

Dynamics of SEAIQR Model with Saturated type Treatment: A case Study of Spain COVID-19

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Abstract:

Background. Outbreak of the Covid-19 is now an ongoing global health emergency. At the end of December 2019, the first infection was reported in Wuhan and the world did not pay attention to this extremely contaminated disease and plucked to react rapidly. The World is in an vulnerable state in disease spreading, facing a great loss of lives and socio-economic aspects also. That is why we have proposed a potential mathematical model with data analysis to predict and control the outcome of this pandemic.

Methods. The model presented the epidemic dynamics of multiple compartments. We collected available online data of Spain. In primary step, we estimated the parameters using either the data analysis or reference papers. Then we did the data fitting analysis in comparison with the outcome of our mathematical results. The results of the system depended not only the parameters also on social consciousness.

Results. It is found that disease progression in this model is determined by the basic reproductive ratio, R_0 , the actual epidemic of R_0 and effective $R(t)$ of each day. If $R_0 > 1$, the number of latently infected individuals grows exponentially; endemic solution is stable while infection rate decays if $R_0 < 1$. The optimal control theory stated that vaccination and treatment strategies are highly effective for reducing both susceptible and infected population and to increase the recover rate high. In Spain, after state of alarm (quarantine) on 14 March 2020, reported cases increasing for 13 days only and from the 14th day, daily reported cases started to decline albeit with small fluctuation. Our proposed model approximates that the disease in Spain could be fully under control by after July 2020.

Conclusion. Outbreak will be in control of health care system, reduce the death rate and will ensure social-economic stability.

Keywords: SEAIQR model; stability analysis; COVID-19; optimal control; model validation.

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1 Introduction

In COVID-19 pandemic, the whole world were apparently unprepared or might did not pay well attention at the earlier stage after spreading in Wuhan, China. The disease caused by SARS-CoV-2 is now having a devastating impact across the world. At the current stage, almost all countries and territories are a victim with 4,269,782 reported cases with 287,529 deaths on May 12, 2020 and this is a global health emergency [1, 2]. Compared to reported cases, the recovery rate is still very slow.

The outbreak of severe acute respiratory syndrome SARS, appeared in November 2002 in China. A newly emerged coronavirus was responsible for this outbreak which is known as SARS-CoV [3]. Various experimental data indicated that wild animals were the source of the SARS. Serological experiment of the people associated with those wild animals revealed that the animal traders consisted larger amount of IgG, an antibody active against the SARS-CoV compared to those who were the traders of vegetables [4]. Evidence showed that 3 out of 4 patients were supposed to have either straight or secondary interaction with the masked palm civets. Among these three patients, one of them was waitress in TDLR restaurant where the animal was kept for bizarre dishes, another one took his meal in that restaurant and the dining table was close to the cage where the animal was kept and the third patient took his meal in another adjacent restaurant. It is remarked that this study did not say anything about the natural reservoir of the virus [5, 6]. Later study revealed that several species of horseshoe bats were the natural reservoir of SARS like-CoV. Among four species, *R. pearsoni* and *R. macrotis* showed affirmative data in serological and PCR test and the remaining species *R. pussilus* and *R. ferrumequinum* showed a positive result in either PCR or serological test [7].

Middle East respiratory syndrome coronavirus MERS-CoV took place in Saudi Arabia in 2012 where dromedary camels were thought to be the intermediate source for the transmission of the virus [8]. Research data suggested that about 55% of primary victims of MERS-CoV had direct contact with the dromedary camels or foods of camels and the remaining 45% portion of the victims did not have any evidence of contact with the camels or infected individuals. Hence still its a question, how they got infected by the virus was unknown [9]. Camels were declared as the zoonotic host for human infection, evidence suggested that bats were the natural reservoir host of the virus [10]. Small genomic sequence analysis of bat acknowledged bat as the natural reservoir of MERS-CoV [11].

As a continuation, the virus SARS-CoV-2 was related to the coronavirus responsible for the SARS outbreak of 2003, and the transmission of the virus was also zoonotic [12]. In March 13, 2020, the World Health Organization considered Europe as hot spot of the 2019–20 coronavirus pandemic, and by April 24 (2020), the maximum part of the Globe were affected by the outbreak [1, 2, 13]. The daily reported cases were being doubled over periods of 2 to 4 days by country across Europe, North-America, Asia [14], and specially the phenomenon was drawn a lot of attention for these zones.

The present hypothesis about SARS-CoV-2 is that the outbreak started in bats, then moved to another unidentified species before being transmitted to humans [6, 15]. Additionally, in recent time COVID-19 reinfection is drawing people's attention. The World Health Organization (WHO) investigating reports of COVID-19 reinfection and the organization is working with clinical experts to get more information on this matter [16]. In South Korea 91 patients who had tested positive, and declared negative after two consecutive tests, tested positive again while 14% of recovered coronavirus patients in China have tested positive again [16, 17].

Since the world is dealing with a highly contagious disease without medication, right now the only effectual way for us to protect is prevention. Social and physical distancing, lock-down and testing are some measures prescribed by WHO to control the outbreak. Data analysis and mathematical modelling are one of the core component to study these undertaken polices for the best outcome. The mathematical growth map of COVID-19 was introduced using two well known growth functions and established that the growth is exponential [18]. In mathematical modelling, some recent studies provided different guidelines by introducing basic reproduction number, education and socio-economic index and lock-down strategies [19, 20, 21, 22, 23]. A recent study developed a COVID-19 epidemic model with five compartments which analyzed both theoretically and numerically by evaluating the equilibrium points and their stability analysis. The dynamics was shown for a different group of the population over time and the findings was based on the sensitivity analysis; highlighted the role of outbreak of the virus that might be useful to avoid a massive collapse a developing country, Bangladesh [22]. In the literature, an ordinary differential equation (ODE) model studied to drag down the spread of COVID-19, with the influence of social consciousness towards the epidemic; where the prescribed model determines the ongoing social response project the scenario of COVID-19 handled with a higher social consciousness level [23]. The dynamics of SEIR model and its optimal policy to control the disease in Italy were studied in [24].

For any data-driven epidemic models, the basic reproduction number, R_0 , is an important measure of the strength of any pandemics. In susceptible population, R_0 is defined as the number of secondary infections generated by one primary case. For any outbreak of disease, if the estimate of R_0 is in early stage then the guidance of control measures can be significant. To calculate the basic reproductive number, we have two phased (i) R_0 for the actual epidemics estimated by parameters, and (ii) the analysis of it's time evolution, $R(t)$, since it changes continuously during the outbreaks [25, 26].

In this paper, we have studied the current scenario of the world and the European country Spain, as a special case since this territory have higher socio-economic index [13, 27, 28]. The study presents an analysis of various control mechanisms using mathematical model and abridged data fitting based on ongoing viral epidemic of the world. The key objectives of this study are as follows:

- We will work with real-life available discrete data of Spain to understand the cases

and project the control of the infection.

- We expect that the prediction of controlling measure of COVID-19 will be able to validate the dynamics of SEAIQR model to get better accuracy of results.

The main novelties in this study are

1. Analytical and Theoretical results are established and presented in terms of reproductive ratio, R_0 . We have obtained the stable DFE for $R_0 < 1$ and endemic solution as long as $R_0 > 1$.
2. Using central manifold theory, we have established the results for backward bifurcation while $R_0 \equiv 1$ with some other conditions.
3. The basic reproduction number for actual epidemic, R_0 and time evolution outbreak, $R(t)$ are calculated and their respective results are established.
4. Numerical demonstrations validated the analytic outcomes.
5. Using optimal control theory, it is concludes that vaccination and treatment are highly effective and gives more number of recovered population.
6. Data analysis and model results predict the time boundary to control the epidemic in Spain.
7. Besides data analysis, the proposed quarantine model shows that human population can control and protect the spread of infectious diseases by creating social isolation, hospitalization, lock-down and physical distancing.

The paper is organized as follows: Mathematical Model is elaborately discussed in Section 2. Positivity and boundedness of solution including auxiliary results are described in subsection 3. Stability analysis and bifurcation analysis are prescribed in Section 4. Section 5 is accomplished the data analysis in comparison with model solution using parameter estimation and model validation with further prediction to control the endemic, as a case study in Spain. We have studied the optimal control theory for vaccination and treatment strategies to increase the recovered rate in Section 6. Finally, Section 7 outlines the summary and discussion of the results.

In the following section, we will discuss our mathematical model and formulation of the model elaborately.

2 Model Formulation

Scientifically it is proven and well established that mathematical and computational models can help to understand biological scenarios and can predict epidemiological aspects. In

Table 1: Model parameters and their descriptions

Notation	Interpretations	Notation	Interpretations
Λ	Recruitment rate of S class	δ_1	Infection rate of A class
b	Delay in treatment of each individual	μ_1	Infection rate of Q class
a	Cure rate of treatment	d	Death rate due to infection
α	Contact rate between S and A class	ϵ	Natural death rate
β	Contact rate between S and I class	γ_4	Recovery rate of E class
γ_1	Transmission rate of E class to A class	δ_2	Recovery rate of A class
γ_2	Transmission rate of E class to Q class	μ_2	Recovery rate of Q class
γ_3	Infection rate of E class	σ_1	Recovery rate of I class

the proposed model, let the total population is divided into six compartment those are the susceptible population (S), exposed population (E), asymptomatic population (A), quarantine population (Q), infected population (I), and recovered population (R). We assume that the disease COVID-19 spreads mainly from A and I compartments and the rate of incidence is of the form $(\alpha A + \beta I)S$. Since a large number of persons is infecting by this disease in very short time but the number of hospital is limited. Due to limited medical facility we consider the rate of treatment is non-linear and of the form $\frac{aI}{1+bI}$. The flow diagram of the proposed model is given in Figure 1 and the corresponding mathematical equations are given in (2.1).

$$\begin{cases} \frac{dS}{dt} = \Lambda - (\alpha A + \beta I)S - \epsilon S \\ \frac{dE}{dt} = (\alpha A + \beta I)S - (\gamma_1 + \gamma_2 + \gamma_3 + \gamma_4 + \epsilon)E \\ \frac{dA}{dt} = \gamma_1 E - (\delta_1 + \delta_2 + \epsilon)A \\ \frac{dQ}{dt} = \gamma_2 E - (\mu_1 + \mu_2 + \epsilon)Q \\ \frac{dI}{dt} = \delta_1 A + \gamma_3 E + \mu_1 Q - (\epsilon + d + \sigma_1)I - \frac{aI}{1+bI} \\ \frac{dR}{dt} = \gamma_4 E + \delta_2 A + \mu_2 Q + \sigma_1 I - \epsilon R + \frac{aI}{1+bI} \end{cases} \quad (2.1)$$

with the initial conditions $S(0) > 0$, $E(0) \geq 0$, $A(0) \geq 0$, $Q(0) \geq 0$, $I(0) > 0$, $R(0) \geq 0$, where the interpretation of parameters is presented in Table 1.

