



Article

Improved Rapid Visual Earthquake Hazard Safety Evaluation of Existing Buildings Using Type-2 Fuzzy Logic Model

Ehsan Harirchian ^{1,*} , Tom Lahmer ¹ 

¹ Institute of Structural Mechanics (ISM), Bauhaus-Universität Weimar, 99423 Weimar, Germany; ehsan.harirchian@uni-weimar.de, tom.lahmer@uni-weimar.de

* Correspondence: ehsan.harirchian@uni-weimar.de

Abstract: Rapid Visual Screening (RVS) is a procedure that estimates structural scores for buildings and prioritize their retrofit and upgrade requirements. Despite the speed and simplicity of RVS, many of the collected parameters are non-commensurable and include subjectivity due to visual observations. It might cause uncertainties in the evaluation, which emphasizes the use of a fuzzy-based method. This study aims to propose a novel RVS methodology based on the interval type-2 fuzzy logic system (IT2FLS) to set the priority of vulnerable building to undergo detailed assessment while covering uncertainties and minimizing their effects during evaluation. The proposed method estimates the vulnerability of a building, in terms of Visual Damage Index, considering the number of stories, age of building, plan irregularity, vertical irregularity, building quality, and peak ground velocity, as inputs with a single output variable. Applicability of the proposed method has been investigated using a post-earthquake damage database of 28 reinforced concrete buildings from the Bingöl earthquake in Turkey.

Keywords: Fuzzy logic system; earthquake safety assessment; seismic vulnerability assessment; Interval Type-2 Fuzzy logic; rapid visual screening; reinforced concrete buildings

1. Introduction

Averting a subsequent natural calamity is certainly relatively impractical. However, due to the rapid progress of simulation science and seismological studies, it is quite possible to mitigate the catastrophic effects post-disaster. If earthquake safety (risk) assessment of buildings is viewed as Heinrich's domino theory of cause and effects [1], damage results from a chain of sequential events, metaphorically like a line of dominoes falling over. Where the first piece is the seismic hazard, which plays an important role and is inherently unavoidable, followed by the building vulnerability, then construction characteristics, which lead to seismic risk and damage of buildings and cause loss and injury of residents, respectively. When one of the dominoes falls, it triggers the next one, and the next, but improving or removing a key factor (such as retrofitting buildings) prevent or minimize the impact of the chain reaction of dominoes. As it is not possible to modify the seismic hazard to reduce the risk, emphasis should be placed on the study of vulnerability assessment and reduction as a measure of damage/loss mitigation. In urban areas midst, the construction of new building stock is a substantial number of structures still in service, which were constructed either when national seismic codes were not evolved due to lack of research or they were not strictly enforced by the law. For instance, in Istanbul, Turkey, as a high seismic area, around 90% of buildings are substandard, which can be generalized into other earthquake-prone regions in Turkey [2]. The reliability of this building stock resulting from earthquake-induced collapse currently is uncertain. Nonetheless, it is

also not feasible to perform a detailed seismic vulnerability analysis on each building as a solution to the scenario, as it will be too complicated and expensive. This indicates the necessity of a reliable, rapid, and computationally easy method for seismic vulnerability assessment, commonly known as Rapid Visual Screening (RVS). In RVS methodology, an observational survey of buildings will be performed, and according to the data collected during the visual inspection, a structural score will be calculated without performing any structural calculations to determine the expected damage of a building and whether the building needs detailed assessment [3]. Although this method might save time and resources due to the subjective/qualitative judgments of experts who performed the inspection, the evaluation process is dominated by vagueness and uncertainties, which vagueness can be handled adequately through the fuzzy set theory [4] but do not cover all sort of uncertainties due to its crisp membership functions [5]. In this study, a novel method of rapid visual hazard safety assessment of buildings against earthquake is introduced in which an interval type-2 fuzzy logic system (IT2FLS) would be used to cover uncertainties.

