Performance Evaluation of Analytical Methods for Parameters Extraction of Photovoltaic Generators

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Abstract This paper presents a concise exploration of several analytical methods for extracting the parameters of the single-diode model (SDM) of a photovoltaic (PV) module under standard test conditions (STC). The paper investigates six methods and presents the detailed mathematical analysis leading to the development of each method. To evaluate the performance of these methods, MATLAB-based software has been developed and deployed to synthesize the results of each method when used to extract the SDM parameters of various PV test modules of different PV technologies. Similar software has also been developed to extract the same parameters using well-established numerical and iterative techniques. A comparison is subsequently made between the synthesized results and those obtained using numerical and iterative methods. The comparison indicates that in spite of the fact that analytical methods may involve fair amount of approximations, their accuracy can be comparable to that of their numerical and iterative counterparts, with the added advantage of significant reduction in computational complexity, and without the initialization and convergence difficulties, which are normally associated with numerical methods.

Keywords: Ideality factor; parameter extraction; photocurrent; saturation current; series resistance; shunt resistance; single-diode model.

Nomenclature

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
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<tbody>
<tr>
<td>a</td>
<td>Modified ideality factor (a = nN_sV_th).</td>
</tr>
<tr>
<td>α_Isc</td>
<td>Temperature coefficient of the short-circuit current (A/ °C).</td>
</tr>
<tr>
<td>β_Voc</td>
<td>Temperature coefficient of the open-circuit voltage (V/ °C).</td>
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<tr>
<td>δ</td>
<td>Coefficient for the single-diode model defined as a/V_ac.</td>
</tr>
<tr>
<td>G</td>
<td>Insolation (W/m²).</td>
</tr>
<tr>
<td>G_0STC</td>
<td>Insolation at standard test conditions (W/m²).</td>
</tr>
<tr>
<td>I</td>
<td>Terminal current of a photovoltaic cell or module (A).</td>
</tr>
<tr>
<td>I_mpp</td>
<td>Current at the maximum power point (A).</td>
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<tr>
<td>I_sc</td>
<td>Short-circuit current (A).</td>
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<tr>
<td>I_sat</td>
<td>Reverse saturation current (A).</td>
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<tr>
<td>I_ph</td>
<td>Photocurrent (A).</td>
</tr>
<tr>
<td>I_phSTC</td>
<td>Photocurrent at standard test conditions (A).</td>
</tr>
<tr>
<td>k</td>
<td>Boltzmann’s constant (1.38065 × 10^-23 J/K).</td>
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<tr>
<td>MPP</td>
<td>Maximum power point.</td>
</tr>
<tr>
<td>n</td>
<td>Ideality factor of a PV cell/diode.</td>
</tr>
<tr>
<td>N_s</td>
<td>Number of series-connected cells in a PV module.</td>
</tr>
<tr>
<td>P</td>
<td>Power (W).</td>
</tr>
<tr>
<td>P_mpp</td>
<td>Power at maximum power point (W).</td>
</tr>
<tr>
<td>PV</td>
<td>Photovoltaic.</td>
</tr>
<tr>
<td>q</td>
<td>Electronic charge 1.602×10^-19 (C).</td>
</tr>
<tr>
<td>R_s</td>
<td>Series resistance of a photovoltaic module (Ω).</td>
</tr>
<tr>
<td>R_so</td>
<td>The negative of the reciprocal of the slope of the I-V curve at the open-circuit voltage point.</td>
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The design of an MPPT system is made more difficult due to the effects of partial shading (PS) [7]. Partial shading can lead to significant reduction of the energy yield of a PV system and its reliability [8, 9]. To mitigate the adverse effects of PS, bypass diodes are normally deployed in PV modules [10] and arrays [11]. However, these diodes can give rise to P-V curves with multiple power peaks placing onerous demands on the design of the MPPT system [5]. Therefore, an equivalent circuit model of a PV generator is also required to aid the design and simulation of the MPPT system, to investigate the adverse effects of PS and explore strategies of mitigating them [12]. The single-diode model (SDM) of a PV generator, is currently the dominant lumped-parameter equivalent circuit model, mainly because it provides a compromise between accuracy and complexity [13, 14, 15] and can be readily modified to model a PV generator of any size, i.e. a cell, a module, or an array of modules [2, 16].

As shown in Figure 2, the SDM involves five parameters which must be estimated: The ideality factor $n$ and the saturation current of the diode $I_{sat}$, the series resistance $R_s$, the shunt resistance $R_{sh}$, and the photocurrent $I_{ph}$ [13]. These parameters are not available in manufacturers’ datasheets of PV generators [1].

Photovoltaic (PV) systems perform direct conversion of the electromagnetic energy in the sunlight into electricity making them one of the most attractive systems for renewable energy generation [1]. The principle component of a PV power plant is the PV generator, which typically consists of an array of PV modules connected in series-parallel combinations to provide the terminal voltage and current required to furnish the rated power of the plant. To harness the harvested solar energy and convert it into a usable form of electricity for the end user, a PV plant uses different types of power electronic systems, such as DC-DC and DC-AC converters [2]. The design, analysis and simulation of a PV system including these power converters, require a lumped-parameter equivalent circuit model of the PV generator. Such an equivalent circuit is used for purposes, such as the normalised I-V curve at the short-circuit point, and the efficiency of the system at a given insolation and temperature [3, 4].

The normalised I-V (current-voltage) and P-V (power-voltage) characteristics of a typical PV generator are shown in Figure 1. The general shapes of these characteristics are similar regardless of the size of the PV generator, i.e. whether it is a cell, a module, or an array of modules. These curves reveal three salient points: the open-circuit (OC) voltage, the short-circuit (SC) current, and the maximum power point (MPP). Clearly, to extract maximum power from a given PV generator, the generator must be operated at its maximum power point (MPP). However, the load is normally variable, which implies that the load-line will not necessarily coincide with the MPP. Moreover, the characteristics of a PV generator vary with climatic conditions of temperature and insolation thus, the MPP will also change with variations in insolation and temperature [3, 4]. Hence, to maintain operation at the current MPP, a PV system utilizes a maximum power point tracker (MPPT) that forces the operating point of a PV generator to continuously follow the prevailing MPP regardless of variations in the load and or environmental conditions [5].

An MPPT system includes a DC-DC power converter controlled by an MPPT algorithm that is normally implemented using a microcontroller [6]. The design of an MPPT system is made more difficult due to the effects of partial shading (PS) [7]. Partial shading can lead to significant reduction of the energy yield of a PV system and its reliability [8, 9]. To mitigate the adverse effects of PS, bypass diodes are normally deployed in PV modules [10] and arrays [11]. However, these diodes can give rise to P-V curves with multiple power peaks placing onerous demands on the design of the MPPT system [5]. Therefore, an equivalent circuit model of a PV generator is also required to aid the design and simulation of the MPPT system, to investigate the adverse effects of PS and explore strategies of mitigating them [12]. The single-diode model (SDM) of a PV generator, is currently the dominant lumped-parameter equivalent circuit model, mainly because it provides a compromise between accuracy and complexity [13, 14, 15] and can be readily modified to model a PV generator of any size, i.e. a cell, a module, or an array of modules [2, 16].

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### Variable Parameters

- **$R_{sh}$**: Shunt resistance of a PV module ($\Omega$).
- **$R_{sho}$**: The negative of the reciprocal of the slope of the I-V curve at the short-circuit current point.
- **SDM**: Single-diode model.
- **STC**: Standard test conditions (Insolation=1000 W/m², air mass AM=1.5, $T$=25 °C).
- **$T$**: Temperature (k).
- **$T_{STC}$**: Temperature at standard test conditions (°C).
- **$V$**: Terminal voltage of a PV module (V).
- **$V_{th}$**: Thermal voltage (V).
- **$V_{oc}$**: Open-circuit voltage of a PV module (V).
- **$V_{mp}$**: Voltage at maximum power point (V).
- **$V_{oc,STC}$**: Open-circuit voltage of a PV module at STC (V).
- **$W$**: Lambert-W function.

### 1. Introduction

Photovoltaic (PV) systems perform direct conversion of the electromagnetic energy in the sunlight into electricity making them one of the most attractive systems for renewable energy generation [1]. The principle component of a PV power plant is the PV generator, which typically consists of an array of PV modules connected in series-parallel combinations to provide the terminal voltage and current required to furnish the rated power of the plant. To harness the harvested solar energy and convert it into a usable form of electricity for the end user, a PV plant uses different types of power electronic systems, such as DC-DC and DC-AC converters [2]. The design, analysis and simulation of a PV system including these power converters, require a lumped-parameter equivalent circuit model of the PV generator. Such an equivalent circuit is used for purposes, such as the normalised I-V curve at the short-circuit point, and the efficiency of the system at a given insolation and temperature [3, 4]. Hence, to maintain operation at the current MPP, a PV system utilizes a maximum power point tracker (MPPT) that forces the operating point of a PV generator to continuously follow the prevailing MPP regardless of variations in the load and or environmental conditions [5].