In the next section we shall establish the positivity and boundedness of solution of (2.1). Positivity of solution in biological model is most important because it establish the non-negativity of the solution curve i.e. non-negativity of the considered compartments.

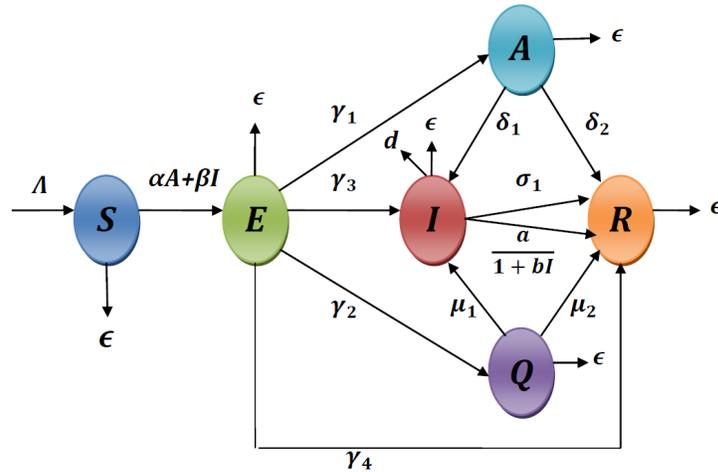


Figure 1: Flow and Model diagram of SEAIQR.

3 Positivity and Boundedness of Solutions

Consider the first equation of (2.1) and multiply it by integrating factor $\exp(\alpha A(t) + \beta I(t) + \epsilon)$, integrating and using the initial condition we get

$$S(t) = \exp(-(\alpha A(t) + \beta I(t) + \epsilon)) \left\{ S(0) + \Lambda \int_{t_0}^t \exp(\alpha A(u) + \beta I(u) + \epsilon) du \right\}$$

It is obvious from the above expression $S(t) \geq 0$. Using the similar arguments it can be easily shown that other variables are also non-negative.

To prove the boundedness of the solutions add the equations in (2.1) and using the notation for total population, $N(t) = S(t) + E(t) + A(t) + Q(t) + I(t) + R(t)$, we have

$$\begin{aligned} \frac{dN}{dt} &= \Lambda - \epsilon N - dI \\ &\leq \Lambda - \epsilon N \end{aligned}$$

Integrating and using the initial conditions and \limsup for $t \rightarrow \infty$, we get

$$N(t) \leq \frac{\Lambda}{\epsilon}.$$

Thus we can summarize the above results in the following theorem:

Theorem 1. *All the solutions are feasible and the set $\Omega = \{(S, E, A, Q, I, R) \in \mathbb{R}_+^6 : S + E + A + Q + I + R \leq \frac{\Lambda}{\epsilon}\}$ is a positively invariant set for the system (2.1).*

In the next section we shall establish the existence of equilibrium points, the expressions of the basic reproduction number (R_0).

4 Stability and Bifurcation Analysis

In this section we first find the disease free equilibrium point (DFE) and then using the next generation matrix approach the basic reproduction number will be found. The stability of the equilibrium point will be discussed in terms the basic reproductive ratio. Then backward bifurcation will be discussed.

4.1 Basic reproduction number, DFE and EEP

The basic reproduction number is denoted by R_0 is defined as expected number of secondary infections that a single infected individual generates [29, 30]. In epidemic system it has great importance as it is the indicator of persistence or irradiation of disease. Using next generation matrix [30, 31] the basic reproduction of (2.1) is found here. Since the DFE is $E_0 \left(\frac{\Lambda}{\epsilon}, 0, 0, 0, 0, 0 \right)$ and hence the basic reproduction number can be found using the analytical approach.

Let $\mathcal{F} = \begin{pmatrix} S(A\alpha + I\beta) \\ 0 \\ 0 \\ 0 \end{pmatrix}$ represents the rate of new infection matrix and

$\mathcal{V} = \begin{pmatrix} D_0 E \\ AD_1 - \gamma_1 E \\ D_2 Q - E\gamma_2 \\ -\gamma_3 E - \delta_1 A - \mu_1 Q + D_3 J + \frac{aI}{1+bI} \end{pmatrix}$ denotes the transfer rate matrix of the individuals.

Let us we define $F = \frac{\partial \mathcal{F}}{\partial x_j}(E_0)$ and $V = \frac{\partial \mathcal{V}}{\partial x_j}(E_0)$ then the next generation matrix FV^{-1} and the spectral radius of $(FV^{-1})=R_0$ is the basic reproduction number is given below

$$R_0 = \frac{\Lambda\alpha\gamma_1}{\epsilon D_0 D_1} + \frac{\Lambda\beta(D_1 D_2 \gamma_3 + D_1 \gamma_2 \mu_1 + D_2 \delta_1 \gamma_1)}{\epsilon D_0 D_1 D_2 (D_3 + a)},$$

where $D_0 = \epsilon + \gamma_1 + \gamma_2 + \gamma_3 + \gamma_4$, $D_1 = \delta_1 + \delta_2 + \epsilon$, $D_2 = \mu_1 + \mu_2 + \epsilon$, $D_3 = d + \epsilon + \sigma_1$.

Let $E^*(S^*, E^*, A^*, Q^*, I^*, R^*)$ be the endemic equilibrium point (EEP) of the considered system then it satisfies the steady state condition for the system (2.1). Solving the steady equations we obtain $J^* = \frac{A^*(A^* D_0 D_1 \alpha + D_0 D_1 \epsilon - \alpha \gamma_1 \Lambda)}{\beta(\gamma_1 \Lambda - A D_0 D_1)}$, $A^* = \frac{\gamma_1 E^*}{D_1}$, $S^* = \frac{\Lambda}{A^* \alpha + I^* \beta + \epsilon}$, $Q^* = \frac{\gamma_2 E^*}{D_2}$, $R^* = \gamma_4 E^* + \delta_2 A^* + \mu_2 Q^* + \frac{aI^*}{1+bI^*} + \sigma_1 I^*$ and E^* satisfies the equation

$$C_0 x^3 + C_1 x^2 + C_2 x + C_3 = 0 \quad (4.1)$$

where

$$\begin{aligned}
C_0 &= D_0^2 D_1 D_2 \alpha b \beta \gamma_1 \gamma_3 + D_0^2 D_1 \alpha b \beta \gamma_1 \gamma_2 \mu_1 + D_0^2 D_2 D_3 \alpha^2 b \gamma_1^2 + D_0^2 D_2 \alpha b \beta \delta_2 \gamma_1^2 \\
C_1 &= -2D_0 D_1 D_2 \alpha b \beta \gamma_1 \gamma_3 \Lambda - 2D_0 D_1 \alpha b \beta \gamma_1 \gamma_2 \Lambda \mu_1 + 2D_0^2 D_1 D_2 D_3 \alpha b \epsilon \gamma_1 + D_0^2 D_1 D_2 b \beta \delta_2 \epsilon \gamma_1 \\
&\quad - 2D_0 D_2 \alpha b \beta \delta_2 \gamma_1^2 \Lambda - D_0^2 D_1^2 D_2 \beta^2 \gamma_3 - D_0^2 D_1^2 \beta^2 \gamma_2 \mu_1 - 2D_0 D_2 D_3 \alpha^2 b \gamma_1^2 \Lambda + D_0^2 D_1^2 D_2 b \beta \epsilon \gamma_3 \\
&\quad + D_0^2 D_1^2 b \beta \epsilon \gamma_2 \mu_1 - D_0^2 D_1 D_2 D_3 \alpha \beta \gamma_1 - D_0^2 D_1 D_2 a \alpha \beta \gamma_1 - D_0^2 D_1 D_2 \beta^2 \delta_2 \gamma_1 \\
C_2 &= -2D_0 D_1 D_2 D_3 \alpha b \epsilon \gamma_1 \Lambda - D_0 D_1 D_2 b \beta \delta_2 \epsilon \gamma_1 \Lambda - D_0 D_1^2 D_2 b \beta \epsilon \gamma_3 \Lambda + D_1 D_2 \alpha b \beta \gamma_1 \gamma_3 \Lambda^2 \\
&\quad - D_0 D_1^2 b \beta \epsilon \gamma_2 \Lambda \mu_1 + D_1 \alpha b \beta \gamma_1 \gamma_2 \Lambda^2 \mu_1 + 2D_0 D_1 D_2 D_3 \alpha \beta \gamma_1 \Lambda + 2D_0 D_1 D_2 a \alpha \beta \gamma_1 \Lambda \\
&\quad + D_2 \alpha b \beta \delta_2 \gamma_1^2 \Lambda^2 + 2D_0 D_1 D_2 \beta^2 \delta_2 \gamma_1 \Lambda + D_0^2 * D_1^2 D_2 D_3 b \epsilon^2 + D_2 D_3 \alpha^2 b \gamma_1^2 \Lambda^2 \\
&\quad - D_0^2 * D_1^2 D_2 D_3 \beta \epsilon - D_0^2 D_1^2 D_2 a \beta \epsilon + 2D_0 D_1^2 D_2 \beta^2 \gamma_3 \Lambda + 2D_0 D_1^2 \beta^2 \gamma_2 \Lambda \mu_1 \\
C_3 &= (D_0 D_1^2 D_2 D_3 \beta \epsilon \Lambda + D_0 D_1^2 D_2 a \beta \epsilon \Lambda)(1 - R_0).
\end{aligned}$$

It is clear from the expression of coefficients the equation (4.1) may have either two positive roots or no positive root if $R_0 < 1$. For $R_0 > 1$ the number of positive roots is one or three if the positivity condition of J^* is satisfied. Thus when $R_0 < 1$ the model (2.1) have at most two endemic equilibrium points and for $R_0 > 1$ the number of equilibrium points are three or one.

4.2 Stability of disease-free equilibrium state (E_0)

To eradication of disease from the system the stability of the DFE is essential.