2. Review of Rapid Visual Screening Procedures

Federal Emergency Management Agency (FEMA), U.S.A in 1988 has proposed the initial Rapid Visual Screening (RVS) methodology as “Rapid Visual Screening of Buildings for Potential Seismic Hazards: A Handbook” [6]. Furthermore, in 2002, because of earthquake disasters in the 1990s, the methodology was modified to integrate the latest technological advancements [7]. RVS has been widely used in seismic countries as a practical and simple tool for evaluating the vulnerability of buildings; therefore, this challenge is in the interest of many researchers and still is under development and improvement. In this manner, some efforts have been made to develop national RVS for India (IITK-GSDMA) [8], Turkey (EMPI) [9], Italy [10], and the Philippines [11]. Some practical comparisons carried out by [12–14] between different national RVS methods and their robustness have been discovered. Although RVS is an acceptable estimation method that gives a general overview to do proper earthquake mitigation planning, the variables considered contain a level of uncertainty [15].

In addition to national and local RVS methods, there are many other RVS methods developed by using linear regression [16,17], Multi-criteria decision making [3], Artificial Neural Networks (ANNs) [18–21], Fuzzy Logic (see Table 1), and some other methods concerning their consideration and experiences on a region or country [22]. These methods can be categorized into two groups: a) methods based on statistical and machine learning approaches, like linear regression and ANN, and b) methods based on expert systems such as Fuzzy based methods.

Methods based on statistical approaches reduce the problem to a linear relationship between inputs and the output, which is not realistic as the relation between building parameters, seismicity parameters, and damageability is a non-linear relation. Methods based on machine learning approaches suffer from a lack of data where there is not enough datasets consisting of building parameters before earthquakes and type of damage after earthquakes. In addition, these approaches are local and limited to a specific area; last approaches, based on Fuzzy systems, consider the expert’s opinion, and model vagueness exist in words that describe the building parameters. Table 1 presents a summary of the fuzzy system type 1 applied to RVS.

Fuzzy systems contributed significant achievements in vulnerability assessment because of making definite decisions based on imprecise or ambiguous data [23]. The main problem with all previous studies based on conventional type-1 FLS (T1FLS) is that they only consider vagueness in membership functions while does not including all types of uncertainties due to its crisp membership functions. However, this issue can be solved by implementing interval type-2 Fuzzy Logic Systems (IT2FLS) as their membership functions (MFs) are themselves fuzzy [5]. Therefore, in this paper, an RVS method based on an interval type-2 fuzzy system is considered to overcome the weakness of RVS methods based on the type-1 fuzzy system.

Table 1. Summary of Fuzzy Logic application in visually earthquake hazard safety assessment of buildings

Author(s)	Year	Studied data	Purpose	Parameters	Fuzzy inference
Ketsap et.al.[15]	2019	Chiang Rai, Thailand	Earthquake risk evaluation of buildings by using Fuzzy risk model	Building occupancy (occupancy risk index), building vulnerability (FEMA 154 final score), Seismic hazard (PGA)	Hierarchical fuzzy rule-based
Irwansyah et.al.[24]	2017	1450 (1000 modeling, 400 tests,50 outlined) non-engineered buildings in Aceh, Indonesia	A three-stage fuzzy rule-based model to determine the hazard rate of building on the impact of earthquake for non-engineered houses	Structural (ring balk, floor block, column, foundation), non-structural (wall crack, wall cover, floor cover, tombak layer), ground condition (PGA, slope, fault distance)	Three-Stage Fuzzy Rule-Based
Shahriar et.al.[25]	2012	43 Steel buildings in Northridge, USA	A risk-based seismic vulnerability assessment method using fuzzy-TOPSIS for damageability evaluation of steel buildings.	Structural system, vertical irregularity, plan irregularity, year of construction, construction quality, spectral acceleration	Fuzzy-TOPSIS, Mamdani
Şen[26]	2011	747 RC buildings in Istanbul, Turkey	Proposed a fuzzy logic model as supervised hazard center classification inference methodology for rapid and rational hazard classification.	Building height, soft height ratio, cantilever extension ratio, moment of inertia, frame number, column ratio, shear wall ratio, and PGV	Supervised fuzzy rule-based, Mamdani
Şen[27]	2010	1249 RC buildings in Istanbul, Turkey	Proposed a fuzzy logic model and software for rapid visual earthquake hazard evaluation of existing buildings.	Story number, cantilever extension, soft story, weak story, building quality, pounding effect, hill-slope effect, and PGV	Fuzzy rule-based, Mamdani
Tesfamariam and Saatcioglu[4]	2010	28 RC buildings in Bingöl, Turkey	Proposed a risk-based seismic vulnerability assessment based on fuzzy logic for prioritizing buildings for retrofit and repair.	Soft story, weak story, and short column effect, relative strength at joints, plan irregularity, torsional irregularity, diaphragm continuity, re-entrant corners, structural walls, construction and design quality, code enforcement, damage from previous earthquake, damage due to deterioration, relative height of slabs	Hierarchical fuzzy rule-based, Mamdani

