Determination of the Earthquake Epicenter from line-of-sight displacement images obtained by Sentinel-1A/B radar data using the GMTSAR software package

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Abstract. This article described the technology of determining earthquake epicenter with radar remote sensing on the example of Sentinel-1A/B. To determine the epicenter of the earthquake, the Earth's crust displacements were analyzed using radar remote sensing data obtained for the ascending and descending flight orbits. Coordinates of Earthquake epicenters were found according to line-of-sight displacement images via its maximum value. Displacement of the Earth's crust was obtained by processing in the GMTSAR package in the VirtualBox virtual machine of the Linux Ubuntu 16.04 operation system. Two earthquakes that occurred in 2020 were studied to determine the accuracy of finding epicenters using the ascending and descending orbits Sentinel-1A/B. These earthquakes occurred in Western Xizang, China, and Doganyol, Turkey. The maximum deviation from the officially registered epicenter coordinates was 15.38 km for Doganyol and 3.2 km for the Western Xizang earthquake. The negative displacement was 90 mm for Doganyol and 50 mm for Western Xizang.

Keywords: displacement, radar image processing, phase difference, interferometry, earthquake epicenter.

Introduction

Based on the difference in phase images obtained from remote sensing radar data, it is possible to detect an earthquake's epicenter visually. The results of radar image processing show that the location of the epicenter is visible in the form of repeated bar spectra in the color palette of the phase image [1, 2]. The pattern that has a rainbow pattern characteristic of an earthquake is concentrated in the epicenter zone in the form of concentric phase transitions, in the center of which the earthquake center can be assumed, and it is proportional to the magnitude of the earthquake. Sentinel-1A/B radar remote sensing satellites launched in 2014 can be used to determine these earthquake epicenters [3, 4]. The main feature of these radar remote sensing data; first, they can be used to detect an earthquake's epicenter with greater coverage of the territory than others, and second, they are free for end-users. Monitoring of a single territory can be repeated every 12 days with the same view or angle geometry. The epicenter of an earthquake is easier to detect than the phenomena caused by landslides and subsidence of the earth's surface [5-7]. The received radar images can be processed by a special software, such as ROI_PAC, GMTSAR, GAMMA, ENVI Sarscape, ESA SNAP [8-11]. Some commercial software is licensed, has for more than \$10,000, and may not be available to the end-user. In contrast, the GMTSAR package, a set of additional GMT scripts developed by David Sandwell and Xiaohua Xu of the University of California, San Diego, can also be successfully used to determine the epicenter of an earthquake. In the future, we will use it to determine the location of the earthquake epicenter and show an algorithm for processing remote sensing radar data.

Study area and data

Two earthquakes are being investigated. The first of them occurred in Turkey near Doganyol on January 24, 2020. The second was in China, western Xizang, in the same year on July 22. They were with magnitudes M6. 7 and 6.3. Sentinel-1 radar remote sensing data before and after the earthquake and DEM-file were used to create the phase difference of VV polarization channel (see Figure 3). Sentinel-1A/B radar remote sensing satellites operate at a wavelength of approximately 5.6 cm. Sentinel-1A and Sentinel-1B radar remote sensing data were used with ascending and descending orbits for two earthquakes (see Table 1). All this data was downloaded from the Copernicus Open Access Hub (https://scihub.copernicus.eu/). Data were obtained for the territory of Turkey and Western Xizang, as shown in Figure 1,2.