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modules, but can be extracted, i.e. estimated, from information provided in datasheets. However, information given in a datasheet of a PV module is specified under only one operating condition, namely the standard test conditions STC (insolation $G = 1000 \text{ W/m}^2$, temperature $T = 25 \degree \text{C}$, and Air mass AM=1.5) thus, the extracted parameters are only valid at STC. For any other arbitrary conditions of insolation and temperature, these STC parameters must be adjusted accordingly [4, 17].

To extract the parameters of the single-diode model at STC, numerous methods with varying degrees of mathematical and computational complexities and accuracy have been reported in the literature, for example [18] [14] and [19]. These methods are generally classified as either numerical or analytical. Numerical methods generate a set of equations whose solution can be achieved using either numerical algorithms such as the Newton-Raphson technique, or using iterative solution strategies [14, 19]. The disadvantages of numerical methods include the need for appropriate initialization, can produce trivial solutions, and may have convergence difficulties. Analytical methods on the other hand, use simple and fast parameter extraction strategies by making use of some simplifying assumptions and approximations [20]. For example, by neglecting some model parameters or assigning some approximate values for some parameters as explained in Section 3 [21], [22].

In addition to analytical and numerical methods for parameters extraction, there are other strategies, such as those based on computational intelligence [23] and those based on the meta-heuristic firefly algorithm [24]. More complex methods of parameter extraction can also be found in the literature, such as those based on optimization algorithms [25, 26] and those based on differential evolution [27]. There are also analytical methods which are based on the double-diode circuit model of a PV generator which has seven parameters [28, 29]. However, the scope of this article is restricted to analytical methods which are based on the universally adopted single-diode equivalent circuit model of a PV module.

Referring to the SDM in Figure 2, the terminal current $I$ of a PV module consisting of $N_s$ series-connected cells, is given by the general current equation:

![Figure 1. I-V and PV characteristics of a typical PV generator.](image1)

![Figure 2. The single-diode model.](image2)
The first term is the photocurrent $I_{ph}$ which is almost directly proportional to the incident insolation. The second term is the Shockley’s diode equation, which represents the diode current $I_d$, while the third term is the current in the shunt resistance $I_{sh}$. The diode’s thermal voltage $V_{th}$ is defined in terms of the electronic charge $q = 1.602 \times 10^{-19}$ C, the Boltzmann’s constant $k = 1.38065 \times 10^{-23}$ J/K and temperature $T$ (K) as:

$$V_{th} = \frac{kT}{q}$$

At room temperature, the thermal voltage is about 26 mV. The ideality factor for a silicon PV cell is typically between 1 and 2. For a typical PV module, the series resistance is in the order of 1 Ω, the parallel resistance is in the region of few hundred ohms, and the saturation current is in the order of nano-Amperes.

Equation (1) is an implicit and transcendental equation that would normally require a numerical solution to obtain the five parameters of the SDM. However, since numerical methods are susceptible to convergence and initialization difficulties, several alternative analytical methods have been described in the literature. These methods aim at reducing the complexity of the implicit general equation of the SDM by introducing some approximations to develop explicit models as detailed in Section 3. For example, some methods use the approximation that the shunt resistance is the reciprocal of the slope of the $I-V$ curve at the short-circuit-point [20]. Others neglect the shunt resistance on the assumption that it is relatively too large [30], while some analytical methods neglect both the series and the shunt resistances [22].

The contributions of this article are: Explore the most literature-reported analytical methods for parameters extraction of the SDM, present detailed derivation of the mathematical expressions that lead to each method which are not normally detailed in the reporting literature, and synthesize the results of each method by deploying them to extract the parameters of PV modules of different technologies. Finally, the paper presents a comparison between these synthesised results and those obtained using numerical and iterative techniques.

Following this introduction, Section 2, presents the mathematical background that underpins the development of the analytical methods investigated in this work. Section 3 presents detailed mathematical derivation and formulation of the expressions required for extracting each parameter using each method. Section 4 provides a discussion of the results and finally, Section 5 summarizes the main findings of the work presented in this article.

2. Mathematical grounds for the analytical methods

When the entire $I-V$ curve is available, the parameters of the SDM may be estimated using curve fitting or optimization algorithm [31, 32, 26]. In general, the $I-V$ characteristics are not given in manufacturers’ datasheets and even when provided, they are specified under only one operating condition, namely the STC [33]. Most methods used to extract the SDM parameters are based on developing the model equations using data at the three salient points (SC, OC, MPP), which are always provided in the datasheet of a PV module. There are three standard equations used in most studies, e.g. in [21], [14] and [18], which are derived from equation (1) at the three salient points: $(0, I_{sc}), (V_{oc}, 0)$, and $(V_{mp}, I_{mp})$ under STC as explained next.

Substituting the SC point $(0, I_{sc})$ in equation (1), we obtain the short-circuit equation as:

$$I_{sc} = I_{ph} - I_{sat} \left[\exp\left(\frac{V + IR}{nNV_{th}}\right) - 1\right] - \frac{V + IR}{R_{sh}}$$

Similarly, substituting the OC point $(V_{oc}, 0)$ in equation (1) and rearranging, we obtain the open-circuit equation as:
Finally, substituting the MPP point \((V_{mp}, I_{mp})\) in equation (1), the MPP equation is:

\[
I_{mp} = I_{ph} - I_{sat} \left[ \frac{V_{mp} + I_{mp} R_s}{n N V_{th}} \right] - \frac{V_{mp} + I_{mp} R_s}{R_{sh}} \tag{5}
\]

Another important quantity required for parameter extraction is the derivative of the module’s current with respect to its voltage, i.e. \(dI/dV\). This is obtained by differentiating equation (1):

\[
\frac{dI}{dV} = -\frac{I_{sat}}{n N V_{th}} \left[ \exp \left( \frac{V + IR_s}{n N V_{th}} \right) \right] \left( 1 + \frac{dI}{dV} \frac{1}{R_s} - \frac{1}{R_{sh}} \right) \tag{6}
\]

Solving for the derivative:

\[
\frac{dI}{dV} = \frac{-\frac{I_{sat}}{n N V_{th}} \left[ \exp \left( \frac{V + IR_s}{n N V_{th}} \right) \right] - \frac{1}{R_s}}{(1 + \frac{\frac{R_s}{R_{sh}} + \frac{I_{sat} R_s}{n N V_{th}} \exp \left( \frac{V + IR_s}{n N V_{th}} \right)}{R_{sh}})} \tag{7}
\]

It is to be noted that the above expression for the derivative is valid at any point along the I-V curve. Another derivative used in parameter extraction procedures is that of the power with respect to voltage defined as:

\[
\frac{dP}{dV} = \frac{d}{dV} (VI) = V \frac{\partial I}{\partial V} + I \frac{\partial V}{\partial V} \tag{8}
\]

At the MPP, this derivative equates to zero:

\[
\left. \frac{dP}{dV} \right|_{MPP} = 0 = V_{mp} \frac{\partial I}{\partial V} + I_{mp} \frac{\partial V}{\partial V} \tag{9}
\]

Therefore, at the MPP the current derivative becomes:

\[
\left. \frac{dI}{dV} \right|_{MPP} = -\frac{I_{mp}}{V_{mp}} \tag{10}
\]

The shunt resistance at the short-circuit point \(R_{sho}\), may be estimated from the gradient of the I-V curve at the short-circuit point as:

\[
\left. \frac{dI}{dV} \right|_{SC} = -\frac{1}{R_{sho}} \tag{11}
\]

Similarly, the series resistance at the open-circuit point \(R_{so}\) is defined as:

\[
\left. \frac{dI}{dV} \right|_{OC} = -\frac{1}{R_{so}} \tag{12}
\]

For the five parameters extraction process, the majority of the parameter extraction methods, for example [14], [19], [22], [34], [35], [36], [37], [38], have taken into account the mathematical correlation between these parameters and separated them into two levels: The main level consists of the ideality factor, series resistance, and shunt resistance, and a secondary level which consists of the photocurrent and the saturation current. This way, the extraction equations are reduced to three instead of five to simplify the mathematical formulation as illustrated in the next section.

**3. Parameters Extraction Methods**
In this section we present the mathematical analysis and derivation of the equations required for the extraction of the SDM parameters for six main analytical methods.

3.1 Method 1

This method was developed to determine the parameters of a blue and grey solar cell using experimentally obtained I-V curve and the three salient points, i.e. the SC, OC, and the MPP, which are available in datasheets [20]. The method uses several approximations to simplify the required extraction equations and is based on calculating a value of the ideality factor as the main parameter, which is consequently used to estimate the remaining four parameters, namely $R_s$, $R_{sh}$, $I_{ph}$, and $I_{sat}$. As explained in the following subsections, the method uses equations (3), (4), (5), (11) and (12) to extract the model parameters with the term $N_s$ set to unity since the method was described for a single PV cell as opposed to a PV module.

3.1.1. Extraction of the photocurrent

The photocurrent is estimated using the short-circuit current point $(0, I_{sc})$, i.e. equation (3), which we can re-arrange to obtain an expression for the photocurrent as:

$$I_{ph} = I_s (1 + \frac{R_s}{R_{sh}}) + I_{sat} \left(\exp\left(\frac{I_s R_s}{nV_{th}}\right) - 1\right)$$

(13)

The short-circuit current $I_{sc}$ is obtained from the datasheet. However, $R_s$, $R_{sh}$, and $I_{sat}$ are unknowns and must be determined.