Theorem 2. *The DFE will be locally asymptotically stable if $R_0 < 1$ and unstable if $R_0 > 1$.*

Proof. The Jacobian matrix corresponding to the system (2.1) at DFE point $E_0(\Lambda/\epsilon, 0, 0, 0, 0, 0)$ is

$$J(E_0) = \begin{pmatrix} -\epsilon & 0 & -\frac{\Lambda\alpha}{\epsilon} & 0 & -\frac{\Lambda\beta}{\epsilon} & 0 \\ 0 & -D_0 & \frac{\Lambda\alpha}{\epsilon} & 0 & \frac{\Lambda\beta}{\epsilon} & 0 \\ 0 & \gamma_1 & -D_1 & 0 & 0 & 0 \\ 0 & \gamma_2 & 0 & -D_2 & 0 & 0 \\ 0 & \gamma_3 & \delta_1 & \mu_1 & -D_3 - a & 0 \\ 0 & \gamma_4 & \delta_2 & \mu_2 & a + \sigma_1 & -\epsilon \end{pmatrix}.$$

The eigenvalues of the Jacobian matrix $J(E_0)$ are $-\epsilon, -\epsilon, \lambda_1, \lambda_2, \lambda_3, \lambda_4$, where $\lambda_i (i = 1 - 4)$ are the roots of the following equation:

$$P(\lambda) \equiv \frac{\Lambda\alpha\gamma_1}{\epsilon(D_0+\lambda)(D_1+\lambda)} + \frac{\Lambda\beta\gamma_3}{\epsilon(D_0+\lambda)(D_3+a+\lambda)} + \frac{\Lambda\beta\gamma_2\mu_1}{\epsilon(D_0+\lambda)(D_2+\lambda)(D_3+a+\lambda)} + \frac{\Lambda\beta\gamma_1\delta_1}{\epsilon(D_0+\lambda)(D_1+\lambda)(D_3+a+\lambda)} - 1 = 0.$$

Thus $P(0) = R_0 - 1$. Now, we shall discuss following two cases.

Case I: Suppose $R_0 > 1$. Then $P(0) > 0$. Again, $\lim_{\lambda \rightarrow \infty} P(\lambda) = -1$. Here $P(\lambda)$ is a continuous function of λ and so by applying Bolzano theorem on continuous function we have

$P(\lambda_k) = 0$ for some $\lambda_k > 0$. Thus, at least one eigenvalue of the Jacobian matrix $J(E_0)$ must be positive and so the DFE, E_0 is unstable.

Case II: Suppose $R_0 < 1$ which yields $P(0) < 0$.

If possible let us assume that $P(\lambda) = 0$ has at least one root of the form $x + iy$, where $x \geq 0$ and $x, y \in \mathbb{R}$. Then $P(x + iy) = 0$.

Again, $|P(x + iy) + 1|$

$$\begin{aligned} &\leq \frac{\Lambda\alpha\gamma_1}{\epsilon|D_0+\lambda||D_1+\lambda|} + \frac{\Lambda\beta\gamma_3}{\epsilon|D_0+\lambda||D_3+a+\lambda|} + \frac{\Lambda\beta\gamma_2\mu_1}{\epsilon|D_0+\lambda||D_2+\lambda||D_3+a+\lambda|} + \frac{\Lambda\beta\gamma_1\delta_1}{\epsilon|D_0+\lambda||D_1+\lambda||D_3+a+\lambda|} \\ &\leq \frac{\Lambda\alpha\gamma_1}{\epsilon(D_0+x)(D_1+x)} + \frac{\Lambda\beta\gamma_3}{\epsilon(D_0+x)(D_3+a+x)} + \frac{\Lambda\beta\gamma_2\mu_1}{\epsilon(D_0+x)(D_2+x)(D_3+a+x)} + \frac{\Lambda\beta\gamma_1\delta_1}{\epsilon(D_0+x)(D_1+x)(D_3+a+x)} \\ &\leq \frac{\Lambda\alpha\gamma_1}{\epsilon D_0 D_1} + \frac{\Lambda\beta\gamma_3}{\epsilon D_0 (D_3+a)} + \frac{\Lambda\beta\gamma_2\mu_1}{\epsilon D_0 D_2 (D_3+a)} + \frac{\Lambda\beta\gamma_1\delta_1}{\epsilon D_0 D_1 (D_3+a)} = R_0 < 1, \text{ which implies } 1 < 1, \text{ clearly a contradiction.} \end{aligned}$$

Hence, all the roots of the equation $P(\lambda) = 0$ have the form $x + iy$, where $x < 0$ and $x, y \in \mathbb{R}$. Thus, in this case the DFE is locally asymptotically stable.

Hence the theorem is proved. \square

4.3 Backward Bifurcation

In this section, we shall investigate the existence of backward bifurcation of the considered COVID-19 model. Biologically, this type of bifurcation is most important because usually the disease eradication happens when $R_0 < 1$ but in this situation there exists another stable endemic equilibrium point for $R_0 < 1$ and so eradication of the disease depends not only on the value of basic reproduction number but also on the initial number of infection level. When $R_0 = 1$ i.e. when

$$\alpha = \frac{D_0 D_1 D_2 D_3 \epsilon + D_0 D_1 D_2 a \epsilon - D_1 D_2 \beta \gamma_3 \Lambda - D_1 \beta \gamma_2 \Lambda \mu_1 - D_2 \beta \delta_1 \gamma_1 \Lambda}{D_2 (D_3 + a) \Lambda \gamma_1} \equiv \alpha^{[BB]},$$

then one of the eigenvalues of the Jacobian matrix corresponding to the system (2.1) at DFE is zero. Using the Theorem by Castillo-Chavez and Song [29, 31, 33], we shall establish the existence of backward bifurcation of the system (2.1).

Theorem 3. *Suppose $c_3 > 0$ and $c_1 c_2 > c_3$. Then the system (2.1) undergoes the backward bifurcation at $R_0 = 1$ with respect to the parameter α if $\phi > 0$, where c_1, c_2, c_3 and ϕ are defined in the text.*

Proof. First we set $x_1 = S, x_2 = E, x_3 = A, x_4 = Q, x_5 = I$ and $x_6 = R$, then the system (2.1) becomes

$$\begin{cases} \frac{dx_1}{dt} = \Lambda - (\alpha x_3 + \beta x_5)x_1 - \epsilon x_1 \equiv f_1 \\ \frac{dx_2}{dt} = (\alpha x_3 + \beta x_5)x_1 - (\gamma_1 + \gamma_2 + \gamma_3 + \gamma_4 + \epsilon)x_2 \equiv f_2 \\ \frac{dx_3}{dt} = \gamma_1 x_2 - (\delta_1 + \delta_2 + \epsilon)x_3 \equiv f_3 \\ \frac{dx_4}{dt} = \gamma_2 x_2 - (\mu_1 + \mu_2 + \epsilon)x_4 \equiv f_4 \\ \frac{dx_5}{dt} = \delta_1 x_3 + \gamma_3 x_2 + \mu_1 x_4 - (\epsilon + d + \sigma_1)x_5 - \frac{\alpha x_5}{1 + b x_5} \equiv f_5 \\ \frac{dx_6}{dt} = \gamma_4 x_2 + \delta_2 x_3 + \mu_2 x_4 + \sigma_1 x_5 - \epsilon x_6 + \frac{\alpha x_5}{1 + b x_5} \equiv f_6 \end{cases} \quad (4.2)$$

At the DFE E_0 the Jacobian matrix $J(E_0)|_{\alpha=\alpha^{[BB]}}$ has the eigenvalues $0, -\epsilon, -\epsilon$ and other three are the roots of the following cubic:

$$\lambda^3 + c_1\lambda^2 + c_2\lambda + c_3 = 0,$$

where $c_1 = D_0 + D_1 + D_2 + D_3 + a$, $c_2 = D_0D_1 + D_0D_2 + D_0D_3 + D_0a + D_1D_2 + D_1D_3 + D_2D_3 + D_2a + D_1a - \frac{\alpha\gamma_1\Lambda}{\epsilon} - \frac{\beta\gamma_3\Lambda}{\epsilon}$, $c_3 = D_0D_1D_2 + D_0D_1D_3 + D_0D_1a + D_0D_2D_3 + D_0D_2a + D_1D_2D_3 + D_1D_2a - \frac{\beta\gamma_3\Lambda D_1}{\epsilon} - \frac{\alpha\gamma_1\Lambda D_2}{\epsilon} - \frac{\beta\gamma_3\Lambda D_2}{\epsilon} - \frac{\alpha\gamma_1\Lambda D_3}{\epsilon} - \frac{\alpha\gamma_1\Lambda a}{\epsilon} - \frac{\beta\gamma_1\Lambda\delta_1}{\epsilon} - \frac{\beta\gamma_2\Lambda\mu_1}{\epsilon}$.

It is obvious that $c_1 > 0$ and $R_0 = 1$ implies $c_2 > 0$. Hence by the given conditions we can conclude that other three eigenvalues have negative real parts. Thus, we can apply the Theorem by Castillo-Chavez and Song to determine the direction of the bifurcation. Let W and V be the right and left eigenvector of $J(E_0)|_{\alpha=\alpha^{[BB]}}$ corresponding to the zero eigenvalue then $W = (w_1, w_2, w_3, w_4, w_5, w_6)^T$ where $w_1 = -\frac{D_0}{\epsilon}$, $w_2 = 1$, $w_3 = \frac{\gamma_1}{D_1}$, $w_4 = \frac{\gamma_2}{D_2}$, $w_5 = \frac{\gamma_3 w_2 + \delta_1 w_3 + \mu_1 w_4}{D_3 + a}$, $w_6 = \frac{\gamma_4 w_2 + \delta_2 w_3 + \mu_2 w_4 + (a + \sigma_1) w_5}{\epsilon}$ and $V = (v_1, v_2, v_3, v_4, v_5, v_6)$ where $v_1 = 0$, $v_2 = \frac{(D_3 + a)D_2\epsilon}{\Lambda\beta}$, $v_3 = \frac{D_2(D_3 + a + \delta_1)}{D_1}$, $v_4 = \mu_1$, $v_5 = D_2$, $v_6 = 0$.

Now, the coefficient

$$\begin{aligned} \phi &= \sum_{k,i,j=1}^6 v_k w_i w_j \frac{\partial^2 f_k}{\partial x_i \partial x_j} \\ &= \frac{2D_2 ab}{(D_3 + a)^2} \left(\gamma_3 + \frac{\delta_1 \gamma_1}{D_1} + \frac{\mu_1 \gamma_2}{D_2} \right)^2 - \frac{2(D_3 + a)D_0 D_2}{\Lambda\beta} \left\{ \frac{\alpha^{[BB]}\gamma_1}{D_1} + \frac{\beta}{D_3 + a} \left(\gamma_3 + \frac{\delta_1 \gamma_1}{D_1} + \frac{\mu_1 \gamma_2}{D_2} \right) \right\} \end{aligned}$$

and the coefficient

$$\psi = \sum_{k,i=1}^6 v_k w_i \frac{\partial^2 f_k}{\partial x_i \partial \alpha} = \frac{(D_3 + a)D_2\gamma_1}{D_1\beta}.$$

Since the coefficient ψ is obviously a positive number, hence the system (2.1) exhibits the backward bifurcation if $\phi > 0$. Hence the theorem is proved. \square

It is clear from Figure 2 that if we vary the transmission rate of infection (α) from the asymptomatic class, then the system generates two endemic equilibrium points for $R_0^* < R_0 < 1$, where R_0^* is some positive quantity, among them one with lower infection level is unstable along with the stable DFE and other with higher infection level is stable. Epidemically, the basic reproduction number less than unity is not enough to eradicate the disease completely if the conditions for backward bifurcation hold.

