optimal maintenance interval for cycle T (planning horizon) has been proposed by (Rezaei, 2017). It assumes that failures occur at times $k\tau$ (τ , 2τ , . . ., $k\tau$), as well as the repair is made at the end of the cycle T (for k=n, at the time $n\tau$). τ is the time between two consecutive maintenances, it means $\tau = T/n$. The objective is to find the optimal maintenance interval time to minimize the total expected cost of the system over the cycle T. Hence, the total expected cost in kth inspection for each cycle (τ) is given by:

$$E_{\tau} \left[C_{Total}^{T} \right] = \sum_{i=1}^{n} \sum_{k=1}^{T/\tau} E_{\tau} \left[C_{i}^{(k-1)\tau, k\tau} \right]$$

$$\left(\sum_{i=1}^{n} \sum_{k=1}^{T/\tau} \left(\tau_{i}^{I} W^{I} + \tau_{i}^{I} P\right) + \sum_{i=1}^{n} \sum_{k=1}^{T/\tau} \left(\operatorname{Re}_{i} + \tau_{i}^{R} W^{R} + \tau_{i}^{R} P\right) (1 - R(k\tau)) + \sum_{i=1}^{n} \sum_{k=1}^{T/\tau} \left(\tau_{i}^{PF} P + L\right) (1 - R(k\tau))\right)$$
(15)

$$\forall \tau = T, T / 2, T / 3, ..., T / T$$

where, $E_{\tau}[C_{Total}^T]$ is total expected cost, W is inspection/preventive cost, Re is repair/perfect replacement cost, P is production loss cost and L is downtime cost. In accordance with the work of Rezaei (2017), the optimal maintenance interval can be estimated as follows:

$$\eta C = \frac{\sum_{i=1}^{n} \sum_{k=1}^{T/\tau} E_{\tau} \left[C_{i}^{(k-1)\tau, k\tau} \right]}{k \int_{0}^{\tau} R(k\tau) dt}$$

$$(16)$$

where, ηC (k τ) is the optimal maintenance interval at $k\tau$ (τ , 2 τ ,..., k τ), and $R(k\tau)$ is the computed reliability based on proposed FTTA-BN model.

4. Results and discussion

4.1. The empirical case study

In order to implement the proposed FTTA-BN model-based maintenance optimization, a semiautomatic filling equipment as the most critical and complex system within an automotive production line was considered. The reliability and safety guarantee of such system from operational and non-operational aspects are important. In fact, the low reliability of system results in an increase in equipment breakdowns as well as assembly line showdowns. Besides, because of the importance of safety guarantee for operators and complexity issues, an effective scheduled-maintenance plan could be useful to prevent the unexpected failures. The system is in charge of filling, levelling and leakage tests in paths and pipes. Fig. 2 (a,b) shows the main blocks and a general illustration of system under filling operations. It consists of seven critical blocks such as initialization and ready blocks, pressure, vacuum and filling blocks, and lubrication and process end blocks which are shown in Fig. 2 (a). The main feature of these blocks is their series configuration with three sub-categories, therefore, any failure of a component in each block leads to system downtime. As seen in Fig. 2 (a), in the first sub-category, from the initialization block, if the filling system tank is under pressure, the process will equalize/release this pressure. Subsequently, the system is ready to perform filling process (Ready block). In the second sub-category, there are two pumps (including vacuum and filling pumps) as well as a Pressure Control Set (PCS) to measure pressure/vacuum level. The pressure block is used to inject air into the system and, to examine the pressure to ensure that the filling system is free of any leakage. Then, the vacuum block performs the evacuation of system and looks for any vacuum leaks for a proper vacuum level. After setting the vacuum and pressure, the filling block is used to perform the fillings with different fluid liquids and to control the level of fluids. Finally, in the third sub-category, in order to ongoing operation of the rotary equipment especially pumps, the oil is needed for lubrication during the filling process provided through a lubrication tank (Lubrication block) and eventually, in the process end block, the operator can unclamp and remove the filling head from the vehicle.