3.1.2 Extraction of the shunt resistance

We can derive an expression to estimate the shunt resistance using the expression for derivative $dl/dV$ expressed at the short-circuit point. Substituting the short-circuit point $(0, I_{sc})$ in the expression of the derivative of equation (7), and setting $N_s = 1$, we obtain:

$$\frac{dl}{dV}_{sc} \left[1 + \frac{R_s}{R_{sh}} + \frac{I_{sat} R_s}{nV_{th}} \exp\left(\frac{I_s R_s}{nV_{th}}\right)\right] = \frac{I_{sat}}{nV_{th}} \left[\exp\left(\frac{I_s R_s}{nV_{th}}\right)\right] + \frac{1}{R_{sh}}$$

(14)

Substituting for the derivative at the OC point from equation (11) into equation (14) we obtain:

$$R_{sh} \left[\frac{I_{sat}}{nV_{th}} \left[\exp\left(\frac{I_s R_s}{nV_{th}}\right)\right] + \frac{1}{R_{sh}}\right] = (1 + \frac{R_s}{R_{sh}} + \frac{I_{sat} R_s}{nV_{th}} \exp\left(\frac{I_s R_s}{nV_{th}}\right))$$

(15)

The exponential term $[I_{sat} \exp\left(\frac{I_s R_s}{nV_{th}}\right)]$ represents the diode current under short-circuit condition, which is too small compared to the short-circuit current hence, it may be neglected [39]. Further, since $R_s \ll R_{sh}$, the term $R_s/R_{sh}$ may also be neglected. Therefore, equation (15) becomes:

$$R_{sh} = R_{sho}$$

(16)

That is, in this method, the shunt resistance is estimated directly from the slope of the I-V curve at the short-circuit point.

3.1.3 Extraction of the series resistance

To estimate the series resistance, we can use the gradient of the I-V curve at the open-circuit voltage point. Substituting the OC point $(V_{oc}, 0)$ and setting $N_s = 1$ in the general expression for the derivative of equation (7), we can write:

$$\frac{dl}{dV}_{oc} \left[1 + \frac{R_s}{R_{sh}} + \frac{I_{sat} R_s}{nV_{th}} \exp\left(\frac{V_{oc}}{nV_{th}}\right)\right] = \frac{I_{sat}}{nV_{th}} \left[\exp\left(\frac{V_{oc}}{nV_{th}}\right)\right] + \frac{1}{R_{sh}}$$

(17)

Substituting for the derivative at the OC point from equation (12) and re-arranging:
\[ R_s \left[ \frac{I_{sat}}{nV_{th}} \cdot \exp\left( \frac{V_{oc}}{nV_{th}} \right) + \frac{1}{R_{sh}} \right] = (1 + \frac{R_s}{R_{sh}}) + \frac{I_{sat} R_s}{nV_{th}} \exp\left( \frac{V_{oc}}{nV_{th}} \right) \] \tag{18} 

The term \([I_{sat} \exp(V_{oc}/nV_{th})]\) represents the diode current under open-circuit condition. Under this condition, the diode current is the photocurrent, which is the same as the short-circuit current less the negligibly small current in the shunt resistance. When this diode current is divided by \(nV_{th}\) the result is much greater than \(1/R_{sh}\) thus, the latter term can be neglected. Further, after neglecting the term \(R_s/R_{sh}\), the expression for series resistance becomes:

\[ R_s = R_{so} - \frac{nV_{th}}{I_{sat}} \exp\left( \frac{V_{oc}}{nV_{th}} \right) \] \tag{19} 

This is not a closed form expression for the series resistance since it contains the ideality factor and the saturation current which needs to be determined. The open-circuit voltage is obtained from the datasheet.

3.1.4 Extraction of the reverse saturation current

By substituting the open-circuit equation (4) into the short-circuit equation (3) and neglecting the \((-1)\) in the exponential terms, we obtain:

\[ I_{sc} = I_{sat} \left[ \exp\left( \frac{V_{oc}}{nV_{th}} \right) - \exp\left( \frac{I_{sat} R_s}{nV_{th}} \right) \right] + \frac{V_{oc}}{R_{sh}} - \frac{I_{sat} R_s}{R_{sh}} \] \tag{20} 

This may be re-arranged as:

\[ I_{sat} \left[ \exp\left( \frac{V_{oc}}{nV_{th}} \right) - \exp\left( \frac{I_{sat} R_s}{nV_{th}} \right) \right] - \left( \frac{R_s}{R_{sh}} + 1 \right) I_{sat} + \frac{V_{oc}}{R_{sh}} = 0 \] \tag{21} 

However, since in practice at \(I_{sc} R_s \ll V_{oc}\) and \(R_s \ll R_{sh}\) [40, 39], the equation for the saturation current becomes:

\[ I_{sat} = \left( I_{sc} - \frac{V_{oc}}{R_{sh}} \right) \exp\left( \frac{-V_{oc}}{nV_{th}} \right) \] \tag{22} 

The shunt resistance and the open-circuit voltage can be determined from the I-V curve however, the ideality factor is still unknown and needs to be determined.

3.1.5 Extraction of the ideality factor \(n\)

Substituting the open-circuit equation for the photocurrent, equation (4), into the MPP equation (5), and after ignoring the \((-1)\) in the exponential terms, we can write:

\[ I_{sat} \exp\left( \frac{V_{oc}}{nV_{th}} \right) - I_{sat} \exp\left( \frac{V_{mp} + I_{mp} R_s}{nV_{th}} \right) + \frac{V_{sc} - V_{mp}}{R_{sh}} - I_{mp} \left( 1 + \frac{R_s}{R_{sh}} \right) = 0 \] \tag{23} 

Since \(R_s \ll R_{sh}\), this reduces to:

\[ I_{sat} \exp\left( \frac{V_{oc}}{nV_{th}} \right) - I_{sat} \exp\left( \frac{V_{sc} + I_{mp} R_s}{nV_{th}} \right) + \frac{V_{sc} - V_{mp}}{R_{sh}} - I_{mp} = 0 \] \tag{24} 

An expression for the ideality factor can now be derived as explained below. Substituting equation (16) into (22):

\[ I_{sat} = \left( I_{sc} - \frac{V_{sc}}{R_{sho}} \right) \exp\left( \frac{-V_{sc}}{nV_{th}} \right) \] \tag{25} 

Substituting equation (25) into (24), we obtain:
\[
\left( I_s - \frac{V_{ac}}{R_{sho}} \right) \exp \left( \frac{-V_{ac}}{nV_{th}} \right) \exp \left( \frac{V_{sc}}{nV_{th}} \right) - \\
\left( I_s - \frac{V_{ac}}{R_{sho}} \right) \exp \left( \frac{-V_{ac}}{nV_{th}} \right) \exp \left( \frac{V_{mp} + I_{mp}R}{nV_{th}} R_{sho} \right) + \frac{V_{ac} - V_{mp}R}{R_{sho}} = 0
\] (26)

This can be simplified to:
\[
\frac{V_{mp} + I_{mp}R_s - V_{ac}}{nV_{th}} = \ln \left( I_s - I_{mp} - \frac{V_{mp}}{V_{sc}R_{sho}} \right) - \ln \left( I_s - \frac{V_{ac}}{R_{sho}} \right)
\] (27)

Therefore, the ideality factor becomes:
\[
n = \frac{V_{mp} + I_{mp}R_s - V_{ac}}{V_{th} \ln \left( I_s - I_{mp} - \frac{V_{mp}}{V_{sc}R_{sho}} \right) - \ln \left( I_s - \frac{V_{ac}}{R_{sho}} \right)}
\] (28)

This is not a closed form expression because it contains the series resistance, which must be determined. This can be obtained by substituting the expression for the saturation current of equation (25) into the expression for the series resistance of equation (19) as:
\[
R_s = R_{so} - \frac{nV_{th}}{\left( I_s - \frac{V_{ac}}{R_{sho}} \exp \left( \frac{-V_{ac}}{nV_{th}} \right) \exp \left( \frac{V_{sc}}{nV_{th}} \right) \right)}
\] (29)

Hence, the expression for the series resistance becomes:
\[
R_s = R_{so} - \frac{nV_{th}}{I_s - \frac{V_{sc}}{nV_{th}}}
\] (30)

Substituting this expression for the series resistance, i.e. equation (30), into equation (28):
\[
n = \frac{V_{mp} - V_{ac} + I_{mp} \left( R_{so} - \frac{nV_{th}}{I_s - \frac{V_{ac}}{R_{sho}}} \right)}{V_{th} \ln \left( \frac{V_{mp}}{R_{sho}} + I_s - I_{mp} \right) - \ln \left( I_s - \frac{V_{ac}}{R_{sho}} \right)}
\] (31)

This can be simplified to:
\[
n V_{th} \ln \left( \frac{V_{mp}}{R_{sho}} + I_s - I_{mp} \right) - \ln \left( I_s - \frac{V_{ac}}{R_{sho}} \right) + \frac{I_{mp}}{I_s - \frac{V_{ac}}{R_{sho}}} = V_{mp} - V_{ac} + I_{mp} R_{so}
\] (32)

Solving for the ideality factor:
\[
n = \frac{V_{mp} - V_{ac} + I_{mp} R_{so}}{V_{th} \ln \left( \frac{V_{mp}}{R_{sho}} + I_s - I_{mp} \right) - \ln \left( I_s - \frac{V_{ac}}{R_{sho}} \right) + \frac{I_{mp}}{I_s - \frac{V_{ac}}{R_{sho}}}}
\] (33)

This is now a closed form expression for the ideality factor because all the variables can be obtained or estimated from the datasheet and the I-V curve of the cell. For a PV module with \(N_s\) cells connected in series, the ideality factor is multiplied by \(N_s\) [2]. Having obtained the value of the
ideality factor, the saturation current can then be estimated using equation (25) and consequently, the series resistance obtained from (19). Finally, the photocurrent can be calculated using (13). The major downside of this method is that it requires the I-V curve, which is not always available in the manufacturer’s datasheet.