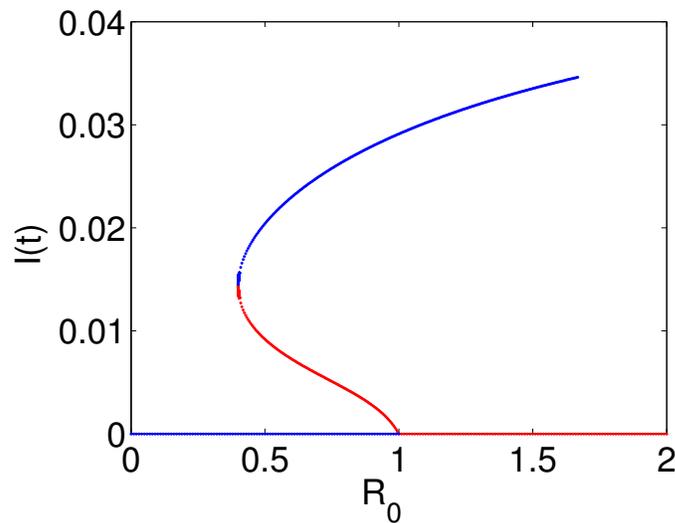


Figure 2: Backward bifurcation diagram for the parametric values $\beta = 0.52, \gamma_1 = 7.81, \gamma_2 = 7.32, \gamma_3 = 7.18, \gamma_4 = 0.5, \epsilon = 0.25, \lambda = 1.2, \delta_2 = 0.6, \delta_3 = 0.9, a = 5.1, b = 65.1, d = 0.15, \sigma_1 = 0.5, \sigma_2 = 0.5, \mu_1 = 1.32, \mu_2 = 0.15$ with different values of α considering R_0 as a function of α . The red and blue lines, respectively, denote the lines of unstable and stable equilibrium points.

4.4 Stability of endemic equilibrium state

The Jacobian corresponding to the endemic equilibrium point E^* is $J(E^*)$ is given below

$$J(E^*) = \begin{pmatrix} \alpha A^* - \beta I^* - \epsilon & 0 & -\alpha S^* & 0 & -\beta S^* & 0 \\ \alpha A^* + \beta I^* & -D_0 & \alpha S^* & 0 & \beta S^* & 0 \\ 0 & \gamma_1 & -D_1 & 0 & 0 & 0 \\ 0 & \gamma_2 & 0 & -D_2 & 0 & 0 \\ 0 & \gamma_3 & \delta_1 & \mu_1 & -D_3 - \frac{a}{1+bI^*} + \frac{abI^*}{(1+bI^*)^2} & 0 \\ 0 & \gamma_4 & \delta_2 & \mu_2 & \frac{a}{1+bI^*} - \frac{abI^*}{(1+bI^*)^2} + \sigma_1 & -\epsilon \end{pmatrix}$$

One characteristic root of the above matrix is $-\epsilon$ and other five satisfies the following equation

$$x^5 + a_1x^4 + a_2x^3 + a_3x^2 + a_4x + a_5 = 0 \quad (4.3)$$

where

$$\begin{aligned}
a_1 &= (D_5 + D_1 + D_2 + D_3 + P + \epsilon + D_0) \\
a_2 &= -S^* \alpha \gamma_1 - S^* \beta \gamma_3 + D_0 D_1 + D_0 D_2 + D_0 D_3 + D_0 D_5 + D_0 P + D_0 \epsilon + D_1 D_2 + D_1 D_3 \\
&\quad + D_1 D_5 + D_1 P + D_1 \epsilon + D_2 D_3 + D_2 D_5 + D_2 P + D_2 \epsilon + D_3 D_5 + D_3 \epsilon + D_5 P + P \epsilon \\
a_3 &= D_0 D_1 D_5 + D_0 D_2 D_5 + D_0 D_3 D_5 + D_0 D_5 P + D_1 D_2 D_5 + D_1 D_3 D_5 + D_1 D_5 P + D_2 D_3 D_5 \\
&\quad + D_2 D_5 P - PS^* \alpha \gamma_1 + D_0 D_2 P + D_1 D_2 P + D_0 P \epsilon + D_1 P \epsilon + D_2 P \epsilon + D_0 D_1 P + D_0 D_2 \epsilon \\
&\quad + D_1 D_3 \epsilon + D_2 D_3 \epsilon + \epsilon D_0 D_1 + \epsilon D_1 D_2 + D_0 D_1 D_2 + D_0 D_1 D_3 + D_0 D_2 D_3 + D_0 D_3 \epsilon + D_1 D_2 D_3 \\
&\quad - D_1 S^* \beta \gamma_3 - D_2 S^* \alpha \gamma_1 - D_2 S^* \beta \gamma_3 - D_3 S^* \alpha \gamma_1 - S^* \alpha \epsilon \gamma_1 - S^* \beta \delta_1 \gamma_1 - S^* \beta \epsilon \gamma_3 - S^* \beta \gamma_2 \mu_1 \\
a_4 &= \epsilon D_1 D_2 D_0 + D_0 D_1 D_5 P + D_0 D_2 D_3 D_5 + D_0 D_2 D_5 P + D_1 D_2 D_3 D_5 + D_1 D_2 D_5 P + D_0 D_1 D_2 D_5 \\
&\quad + D_0 D_1 D_3 D_5 + D_0 D_1 D_2 P + D_0 D_1 P \epsilon + D_0 D_2 P \epsilon + D_1 D_2 P \epsilon - D_2 PS^* \alpha \gamma_1 - PS^* \alpha \epsilon \gamma_1 \\
&\quad - D_2 S^* \alpha \epsilon \gamma_1 - D_2 S^* \beta \delta_1 \gamma_1 - D_2 S^* \beta \epsilon \gamma_3 - D_3 S^* \alpha \epsilon \gamma_1 - S \beta \delta_1 \epsilon \gamma_1 - S^* \beta \epsilon \gamma_2 \mu_1 - D_1 D_2 S^* \beta \gamma_3 \\
&\quad - D_1 S^* \beta \epsilon \gamma_3 - D_1 S^* \beta \gamma_2 \mu_1 - D_2 D_3 S^* \alpha \gamma_1 + \epsilon D_1 D_2 D_3 + D_0 D_2 D_3 \epsilon + D_0 D_1 D_3 \epsilon + D_0 D_1 D_2 D_3 \\
a_5 &= -\gamma_1 D_2 D_3 S^* \alpha \epsilon - \gamma_1 D_2 S^* \beta \delta_1 \epsilon - D_1 S^* \beta \epsilon \gamma_2 \mu_1 - D_1 D_2 S^* \beta \epsilon \gamma_3 + D_0 D_1 D_2 D_3 D_5 + D_0 D_1 D_2 D_5 P \\
&\quad - D_2 PS^* \alpha \epsilon \gamma_1 + D_0 D_1 D_2 P \epsilon + \epsilon D_1 D_2 D_0 D_3 \\
D_5 &= \alpha A^* + \beta I^*, \quad P = \frac{a}{1 + bI^*} - \frac{abI^*}{(1 + bI^*)^2}.
\end{aligned}$$

Since one root of the characteristic equation is negative and the system will be locally asymptotically stable if other roots are negative or real part is negative. The other roots will be negative or negative real part if the Routh–Hurwitz [29] is satisfied i.e. $a_1, a_2, a_3, a_4, a_5 > 0$, $a_1 a_2 a_3 > a_3^2 + a_1^2 a_4$ and $(a_1 a_4 - a_5)(a_1 a_2 a_3 - a_3^2 - a_1^2 a_4) > a_5(a_1 a_2 - a_3)^2 + a_1 a_5^2$. Since expressions of the coefficients a_i 's, $i = 1 - 5$ are large, verifying the above conditions is difficult task. Numerically we shall justify the condition of stability of the endemic equilibrium point.

5 Parameter Estimation, Model Validation and Prediction

5.1 Model fitting with data

To estimate the important model parameters we consider the cumulative number of infected persons from the real data source and the model predicted cumulative number of infected persons. Let $\{y_i\}$ be the cumulative number of infected persons and

$$\{Z(t_i, \theta), \theta \in \Theta(\theta_1, \theta_2, \dots, \theta_l)\}$$

be the corresponding model predicted cumulative number of model predicted infected population where $Z(t, \theta)$ satisfies the differential equation

$$\frac{dZ}{dt} = \delta_1 A + \gamma_3 E + \mu_1 Q.$$

Since $Z(t_i, \theta)$ is function of the model parameters $\theta \in \Theta$, our aim in the present section is to find $\theta \in \Theta$ such that

$$SSE(\theta) = \sum_{i=1}^n \{(y_i - Z(t_i, \theta))^2\}$$

is minimized subject to $\theta \in \Theta$, n is the number of observations [34]. There are several optimization technique to minimize the error for suitable $\theta \in \Theta$, here we have used the Matlab package `fminsearch` to estimate important model parameters. Rest other parameters are collected from published research documents.

5.2 Sensitivity index

The sensitivity analysis reveals parametric influence of the disease spreading in epidemic modelling. Usually the used methods for sensitivity analysis are the perturbation of fixed point analysis and the uncertainty in parameter estimation. Using the sensitivity index one can estimate the rate of change of variables when the parameter changes [35, 36]. On the other hand the most important tool to study the dynamics of epidemic model is R_0 and it is function of the model parameters. Here our goal is to determine the significant model parameters which are controlling R_0 . To study the effect of sensitivity here we use global sensitivity index [35] for R_0 with respect to the model parameter ϕ is denoted by $\Gamma_{R_0}^\phi$ and is defined by

$$\Gamma_{R_0}^\phi = \frac{\partial R_0}{\partial \phi} \frac{\phi}{R_0}$$

If $\Gamma_{R_0}^\phi = \xi$ then $y\%$ increase (decrease) of ϕ will increase (decrease) $\xi y\%$ when ξ is positive and for negative ξ increase of parameter will decrease R_0 .