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Table 1 – continued from previous page

Author(s)	Year	Studied data	Purpose	Parameters	Fuzzy inference
Tesfamariam and Saatcioglu[28]	2008	93 RC (73 modeling and 20 test) buildings in Northridge, USA	Proposed a risk-based seismic vulnerability assessment based on FEMA154 and fuzzy logic for prioritizing buildings for retrofit and repair.	Structural system, plan irregularity, vertical irregularity, year of construction, construction quality, building importance and occupancy	Hierarchical fuzzy rule-based, Mamdani
Moseley and Dritsos[29]	2008	101 and 454 buildings in Athens, Greece	Proposed a fuzzy logic rapid visual screening procedure based on Greece method to improve the screening procedures	Same as below parameters	Hierarchical fuzzy rule-based, Sugano
Demartinos and Dritsos[30]	2006	102 buildings in Athens, Greece	Fuzzy logic-based rapid visual screening procedure for categorization of buildings into five different types of possible damage with respect to the potential occurrence of a major seismic event.	Seismic hazard (ground motion, soil quality, building height), structural strength (building height, infill wall layout, soft story, short columns, design code), regularity (plan regularity, torsion possibility, height regularity, pounding possibility, plan regularity), structure's condition (previous damage, maintenance)	Hierarchical fuzzy rule-based, Sugano

3. Type-2 Fuzzy Logic System

Lotfi Zadeh introduced the initial concept of Fuzzy set (type-1) in 1965 [31] and later in 1975 developed the extension of it as the type-2 fuzzy set [32]. In this paper, it has been assumed that the reader is familiar with the basics of the Fuzzy logic system and type-1 Fuzzy Logic Systems (T1FLS) so that here the focus is entirely on the interval type-2 Fuzzy Logic Systems (IT2FLS) and its advantages over type-1 FLSs (T1FLS). The main limitations of the T1FLS is that it cannot adequately handle the linguistic, measurement and parameter uncertainties [33] due to [5]: 1- the expressions and words that are used in the antecedents and consequents of rules can be uncertain, and 2- consequents may have a histogram of values associated with them, mainly when knowledge is obtained from a group of experts who do not all agree. In this regard, IT2FLS, characterized by MFs that are themselves fuzzy, therefore, in case there are difficulties in the determination of membership grade even as a crisp number in [0,1], type-2 fuzzy sets are then adequate to use. So far, IT2FLSs have been used in different areas to deal with high uncertainty, nonlinearity and time-varying behavior [34], including computing with words [35], intelligent controllers [36], pattern recognition [37], and so on. A typical IT2 FLS consists of five parts as fuzzifier, rule base, inference engine, type-reducer, and defuzzifier. Moreover, in T2FLS, at least one of the fuzzy sets (membership functions) in the rule base must be type-2. All parts of T2FLS are similar to T1FLS except the type-reducer, which is introduced to convert the type-2 membership functions into a type-1 before defuzzification. The process of type-reduction is usually performed by the most popular computationally intensive Karnik-Mendel (KM) iterative algorithms proposed by Wu and Mendel [38]. A T2 fuzzy set \tilde{A} can be defined by its T2 membership function $\mu_{\tilde{A}}(x, u)$ as:

$$\tilde{A} = \int_{x \in X} \int_{u \in J_x} \frac{\mu_{\tilde{A}}(x, u)}{(x, u)} \quad (1)$$

where $x \in X$, $u \in J_x \subseteq [0, 1]$, and X represent the universe of the primary variable x of \tilde{A} . Here $\int \int$ denotes all the admissible x and u . The point-value representation of \tilde{A} is as:

$$\tilde{A} = \left\{ ((x, u), \mu_{\tilde{A}}(x, u)) \mid \forall x \in X, \forall u \in [0, 1] \right\} \quad (2)$$