3.2 Method 2

This method is based on using the ideal single-diode model of a PV generator shown in Figure 3, which neglects the effects of the series and shunt resistances. The method results in simplified analytical expressions for current, voltage, and power [22].

![Figure 3. The ideal SDM model of a PV generator.](image)

The general current equation for this model is:

\[
I = I_{ph} - I_{sat} \left( \exp\left(\frac{V}{nN V_{th}}\right) - 1 \right)
\]

At the short-circuit point \((0, I_{sc})\), this reduces to:

\[
I_{ph} = I_{sc}
\]

That is the photocurrent is the same as the short-circuit current, which is always available in the datasheet. At the open-circuit point \((V_{oc}, 0)\), we have:

\[
I_{ph} = I_{sat} \left( \exp\left(\frac{V_{oc}}{nN V_{th}}\right) - 1 \right)
\]

Alternatively, since in this model, \(I_{sc} = I_{ph}\) we may write:

\[
I_{sc} = I_{sat} \left[ \exp\left(\frac{V_{oc}}{nN V_{th}}\right) - 1 \right]
\]

Solving for the open-circuit voltage:

\[
V_{oc} = nN V_{th} \ln \left( \frac{I_{sc}}{I_{sat}} + 1 \right)
\]

From equation (37), we can express the saturation current as:

\[
I_{sat} = \frac{I_{sc}}{\exp\left(\frac{V_{oc}}{nN V_{th}}\right) - 1}
\]

At the maximum power point, we can express the MPP current as:

\[
I_{mp} = I_{sc} - I_{sat} \left[ \exp\left(\frac{V_{mp}}{nN V_{th}}\right) - 1 \right]
\]
The derivative \( \frac{dI}{dV} \) at any point along the I-V curve is obtained from equation (34) as:

\[
\frac{dI}{dV} = - \frac{I_{sat}}{nN_iV_{th}} \exp\left(\frac{V_{th}}{nN_iV_{th}}\right)
\]  

(41)

The derivative at the maximum power point is:

\[
\frac{dI}{dV}_{MPP} = - \frac{I_{mp}}{V_{mp}}
\]  

(42)

Substituting equation (42) into equation (41), the current at the MPP becomes:

\[
I_{mp} = \frac{V_{mp} I_{sat}}{nN_iV_{th}} \exp\left(\frac{V_{mp}}{nN_iV_{th}}\right)
\]  

(43)

Substituting (37) and (43) into (40) and ignoring the (-1) in the exponential terms:

\[
[\exp(\frac{V_{oc}}{nN_iV_i})] = \exp\left(\frac{V_{mp}}{nN_iV_{th}}\right)(1 + \frac{V_{mp}}{nN_iV_{th}})
\]  

(44)

Equations (35), (38), (43) and (44) represent the main equations of the explicit model. To estimate the maximum power point voltage \( V_{mp} \), the derivative in equation (41) at the MPP is solved for the MPP voltage as:

\[
V_{mp} = nN_iV_i \ln\left(\frac{nN_iV_{th}}{I_{sat}} \left| \frac{dI}{dV}\right|_{mp}\right)
\]  

(45)

The asymptotic behaviour of the I-V curve around the open-circuit and short-circuit points were used to estimate the derivative needed in the above equation as [22]:

\[
\frac{dI}{dV}_{MPP} \approx \frac{\Delta I}{\Delta V} = \frac{0 - I_{sc}}{V_{oc} - 0} = -\frac{I_{sc}}{V_{oc}}
\]  

(46)

Substituting equation (46) into (45), we obtain:

\[
V_{mp} = nN_iV_i \ln\left(\frac{nN_iV_{th}}{I_{sat}} \frac{I_{sc}}{V_{oc}}\right)
\]  

(47)

Substituting equation (47) into (40):

\[
I_{mp} = I_{sc} - I_{sat} \left(\frac{nN_iV_{th} \ln\left(\frac{nN_iV_{th}}{I_{sat}} \frac{I_{sc}}{V_{oc}}\right)}{nN_iV_{th}} - 1\right)
\]  

(48)

Simplifying the above, we obtain:

\[
I_{mp} = I_{sc} + I_{sat} - I_{sat} \left(\frac{nN_iV_{th} I_{sc}}{I_{sat} V_{oc}}\right)
\]  

(49)

\[
I_{mp} = I_{sc} + I_{sat} - nN_iV_{th} \frac{I_{sc}}{V_{oc}}
\]  

(50)

The maximum power is:

\[
P_{mp} = V_{mp} I_{mp}
\]  

(51)
Therefore,

\[ P_n = nN_s V_{th} (I_{sc} + I_{sat} - nN_s V_{th} \frac{I_{sc}}{V_{th}}) \ln \left( \frac{nN_s V_{th} (I_{sc} - I_{sat})}{I_{sat} V_{sc}} \right) \]  \hspace{1cm} (52)

In order to calculate the ideality factor under STC conditions, we substitute equation (39) into (40) and ignore the (-1) in the exponential terms:

\[ I_{mp} = I_{sc} - \frac{I_{sc}}{\exp \left( \frac{V_{mp}}{nN_s V_{th}} \right)} \exp \left( \frac{V_{mp}}{nN_s V_{th}} \right) \]  \hspace{1cm} (53)

Re-arranging and simplifying, we obtain:

\[ nN_s V_{th} \ln \left( 1 - \frac{I_{sc}}{I_{sc}} \right) = (V_{mp} - V_{sc}) \]  \hspace{1cm} (54)

Solving for the ideality factor at STC, we obtain:

\[ n = \frac{V_{mp} - V_{sc}}{nN_s V_{th} \ln \left( 1 - \frac{I_{sc}}{I_{sc}} \right)} \]  \hspace{1cm} (55)

In attempting to improve the accuracy of this method, Mahmoud et al [41] modified the saturation current equation as:

\[ I_{sat} = \frac{nN_s kT}{(G I_{sat,STC} / I_{sat}) + 1} - \exp \left( \frac{\beta \Delta T q G (I_{sc} + \alpha \Delta T)}{nN_s kT} \right) \]  \hspace{1cm} (56)

Where \( \Delta T = T - T_{STC} \) and \( \beta \) is the voltage temperature coefficient, which is always included in the datasheet. The saturation current at STC can be computed as [14]:

\[ I_{sat,STC} = \frac{I_{sc}}{[\exp(V_{sc} / nN_s V_{th}) - 1]} \]  \hspace{1cm} (57)

Yousef et al [42] improved the accuracy of the ideal model of the PV module at low irradiance without affecting the simplicity of the model by modifying the equation of saturation current to take into account the effect of the low irradiance on the open-circuit voltage as:

\[ I_{sat} = \frac{I_{ph} (G, T)}{[\exp(q(V_{oc} - [\beta \Delta T + \Delta V_{oc} (G_1, T_{STC})]) - 1] \]  \hspace{1cm} (58)

\[ V_{oc} = \frac{nN_s kT}{q} \ln \left( \frac{I_{ph}}{I_{sat}} + 1 \right) \]  \hspace{1cm} (59)

\[ \Delta V_{oc} (G, T_{STC}) = \frac{nN_s kT}{q} \ln \left( \frac{G}{G_{STC}} \right) \]  \hspace{1cm} (60)

3.3 Method 3

This method assumes that the shunt resistance is very large so that it can be neglected hence, it is developed using the single-diode equivalent circuit model shown in Figure 4. This model, which is known as the four parameters model, has been found to offer good accuracy [30, 43]. The method uses the datasheet, but does not require the full I-V curve [44, 30, 43, 45] which is not normally
available. The model equations can be derived as illustrated below. The general current equation for this model is:

\[ I = I_{ph} - I_{sat} \left[ \exp \left( \frac{V + IR}{nN_iV_{th}} \right) - 1 \right] \]  \hspace{1cm} (61)

The short-circuit equation is:

\[ I_{sc} = I_{ph} - I_{sat} \left[ \exp \left( \frac{I_{sc}R_s}{nN_iV_{th}} \right) - 1 \right] \]  \hspace{1cm} (62)

The open-circuit equation is:

\[ 0 = I_{ph} - I_{sat} \left[ \exp \left( \frac{V_{sc}}{nN_iV_{th}} \right) - 1 \right] \]  \hspace{1cm} (63)

The MPP equation is:

\[ I_{mp} = I_{ph} - I_{sat} \left[ \exp \left( \frac{V_{mp} + I_{mp}R_s}{nN_iV_{th}} \right) - 1 \right] \]  \hspace{1cm} (64)

![Diagram](image)

Figure 4. The four-parameters SDM.