Table 1. Satellite data

F	1 able 1. Sateline data						
№	Study area	Date	Orbits				
1	China, Western	18.07.2020		S1A_IW_SLC1SDV_20200718T121528_20200718T121555_033			
			Ascending	Satellite data \$1A_IW_SLC1SDV_20200718T121528_20200718T121555_033 509_03E207_57A0 \$1A_IW_SLC1SDV_20200730T121529_20200730T121556_033 684_03E765_141D \$1A_IW_SLC1SDV_20200714T000951_20200714T001018_033 443_03E012_72CA \$1A_IW_SLC1SDV_20200726T000952_20200726T001019_033 618_03E572_17E0 \$1A_IW_SLC1SDV_20200115T152550_20200115T152618_030 813_0388EA_9B20 \$1A_IW_SLC1SDV_20200127T152550_20200127T152618_030 988_038F14_4686 \$1A_IW_SLC1SDV_20200116T032559_20200116T032627_030 820_038928_F5DC \$1A_IW_SLC1SDV_20200128T032559_20200128T032627_030 995_038F51_7D4F			
2		30.07.2020	Ascending	S1A_IW_SLC1SDV_20200730T121529_20200730T121556_033			
				684_03E765_141D			
3		14.07.2020		S1A_IW_SLC1SDV_20200714T000951_20200714T001018_033			
	Xizang		Descending	443_03E012_72CA			
4		29.07.2020	Descending	S1A_IW_SLC1SDV_20200726T000952_20200726T001019_033			
		28.07.2020		618_03E572_17E0			
5		15.01.2020		S1A_IW_SLC1SDV_20200115T152550_20200115T152618_030			
			A 1"	813_0388EA_9B20			
6		27.01.2020	Ascending	S1A_IW_SLC1SDV_20200127T152550_20200127T152618_030			
				988_038F14_4686			
7		16.01.2020		S1A_IW_SLC1SDV_20200116T032559_20200116T032627_0			
			D 1'	820_038928_F5DC			
8		28.02.2020	Descending	S1A_IW_SLC1SDV_20200128T032559_20200128T032627_030			
	Turkey,			995_038F51_7D4F			
9	Doganyol	21.01.2020		S1B_IW_SLC_1SDV_20200121T152522_20200121T152549_019			
			A 1"	917_025AC5_405C			
10		02.02.2020	Ascending	S1B_IW_SLC1SDV_20200202T152522_20200202T152549_020			
				092_02606E_C4DB			
11		22.01.2020		S1B IW SLC 1SDV 20200122T032514 20200122T032541 019			
			D 1'	924_025B00_46C6			
12		03.02.2020	Descending	S1B IW SLC 1SDV 20200203T032513 20200203T032540 020			
				099 0260A8 412D			

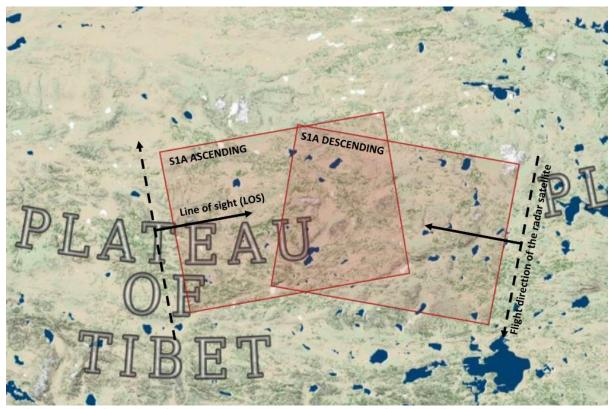


Figure 1. The footprint of selected Sentinel-1A master scenes for ascending and descending orbits.

Western Xizang, China

Accurate data about the orbital coordinates of the satellite's flight and digital elevation model (DEM) is necessary to work with Sentinel-1A/B data in the GMTSAR package. Updated orbit-file data is available in 20 days for Sentinel-1A/B satellite data via the website https://qc.sentinel1.eo.esa.int/aux_poeorb/ (see Table 2). Digital elevation model DEM-file can be obtained via the website https://topex.ucsd.edu/gmtsar/demgen/ for the GMTSAR package.

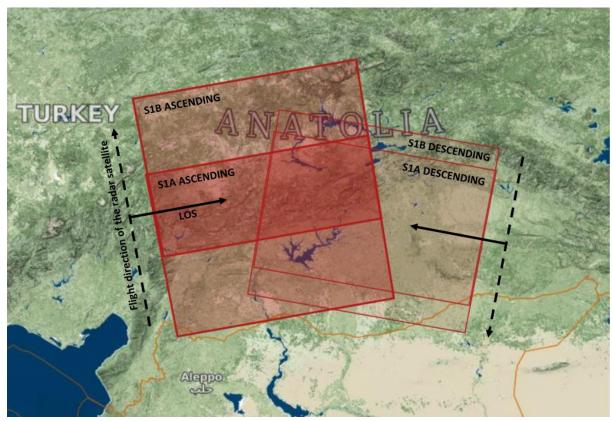


Figure 2. The footprint of selected Sentinel-1A/B master scenes for ascending and descending orbits.

Doganyol, Turkey

Таблица 2. Satellite data and related orbital files for Sentinel-1A/B.