5.3 Confidence interval of the model Parameters

The confidence interval for the model parameter can be computed using the sensitivity matrix as described in [34] and used by [37]. The sensitivity matrix (J) for the parameters $\Theta(\theta_1, \theta_2, \dots, \theta_l)$ is defined as

$$J = \begin{pmatrix} \frac{\partial Z_{t_1}}{\partial \theta_1} & \frac{\partial Z_{t_1}}{\partial \theta_2} & \dots & \frac{\partial Z_{t_1}}{\partial \theta_l} \\ \frac{\partial Z_{t_2}}{\partial \theta_1} & \frac{\partial Z_{t_2}}{\partial \theta_2} & \dots & \frac{\partial Z_{t_2}}{\partial \theta_l} \\ \dots & \dots & \dots & \dots \\ \frac{\partial Z_{t_n}}{\partial \theta_1} & \frac{\partial Z_{t_n}}{\partial \theta_2} & \dots & \frac{\partial Z_{t_n}}{\partial \theta_l} \end{pmatrix} \quad (5.1)$$

Using the complex-step approximation method the partial derivative $\frac{\partial Z_{t_k}}{\partial \theta_j}$ can be calculated [38, 39]. Using complex step ih for small h (for computation purpose we use $h = 10^{-40}$, i is the unit complex number).

Using Taylor's

$$Z_{t_k}(\theta_j + ih) \approx Z_{t_k}(\theta_j) + ihZ'_{t_k}(\theta_j) - \frac{h^2}{2!}Z''_{t_k}(\theta_j) + \dots$$

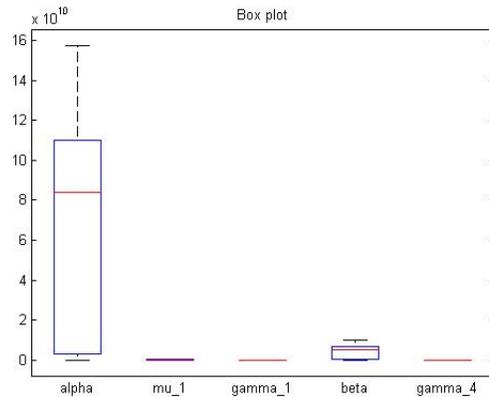


Figure 3: Box plot of the most sensitive parameters

The imaginary part of the both side gives the corresponding partial derivative

$$Z'_{t_k}(\theta_j) = \frac{\partial Z_{t_k}}{\partial \theta_j} \approx \frac{\text{Im}[Z_{t_k}(\theta_j + ih)]}{h} + O(h^2)$$

where $O(h^2)$ represents the second and higher order terms. From the above J , one can be obtained then the standard order ($SE_{\theta_j^*}$) for the parameter θ_j as defined

$$SE_{\theta_j^*} = \sqrt{(\sigma^2 \{J^T(\theta^*)J(\theta^*)\})_{jj}}$$

where $\sigma^2 = \frac{SSE(\theta^*)}{n-l}$ is computed for the basic estimated parameter (θ^*). Using the above results the confidence interval can be obtained.

Since we have data availability only for cumulative infected populations (Z -class). Using the method defined above we found that confidence interval for most of the model parameters are negative and the SSE is large. The uncertainty embedded in the large interval can be minimize fixing in the less effective model parameters. This processes was successfully applied in the previous studies [37] and not violated the significance of data fitting. For this purpose we first compute the sensitivity matrix and the most sensitive parameters are presented in the box diagram (see Figure 3). We have computed the confidence interval for the most sensitive model parameters and other parameters are fixed as initial least square estimation level.

5.4 Data management

In this study we considered the country Spain drastically infected by SARS-CoV-2 virus and collected available online data in chronological order from Worldometer [1, 2]. We considered Spain since it was one of the most affected country in the world at the time of this study. We included the data from February 14 to April 28, 2020 (total 65 days).

Table 2: Model estimated parameters and Sensitivity index

Parameters	Values	Confidence Interval	Source	Sensitivity Index
Λ	1021	–	[40]	1.000
γ_1	0.1534×10^{-1}	(0.01199 0.01774)	[Estimated]	0.851
β	1.5498×10^{-6}	(0.030996 0.278964) $\times 10^{-5}$	[Estimated]	0.644
α	9.8634×10^{-7}	(0.08038 0.12363) $\times 10^{-5}$	[Estimated]	0.356
μ_1	4.2069×10^{-4}	(0.41223 0.43175) $\times 10^{-3}$	[Estimated]	0.0814
γ_4	0.1485	(0.02970 0.26732)	[Estimated]	-0.603
γ_3	7.8774×10^{-5}	–	[Estimated]	0.002
b	0.1470×10^{-2}	–	[Estimated]	NA
δ_1	0.6129×10^{-2}	–	[Estimated]	-0.012
σ_1	0.4003×10^{-1}	–	[Estimated]	-0.055
μ_2	0.1477×10^{-1}	–	[Estimated]	-0.0813
d	0.1600	–	[1]	-0.218
γ_2	0.8232×10^{-1}	–	[Estimated]	-0.250
δ_2	0.4688	–	[Estimated]	-0.344
a	0.2709	–	[Estimated]	-0.370
ϵ	2.4931×10^{-4}	–	[40]	-1.000

To ensure the curve fitting we did not include any additional data outside the time interval as declared above. For simplicity and to compare the results, zero (0) was used to denote the first day when a case was reported for Spain; see graphical presentations in later section.

5.5 Case study: Spain

To study the particular case: the spreading of COVID-19 in Spain we have considered the real cases in cumulative number of infection (from Feb 14 to April 28 2020) and using the above described formula we have estimated the model parameters, using the global sensitivity index method we found the sensitivity index of the parameters. To calibrate the numerical simulation the initial population size of the susceptible and infected population is taken as $S(0) = 46751619$ and $I(0) = 3$ and other four initial conditions are estimated as $E(0) = 10$, $Q(0) = 1$, $A(0) = 2$, and $R(0) = 0$. The estimated model parameters, sensitivity index and the corresponding sources are in Table 2. Using the procedure described in section 5.3 we have identified the most sensitive model parameters which is given in the box plot of the parameters and the confidence interval for the parameters, see Figure 3.

It is clear from the Table 2 that the first six parameters have positive correlation with R_0 and the rest nine parameters have negative correlation with R_0 . With the increase of positive correlated model parameters the prevalence of infection will increase and for negatively related parameters will decrease the number of infection.

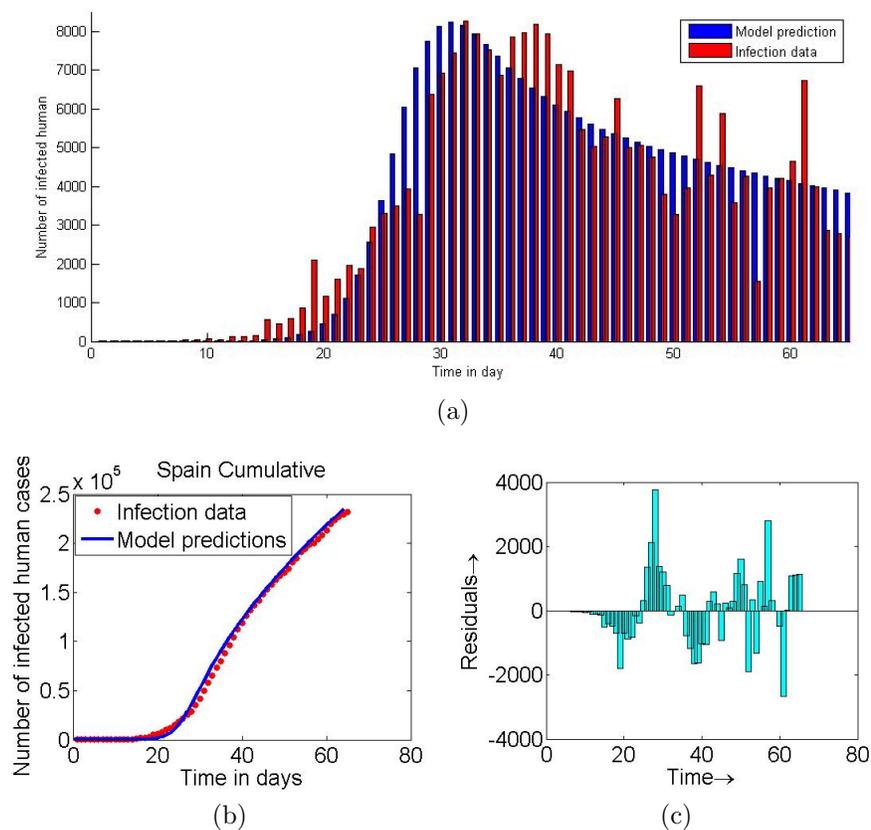


Figure 4: Real data and model fitted infection cases of Spain: (a) Bar diagram of Infected data and Model prediction (b) Cumulative Infected data and Model prediction (c) Residuals

The best model predicted cumulative curve and the real cumulative, bar presentation of the daily infected cases & the model predicted values and corresponding residuals is given in Figure 4. It is clear from Figure 4 (c) that the residuals are randomly distributed. The random distribution of the residuals imply that the fitness of the data with the model is over all good [29].

5.6 Model Validation

In previous section we consider the real data of Spain to predict the model parameters up to April 28, 2020. To validate the model we have presented the model predicted per day new infection and the real cases in Figure 5 from April 28 to May 10, 2020. It is clear from the figure there are minimum variation of the model prediction and the real cases.

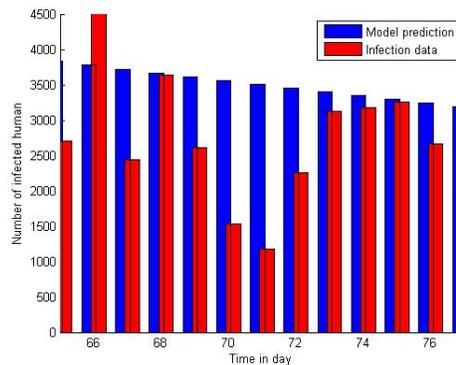


Figure 5: Model Validation: Daily new infection from April 28 to May 10, 2020

5.7 Effect of Significant model parameters

Now we shall investigate the effect of significant model parameters in the spreading of COVID-19 in Spain. Keeping other parameters fixed as in second column of Table 2 we varied the parameters α , β , μ_1 , γ_1 and γ_4 once at a time.

(a) Effect of α , contact rate between S and A class

In Figure 6 we present the time series of the infected population for different values of the model parameter α in the estimated interval as given in Table 2. It is clear from the sensitivity index that with the increase of α the basic reproduction number increases i.e. prevalence of the disease will increase. In the figure the red curve denotes time series of the infected population for the model predicted parametric values, the upper and lower curve denotes the same for upper limit and lower limit of α in the interval, the space between the curves denotes the prevalence of infection for different values of infection rate between the asymptotic and susceptible class in the estimated interval.