3.3.1 Extraction of the photocurrent

Referring to the equation of the short-circuit condition, i.e. equation (62), the second term represents the diode current. In practice, since the voltage \( I_{sc}R_{sc} \) is too small and comparable to the thermal voltage, the exponential term \( \exp \left( I_{sc}R_{sc}/nN_iV_{th} \right) \) is close to unity. Further, since this is multiplied by the very small value of the saturation current, it is reasonable to assume that the under short-circuit condition, the diode current is much smaller than the short-circuit current and can be neglected, i.e. the entire photocurrent is the short-circuit current, hence equation (62) reduces to:

\[ I_{ph} = I_{sc} \]  \hspace{1cm} (65)

That is the photocurrent is the same as the short-circuit current, which is always given in datasheets.

3.3.2 Extraction of the saturation current

Under open-circuit condition, the entire short-circuit current is the diode current, i.e.

\[ I_{sc} = I_{sat} \left[ \exp \left( \frac{V_{sc}}{nN_iV_{th}} \right) - 1 \right] \]  \hspace{1cm} (66)

Since the exponential term is much larger than unity, we can ignore the (-1) hence, the saturation current can be expressed as:

\[ I_{sat} = I_{s} \left[ \exp \left( \frac{V_{sc}}{nN_iV_{th}} \right) \right] \]  \hspace{1cm} (67)

This is, however, not a closed form expression for the saturation current since it includes the ideality factor which must be determined.
3.3.3 Extraction of the series resistance

The series resistance can be found by substituting equation (67) into the MPP equation (64) as:

\[ I_{mp} = I_{ph} - I_{sc} \left[ \exp \left( \frac{-V_{oc}}{nN_{th}V_{th}} \right) \left[ \exp \left( \frac{V_{mp} + I_{mp}R_s}{nN_{th}V_{th}} \right) - 1 \right] \right] \]  

(68)

Neglecting the (-1) in the second exponential term and replacing the photocurrent by the short-circuit current and re-arranging:

\[ 1 - \frac{I_{mp}}{I_{sc}} = \frac{\exp(-V_{oc})}{\left[ \exp \left( \frac{V_{mp} + I_{mp}R_s}{nN_{th}V_{th}} \right) \right]} \]  

(69)

Re-arranging and solving for the series resistance, we obtain:

\[ R_s = \frac{nN_{th}V_{th} \ln(1 - \frac{I_{mp}}{I_{sc}}) + V_{oc} - V_{mp}}{I_{mp}} \]  

(70)

This is not a closed form expression since it includes the ideality factor, which needs to be determined.

3.3.4 Extraction of the ideality factor

The ideality factor is derived using the fact that the slope of the I-V curve at the MPP is equal to zero. Equating equation (10) and equation (7) at the MPP:

\[ \frac{I_{mp}}{V_{mp}} = -\frac{I_{sat}}{nN_{th}V_{th}} \left[ \exp \left( \frac{V_{mp} + I_{mp}R_s}{nN_{th}V_{th}} \right) \right] \]  

(71)

Re-arranging as:

\[ V_{mp} = -\frac{1}{I_{mp}} \frac{I_{sat}}{nN_{th}V_{th}} \left[ \exp \left( \frac{V_{mp} + I_{mp}R_s}{nN_{th}V_{th}} \right) \right] + R_s \]  

(72)

The above may be written as:

\[ R_s \frac{V_{mp}}{I_{mp}} = \frac{-nN_{th}V_{th}}{I_{sat}} \left[ \exp \left( \frac{V_{mp} + I_{mp}R_s}{nN_{th}V_{th}} \right) \right] \]  

(73)

Substituting for the series resistance \( R_s \) from (70) into (73) we obtain:

\[ \frac{nN_{th}V_{th} \ln(1 - \frac{I_{mp}}{I_{sc}}) + V_{oc} - 2V_{mp}}{I_{mp}} = \frac{-nN_{th}V_{th}}{I_{sat} \left[ \exp \left( \frac{V_{mp} + I_{mp}R_s}{nN_{th}V_{th}} \right) \right]} \]  

(74)

This may be re-arranged as:

\[ \frac{-\ln(1 - \frac{I_{mp}}{I_{sc}})}{I_{mp}} + \frac{(2V_{mp} - V_{oc})}{nN_{th}V_{th}} = \frac{1}{I_{sat} \left[ \exp \left( \frac{V_{mp} + I_{mp}R_s}{nN_{th}V_{th}} \right) \right]} \]  

(75)

Substituting for the saturation current from equation (67):
\[
\frac{-\ln(1 - \frac{I_{mp}}{I_{sc}}) + \frac{(2V_{mp} - V_{oc})}{nN_sV_{th}}}{I_{mp}} = \frac{1}{I_{sc}[\exp(-\frac{V_{oc}}{nN_sV_{th}})]}
\]

(76)

This may be re-arranged as:

\[
\frac{-\ln(1 - \frac{I_{mp}}{I_{sc}}) + \frac{(2V_{mp} - V_{oc})}{nN_sV_{th}}}{I_{mp}} = \frac{1}{I_{sc}[\exp(-\frac{V_{mp} + I_{mp}R_s - V_{oc}}{nN_sV_{th}})]}
\]

(77)

The denominator on the right-hand side of equation (77) may be re-written with the series resistance substituted by its expression from equation (70) and simplified as follows:

\[
I_{sc}[\exp(-\frac{V_{mp} + I_{mp}R_s - V_{oc}}{nN_sV_{th}})] = I_{sc}\exp[-\frac{V_{mp} + I_{mp}R_s}{nN_sV_{th}}]
\]

(78)

Re-arranging:

\[
I_{sc}[\exp(-\frac{V_{mp} + I_{mp}R_s - V_{oc}}{nN_sV_{th}})] = I_{sc}\exp[-\frac{1 - \frac{I_{mp}}{I_{sc}}}{I_{sc}}]
\]

(79)

Therefore:

\[
I_{sc}[\exp(-\frac{V_{mp} + I_{mp}R_s - V_{oc}}{nN_sV_{th}})] = I_{sc} - I_{mp}
\]

(80)

Substituting (80) into (77)

\[
\frac{-\ln(1 - \frac{I_{mp}}{I_{sc}}) + \frac{(2V_{mp} - V_{oc})}{nN_sV_{th}}}{I_{mp}} = \frac{1}{I_{sc} - I_{mp}}
\]

(81)

Simplifying and solving for the ideality factor:

\[
n = \frac{(2V_{mp} - V_{oc})}{N_sV_{th}[\frac{I_{mp}}{I_{sc} - I_{mp}} + \ln(1 - \frac{I_{mp}}{I_{sc}})]}
\]

(82)

This is a closed form expression for the ideality factor since all variables in its expression are available in the datasheet. Therefore, \(R_s\) and \(I_{sat}\) can now be determined.

### 3.4 Method 4

This method uses the datasheet information to extract the five parameters of the SDM using a piecewise I-V curve fitting method combined with the four parameters PV model to evaluate them [45]. In this method the definition of the modified ideality factor is introduced as:

\[
a = nN_sV_{th}
\]

(83)

Using equation (7) the derivative of voltage with respect to current \(dV/dI\) is:

\[
\frac{dV}{dI} = -\frac{R_s(\frac{1}{R_{sh}} + \frac{I_{sc}}{a})\exp(\frac{V + IR_s}{a}) + 1}{I_{sc}[\exp(\frac{V + IR_s}{a}) + \frac{1}{R_{sh}}]}
\]

(84)
Simplifying:
\[
\frac{dV}{dl} = -R_s - \frac{aR_{sh}}{a + I_{sat}R_{sh}\exp\left(\frac{V + IR_s}{a}\right)}
\]  

(85)

At the short-circuit point, the derivative becomes:
\[
\left.\frac{dV}{dl}\right|_{sc} = -R_s - \frac{aR_{sh}}{a + I_{sat}R_{sh}\exp\left(\frac{I_{sc}R_s}{a}\right)}
\]  

(86)

At the open-circuit point, the derivative becomes:
\[
\left.\frac{dV}{dl}\right|_{oc} = -R_s - \frac{aR_{sh}}{a + I_{sat}R_{sh}\exp\left(\frac{V_{oc}}{a}\right)}
\]  

(87)

At the maximum power point, the derivative is:
\[
\left.\frac{dV}{dl}\right|_{mpp} = -\frac{V_{mp}}{I_{mp}}
\]  

(88)

Equating equations (88) and (87):
\[
\frac{V_{mp}}{I_{mp}} = R_s + \frac{aR_{sh}}{a + I_{sat}R_{sh}\exp\left(\frac{V_{mp} + I_{mp}R_s}{a}\right)}
\]  

(89)