	Taomique 2. Saleme data and related orbital mes for Sentiner-177B.					
$N_{\underline{0}}$	Satellite data	Precise Orbit Ephemerides				
1	S1A_IW_SLC1SDV_20200718T121528_20200718T12	S1A_OPER_AUX_POEORB_OPOD_20200807T12080				
	1555_033509_03E207_57A0	0_V20200717T225942_20200719T005942				
2	S1A_IW_SLC1SDV_20200730T121529_20200730T12	S1A_OPER_AUX_POEORB_OPOD_20200819T12120				
	1556_033684_03E765_141D	2_V20200729T225942_20200731T005942				
3	S1A_IW_SLC1SDV_20200714T000951_20200714T00	S1A_OPER_AUX_POEORB_OPOD_20200803T12080				
	1018_033443_03E012_72CA	0_V20200713T225942_20200715T005942				
4	S1A_IW_SLC1SDV_20200726T000952_20200726T00	S1A_OPER_AUX_POEORB_OPOD_20200815T12074				
	1019_033618_03E572_17E0	5_V20200725T225942_20200727T005942				
5	S1A_IW_SLC1SDV_20200115T152550_20200115T15	S1A_OPER_AUX_POEORB_OPOD_20200204T12070				
	2618_030813_0388EA_9B20	0_V20200114T225942_20200116T005942				
6	S1A_IW_SLC1SDV_20200127T152550_20200127T15	S1A_OPER_AUX_POEORB_OPOD_20200216T12073				
	2618_030988_038F14_4686	2_V20200126T225942_20200128T005942				
7	S1A_IW_SLC1SDV_20200116T032559_20200116T03	S1A_OPER_AUX_POEORB_OPOD_20200205T12070				
	2627_030820_038928_F5DC	7_V20200115T225942_20200117T005942				
8	S1A_IW_SLC1SDV_20200128T032559_20200128T03	S1A_OPER_AUX_POEORB_OPOD_20200217T12095				
	2627_030995_038F51_7D4F	7_V20200127T225942_20200129T005942				
9	S1B_IW_SLC1SDV_20200121T152522_20200121T152	S1B_OPER_AUX_POEORB_OPOD_20200210T11055				
	549_019917_025AC5_405C	2_V20200120T225942_20200122T005942				
10	S1B_IW_SLC1SDV_20200202T152522_20200202T152	S1B_OPER_AUX_POEORB_OPOD_20200222T11083				
	549_020092_02606E_C4DB	1_V20200201T225942_20200203T005942				
11	S1B_IW_SLC1SDV_20200122T032514_20200122T032	S1B_OPER_AUX_POEORB_OPOD_20200211T11053				
	541_019924_025B00_46C6	2_V20200121T225942_20200123T005942				
12	S1B_IW_SLC1SDV_20200203T032513_20200203T032	S1B_OPER_AUX_POEORB_OPOD_20200223T11085				
	540_020099_0260A8_412D	4_V20200202T225942_20200204T005942				

Six interferometric pairs of Sentinel-1 data were obtained using the GMTSAR package:

- 1) The first pair for dates: July 18 and July 30, 2020.
- 2) The second pair for dates: July 14 and July 26, 2020.
- 3) The third pair for dates: January 15 and January 27, 2020.
- 4) The fourth pair for dates: January 16 and January 28, 2020.
- 5) The fifth pair for dates: January 21 and February 2, 2020.
- 6) The sixth pair for dates: January 22 and February 3, 2020.

Radar image processing

Radar images are processed using the GMTSAR package. Radar image processing involves the sequential execution of scripts in Fortran and C, one of the most important is the procedure of joint registration of each sub-swath IW1, IW2, IW3 and the formation of an interferogram from Sentinel-1 data [13]. The output products of interferogram formation are the phase difference (see Figure 3). The phase difference is calculated as follows for each pixel for a pair of jointly co-registered radar images:

$$\Delta \varphi = \arctan\left(\frac{b_1}{a_1}\right) - \arctan\left(\frac{b_2}{a_2}\right) = \varphi_1 - \varphi_2$$

where a_1 , a_2 — the real part of a complex number from a pair of radar images, and b_1 , b_2 — the imaginary part of the complex number of each pixel of these radar images [14].