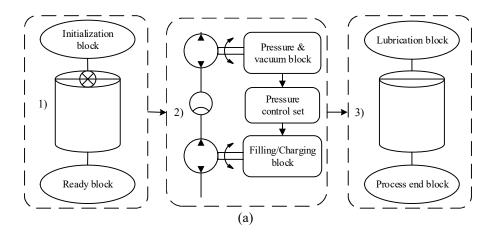






Fig. 2. A fluid filling process in the automotive industry a) block diagram b) operational view

4.2. The FFTA-BN model results

Fig. 3 represents a FTA structure for the failures in a fluid filling system as TE. The operational units of system include the hydraulic-pneumatic circuit, the electronic circuit, and the filling headset. The filling pump is used for fluid injection, the pressure set controls the required pressure, and the pipes and fittings are designed to transfer air and various fluids. The Electronic circuit includes a Programmable Logic Controller (PLC) unit which comprises several sensors, such as the Anti-lock Braking System (ABS) and the starters. The filling headset is mounted on the vehicles. The critical components of this set include mini-valves, pipes, couplings, and seals. The pumps, especially the vacuum pump, operate more often and they are active in all of filling process. Therefore, they are subjected to a higher occurrence of failures. The major failure modes for pumps are filtering failure, corrosive bearing, and seals failures. The main failure modes for filling headset are couplings, mini-valves, and seals. The failure modes for electronic circuit are sensors, ABS, and starter.

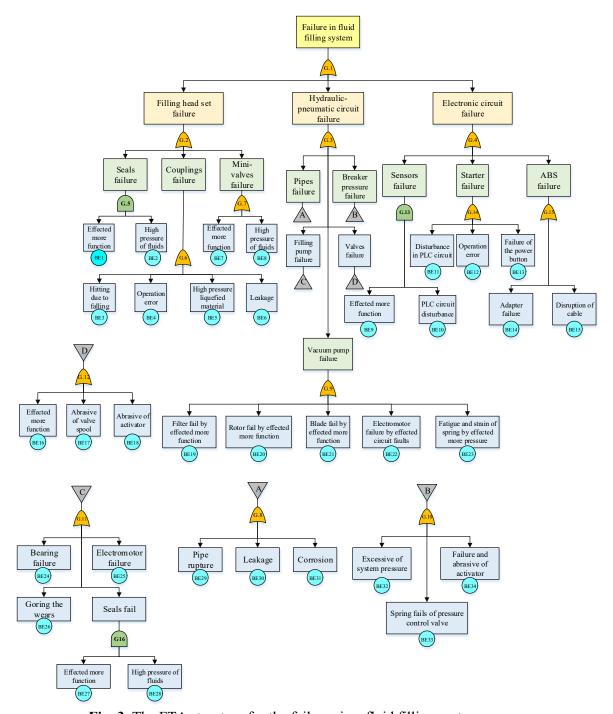


Fig. 3. The FTA structure for the failures in a fluid filling system

Table 7 illustrates 33 BEs for fluid filling system which are linked directly and/or indirectly to the specified TE. In order to calculate the FP of BEs, the questionnaire-based method was employed involving a group of experts and their opinion to express the lowest to highest value

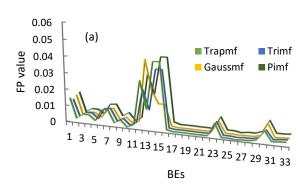
of FP from the range number of 1 to 10 for each BE. The experts' characteristics and their weighting results were provided in Table 3 to complete the process judgment in FTA approach.

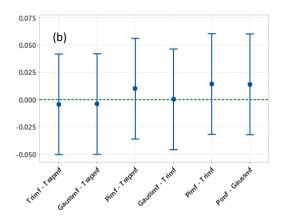
Table 7. The details of BEs under experts' judgments

Unit	Component	BE tag	BEs description	Expert 1	Expert 2	Expert 3	Expert 4
	O-rings &	BE.1	Effected more function	9	5	5	8
Filling headset failure	Seal's failure	BE.2	High pressure of fluids	4	5	5	3
ıt fa		BE.3	Hitting due to falling	5	6	5	7
adse	Coupling's	BE.4	Operation error	5	6	7	5
he	failure	BE.5	High pressure liquefied material	6	5	3	4
lling		BE.6	Leakage	6	7	8	5
Εï	Mini-valve's	BE.7	Effected more function	7	8	5	6
	failure	BE.8	High pressure of fluids	7	5	3	5
ە	Sensor's	BE.9	Effected more function	3	5	5	8
ailur	failure	BE.10	PLC circuit disturbance	3	4	3	2
nit f	G	BE.11	Disturbance in PLC circuit	3	5	5	5
ircı	Stater's failure	BE.12	Operation error	5	9	9	8
ic c	ranure	BE.13	Failure of the power button	3	9	9	8
fron	ABS's	BE.14	Adapter failure	8	9	8	9
Electronic circuit failure	failure	BE.15	Disruption of cable	8	9	8	8
	Valve's failure	BE.16	Effected more function	7	3	3	8
		BE.17	Abrasive of valve spool	3	3	5	5
		BE.18	Abrasive of activator	4	5	3	2
	Vacuum pump's failure	BE.19	Filters fail by effected more function	3	5	3	5
		BE.20	Rotors fail by effected more function	4	3	4	2
failure		BE.21	Blades fail by effected more function	3	3	7	5
Hydraulic-pneumatic circuit failure		BE.22	Electromotor failure by effected circuit faults	2	3	5	5
natic c		BE.23	Fatigue and strain of spring by effected more pressure	5	5	5	8
nen		BE.24	Bearing failure	4	3	2	5
c-p1	Filling	BE.25	Electromotor failure	6	3	3	5
auli	pump's	BE.26	Goring the wears	5	3	3	2
ydra	failure	BE.27	Effected more function	4	3	2	5
Н		BE.28	High pressure of fluids	4	3	2	6
	D	BE.29	Pipe rupture	7	3	9	3
	Pipe's	BE.30	Leakage	3	9	5	8
	failure	BE.31	Corrosion	3	3	7	8
	Pressure	BE.32	Excessive of system pressure	5	2	7	5
	control's failure	BE.33	Spring fails of pressure control valve	3	5	7	5