Using (3), (4), (87), (88) and (89) with a series of simplifications, the following equations are obtained to extract the five parameters $R_s$, $R_{sh}$, $I_{ph}$, $a$, and the saturation current $I_{sat}$ [45]:

\[
R_s = \left(\frac{V_{mp}}{I_{mp}} - \frac{dV}{dl}\right)_{sc} - \frac{dV}{dl}\left(I_{sc} - I_{mp} + V_{mp}\right) - \frac{dV}{dl}\left(I_{sc} - I_{mp} + V_{mp}\right) - \left(I_{sc} - I_{mp} + V_{mp}\right) - \left(I_{sc} - I_{mp} + V_{mp}\right)
\]  

(90)

\[
R_{sh} = -R_s - \left.\frac{dV}{dl}\right|_{sc}
\]  

(91)

\[
I_{ph} = I_{sc}(1 + \frac{R_s}{R_{sh}})
\]  

(92)

\[
a = \left(\frac{dV}{dl}\right)_{sc} + R_s\left(\frac{dV}{dl}\right)_{oc} + V_{oc}\left(\frac{dV}{dl}\right)_{oc} - \left(\frac{dV}{dl}\right)_{oc}
\]  

(93)

and

\[
I_{sat} = (I_{ph} - V_{oc}R_{sh})/(\exp(V_{oc}/a) - 1)
\]  

(94)

According to the actual measurement of a PV module, the $I$–$V$ curve in the low- and high-voltage zones is smooth and can be represented by straight lines therefore, the slopes of the straight lines can be considered as the differential values of the I-V curve in the two zones as explained in [46], that is:
\[
\frac{dV}{dI} = \frac{\Delta V}{\Delta I} \quad (95)
\]

### 3.5 Method 5

This method which is also based on the manufacturer’s datasheet, uses a reduced set of approximations compared to the previous analytical methods without increasing complexity by incorporating two boundary conditions [40]. The first boundary condition is the derivative of the maximum power with respect to voltage, which is used to derive expressions for the series and shunt resistances. The second condition is the slope at short-circuit point, which is used to determine the ideality factor. Both boundary conditions contributed significantly to improving the accuracy of the parameter extraction process [40].

Referring to equation (3), the term \[\exp(I_{sc}R_s/nV_{th})\] is very close to unity and hence, the diode current is very small compared to either the short-circuit current or the shunt resistance current and hence, may be neglected [39, 47, 48]. This leads to:

\[I_{sc} = I_{ph} - \frac{I_{sc}R_s}{R_{sh}} \quad (96)\]

Therefore, we can write for the photocurrent:

\[I_{ph} = I_{sc} \frac{R_s + R_{sh}}{R_{sh}} \quad (97)\]

Substituting (97) in equation (4), and neglecting the (-1) in the exponential term of the latter, we have:

\[I_{sc} \frac{R_s + R_{sh}}{R_{sh}} = I_{sat} \left[ \exp\left(\frac{V_{ac}}{nN_sV_{th}}\right) \right] + \frac{V_{ac}}{R_{sh}} \quad (98)\]

Solving for the saturation current:

\[I_{sat} = I_{sc} \left( \frac{R_s + R_{sh}}{R_{sh}} \right) \frac{V_{ac}}{R_{sh}} \exp\left(-\frac{V_{ac}}{nN_sV_{th}}\right) \quad (99)\]

Substituting equations (97) and (99) into equation (5) and ignoring the (-1) in the exponential term in the latter:

\[I_{mp} = I_{sc} \frac{R_s + R_{sh}}{R_{sh}} - I_{sc} \left( \frac{R_s + R_{sh}}{R_{sh}} \right) \frac{V_{ac}}{R_{sh}} \exp\left(-\frac{V_{ac}}{nN_sV_{th}}\right) \left[ \exp\left(\frac{V_{mp} + I_{mp}R_s}{nN_sV_{th}}\right) \right] - \frac{V_{mp} + I_{mp}R_s}{nN_sV_{th}} \quad (100)\]

Simplifying:

\[I_{mp} = \frac{I_sR_s + I_{mp}R_{sh} - V_{mp} - I_{mp}R_s}{R_{sh}} - I_sR_s - \frac{V_{mp} - I_{mp}R_s}{R_{sh}} \exp\left(-\frac{V_{mp}}{nN_sV_{th}}\right) \quad (101)\]

This may be re-arranged as:

\[I_{mp} = (I_{sc} - \frac{V_{mp} + I_{mp}R_s}{R_{sh}}) - (I_{sc} - \frac{V_{ac} - I_{mp}R_s}{R_{sh}}) \left[ \exp\left(\frac{V_{mp} + I_{mp}R_s}{nN_sV_{th}}\right) \right] \quad (102)\]

Consider the expression for the derivative equation (6) which is valid at any point on the I-V curve. At the MPP and using equation (10), we can write:

\[\frac{I_{mp}}{V_{mp}} = \frac{I_{sat}}{nN_sV_{th}} \left[ 1 - I_{mp} \frac{R_s}{V_{mp}} \right] \left[ \exp\left(\frac{V_{mp} + I_{mp}R_s}{nN_sV_{th}}\right) \right] + \frac{1}{R_{sh}} \frac{V_{mp}}{V_{mp}} \quad (103)\]
Substituting (97), (99) and (102) in (103):

\[
\frac{I_{mp}}{V_{mp}} = \frac{1}{nN_sV_{th}} \left( I_{mp}(R_s + R_{th}) - V_{oc} \right) - \frac{1}{R_{th}V_{mp}} \left( \exp \left( \frac{V_{mp} + I_{mp}R_s - V_{oc}}{nN_sV_{th}} \right) \right) \left( \frac{1}{R_{th}V_{mp}} \right) + \frac{1}{R_{th}V_{mp}} \left( \frac{1}{R_{th}} \right)
\]

Using equations (97) and (102), we can re-write equation (104) as:

\[
I_{mp} + V_{mp} \left( \frac{1}{R_{th}V_{mp}} \right) \left( \frac{1}{R_{th}} \right) \left( \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \right) \exp \left( \frac{V_{mp} + I_{mp}R_s - V_{oc}}{nN_sV_{th}} \right) = 0
\]

From equation (105), an expression for the shunt resistance may be obtained as follows:

\[
I_{mp} \left( \frac{1}{R_{th}} \right) \left( \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \right) \exp \left( \frac{V_{mp} + I_{mp}R_s - V_{oc}}{nN_sV_{th}} \right) = -V_{mp} \left( \frac{1}{R_{th}} \right) \left( \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \right) \exp \left( \frac{V_{mp} + I_{mp}R_s - V_{oc}}{nN_sV_{th}} \right) - V_{mp} \left( \frac{1}{R_{th}} \right) \left( \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \right) \exp \left( \frac{V_{mp} + I_{mp}R_s - V_{oc}}{nN_sV_{th}} \right) = 0
\]

Multiplying equation (106) by \( \frac{nN_sV_{th}}{I_{mp}} \) and re-arranging:

\[
\left( \frac{nN_sV_{th}}{I_{mp}} \right) I_{mp} + \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) = \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) - I_{mp}R_s \exp(x) = \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) - \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) = 0
\]

Let \( x \) be defined as:

\[
x = \frac{V_{mp} + I_{mp}R_s - V_{oc}}{nN_sV_{th}}
\]

Hence, (107) becomes:

\[
R_{th} \left( \frac{nN_sV_{th}}{I_{mp}} \right) I_{mp} + \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) - I_{mp}R_s \exp(x) = \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) - \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) = 0
\]

Simplifying:

\[
R_{th} \left( \frac{nN_sV_{th}}{I_{mp}} \right) I_{mp} + \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) - I_{mp}R_s \exp(x) = \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) - \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) = \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) - \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) = 0
\]

Re-arranging:

\[
R_{th} \left( \frac{nN_sV_{th}}{I_{mp}} \right) I_{mp} + \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) - I_{mp}R_s \exp(x) = \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) - \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) = \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) - \frac{I_{mp}(R_s + R_{th}) - V_{oc} + I_{mp}R_s}{nN_sV_{th}} \exp(x) = 0
\]

Solving for the shunt resistance

\[
R_{th} = \frac{nN_sV_{th} \left( \frac{V_{mp} - I_{mp}R_s}{nN_sV_{th}} \right) + \left( \frac{V_{mp} - I_{mp}R_s}{nN_sV_{th}} \right) \exp(x) - nN_sV_{th} \exp(x) + \left( \frac{V_{mp} - I_{mp}R_s}{nN_sV_{th}} \right) \exp(x)}{nN_sV_{th} \left( \frac{V_{mp} - I_{mp}R_s}{nN_sV_{th}} \right) + \left( \frac{V_{mp} - I_{mp}R_s}{nN_sV_{th}} \right) \exp(x) - nN_sV_{th} \exp(x) + \left( \frac{V_{mp} - I_{mp}R_s}{nN_sV_{th}} \right) \exp(x)}
\]
Using the definition of $x$ in equation (108), we can re-write equation (102) as:

$$R_{sh} [I_{mp} - I_{sc} + I_{sc} \exp(x)] = (V_{oc} - I_{sc} R_{s}) \exp(x) - V_m - I_{mp} R_s + I_{sc} R_s$$  \hfill (113)