The phase difference is the sum of several components associated with the displacement $\Delta \varphi_{defo}$, related by topographic phase $\Delta \varphi_{topo}$, by atmospheric phase delay $\Delta \varphi_{atmo}$ and noise effect $\Delta \varphi_{noise}$ [15]:

$$\Delta \varphi = \Delta \varphi_{defo} + \Delta \varphi_{topo} + \Delta \varphi_{atmo} + \Delta \varphi_{noise}$$

An earthquake causes a displacement of the earth's surface, where the phase associated with the displacement is significantly larger than the phase associated with the atmosphere and noise $\Delta \varphi_{defo} \gg \Delta \varphi_{atmo} + \Delta \varphi_{noise}$. Knowing this, we can conclude that sum of atmospheric and noise phase effects is negligible compared to what is caused by displacement from an earthquake. Therefore, the phase associated with the offset is calculated as subtracting the topographic phase from the phase difference:

$$\Delta \varphi_{defo} = \Delta \varphi - \Delta \varphi_{topo}$$

Subtraction of the topographic phase is used to calculate the phase associated with displacement in radar image processing. The topographic phase depends on the spatial baseline B_{\perp} [16] (See Figure 4). The topographic phase is calculated as follows:

$$\Delta \varphi_{topo} = \frac{4\pi}{\lambda} \cdot \frac{B_{\perp}}{R \sin(\theta)} h$$

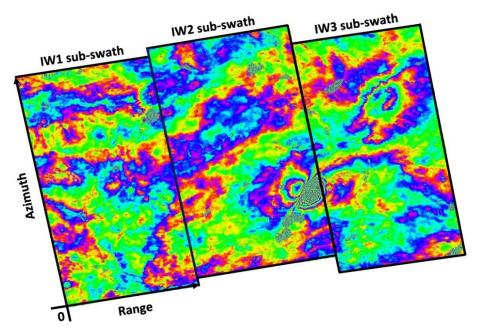


Figure 3. Geocoded image of the phase difference with the subtraction of the topographic component obtained from Sentinel-1A data with an ascending orbit for the Xinjiang earthquake for July 18 and July 30, 2020

The procedure for subtracting the topographic phase is performed using a digital elevation model (DEM) and phase difference image. The DEM image contains the height value h. The DEM image is used to calculate the topographic phase component $\Delta \varphi_{topo}$ [17-19].

The phase associated with displacement can be distorted by noise. Noise can occur due to temporal decorrelation, geometric decorrelation, volume scattering, and processing error. The Goldstein filter is used to eliminate or partially reduce the influence of the phase noise effect [20-24].

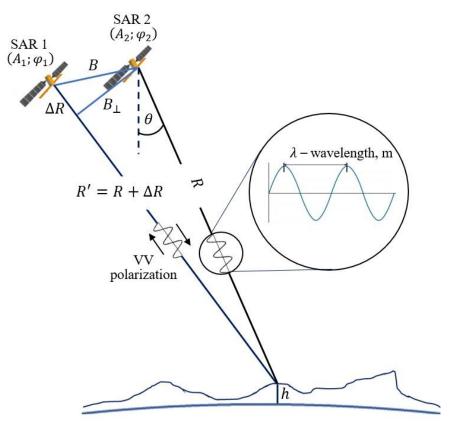


Figure 4. Application of Sentinel-1A/B remote sensing radar satellites for obtaining phase difference images from pre-earthquake (SAR 1) and post-earthquake (SAR 2)

To generate an interferogram in the GTMSAR package, we need to run the script "p2p_S1_TOPS_Frame.csh", the command line looks like this for the first pair of the VV polarization interferogram for July 18 and July 30, 2020.

```
p2p_S1_TOPS_Frame.csh
S1A_IW_SLC__1SDV_20200718T121528_20200718T121555_033509_03E207_57A0.SAFE
S1A_OPER_AUX_POEORB_OPOD_20200807T120800_V20200717T225942_20200719T005942.EOF
S1A_IW_SLC__1SDV_20200730T121529_20200730T121556_033684_03E765_141D.SAFE
S1A_OPER_AUX_POEORB_OPOD_20200819T121202_V20200729T225942_20200731T005942.EOF
config.sla.txt vv 0
```

Before running the script, two folders called "raw" and "topo" should be prepared. The raw folder must contain Sentinel-1 satellite data in the directory with the name*. SAFE at the end. The topo folder must contain a DEM file generated from https://topex.ucsd.edu/gmtsar/demgen/.

The execution time of the "p2p_s1_tops_frame.csh" script depends on the computer's performance and takes the longest time, unlike other scripts. In general, the duration is 2 hours in VirtualBox Ubuntu 16.04 on an Intel® CoreTM i7 - 8565U 1.8 GHz processor with RAM 8 GB.