The secondary MF of \tilde{A} is also called a vertical slice of $\mu_{\tilde{A}}(x, u)$:

$$\mu_{\tilde{A}}(x = x', u) \equiv \mu_{\tilde{A}}(x') = \int_{u \in J_{x'}} \frac{f_{x'}(u)}{u} \quad (3)$$

where $0 \leq f_{x'}(u) \leq 1$, and $\mu_{\tilde{A}}(x')$ denotes the secondary MF of \tilde{A} . The secondary membership grades of IT2FS all equal 1, that is to say, for any $x=x'$, $f_{x'}(u) \equiv 1$.

T2 carries the UMFs, LMFs, and FOU. The FOU is uncertainty in the primary membership grades of a type-2 MF, which consists of a bounded region; the UMF is a subset that has the maximum membership grade of the FOU, and the LMF is a subset that has the minimum membership grade of the FOU. The two-dimensional $\mu_{\tilde{A}}(x, u)$ is referred to as the footprint of uncertainty (FOU) of \tilde{A} :

$$FOU(\tilde{A}) = \bigcup_{x \in X} J_x = \{(x, u) \mid u \in J_x \subseteq [0, 1]\} \quad (4)$$

where J_x is the primary membership of \tilde{A} ; here the lower MF (LMF) $\underline{\mu}_{\tilde{A}}(x)$ and upper MF (UMF) $\bar{\mu}_{\tilde{A}}(x)$ comprise the FOU, where [39]:

$$\underline{\mu}_{\tilde{A}}(x) = LMF(\tilde{A}) = \inf\{u \mid u \in [0, 1], \mu_{\tilde{A}}(x, u) > 0\} \quad (5)$$

And,

$$\bar{\mu}_{\tilde{A}}(x) = UMF(\tilde{A}) = \sup\{u \mid u \in [0, 1], \mu_{\tilde{A}}(x, u) > 0\} \quad (6)$$

There are two types of T2FL systems as Mamdani and Takagi-sugeno [34]. Here our focus is on Mamdani type as it is more popular than Takagi-Sugeno. Therefore, the rules of IF-THEN [40] can be written as:

$$\tilde{R}^l : \text{IF } x_1 \text{ is } \tilde{F}_1^l \text{ and } \dots \text{ } x_p \text{ is } \tilde{F}_p^l \text{ THEN } y \text{ is } \tilde{G}^l \quad l = 1, \dots, N \quad (7)$$

Or in another way:

$$\tilde{R}^l : \tilde{F}_1^l \times \dots \times \tilde{F}_p^l \rightarrow \tilde{G}^l = \tilde{A}^l \rightarrow \tilde{G}^l \quad (8)$$

Where l is the rule number, x_i and \tilde{F}_i^l are the i th ($i=1, \dots, p$) input and antecedent set of rule l , respectively, \tilde{G}^l are consequent sets and \tilde{A} is the input fuzzy sets, while y is the input and " \sim " shows that the fuzzy set is a T2 fuzzy set.

According to equation 8, the output of inference engine for each rule can be defined as [34]:

$$\mu_{\tilde{B}^l}(y) = \mu_{\tilde{A}^l \rightarrow \tilde{G}^l}(x, y) = \mu_{\tilde{F}_1^l}(x_1) \cap \dots \cap \mu_{\tilde{F}_p^l}(x_p) \cap \mu_{\tilde{G}^l}(y) = \left[\bigcap_{i=1}^p \mu_{\tilde{F}_i^l}(x_i) \right] \cap \mu_{\tilde{G}^l}(y) \quad (9)$$