Substituting the value of the shunt resistance from equation (112) into equation (113), we obtain:

$$\frac{nN_s V_i (V_{mp} - I_{mp} R_s) - (V_{oc} - I_{sc} R_s) \exp(x) [I_{mp} - I_{sc} \exp(x)]}{[nN_s V_i (V_{mp} - I_{mp} R_s)]} = (V_{oc} - I_{sc} R_s) \exp(x) - V_m - I_{mp} R_s + I_{sc} R_s$$  \hfill (114)

Cross multiplying and simplifying, the above may be re-arranged as:

$$nN_s V_i (V_{mp} - I_{mp} R_s) (I_{mp} - I_{sc}) + nN_s V_i I_{mp} V_{mp} + nN_s V_i I_{mp}^2 R_s - nN_s V_i I_{mp} I_{sc} R_s = (V_{mp} - I_{mp} R_s) (V_{oc} - I_{sc} R_s) \exp(x) - nN_s V_i (V_{mp} - I_{mp} R_s) I_{sc} \exp(x)$$

$$+ nN_s V_i I_{mp} (V_{oc} - I_{sc} R_s) \exp(x) + (V_{mp} - I_{mp} R_s) V_{mp} I_{sc} \exp(x) + (V_{mp} - I_{mp} R_s) I_{sc}^2 R_s \exp(x)$$  \hfill (115)

The left-hand side of equation (115) may be simplified to:

$$nN_s V_i (V_{mp} - I_{mp} R_s) (I_{mp} - I_{sc}) + nN_s V_i I_{mp} V_{mp} + nN_s V_i I_{mp}^2 R_s - nN_s V_i I_{mp} I_{sc} R_s = nN_s V_i (2I_{mp} - I_{sc})$$  \hfill (116)

The right-hand side of equation (115) may be reduced to:

$$\left[(V_{mp} I_{sc} + V_{oc} (I_{mp} - I_{sc}))(V_{mp} - I_{mp} R_s) - nN_s V_i (V_{mp} I_{sc} - V_{oc} I_{mp})\right] \exp\left(\frac{V_{mp} + I_{mp} R_s - V_{oc}}{nN_s V_i}\right)$$  \hfill (117)

Therefore, equation (115) simplifies to:

$$\exp\left(\frac{V_{mp} + I_{mp} R_s - V_{oc}}{nN_s V_i}\right) = \frac{nN_s V_i (2I_{mp} - I_{sc})}{(V_{mp} I_{sc} + V_{oc} (I_{mp} - I_{sc}))(V_{mp} - I_{mp} R_s) - nN_s V_i (V_{mp} I_{sc} - V_{oc} I_{mp})}$$  \hfill (118)

Combining equations (102) and (118) an alternative expression for the shunt resistance is obtained as:

$$R_{sh} = \frac{(V_{mp} - I_{mp} R_s)(V_{mp} - R_s (I_{sc} - I_{mp}) - nN_s V_i)}{(V_{mp} - I_{mp} R_s)(I_{sc} - I_{mp}) - nN_s V_i}$$  \hfill (119)

Using the above expression for the shunt resistance, i.e. equation (119), an expression for the ideality factor can be derived as follows:

$$nN_s V_i = \frac{(V_{mp} - I_{mp} R_s)(V_{mp} - (I_{sc} - I_{mp})(R_{sh} + R_s))}{V_{mp} - I_{mp}(R_{sh} + R_s)}$$  \hfill (120)

The expression in (15) may be re-expressed as:

$$\frac{R_{sh}}{R_{sh}} - 1 + \frac{R_{sh} - R_s}{nV_{th}} \exp\left(\frac{I_{sc} R_s}{nV_{th}}\right) = 0$$  \hfill (121)

Simplifying, we obtain:

$$\frac{1}{R_{sh}} - \frac{1}{(R_{sh} - R_s)} + \frac{I_{sc} R_s}{nV_{th}} \exp\left(\frac{I_{sc} R_s}{nV_{th}}\right) = 0$$  \hfill (122)
Ignoring the exponential term, we obtain:

\[ R_{sho} = R_{sh} + R_s \] (123)

Substituting equation (123) into equation (120) we obtain the expression given in [40] as:

\[ nN_fV_f = \frac{(V_{mp} - I_{mp}R_s)(V_{mp} - (I_{sc} - I_{mp})R_{sho})}{V_{mp} - I_{mp}R_{sho}} \] (124)

Substituting equation (124) into (118) we obtain an explicit and closed form expression for the series resistance as:

\[ R_s = \frac{V_{mp} [\alpha - \beta] + V_{oc} \beta}{I_{mp} [\alpha + \beta]} \] (125)

where

\[ \alpha = (V_{mp} + (I_{mp} - I_{sc})R_{sho}) \ln(\frac{V_{mp} + I_{sc} + (I_{mp} - I_{sc})R_{sho}}{V_{oc} - I_{sc}R_{sho}}) \] (126)

and

\[ \beta = V_{mp} - I_{mp}R_{sho} \] (127)

Finally, the slopes of the I-V curve at the short-circuit and open-circuit points may be estimated as [46]:

\[ R_{sho} = C_{sh} \frac{V_{oc}}{I_{sc}} \] (128)

and

\[ R_{so} = C_s \frac{V_{oc}}{I_{sc}} \] (129)

where, for silicon, \( C_{sh} = 34.49692 \) and \( C_s = 0.11175 \).

3.6 Method 6

This method presented a unique strategy for developing the analytical expressions required for the extraction of the parameters of the single-diode model [49]. The method is also based on using manufacturer’s datasheet but does not require the slopes of the I-V curve. Two approaches are used in this method: The first is based on developing a relationship between the modified ideality factor and the open-circuit voltage making use of the voltage and current temperature coefficients. The second approach depends on the simplified Lambert-W function of the single-diode model to extract the parameters of the SDM [50].

Using the open-circuit voltage of equation (4) and after neglecting the shunt resistance, a new expression that connects the modified ideality factor and the open-circuit voltage at STC is given as:

\[ \delta_{STC} = \frac{a_{sc}}{V_{oc,STC}} = \frac{1 - T_{STC} \mu_{oc}}{50.1 - T_{STC} \mu_{oc}} \] (130)

In this method the modified ideality factor is assumed to vary linearly with temperature but is independent of insolation. For any arbitrary temperature, equation (130) is adjusted as:

\[ \delta(T) = \frac{a(T)}{V_{oc}(T)} = a_{STC} \frac{V_{oc,STC}}{V_{oc}} \frac{T}{T_{STC}} \] (131)
Using (3), (4), (5), (8) and (130), the parameters of the SDM can be extracted numerically. The method relies on using equations presented in [50], which correlate the maximum power point with the SDM parameters using the Lambert W-function and properties of the ideal model to extract the five model parameters as follows:

\[
a_{sc} = \delta_{STC} V_{oc,STC}
\]

\[
R_s = \frac{a_{SC}(w_{STC} - 1) - V_{mp}}{I_{mp}}
\]

\[
R_{sh} = \frac{a_{SC}(w_{STC} - 1)}{(1 - \frac{1}{w_{STC}})I_{STC} - I_{mp}}
\]

\[
I_{ph} = (1 + R_s / R_{sh})I_{mp}
\]

\[
I_{sat} = I_{ph} \exp(-1 / \delta_{STC})
\]

Where the parameter \( \delta_{STC} \) is estimated using equation (130) and \( w_{STC} \) is given as:

\[
w_{STC} = W\left(\frac{1}{a_{SC} w_{STC} + 1}\right)
\]

All the mathematical derivations of (130) - (137) can be found in references [49] and [50].

4. Results and Discussion

To synthesize the results of the analytical methods described above, software has been developed using MATLAB to extract the five parameters of the single-diode model for different PV modules. Similar software has also been developed to extract the same parameters using two numerical methods: the first is based on the Newton-Raphson algorithm and uses the initialization given in [34], whilst the second is based on an iterative solution procedure [14]. In order to preserve generality when comparing various methods, three PV modules of different PV technologies were used in the investigation: The multicrystalline Kyocera KC200GT [51], monocrystalline Lorentz LC50-12M [52], and thin film Sanyo 180BA19 [53]. The datasheet parameters of these test modules are summarized in Table 1.

The results for the analytical and numerical methods are shown in Tables 2 to 4. It is evident from Table 2, that the reference results of the iterative [14] and the numerical method [34] are close as expected. For the monocrystalline and thin-film PV modules used in this investigation, the Newton-Raphson method failed to converge, see Tables 3 and 4, demonstrating the convergence difficulties that can accompany numerical methods. From Table 2, 3, and 4, methods 1 and 5 outperform all other analytical methods and are most accurate in the case of multi and monocrystalline technologies. These two methods also offer simpler mathematical formulation. They both depend on the slope of the I-V curve with the difference that method 5 uses the slope at the MPP for the main equation instead of the slope at the open-circuit voltage point. Methods 2 and 3 showed degraded accuracy compared to methods 1 and 5 and can result in higher and unrealistic values for the ideality factor when used with thin-film technologies. These two methods have been formulated by neglecting some model parameters to simplify the modelling process, resulting in higher than normal values for the ideality factor.