The fuzzy linguistic expressions considering various fuzzy scales and diverse Membership Functions (MFs) and defuzzification algorithms were used to fulfil the experts' judgments to

be able to predict the FP of BEs related to fluid filling system. Fig. 4 (a) to Fig. 4 (e) displays the impact of four MFs subjected to three modes of 3-scale, 5-scale, and 10-scale of fuzzy numbers for predicting the FP of BEs, respectively. As seen, Fig. 4 (a and b) reflects the effect of four MFs in 3-scale of fuzzy numbers and their statistics test results. The average values of FP under Trimf, Trapmf, Pimf and Gaussmf of MFs in 3-scale of fuzzy numbers were obtained as 0.006, 0.006, 0.005 and 0.007, respectively. Based on the mean comparison test (Tukey's test), there is no significant difference between MFs in 3-scale of fuzzy numbers for estimating FP, statistically (P value >0.05). In other words, if an interval does contain zero, the corresponding means are not significantly different. Fig. 4 (c and d) shows the effect of four MFs in 5-scale of fuzzy numbers and their statistics test results for estimating the FP. The average values of FP under Trimf, Trapmf, Pimf and Gaussmf MFs in 5-scale of fuzzy numbers were acquired as 0.008, 0.008, 0.005 and 0.007, respectively. As observed, based on Tukey's test, there is no significant difference between MFs in 5-scale of fuzzy numbers for estimating the FP, statistically (Pvalue>0.05). These results are also same for MFs in 10-scale of fuzzy which their outcomes are shown in Fig. 4 (e and f). Therefore, it can be concluded that the impact of four MFs subjected to three modes of 3-scale, 5-scale, and 10-scale of fuzzy numbers was not significant statistically for predicting the FP of BEs.





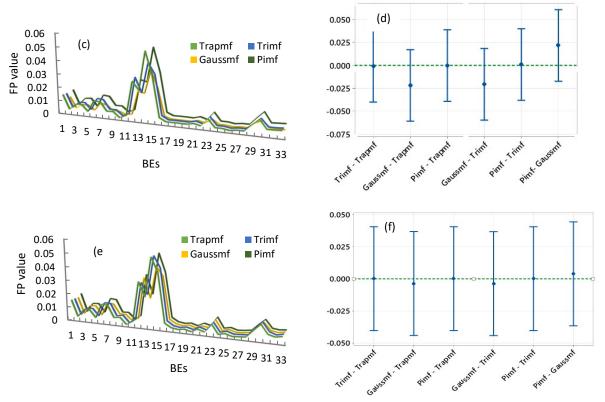


Fig. 4. The results of FP for BEs considering the effects of membership functions.

Fig. 5 (a and b) shows the effects of various scales of fuzzy numbers and their statistics test results for estimating FP of BEs. The average values of FP under 3, 5 and 10-scale of fuzzy numbers were gained as 0.006, 0.007 and 0.009, respectively. As seen, based on Tukey's test, there is no significant difference between 3, 5 and 10-scale of fuzzy numbers for predicting FP, statistically (Pvalue>0.05). In other words, if an interval does contain zero, the corresponding means are not significantly different.

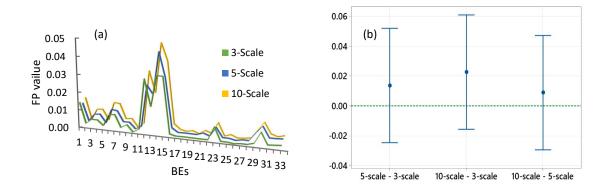


Fig. 5. The results of FP for BEs considering the effects of various scales of fuzzy numbers.