While adopting the popular centroid TR [41], the firing output set \tilde{B}^l is generated from by each fuzzy rule and the corresponding consequent IT2FS, i.e.,

$$\tilde{B}^l : \begin{cases} FOU(\tilde{B}^l) = [\underline{\mu}_{\tilde{B}^l}(y \mid x'), \bar{\mu}_{\tilde{B}^l}(y \mid x')] \\ \underline{\mu}_{\tilde{B}^l}(y \mid x') = \underline{f}^l(x') \cap \underline{\mu}_{\tilde{G}^l}(y) \\ \bar{\mu}_{\tilde{B}^l}(y \mid x') = \bar{f}^l(x') \cap \underline{\mu}_{\tilde{G}^l}(y) \end{cases} \quad (10)$$

While \cap denotes the minimum or product t-norm operation. The final output \tilde{B} can be achieved by merging all the rule firing output sets \tilde{B}^l :

$$\tilde{B} : \begin{cases} FOU(\tilde{B}) = [\underline{\mu}_{\tilde{B}}(y \mid x'), \bar{\mu}_{\tilde{B}}(y \mid x')] \\ \underline{\mu}_{\tilde{B}}(y \mid x') = \underline{\mu}_{\tilde{B}^1}(y \mid x') \cup \dots \cup \underline{\mu}_{\tilde{B}^M}(y \mid x') \\ \bar{\mu}_{\tilde{B}}(y \mid x') = \bar{\mu}_{\tilde{B}^1}(y \mid x') \cup \dots \cup \bar{\mu}_{\tilde{B}^M}(y \mid x') \end{cases} \quad (11)$$

Here \cup indicates the maximum operation. Then the type-reduced set $Y_c(x')$ can be obtained by computing the centroid $C_{\tilde{B}}$ of \tilde{B} :

$$Y_c(x') = C_{\tilde{B}}(x') = \frac{1}{[l_{\tilde{B}}(x'), r_{\tilde{B}}(x')]} \quad (12)$$

To find the final crisp output value for the inference process, the aggregate type-2 fuzzy set is first reduced to an interval type-1 fuzzy set, which is a range with lower limit and upper limit. This interval type-1 fuzzy set is commonly referred to as the centroid of the type-2 fuzzy set. In theory, this centroid is the average of the centroids of all the type-1 fuzzy sets embedded in the type-2 fuzzy set. In practice, it is not possible to compute the exact values of lower and upper limits. Instead, iterative type-reduction methods are used to estimate these values. Here the two points $l_{\tilde{B}}(x')$ and $r_{\tilde{B}}(x')$ can be calculated by common type-reduction algorithms like Karnik-Mendel (KM) [42], Enhanced Karnik-Mendel (EKM) [43] and weighted EKM [44].

3.1. RVS Modelling Based on Interval Type 2 Fuzzy System

Figure 1 presents the schematic structure of a proposed RVS model based on IT2FLS. The model consists of 6 input variables and one output variable as damage category (damage index).