Method 4 suffers a marked inaccuracy in estimating the ideality factor and saturation current for all three PV technologies. The values of the series and shunt resistances are also unrealistic.
Method 6 depends on a procedure that is entirely different to all other methods. It results in reduced values of the ideality factor and saturation current. The value of the ideality factor is limited to $1 \pm 5\%$. The reduction in the ideality factor and the saturation current have an adverse effect on the accuracy of estimating the values of the series and shunt resistances.

However, it is a matter of fact that there are different combinations of the five parameters of the SDM whose I-V curve pass through the same salient points (SC, OC, and MPP) which does not necessarily imply that all these curves represent physical meaning [54]. Therefore, to verify the performance of the analytical methods to represent the behaviour of PV modules, the characteristic curves for the KC200GT module were plotted for different combination of parameters alongside those obtained using numerical methods. For example, Methods 1 and 5 outperformed Methods 2 and 3 for the parameter extraction process. However, Methods 2 and 3 outperformed Methods 1 and 5 in presenting the characteristic curves as shown in Figures 5 and 6 under STC conditions.

Methods 1 and 5 exhibit similar performance, particularly in the higher current region of the I-V curve since both are based on the slope of the I-V curve in this region as shown in Figure 6. Method 4 slightly underestimates the I-V curve in the high current region, since it is derived on the assumption of a flat line in this region, as shown in Figure 7. Method 6 demonstrated good agreement with the iterative method as illustrated in Figure 8. All methods resulted in similar MPP except Method 4 which resulted in slightly higher peak power.

### Table 1. Parameters for the Multi-crystalline (Kyocera KC200GT).

<table>
<thead>
<tr>
<th>Parameters</th>
<th>KC200GT</th>
<th>LC50-12M</th>
<th>180BA19</th>
</tr>
</thead>
<tbody>
<tr>
<td>$I_{sc}$ (A)</td>
<td>8.21 A</td>
<td>3.2 A</td>
<td>3.65 A</td>
</tr>
<tr>
<td>$V_{oc}$ (V)</td>
<td>32.9 V</td>
<td>22.5 V</td>
<td>66.4 V</td>
</tr>
<tr>
<td>$I_{mp}$ (A)</td>
<td>7.61 A</td>
<td>2.9 A</td>
<td>3.33 A</td>
</tr>
<tr>
<td>$V_{mp}$ (V)</td>
<td>26.3 V</td>
<td>17.2 V</td>
<td>54 V</td>
</tr>
<tr>
<td>$\mu_{oc}$ (V/°C)</td>
<td>-1.23×10-1</td>
<td>-7.88×10-2</td>
<td>-173×10-3</td>
</tr>
<tr>
<td>$\mu_{sc}$ (A/°C)</td>
<td>3.18×10-3</td>
<td>2.88×10-3</td>
<td>1.01×10-3</td>
</tr>
<tr>
<td>$N_s$</td>
<td>54</td>
<td>36</td>
<td>96</td>
</tr>
</tbody>
</table>

### Table 2. Parameters for the Multicrystalline (Kyocera KC200GT).

<table>
<thead>
<tr>
<th>Method</th>
<th>$n$</th>
<th>$R_s$</th>
<th>$R_{sh}$</th>
<th>$I_{sat}$</th>
<th>$I_{ph}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Method 1</td>
<td>1.08317</td>
<td>0.27077</td>
<td>124</td>
<td>2.4885×10-9</td>
<td>8.22793</td>
</tr>
<tr>
<td>Method 2</td>
<td>1.81764</td>
<td>infinite</td>
<td>infinite</td>
<td>1.78074×10-5</td>
<td>8.21</td>
</tr>
<tr>
<td>Method 3</td>
<td>1.40991</td>
<td>0.19455</td>
<td>infinite</td>
<td>4.09919×10-7</td>
<td>8.21</td>
</tr>
<tr>
<td>Method 4</td>
<td>0.65008</td>
<td>0.39999</td>
<td>82.5508</td>
<td>1.14541×10-15</td>
<td>8.24978</td>
</tr>
<tr>
<td>Method 5</td>
<td>0.88423</td>
<td>0.38033</td>
<td>123.62</td>
<td>1.81544×10-11</td>
<td>8.23526</td>
</tr>
<tr>
<td>Method 6</td>
<td>1.00258</td>
<td>0.30567</td>
<td>130.466</td>
<td>4.43777×10-10</td>
<td>8.22924</td>
</tr>
<tr>
<td>Numerical [14]</td>
<td>1.3</td>
<td>0.2283</td>
<td>572.124</td>
<td>9.89443×10-8</td>
<td>8.21329</td>
</tr>
</tbody>
</table>

### Table 3. Parameters for the Monocrystalline (Lorentz LC50-12M).

<table>
<thead>
<tr>
<th>Method</th>
<th>$n$</th>
<th>$R_s$</th>
<th>$R_{sh}$</th>
<th>$I_{sat}$</th>
<th>$I_{ph}$</th>
</tr>
</thead>
<tbody>
<tr>
<td>Method 1</td>
<td>2.0361</td>
<td>0.19455</td>
<td>206</td>
<td>2.0109×10-5</td>
<td>8.21</td>
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<tr>
<td>Method 2</td>
<td>2.41979</td>
<td>0</td>
<td>infinite</td>
<td>1.3832×10-4</td>
<td>3.2</td>
</tr>
<tr>
<td>Method 3</td>
<td>1.76187</td>
<td>0.4969</td>
<td>infinite</td>
<td>3.2464×10-6</td>
<td>3.2</td>
</tr>
</tbody>
</table>
Table 4. Parameters for the Thin film (Sanyo 180BA19).

<table>
<thead>
<tr>
<th>Method</th>
<th>Parameter</th>
<th>( n )</th>
<th>( R_s )</th>
<th>( R_{sh} )</th>
<th>( I_{sat} )</th>
<th>( I_{ph} )</th>
</tr>
</thead>
<tbody>
<tr>
<td>Method 1</td>
<td></td>
<td>0.55767</td>
<td>2.69004</td>
<td>2329</td>
<td>3.99938×10^{-21}</td>
<td>3.65422</td>
</tr>
<tr>
<td>Method 2</td>
<td></td>
<td>2.06455</td>
<td>0</td>
<td>( \infty )</td>
<td>7.9701×10^{-6}</td>
<td>3.65</td>
</tr>
<tr>
<td>Method 3</td>
<td></td>
<td>2.11483</td>
<td>-0.09068</td>
<td>( \infty )</td>
<td>1.08651×10^{-5}</td>
<td>3.65</td>
</tr>
<tr>
<td>Method 4</td>
<td></td>
<td>0.95729</td>
<td>1.13544</td>
<td>313.85129</td>
<td>2.13594×10^{-12}</td>
<td>3.6632</td>
</tr>
<tr>
<td>Method 5</td>
<td></td>
<td>1.95145</td>
<td>0.10657</td>
<td>2328.8934</td>
<td>3.71538×10^{-6}</td>
<td>3.65017</td>
</tr>
<tr>
<td>Method 6</td>
<td></td>
<td>0.95589</td>
<td>1.41883</td>
<td>327.95525</td>
<td>2.1766×10^{-12}</td>
<td>3.66579</td>
</tr>
<tr>
<td>Iterative</td>
<td></td>
<td>1.8</td>
<td>0.27300</td>
<td>1181.56509</td>
<td>1.17348×10^{-12}</td>
<td>3.65084</td>
</tr>
<tr>
<td>Numerical method [19]</td>
<td>No convergence</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Figure 5. Comparison between the I-V (left) and P-V (right) curves obtained using Methods 2 and 3 with those obtained using numerical method for the KC200GT module.
Figure 6. Comparison between the I-V (left) and P-V (right) curves obtained using Methods 1 and 5 with those obtained using numerical method for the KC200GT module.

Figure 7. Comparison between the I-V (left) and P-V (right) curves obtained using Method 4 with those obtained using numerical method for the KC200GT module.

Figure 8. Comparison between the I-V (left) and P-V (right) curves obtained using Method 6 with those obtained using numerical method for the KC200GT module.
5. Conclusion

The paper presented a detailed mathematical analysis and comparative evaluation of the performance of the commonly reported analytical methods for parameters extraction of the single-diode model of a PV module. Six prevalent methods have been explored and deployed to extract the parameters of three PV modules of different PV technologies. The extracted parameters were compared with reference values extracted using numerical and iterative methods. It has been confirmed that while some methods may not be the most accurate in extracting the parameters, e.g. Methods 2 and 3, they can still provide good agreement between their I-V curves and those obtained numerically. The reduced accuracy of Method 2 in the parameter extraction process could be attributed to the fact that it neglects the shunt resistance which can reduce the accuracy particularly at low levels of insolation. Methods 1 and 5 use the slope of the I-V curve about the short-circuit point which led to both methods having similar results. Method 4 resulted in slight overestimation in the high current region of the I-V curve since it approximated the I-V curve by a straight line in this region to simplify the model equations. Method 6 resulted in good agreement with the iterative I-V curve. It is recommended that additional extensive investigation should study the dependence of the analytical methods on the technology and different materials of PV modules.

References