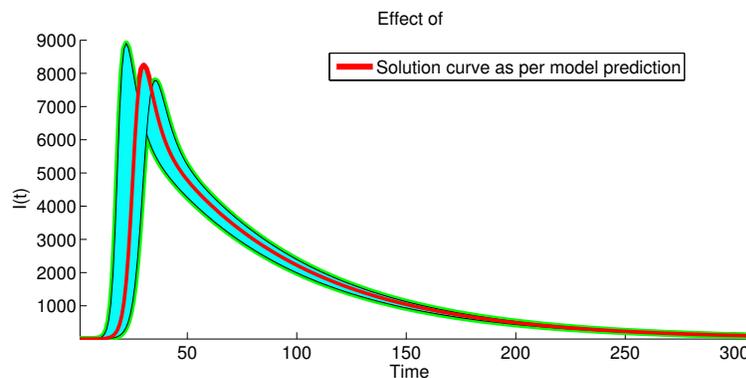


Figure 6: Time series of infectious persons for the model parameter α in confidence interval.

It is clear from the figure that for higher values of α the daily new infection will reach the highest value shortly then it will start to decrease.

(b) Effect of β , contact rate between S and I class

The Figure 7 denotes the daily number of new infection for different values of β . Description of the figure is similar as previous figure. The nature of the solution for both cases shows the same result that with the increasing rate of infection, the number of infection first rapidly increase; reaching the peak point and then it start to decrease but lower rate of recovery. In all condition the disease will persist in the system for long time these values of Figures 6 and 7.

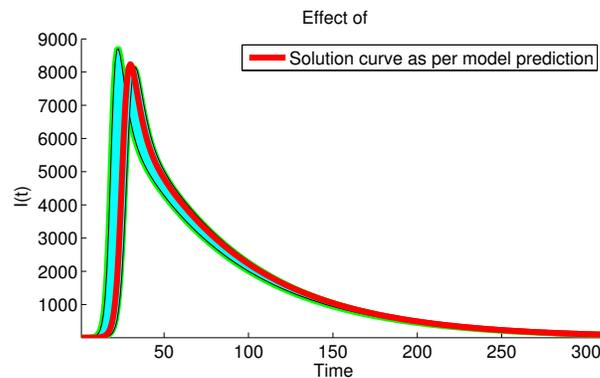


Figure 7: Time series of infectious persons for the model parameter β in confidence interval.

(c) Effect of μ_1 , infection rate of Q class

Figure 8 shows the time series for the I - class for different values of μ_1 . Description of the figure is similar as the previous figures. Like the other two figure it is clear from the figure with the increase of this parameter the abundance of the infected population will increase. Thus the infection from the quarantine class plays important role in spreading the disease. To minimize value of μ_1 we have to quarantine the exposed properly then spreading of disease can be controlled easily.

(d) Effect of γ_1 , transmission rate of E class to A

Since γ_1 is the rate at which the exposed class transfer to the asymptomatic class. If γ_1 higher then a large number of infectious people will enter the asymptomatic compartment and consequently the disease will spread among the susceptible people shortly. For lower values of γ_1 disease spreading will be lower. In Figure 9 we have presented the time series of the infected persons for different values of γ_1 . The description of the graph is similar as the last three. It is clear from the figure to control the disease spreading we have to control the parameter γ_1 .

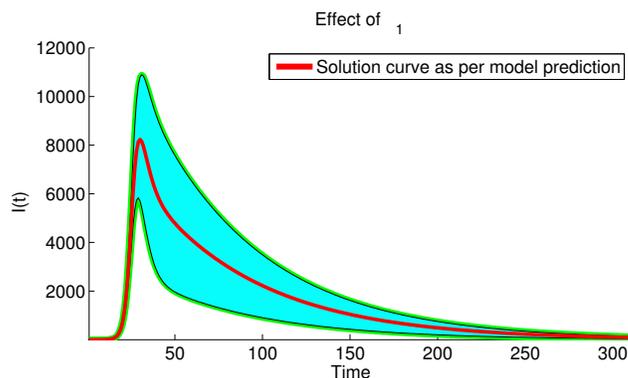


Figure 8: Effect of solution in the confidence interval for the model parameter μ_1 .

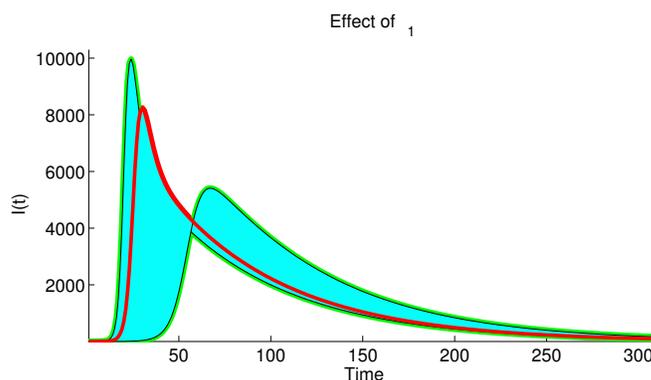


Figure 9: Effect of solution in the confidence interval for the model parameter γ_4 .

(e) Effect of γ_4 , recovery rate of E class

In Figure 10 we have presented the time series of the infected population for different values of recovery rate of the exposed class (γ_4) as given in the confidence interval. Like the previous two figures here the red line is the model predicted daily new infection for COVID-19 but the lower line is for highest value of γ_4 and the upper line is for lowest value. Hence with the increase of this parameter the number of infected population decreases i.e. to control the disease the recovery rate of the infected population plays important role. The recover rate will increase if the immunity of the infected person is high. So, to get recovery form the disease individual have to gain high immunity through life style.

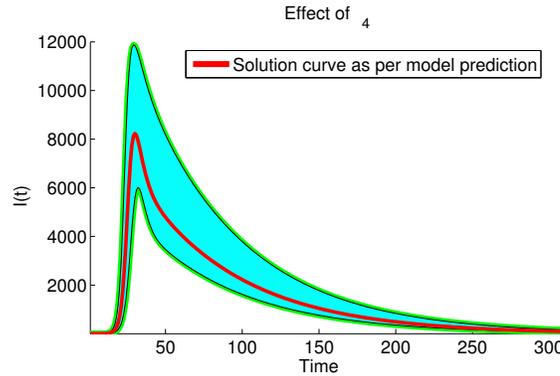


Figure 10: Effect of solution in the confidence interval for the model parameter γ_4 .

5.8 Contribution of R_0 by infectious and asymptomatic persons

It is clear from the expression of R_0 , the two parts

$$R_{01} = \frac{\Lambda\alpha\gamma_1}{\epsilon D_0 D_1}, \text{ and } R_{02} = \frac{\Lambda\beta(D_1 D_2 \gamma_3 + D_1 \gamma_2 \mu_1 + D_2 \delta_1 \gamma_1)}{\epsilon D_0 D_1 D_2 (D_3 + a)}$$

are respectively arises due to the effect of asymptomatic and infectious class. Using the estimated parameter values we obtain $R_0 = 6.692558249$ and the value of two parts are $R_{01} = 5.296117140$ and $R_{02} = 1.396441109$. It is clear from the values that the asymptomatic class gives the 79% contribution and the infectious class gives 21% contribution in the basic reproduction number. Thus the asymptomatic class gives most contribution i.e. in spreading the COVID-19 infection, the asymptomatic class take most important part compare to the infectious individuals. Thus to control the disease of we have to minimize the asymptomatic persons and after test we have to transfer them in the infectious compartment.

5.9 Estimation of R_0 for actual epidemic

Several methods are existing to estimate the reproductive ratio, R_0 for vector-transmitted diseases using actual data of epidemics. In this paper, we calculated R_0 from the initial growth phase of the diseases. At the primary stage of the epidemic, we assumed that the number of cumulative cases, $H(t)$, varies as $H = \exp(\zeta t)$, where ζ is the force of infection. In this case, the number of asymptomatic, exposed and infectious vectors vary similarly,

$$\begin{cases} A(t) \sim A_0 \exp(\zeta t) \\ E(t) \sim E_0 \exp(\zeta t) \\ Q(t) \sim Q_0 \exp(\zeta t) \\ I(t) \sim I_0 \exp(\zeta t) \end{cases} \quad (5.2)$$

where A_0 , E_0 , Q_0 , and I_0 are constants. Also form the first equation of (2.1), the constant susceptible population is $S_0 = \frac{\Lambda}{\epsilon}$. Assume that delay in treatment parameter,

$b = 0$. Moreover, the number of recovered vectors (non-susceptible class) can be assumed negligible such that

$$R(t) \equiv R_0 \quad (5.3)$$

Substituting equations (5.2) and (5.3) in the respective expression for the derivative as presented in the system (2.1), we obtain first form E -equation such that

$$\zeta E_0 = (\alpha A_0 + \beta I_0) S_0 - (\gamma_1 + \gamma_2 + \gamma_3 + \gamma_4 + \epsilon) E_0 \quad (5.4)$$

which yields

$$\left(\frac{\zeta}{\gamma_1 + \gamma_2 + \gamma_3 + \gamma_4 + \epsilon} + 1 \right) E_0 = \frac{\Lambda(\alpha A_0 + \beta I_0)}{\epsilon(\gamma_1 + \gamma_2 + \gamma_3 + \gamma_4 + \epsilon)}$$

Similarly, we obtain from A , Q and I - equations, respectively

$$\left(\frac{\zeta}{\delta_1 + \delta_2 + \epsilon} + 1 \right) A_0 = \frac{\gamma_1}{\delta_1 + \delta_2 + \epsilon} E_0$$

$$\left(\frac{\zeta}{\mu_1 + \mu_2 + \epsilon} + 1 \right) Q_0 = \frac{\gamma_2}{\mu_1 + \mu_2 + \epsilon} E_0$$

$$\left(\frac{\zeta}{\epsilon + \delta + \sigma_1 + a} + 1 \right) I_0 = \frac{\delta_1 A_0 + \gamma_3 E_0 + \mu_1 Q_0}{\epsilon + \delta + \sigma_1 + a}$$

For simplicity, using the notations D_0 , D_1 , D_2 , and D_3 as defined in section 4.1, we have

$$\left(\frac{\zeta}{D_0} + 1 \right) E_0 = \frac{\Lambda(\alpha A_0 + \beta I_0)}{\epsilon D_0}$$

$$\left(\frac{\zeta}{D_1} + 1 \right) A_0 = \frac{\gamma_1}{D_1} E_0$$

$$\left(\frac{\zeta}{D_2} + 1 \right) Q_0 = \frac{\gamma_2}{D_2} E_0$$

$$\left(\frac{\zeta}{D_3 + a} + 1 \right) I_0 = \frac{\delta_1 A_0 + \gamma_3 E_0 + \mu_1 Q_0}{D_3 + a}$$

Using the above four relation the association of R_0 and the force of infection can be done in the form

$$R_0 = \frac{S_0 \alpha \gamma_1}{D_0 D_1} + \frac{P_2 (D_1 P_1 - S_0 \alpha \gamma_1) (D_1 D_2 \gamma_3 + D_1 \gamma_2 \mu_1 + D_2 \gamma_1 \delta_1)}{D_0 D_1 (D_1 D_2 P_1 P_3 \gamma_3 + D_1 P_1 \mu_1 \gamma_2 + D_2 P_2 \delta_1 \gamma_1)} \quad (5.5)$$

where $P_0 = \frac{\zeta}{D_0} + 1$, $P_1 = \frac{\zeta}{D_1} + 1$, $P_2 = \frac{\zeta}{D_2} + 1$ and $P_3 = \frac{\zeta}{D_3 + a} + 1$.