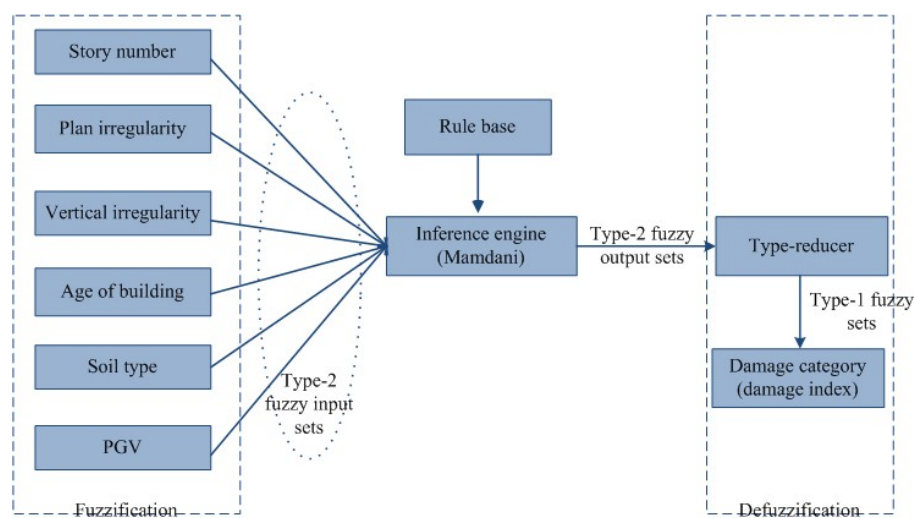


Figure 1. The structure of the IT2FLS in this study

Following are the explanation of different parts of the model: Input variables represent structural and environmental characteristics, which affect the global seismic response of a structure. These characteristics are presented in Figure 1 as input variables and in the fuzzification component. Each characteristic is described in linguistic terms that indicate its state. These terms are attributed to fuzzy sets, which are defined over the variable's universe of discourse via MFs. As can be seen in Figure 1 the fuzzifier maps a vector of six inputs $x = (x'_1, \dots, x'_6)^T$ into six IT2 fuzzy sets $\tilde{X}_i, i=1,2,\dots,6$. In this study a non-singleton fuzzifier has been considered because it is useful when the measurements are corrupted by non-stationary noise and has shown better performance [45].

Generally, there is no restriction on the number of MFs one could use; however, it is practically recommended to use less than 7 MFs in each input domain of a T1 or T2 fuzzy system to reduce computational cost, reduce number of rules, and make interpreting more straightforward [46]. The common MF shapes in T2 are Gaussian, bell-shaped and piecewise linear. Figure 2 shows the Gaussian and generalized bell-shaped MFs for story number, plan irregularity, vertical irregularity, age, soil type, and PGV, respectively. While a few of these variables have numerical values, the others are all in linguistic forms. However, in the classical modeling the inputs, plan irregularity and vertical irregularity are quantified as 1 implying existence (yes) and 0 as nonexistence (no) of the effect according to the crisp two-valued logic. The linguistic terms used for the definition of each variable and the respective fuzzy sets are described as:

Story number: Depending on the number of stories, either of these classes should be selected. The classifications on this study are for mid-rise buildings as the number of stories less than 3 (*Low*), between 3 and 6 (*Medium*), and more than 6 (*High*) as presented in Figure 2(a).

Plan Irregularity: This parameter should be considered when any of the irregularities, like buildings with re-entrant corners (L, T, U, E, + shape) and buildings with different lateral resistance in both directions, have been

observed. Any asymmetrical plan and distribution of vertical elements can cause torsion to the building (Figure 2(b)).

Vertical irregularity: If any of the irregularities such as steps in elevation view, inclined walls, buildings on a hill, soft story, buildings with short columns, and discontinuity in frames are identified, then this parameter should be considered (see Figure 2(c)).

Age of building: This parameter is classified into three different input variable membership function as *New* (age < 15 years), *Moderate* (15 < age < 30), and *Old* (age > 30) as presented in Figure 2(d).

Soil type: The soil type is classified into three different input variable membership function as *A/B* (rock and dense soil), *C* (stiff soil), and *E* (soft) as shown in Figure 2(e).

Peak Ground Velocity (PGV): The velocity is used to characterize the amplitude of seismic motion at intermediate frequencies, and, therefore, it is useful to indicate the potential damage for structures sensitive to the field of intermediate frequencies [9], [47]. In this paper, the PGV numerical values at any desired locations are based on the micro zoning studies by [48], which are fuzzified into three MFs as *Low*, *Medium*, and *High*, which are illustrated in Figure 2(f).