Additionally, the various defuzzification algorithms were compared to determine the FP of BEs which their results are given in Fig. 6 (a, b). The average values of FP under centroid, bisector, mom, lom and som defuzzification algorithms were obtained as 0.008, 0.009, 0.010, 0.008 and 0.102, respectively. The comparison mean test shows that there is no significant difference between defuzzification algorithms for predicting FP, statistically (P value > 0.05). Since in FFTA model, the effect of various attributes such as scales variation and, assorted membership and defuzzification functions was not statistically significant, the average values can be considered to estimate the FP of BEs in the fluid filling system.

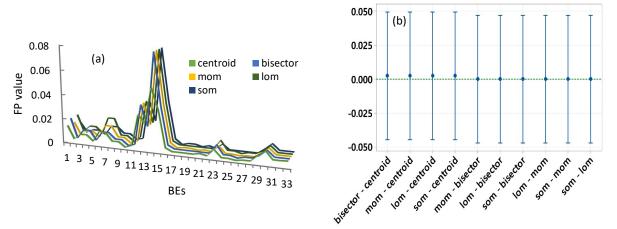


Fig. 6. The results of FP for BEs considering the effects of defuzzification algorithms.

Moreover, due to the static structure assumption of FFTA model throughout estimating FP of BEs, the Bayesian mechanism was employed to consider all possible dynamic interactions between components. The FFTA model is mapped into BN structure shown in Fig. 7. In this BN, G.1 is a leaf node that corresponds to the TE of the FTA model and G.2 to G.16 are the intermediate nodes associated with IEs of the FTA model in which the conditional probability values of each node are occupied based on the type of logic gates (state=0 means faulty, state=1 means healthy) using GeNIe 3.0 software (Fig. 8).

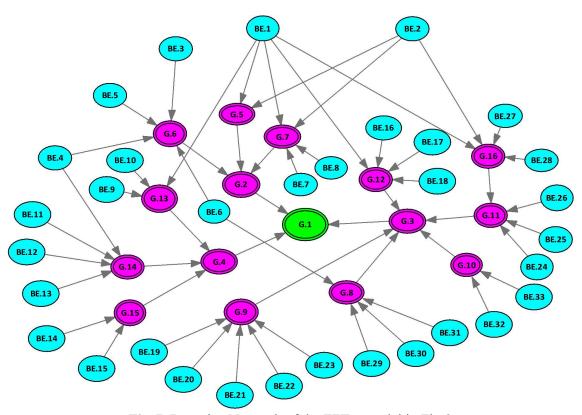


Fig. 7. Bayesian Network of the FFTA model in Fig.3

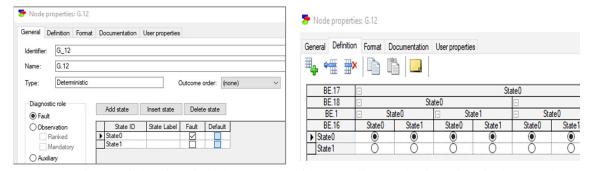


Fig. 8. The conditional probability process of intermediate nodes based on logic gates in GeNIe 3.0 software.

The average values of FP derived from the FFTA method were used as prior probability values of the root nodes in Bayesian mechanism to predict the posterior FP considering all possible dynamic interactions between BEs. Meanwhile, Fig. 9 shows the comparison results of FP based on FFTA and BN models for three sub-units of fluid filling system such as hydraulic-pneumatic circuit, the electronic circuit, and the filling headset along their critical components. As seen, since the BN method approaches the dynamic relationship between events, the FP values are

higher in most cases with that of the results of FFTA model. According to the BN analysis, the FP of the leaf node (G.1) or failure of whole filling system was estimated as 0.206 in which the system reliability (exp(-FP)) was around 0.813. Meanwhile, the FPs of the intermediate nodes including three subsystems such as filling headset (G.2), hydraulic-pneumatic circuit (G.3) and the electronic circuit (G.4) were obtained as 0.057, 0.065 and 0.129, respectively, in which the reliability (exp (-FP)) was around 0.945, 0.936 and 0.879, respectively. Among other subintermediate nodes, ABS's failure (G.15), starter's failure (G.14), mini-valve's failure (G.7), pipes' failure (G.8) and Coupling's failure (G.8) have allocated the highest FP values with 0.075, 0.058, 0.030, 0.029 and 0.027, respectively. Additionally, the FP of system components such as adapter's failure (BE.14) with 0.042 FP and disruption of cable (BE.15) with 0.034 related to ABS unit, operation error (BE.12) with 0.030 FP and failure of the power button (BE.13) with 0.019 FP related to stater's failure as well as affected by more function fault (BE.1) with 0.014 FP related to O-ring and seal's failure had the highest rank at root nodes level in BN model. As a consequence, it is also worth to perform the convenient maintenance and inspection programs to prevent such failures/faults with the highest FP in fluid filling systems in automotive production lines.