Now it is time to estimate the force of infection, ζ . Since the number of new cases per day, $I(t)$, is the derivative of $I(t)$ in relation to time t , then at the beginning of the epidemics, $I(t) \sim I_0 \exp(\zeta t)$.

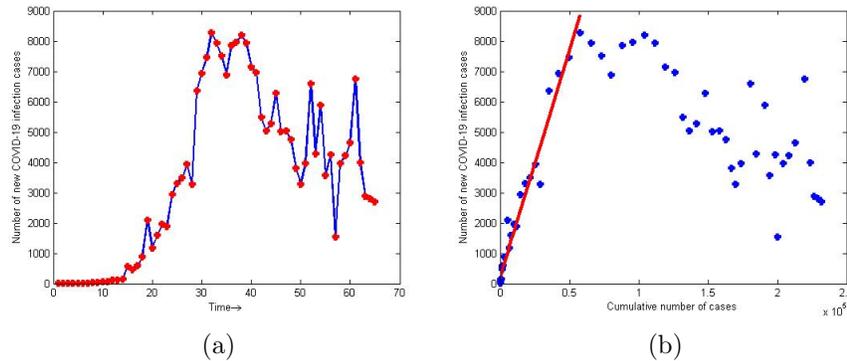


Figure 11: (a) The time series of new cases of COVID-19 in Spain in 14 Feb to 28 April, 2020, (b) the daily number of cases against the cumulative number of cases for the same time period in (a).

Plotting the number of new cases per day against the cumulative number of cases $Z(t)$, the phase of exponential growth of the cumulative number of cases is evidenced by a linear growth of the curve, the slope of which is the force of infection and which can be computed by a least-square linear fit of this linear phase [41, 42]. For the data of Spain in 14 Feb to 28 April, 2020 for the COVID-19 outbreak, shown in Figure 11(a), we obtain the calculated range of $\zeta = 0.1497553492834 \pm 0.0091 \text{ day}^{-1}$ based on the slope shown in Figure 11(b). The straight line (red color) indicates the growing linear parts of the plots corresponding to the initial exponential growth of the epidemics.

Substituting the parameter values as presented in Table 2 (no systematic vector control was in place during this epidemic) in expression (5.5), we obtain an estimation of $R_0 = 5.4925$ and the range is $R_0 \in (5.1514, 5.8448)$.

5.10 Effective reproduction number

In epidemiology the basic reproduction number (R_0) denotes the average number of secondary infection produced by one infected individual during the course of mean infection time. But usually when disease start to spread initially the secondary number of infected in higher and it reaches to a peak point then it decrease i.e. the reproduction number is not always fixed. Our aim in this part to define the time varying reproduction i.e. the reproduction number per day for COVID-19 and determine it using the available method. This type of estimation of the reproduction number is defined as the effective reproduction number at time t and denoted by $R(t)$ [41, 42, 43]. Here $R(t)$ yields the information about the invade of infection among the susceptible populations with time. To adopt the control

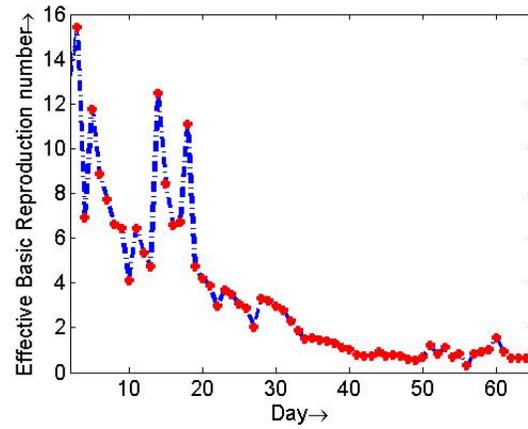


Figure 12: Effective basic reproduction number of Spain from Feb 14 to April 28, 2020

policy of COVID-19 in Spain for day to day it is most important to know the time varying reproduction number. The authors in [41, 42] defined the renewal equation in the form

$$F(t) = \frac{b(t)}{\int_{\tau=0}^{\infty} b(t-\tau)g(\tau)d\tau}$$

where $b(t)$ is the number of new cases at t^{th} day and $g(\tau)$ is the generation interval distribution for the disease. Using the procedure described in [41, 42] to the model (2.1) the generation distribution can be obtained. Let the rate of leaving of the exposed, asymptomatic people are respectively $p_1 = \epsilon + \gamma_1 + \gamma_2 + \gamma_3 + \gamma_4$, $p_2 = \delta_1 + \delta_2 + \epsilon$ and $p_3 = d + \epsilon + \sigma_1$ the generation interval distribution can be obtained as the combination of $p_1e^{-p_1t}$, $p_2e^{-p_2t}$ and $p_3e^{-p_3t}$ in the form

$$g(t) = \sum_{i=1}^3 \frac{p_1 p_2 p_3 e^{-p_1 t}}{\prod_{j=1, j \neq i}^3 (p_j - p_i)}$$

and mean of the distribution is $T = \frac{1}{p_1} + \frac{1}{p_2} + \frac{1}{p_3}$ and $\tau > 0$. The above relation valid when the force of infection $\zeta > \min\{-p_1, -p_2, -p_3\}$. From the expression of $F(t)$ the effective reproduction per day for the COVID-19 model can be estimated as $R(t) = F(t)$. The value of $R(t)$ for the present model for the date 14 Feb to 28 April, 2020 of Spain COVID-19 spreading is given in Figure 12. The value of $R(t)$ strictly greater than one upto 3rd April 2020 and then it move up and down of one. Thus growth of disease start to decrease 3rd April.

6 Optimal Control

In this section, we have formulated an optimal control problem by introducing time dependent controls due to lock down adapted by some countries to maintain social distancing,

causing the reduction of transmission rate of infections. Again, for applying lock down policy by the countries they face huge financial losses and for this reason some countries are adapting partial lock down. On the other hand, in spite of huge financial losses some countries are adapting total lock down to control the spreading of COVID-19. The control of spreading of COVID-19 infections depends on how the lock down is maintained. For the implementation of lock down, we can replace the incidence rate $\alpha AS + \beta IS$ in the system (2.1) by $\alpha(1 - u_1)AS + \beta(1 - u_2)IS$, where two controls u_1 and u_2 , respectively, measure the reduction of transmission from asymptomatic and infectious individuals due to social distancing. Thus we formulate an optimal control problem as follows:

$$\begin{cases} \frac{dS}{dt} = \Lambda - \{\alpha(1 - u_1)A + \beta(1 - u_2)I\}S - \epsilon S \\ \frac{dE}{dt} = \{\alpha(1 - u_1)A + \beta(1 - u_2)I\}S - (\gamma_1 + \gamma_2 + \gamma_3 + \gamma_4 + \epsilon)E \\ \frac{dA}{dt} = \gamma_1 E - (\delta_1 + \delta_2 + \epsilon)A \\ \frac{dQ}{dt} = \gamma_2 E - (\mu_1 + \mu_2 + \epsilon)Q \\ \frac{dI}{dt} = \delta_1 A + \gamma_3 E + \mu_1 Q - (\epsilon + d + \sigma_1)I - \frac{aI}{1+bI} \\ \frac{dR}{dt} = \gamma_4 E + \delta_2 A + \mu_2 Q + \sigma_1 I - \epsilon R + \frac{aI}{1+bI} \end{cases} \quad (6.1)$$

Here, we construct the cost functional as follows:

$$\min J(u_1, u_2) = \int_0^T (B_1 E + B_2 A + B_3 Q + B_4 I + B_5 u_1^2 + B_6 u_2^2) dt,$$

where the constants B_1, B_2, B_3, B_4 are, respectively, the losses due to presence of exposed, asymptomatic, quarantined and infectious individuals. The constants B_5 and B_6 are the losses associated with respective controls. Main objective of this study is to minimize the COVID-19 infections as well as the financial losses due to implement of lock down for the time T . In order to obtain optimal control strategies we have to find optimal functions $u_1^*(t)$ and $u_2^*(t)$ such that $J(u_1^*, u_2^*) = \min\{J(u_1, u_2), (u_1, u_2) \in U\}$, where the control set $U = \{(u_1, u_2)/u_i(t) \text{ is Lebesgue measurable on } [0, 1] \text{ and } 0 \leq u_1(t), u_2(t) \leq 1 \text{ for all } t \in [0, T]\}$. Now, the existence of such optimal control functions for the system (6.1) has been shown by the following theorem.