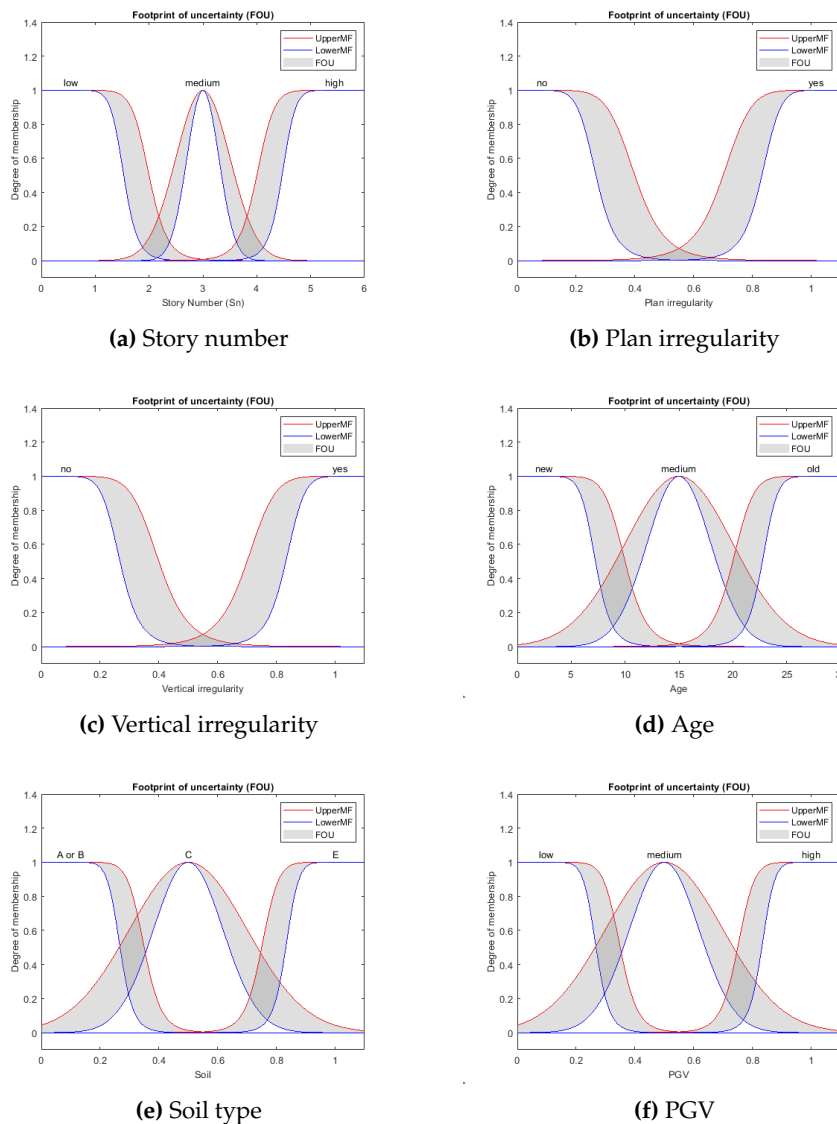


Figure 2. Gaussian and generalized bell-shaped membership function for input variables (a) story number, (b) plan irregularity, (c) vertical irregularity, (d) age, (e) soil type, (f) PGV

Lastly, the output variable *damage index* represents the possibility that a structure will suffer a particular damage type. Five MFs for the building damage categorization (Output variable) are considered as: *No damage*, *Low*, *Medium*, *Severe*, and *Collapse*. Figure 3 presents the building damage index categorization MFs.

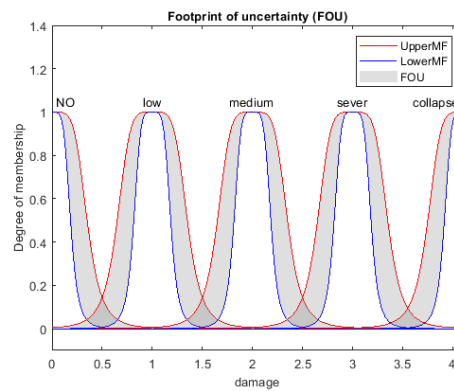


Figure 3. Gaussian and generalized bell-shaped membership function for damage as output variable

Following the above explanations, the logical rules for each variable are presented with the building assessment, and their fuzzification can be achieved by considering fuzzy words for input variables and damage categories. The defined rules in this study are $3 \times 2 \times 2 \times 3 \times 3 \times 3 = 324$ rules, of which some examples are presented in Table 2. In this study Mamdani Fuzzy system is considered where the rule consequents are fuzzy IT2 sets. Therefore, all rules defined based on Mamdani Type.