As a result of executing the script "p2p_s1_tops_frame. csh", three folders F1, F2, and F3, are created for each sub-swath IW1, IW2, and IW3. There are corresponding interferograms in those directories. In addition to these directories, the "merge" directory is formed, where the result of gluing interferograms of all sub-swaths are located (See Figure 3).

The epicenter of an earthquake exists in one of the sub-bands, and it is further processed to calculate the absolute unwrapped phase. The location of the earthquake epicenter is visible in the filtered phase difference images associated with the displacement, as a rainbow pattern periodically repeated in the color palette, their concentration consists of a large number of phase transitions from $-\pi$ to $+\pi$ (See Figure 5).

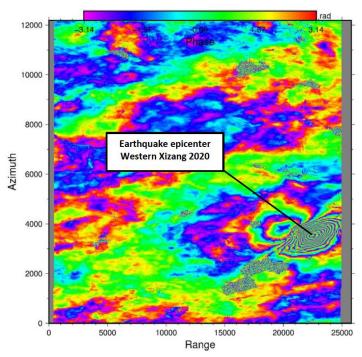


Figure 5. Filtered phase difference image of the IW2 sub-swath Sentinel-1A with an ascending orbit for the Xizang earthquake on July 18 and 30, 2020

Using the script "snaphu. csh.12" in the GMTSAR package, the phase difference image is converted to an absolute unwrapped phase, the program code is developed by Chen and Zebker [25-27]. This script is written in C and must be executed separately.

snaphu.csh .12

The absolute unwrapped phase difference image has a negative part - 8 and a positive part up to 12 radians in Figure 6. The script ".12" value means that the part of the image that has coherence less than 0.12 will be masked and will not be subjected to absolute phase calculation.

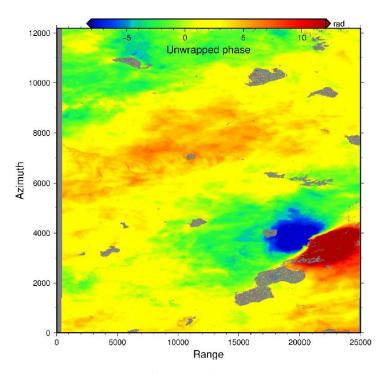


Figure 6. The absolute unwrapped phase difference of IW2 sub-swath Sentinel-1A with an ascending orbit for the Xizang earthquake on July 18 and July 30, 2020

The following script is "geocode. csh.12" calculates the line-of-sight displacement image (See Figure 7) and georeferences all data from radar coordinates (range, azimuth) to latitude and longitude geographic coordinates, along with kml-files for Google Earth.

geocode.csh .12

The line-of-sight displacement d_{los} radar is the difference between the distances before and after an earthquake, the shortest way a radio wave propagates from the antenna to the earth's surface and back. Displacement on line-of-sight may differ depending on ascending (asc) and descending (desc) orbits of Sentinel-1A/B satellite d_{los}^{asc} , d_{los}^{desc} . These displacements at each point of the earth's surface depend on the radio waves' angle of incidence for the ascending and descending orbits θ_{asc} , θ_{desc} , respectively. The essence of line-of-sight displacement caused by the Earth's crust movement is illustrated in Figure 8 when deforming up.

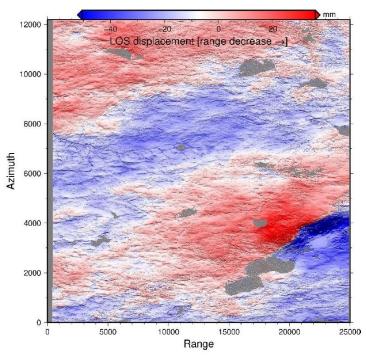


Figure 7. The line-of-sight displacement image of IW2 sub-swath Sentinel-1A with an ascending orbit for the Xizang earthquake on July 18 and July 30, 2020

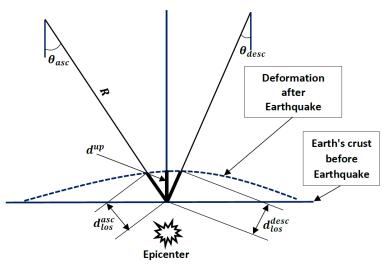


Figure 8. An image illustrating the line-of-sight displacement caused by the Earth's crust movement after an earthquake when deformed to the top

Thus, the radar image processing algorithm consists of the following operations shown in the block diagram in Figure 9.