Theorem 4. *There exists optimal control functions $u_1^*(t)$ and $u_2^*(t)$ that minimize J over U .*

Proof. It is obvious that the integrand of the cost functional $J(u_1, u_2)$ is a convex function of u_1 and u_2 . Again, Theorem 1 implies that all the solutions of the system (2.1) are bounded and in similar manner it can be easily proved that all the solutions of the system (6.1) are also bounded, which claims that the system (6.1) satisfies the Lipschitz property with respect to the state variables. Therefore, there exists an optimal pair $(u_1^*(t), u_2^*(t))$. Hence the theorem is proved. \square

Now, we shall determine the optimal control functions by using Pontryagin's minimum principle [32, 44, 45]. To apply Pontryagin's minimum principle, we construct the Hamiltonian H :

$$H(S, E, A, Q, I, R, u_1, u_2, \lambda_1, \lambda_2, \lambda_3, \lambda_4, \lambda_5, \lambda_6) = B_1 E + B_2 A + B_3 Q + B_4 I + B_5 u_1^2 + B_6 u_2^2 + \lambda_1(t) \frac{dS}{dt} + \lambda_2(t) \frac{dE}{dt} + \lambda_3(t) \frac{dA}{dt} + \lambda_4(t) \frac{dQ}{dt} + \lambda_5(t) \frac{dI}{dt} + \lambda_6(t) \frac{dR}{dt}.$$

Here the adjoint variables λ_i , $i = 1 - 6$ satisfy the equations $\frac{d\lambda_1(t)}{dt} = -\frac{\partial H}{\partial S}$, $\frac{d\lambda_2(t)}{dt} = -\frac{\partial H}{\partial E}$, $\frac{d\lambda_3(t)}{dt} = -\frac{\partial H}{\partial A}$, $\frac{d\lambda_4(t)}{dt} = -\frac{\partial H}{\partial Q}$, $\frac{d\lambda_5(t)}{dt} = -\frac{\partial H}{\partial I}$, $\frac{d\lambda_6(t)}{dt} = -\frac{\partial H}{\partial R}$ with the transversality conditions $\lambda_i(T) = 0$, $i = 1 - 6$,

i.e. λ_i , $i = 1 - 6$ satisfy the adjoint equations:

$$\begin{cases} \frac{d\lambda_1}{dt} = \{\alpha(1 - u_1)A + \beta(1 - u_2)I\}(\lambda_1 - \lambda_2) + \epsilon\lambda_1 \\ \frac{d\lambda_2}{dt} = -B_1 + (\gamma_1 + \gamma_2 + \gamma_3 + \gamma_4 + \epsilon)\lambda_2 - \gamma_1\lambda_3 - \gamma_2\lambda_4 - \gamma_3\lambda_5 - \gamma_4\lambda_6 \\ \frac{d\lambda_3}{dt} = -B_2 + \alpha(1 - u_1)S(\lambda_1 - \lambda_2) + (\delta_1 + \delta_2 + \epsilon)\lambda_3 - \delta_1\lambda_5 - \delta_2\lambda_6 \\ \frac{d\lambda_4}{dt} = -B_3 + (\mu_1 + \mu_2 + \epsilon)\lambda_4 - \mu_1\lambda_5 - \mu_2\lambda_6 \\ \frac{d\lambda_5}{dt} = -B_4 + \beta(1 - u_2)S(\lambda_1 - \lambda_2) + \frac{a}{(1+bI)^2}(\lambda_5 - \lambda_6) + (\sigma_1 + d + \epsilon)\lambda_5 - \sigma_1\lambda_6 \\ \frac{d\lambda_6}{dt} = \epsilon\lambda_6 \end{cases} \quad (6.2)$$

with the transversality conditions

$$\lambda_i(T) = 0, i = 1, 2, \dots, 6. \quad (6.3)$$

For optimality conditions, we differentiate the Hamiltonian H partially with respect to u_1, u_2 and we have $u_1 = \frac{(\lambda_2 - \lambda_1)\alpha SA}{2B_5}$ and $u_2 = \frac{(\lambda_2 - \lambda_1)\beta SI}{2B_6}$. This leads to the following expressions of the optimal control functions $u_1^*(t)$ and $u_2^*(t)$:

$u_1^*(t) = \max \{0, \min \{ \frac{(\lambda_2^* - \lambda_1^*)\alpha S^* A^*}{2B_5}, 1 \} \}$ and $u_2^*(t) = \max \{0, \min \{ \frac{(\lambda_2^* - \lambda_1^*)\beta S^* I^*}{2B_6}, 1 \} \}$, where $S^*, E^*, A^*, Q^*, I^*, R^*$ are, respectively, the optimum values of S, E, A, Q, I, R and $(\lambda_1^*, \lambda_2^*, \lambda_3^*, \lambda_4^*, \lambda_5^*, \lambda_6^*)$ is the solution of the system (6.2) with the transversality conditions (6.3). Again, that critical point is indeed a minimum because $\frac{\partial^2 H}{\partial u_1^2} = 2B_5 > 0$

and $\begin{vmatrix} \frac{\partial^2 H}{\partial u_1^2} & \frac{\partial^2 H}{\partial u_1 \partial u_2} \\ \frac{\partial^2 H}{\partial u_2 \partial u_1} & \frac{\partial^2 H}{\partial u_2^2} \end{vmatrix} = 4B_5 B_6 > 0$. Thus, we can summarize the above in the following theorem:

Theorem 5. *The optimal pair $(u_1^*(t), u_2^*(t))$ minimizes the cost functional J over the region U , where $u_1^*(t) = \max \{0, \min \{ \frac{(\lambda_2^* - \lambda_1^*)\alpha S^* A^*}{2B_5}, 1 \} \}$ and $u_2^*(t) = \max \{0, \min \{ \frac{(\lambda_2^* - \lambda_1^*)\beta S^* I^*}{2B_6}, 1 \} \}$.*

Now, we have performed the numerical simulations of the optimal control problem (6.1) by using forward-backward sweep method [44] written in MATLAB programming. For this simulation we fix the parameters given as in Table 2 with the initial conditions $S(0) = 46751619$, $E(0) = 10$, $A(0) = 2$, $Q(0) = 1$, $I(0) = 3$ and $R(0) = 0$. For this simulation we also assume that $B_1 = 0.05$, $B_2 = 0.12$, $B_3 = 0.1$, $B_4 = 0.2$, $B_5 = 5000$ and $B_6 = 5000$.

We simulate the model in two different ways, one is without using any control variables and other is with both the control variables and we run the programme for 100 days (i.e. $T = 100$ days) in both cases. We adopt this in order to see the comparison of state

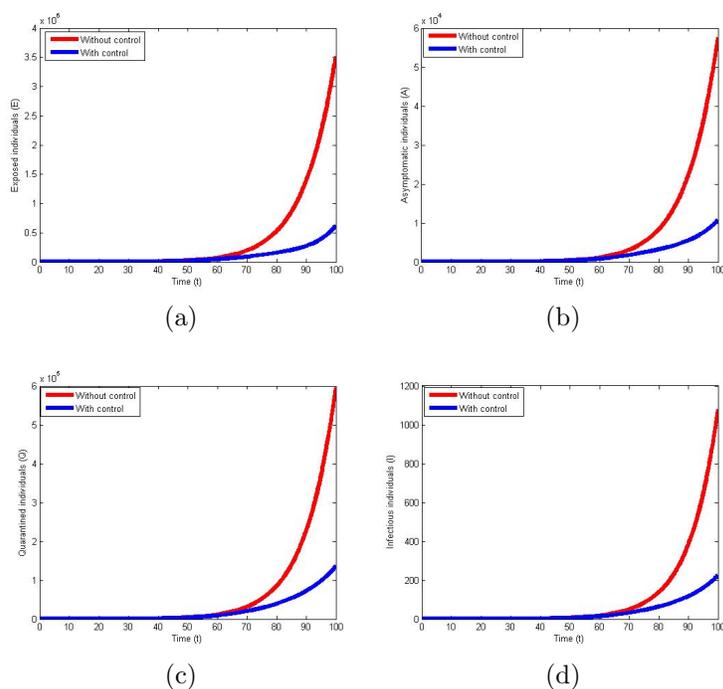


Figure 13: Time series of the populations for both with control and without control for 100 days timeline: (a) exposed individuals, (b) asymptomatic individuals, (c) quarantined individuals, (d) infectious individuals.

trajectories for with and without control in the same frame (see Fig. 13(a)-(d)). For this simulation the optimal control functions have been illustrated in Fig. 14(a)-(b). The figures depict the influence of implementing 100 days time lock down to control the spreading of COVID-19 infections.

7 Conclusion

The time varying pattern mathematical model SEAQIR of the pandemic COVID-19 presented several interesting features in this paper. Considering all major parameters of the progression of the disease, several analytic results established. All the properties necessary for epidemiological relevance have also been proved. We estimated the parametric values for Spain using the existing online available data. The acceptable agreement between data analysis and numerical solutions were established.

Theoretical results established and presented in terms of basic reproduction number and the dynamics of the model are determined by the threshold levels of R_0 . We have disease free solution for $R_0 < 1$ and endemic solution while $R_0 > 1$. Both theoretically and numerically with data analysis we demonstrated that the infected population will be decrease asymptotically as long as R_0 less than 1. Data analysis and model results

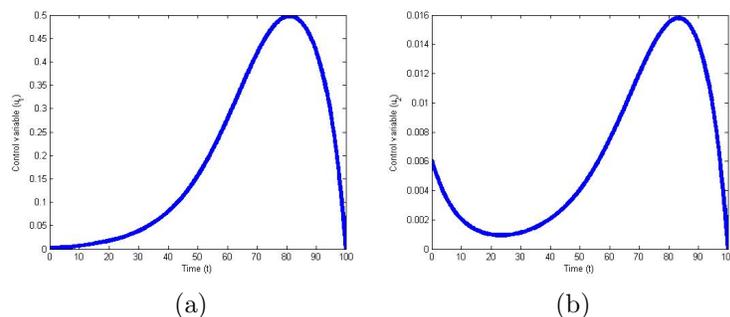


Figure 14: The optimal control function: (a) u_1 , (b) u_2 .

predicted the time boundary to control the epidemic in Spain. Besides data analysis, the proposed model showed the vaccination and treatment strategies to control the epidemic; human population can control and protect the spread of infectious diseases by creating social isolation, hospitalization, lock-down and physical distancing. The model ensured the efficiency of the approach to intercept the disease by the limitation of contacts between the individuals through quarantine of infected individuals.

The proposed model confirmed the efficiency of the approach to reduce and gradually stop the disease by the limitation of contacts between the individuals through quarantine of infected individuals. In the model results, we compared outbreak data from Spain with the quarantine model to calculate the growth and decay of the current outbreak. In Spain, lock-down (quarantine) was initiated on 14 March-2020. The maximum number of reported cases was observed on 26 March-2020; which means that the number of infections was on an upward trend for only 13 days. After that day, the number of daily reported cases was observed to decrease asymptotically after which the health authorities appeared to gain control of the situation, which is an the most important interpretation of mathematical model. These values can be used by policy makers and other professionals to make decisions on how certain interventions such as distancing and isolation can be effectively implemented. Similar scenarios can be observed in several European countries such as Germany, UK and France.

The current viral epidemic pushed every medical system to its breaking point without any permanent solution to the disease. So far, there has been minimal advancement towards the use of medication or vaccination to control the spread of COVID-19. As such the most effective mitigation measure currently available is physical distancing to reduce interaction between infected individuals and susceptible populations. The efficiency of quarantine methods determines our protection against the virus.

In this study there were one notable limitation, for example: the model taken into account the beginning of the disease development and we ignored the spatial distribution (space x) of population densities. Instead we considered the case when infection rate and other compartments population were changing with time. Due to these limitations, the accuracy of the existing results and prediction in this paper could vary for a short period

of time. For this type of pandemic, the standard modelling is the partial delay differential equations (PDDEs) which concludes both time-space distributions and incubation period. The final conclusion about modelling is that all mathematical models have some limitations and is not perfect for all countries.

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