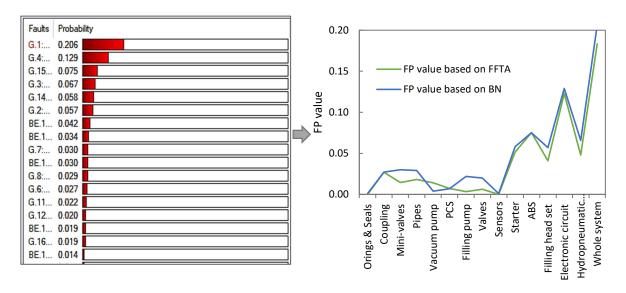


Fig. 9. The comparison results of FP throughout mapping FFTA to BN model

4.3. Maintenance optimization results

A scheduled-maintenance model is proposed subjecting to total expected cost (e.g., repair cost, inspection/preventive cost, and downtime cost) as well as the computed FP or reliability derived from above BN model for a finite period (5000 hours of operation). As shown in Fig.10 (a) for whole fulling filling system, the optimal maintenance intervals considering the repair, inspection, downtime, and total expected costs are estimated as 18th, 4th, 10th and, 7th, with 1967\$, 469\$, 176\$, and 3286\$ during plan horizon (T=5000 hours), respectively. Moreover, Fig. 10(b) displays the optimal maintenance intervals for each component of fluid filling system based on total expected cost, the optimal number of intervals for the mini-valves, PCS, valves, sensors, O-rings & seals, starter, coupling and vacuum pump, were obtained as 10th, 5th, 4th, 5th, 3rd, 6th, and 11th with 475 \$, 34 \$, 21\$, 75\$, 58\$, 471\$ and 1630 \$, during plan horizon (T=5000) hours), respectively. The majority of failures affecting on vacuum pump are related to fatigue and strain of spring, as well as filter's failure due to more usage. Corrosion of O-ring and seals due to the chemical impact of fluids results in leakage in couplings and mini-valves within filling headset. The mentioned maintenance activities/intervals would help the engineers to detect and prevent the unexpected failures to achieve the higher safety and availability of complex fluid filling system in automotive production line.

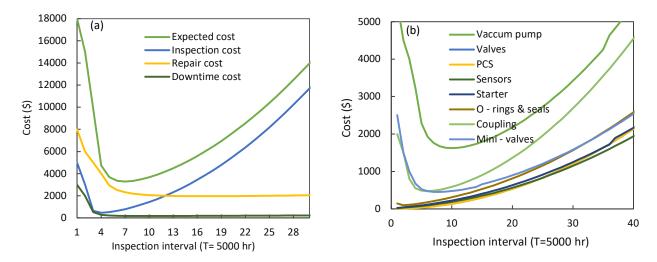


Fig.10. The optimal maintenance intervals for a) whole system and b) critical components

5. Conclusion

This study aimed to propose a knowledge-based framework for optimization of maintenance intervals within manufacturing systems. Knowledge-based approaches are recognized as quite useful alternative with that of data driven-based methods for evaluating risk and reliability, fault detection, and maintenance decision making face the imprecise and insufficient data related to equipment failures, environmental factors, and human activities. We developed a FTA approach to find an optimized scheduled-based maintenance with subjective information derived by domain experts. Since the classical-FTA still suffers from the epistemic uncertainty and static structure limitations, the fuzzy set theory and Bayesian mechanism was conducted to dominate such deals by statistical analyzing the effective attributes such as experts' trait impacts, scales variation and, assorted membership and defuzzification functions. The results revealed that in the fuzzy model, the changes in decision attributes were not statistically significant on FP estimation, while in the Bayesian model considering conditional rules to reflect the interaction between events that had more impact on the FP values. Ultimately, the result of integrated FTTA-BN model was employed in optimization model to find optimal maintenance intervals associated with estimated FP values and total expected cost. To demonstrate the feasibility of the proposed framework, it was implemented in a complex fluid filling system in an automotive production line. As a consequence, the proposed framework could help engineers to make better decisions on how to improve the availability and safety of complex equipment within the automotive manufacturing systems.

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Conflict of interest

The authors have declared no conflicts of interest for this article.

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