Table 2. The structure of the T2FLS in this study

Rule No.	Input variable												Output (Damage)
	NS		PI		VI		Age		ST		PGV		
1	Low	and	No	and	No	and	Old	and	A/B	and	Low	Then	No damage
...
171	Medium	and	Yes	and	No	and	Old	and	E	and	Medium	Then	Severe
...
324	High	and	Yes	and	Yes	and	New	and	E	and	High	Then	Severe

Minimum and product t-norms are the most popular inference methods to compute firing intervals of the rules for IT2 fuzzy systems. However, there is not too much difference between the outcome of each method. Therefore, in this study, minimum t-norm is applied for the inference engine. Finally, for Type reduction, the EKM method is applied as it is Modification of the Karnik-Mendel (KM) algorithm with an improved initialization, modified termination condition, and improved computational efficiency.

4. Results and discussion

The methodology based on IT2FLS was implemented on MATLAB (MATLAB is a registered trademark of The MathWorks, Inc.) using the provided Fuzzy Logic Toolbox. The version of the IT2FLS toolbox used allows the intuitive implementation of IT2FLSs, where it can cover all the phases of its design. Furthermore, the proposed method of this study has been examined by evaluating the buildings database of the Bingöl earthquake (2003) in Turkey. For this purpose, the information of 28 buildings has been selected from the SERU (Structural Engineering Research Unit) database [49], which was collected from the street survey by a team of researchers from Middle East Technical University (METU), Ankara. The Bingöl earthquake struck with a $M_w = 6.4$, reported peak ground acceleration (PGA) 535.3 cm/s^2 , and PGV 36.1 cm/s [50]. Moreover, a study by Akkar et al. [51] provide detailed technical information about the characteristics of the Bingöl earthquake. A report from the observed damage to the buildings in different places in Bingöl stated that damages were mostly due to the properties of structures, and not due to the foundation conditions or any gross ground deformation [52]. Therefore, in this paper, it has been assumed that, for assessing the vulnerability of the buildings in Bingöl there are no corrections or additional parameters required for different soil conditions, and the soil condition of the selected area are quite uniform, predominantly granular alluvial deposits, which are dense to very dense (Soil Type A or B) [53].

Table 3. Damage distribution of studied data

	No damage	Low damage	Moderate damage	Severe damage	Collapse
Observed damage [49]	21.4%	32.1%	25%	17.9%	3.6%
Estimated by Tesfamariam [54]	25%	32.1%	7.2%	35.7%	0%
Estimated by proposed method	14.3%	21.4%	32.1%	25%	7.1%

Table 3 shows the distribution of the observed damage categories of buildings [49], the estimation based on the fuzzy synthetic evaluation proposed by Tesfamariam [54], and the estimation by the proposed method in this paper based on IT2FLS. It shows that the proposed method agrees with the observed damage states. However, depending on the requirements of the authorities, each model can be selected for classification and further purposes. Table 4 presents the description of damage state of Table 3 and related decision and recommendations for each of them.

Table 4. Description of damage levels and recommended decision (adopted from [55])

Damage state	Description	Decision
No damage	No damage, small cracks	Safe
Low damage	Isolated non-structural damage, cracks in the interior walls or ceilings, damage in water lines, etc.	Slightly safe, might need small repair
Moderate damage	Significant non-structural damage and slight structural damage	Moderate safe, needs repair and retrofitting
Severe damage	Heavy non-structural damage and important structural damage	Slightly dangerous, need immediate repair and strengthening
Collapse	Collapsed buildings or condemned to demolition	Dangerous, evacuation and demolish needed

5. Conclusion

The assessment of earthquake resistance identification of existing buildings in the pre-earthquake period presents a very significant task, which must be accomplished in a rapid, simple, economical, and efficient manner. In this regard, the RVS methods were developed to assess the seismic vulnerability of buildings via an observation survey. Despite its efficiency, the evaluation process is dominated by vagueness type uncertainty. This issue has been addressed by proposing a novel interval type-2 Fuzzy system of rapid visual hazard safety assessment of buildings against earthquake. Later, for efficiency validation of the proposed method, it has been used to estimate the building damage category of the Bingöl earthquake dataset, which shows a good estimation. Nonetheless, the small size of the existing database used did not lead to a robust method and needs further investigation using more data. Therefore, it is worthwhile to spend time and funds to collect data after future seismic events to optimize the proposed method, when considering that pre-earthquake assessment aims to reduce seismic risk, which in turn can be interpreted in terms of economic benefits and life protection.

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