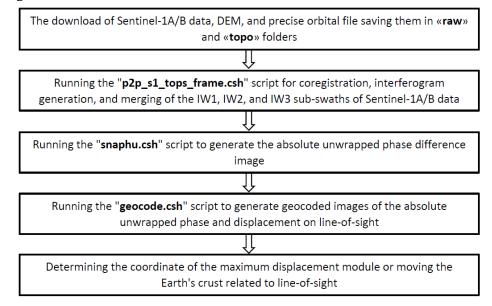


Figure 9. Radar image processing algorithm for determining the Earthquake's Epicenter coordinates based on maximum line-of-sight displacement using Sentinel-1A/B satellite data

Results

To determine the earthquake's epicenter, various line-of-sight images of both the ascending and descending orbits of Sentinel-1A/B were obtained. The maximum displacement modulus determined the coordinates of the epicenters. The displacement values have both positive and negative values. To determine the maximum displacement modulus, select the negative part when deformed to the up and positive when deformed to the bottom. The results of determining the epicenter coordinate through the maximum line-of-sight displacement module for the Western Xinjiang and Doganyol earthquakes using Sentinel-1A from the ascending orbit are presented in Figures 10-11.

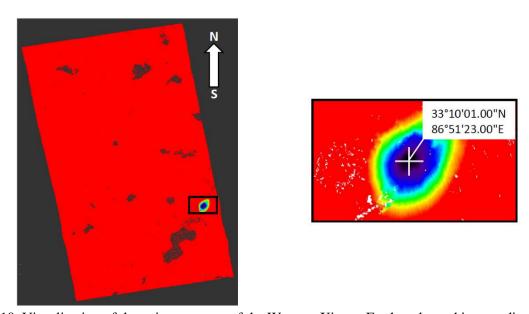
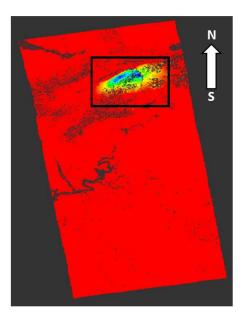


Figure 10. Visualization of the epicenter zone of the Western Xizang Earthquake and its coordinates: Left side – geocoded line-of-sight displacement image of the IW2 Sentinel - 1A sub-swath with an ascending orbit, black contour frame – the place of existence of the maximum displacement; Right side – zoomed image of the earthquake zone and its coordinates



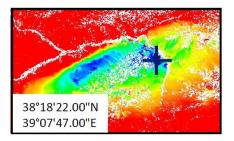


Figure 11. Visualization of the epicenter zone of the Doganyol Earthquake and its coordinates: Left side – geocoded line-of-sight displacement image of the IW3 Sentinel - 1A sub-swath with an ascending orbit, black contour frame – the place of existence of the maximum displacement; Right side – zoomed image of the earthquake zone and its coordinates

The accuracy of determining the epicenters of earthquakes was carried out according to the US Geological Survey's official data using a priori information about the coordinates of the epicenters. Western Xizang: 33.144°N 86.864°E; Doganyol: 38.431°N 39.061°E. The distance between the official epicenter of the earthquake and the data obtained after processing the Sentinel-1A/B radar remote sensing data is presented in Table 3 and Figure 12. The distance between the near epicenters S1A and S1B with ascending and descending orbits is 0.32 km for the Doganyol earthquake.

Table 2. Baseline estimation

Tuois 21 Dussilis communici						
$N_{\underline{0}}$	Study area	Orbits	Date before earthquake	Date after earthquake	Baseline B, meter	
1	China, Western	ascending	18.07.2020	30.07.2020	110.411	
2	Xizang	descending	14.07.2020	26.07.2020	122.695	
3		ascending	15.01.2020	27.01.2020	21.374	
4	D 177 1	descending	16.01.2020	28.01.2020	76.907	
5	Doganyol, Turkey	ascending	21.01.2020	02.02.2020	58.858	
6		descending	22.01.2020	03.02.2020	39.15	

Таблица 3. The accuracy of determining the epicenters of earthquakes

No	Study area	Orbits	Date before earthquake	Date after earthquake	Deviation from the official data, distance	
1	China, Western	S1A ascending	18.07.2020	30.07.2020	2.68 км	
2	Xizang	S1A descending	14.07.2020	26.07.2020	3.2 км	
3		S1A ascending	15.01.2020	27.01.2020	15.38 км	
4	December Tuelcar	S1A descending	16.01.2020	28.01.2020	15.06 км	
5	Doganyol, Turkey	S1B ascending	21.01.2020	02.02.2020	4.79 км	
6		S1B descending	22.01.2020	03.02.2020	16.3 км	

Note: S1A – Sentinel-1A, S1B – Sentinel-1B radar remote sensing satellites

Changes in displacement values from negative to positive were considered for the Western Xizang and Doganyol earthquakes (see Table 4). Negative values were used to determine the maximum changes that characterize the uplift of the Earth's crust. The absolute value displacement along the direct line-of-sight, which has negative values for Doganyol, is 90 mm, for the Western Xizang Earthquake is 50 mm. These values are completely consistent with the magnitude of the earthquake, which shows that the larger the magnitude, the greater the displacement we observe. The Doganyol earthquake magnitude of 6.7 M is greater than Western Xizang of 6.3 M.

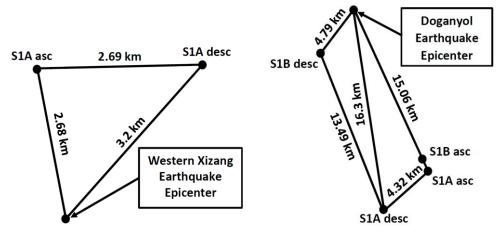


Figure 12. Distance between official and obtained epicenters for Western Xizang and Doganyol earthquakes with ascending (asc) and descending (desc) orbits of Sentinel-1A/B satellites

Table 4. Value of displacements on the line-of-sight

No	Studu area	Satellite, Sub-s	Sub-swath	Date before	Date after	Line-of-sight displacement, mm	
145		orbit	Sub-swam	earthquake	earthquake	Negative	Positive
1	China, Western	S1A asc	IW2	18.07.2020	30.07.2020	-50	36
2	Xizang	S1A desc	IW3	14.07.2020	26.07.2020	-32	52
3		S1A asc	IW3	15.01.2020	27.01.2020	-90	70
4	Doganyol,	S1A desc	IW2-IW3	16.01.2020	28.01.2020	-54	55
5	Turkey	S1B asc	IW3	21.01.2020	02.02.2020	-55	92
6		S1B desc	IW2-IW3	22.01.2020	03.02.2020	-56	32

Conclusion

Sentinel-1A/B radar remote sensing data is applicable for determining earthquake epicenter. The maximum error of deviation from the official one is 15.38 km for the Doganyol earthquake. The distance between the ascending orbits for the Doganyol earthquake is up to 0.32 km. A different geometric view with different orbits (ascending and descending) leads to a greater deviation of the distance error. In the case of the Doganyol earthquake, we have volumetric scattering from vegetation; therefore, the phase is with noise in some places than in Xizang. Western Xizang has a distance error of 3.2 km, which is better than the Doganyol case.

Determining the earthquake epicenter location associated with displacement, we can find the maximum value (in millimeters) of pixels to displacement in line-of-sight on the resultant image. This method will determine earthquake epicenter using modulo the maximum displacement along the direct line of sight of the radar. As the results show, the displacement values along the line of sight (see Table 4) are directly proportional to earthquake magnitude. Doganyol Earthquake with magnitude 6.7 M has a line-of-sight displacement - 90 mm, Western Xinjiang with a magnitude 6.3 M - 50 mm.

Despite the GMTSAR package's availability, a drawback is the lack of a user-friendly interface in the ESA SNAP software. There are inconveniences, and they are associated with the manual launch of GMTSAR scripts and pre-preparation of data. This GMTSAR package is more intended for experts than ordinary users who do not have enough experience with commands in the Linux terminal. Radar image processing in GMTSAR to create displacement images and determine the maximum displacement coordinates takes less elapsed time than ESA SNAP. The GMTSAR package is undemanding to use more powerful computers than other software on Windows operation system. The original Sentinel-1A/B data takes up 14 gigabytes of data, and it can increase several times due to data processing, so more capacious memory drives are needed. Therefore, more productive computing systems are required to work with such data arrays in some cases. We need a supercomputer with more RAM and high-speed SSD-based hard drives for fast, automatic radar image processing, a program code that implements the entire algorithm as in Figure 9, and a friendly interface for interacting with radar remote sensing data.

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