

On the Solutions of Nonlinear Hybrid Fractional Integrodifferential Equations

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Abstract: In the present work we study the existence of solutions for hybrid nonlinear fractional integrodifferential equations. We developed an algorithm by using the operator theoretical techniques in order to obtain the approximate solutions. The main results depend on the Dhage iteration method that were incorporated with the modern hybrid fixed point theorems. The approximate solutions were obtained by using Lipschitz conditions and weaker form of mixed partial continuity. Further, we provide some examples to explain the hypotheses and the related results.

Keywords: Hybrid Fractional Integrodifferential Equation; hybrid fixed point theorems of Dhage; approximations solutions; Lipschitz conditions; weaker mixed partial continuity.

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1 Introduction

Nonlinear fractional integrodifferential equations are important and widely applied in many areas such as in physics, mechanics, electromagnetics, biology, signal processing, economics and more. There are also many different methods to solve these type of equations. In particular, the solutions of existence, uniqueness and other properties for these type of equations have been studied by many authors by using different techniques. In 2016 Dhage et al. (see, [1]) introduced and proved algorithms for the existence of nonlinear first order ordinary integrodifferential equations and the approximation of solutions to initial value problems. In this paper, we extend their study into the classes of nonlinear hybrid fractional integrodifferential equations. Let $J = [t_0, t_0 + a]$ be a closed-bounded interval in the real space R for some $t_0, a \in R$ with $t_0 \geq 0$ and $a > 0$. Consider the nonlinear hybrid fractional integrodifferential equation (*Non-HFIDE*) of the initial value problem (*IVP*)

$$(D^\alpha u)(t) + \lambda u(t) = f \left(t, u(t), \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} g(s, u(s)) ds \right),$$

$$u(t_0) = B_0 \in R. \quad (1)$$

where $f : J \times R \times R \rightarrow R$ and $g : J \times R \rightarrow R$ continuous functions and $\lambda \in R (\lambda > 0)$, for all $t \in J$. We mean by the solution of Eq.(1), the function $u \in C^1(J, R)$ that holds Eq.(1), where $C^1(J, R)$ the space of continuously differentiable real-valued functions on J .

2 Preliminaries

Next, we introduce some related concepts which will be useful in our study, details can be found for example in [4, 5, 6, 7, 8]

Definition 2.1 [2, 3] Let $\alpha \in R_+$. The operator I^α is defined on $L_1[a, b]$ by

$$I^\alpha h(x) = \frac{1}{\Gamma(\alpha)} \int_a^x \frac{h(\mu)}{(x-\mu)^{1-\alpha}} d\mu, \quad \alpha > 0, \quad (2)$$

for $a \leq x \leq b$, is said to be Riemann-Liouville fractional integral having order α .

Definition 2.2 [9, 10] **Riemann & Liouville** fractional differential operator is defined by

$$D^\alpha h(u) = \frac{1}{\Gamma(m-\alpha)} \left[\frac{d}{du} \right]^m \int_a^u \frac{h(\mu)}{(u-\mu)^{\alpha-m+1}} d\mu, \quad (m-1) \leq \alpha < m, \quad (3)$$

where m is an integer and α is a real number.

Throughout this study, E denotes a partially ordered real linear normed space with order relation \preceq and the norm $\|\cdot\|$ in which the scalar product and the addition by non-negative real numbers are preserved by \preceq .

The space E is called a regular (see, [11]) if for any non-increasing (resp., non-decreasing) sequence $\{u_n\}$ in E such that $u_n \rightarrow u^*$ as $n \rightarrow \infty$, $u_n \succeq u^*$ (resp., $u_n \preceq u^*$) for all $n \in N$.

Definition 2.3 [12, 14] A function $T : E \rightarrow E$ is said to be partially continuous at point $a \in E$ if for every $\epsilon > 0$ there exists $\delta > 0$ such that

$$\|u - a\| < \delta \Rightarrow \|Tu - Ta\| < \epsilon,$$

then the map T is called partially continuous on E if it is partially continuous in E .

Definition 2.4 [13, 15] A subset $\Omega \neq \emptyset$ of the partially ordered Banach space E is said to be partially compact if B in Ω is a relatively compact set in E .

Definition 2.5 [13, 16] A function $T : E \rightarrow E$ is called:

1. partially compact if $T(E)$ is a partially relatively compact set in E ,
2. uniformly partially compact if it is partially compact and uniformly partially bounded on E ,
3. partially totally bounded if for any bounded subset Ω of E , $T(\Omega)$ is a partially relatively compact subset of E ,
4. partially continuous and partially totally bounded, then it is called partially completely continuous on E .

Definition 2.6 [12, 1] The metric d and the order relation \preceq on $E \neq \emptyset$ are called compatible if for every monotone sequence $\{u_n\}$ in E with a subsequence $\{u_{nk}\}$ of $\{u_n\}$ converges to u^* , the sequence $\{u_n\}$ converges to u^*

Theorem 2.1 [13] Let $(E, \preceq, \|\cdot\|)$ be a complete regular space partially ordered so that the norm $\|\cdot\|$ and the order relation \preceq in E are compatible in any compact chain C of E . Then $T : E \rightarrow E$ is a partially continuous, partially compact operator and increasing. If an element $u_0 \in E$ exists such that $u_0 \preceq Tu_0$ or $Tu_0 \preceq u_0$, then the equation of the operator $Tu = u$ has a solution u^* in E , and the sequence $\{T^n u_0\}$ of successive iterations converges monotonously towards u^* .

Remark 2.1 The regularity of E in Theorem 2.1 above can be substituted by a stronger continuity condition in the operator T in E (see [13]).

In this work, we will prove the existence and uniqueness solution of the Non – HFIDE (1) by using hybrid fixed point theorems where we need the following notion of a D–function.

Definition 2.7 An upper semi-continuous and monotone increasing function $\Xi : R_+ \rightarrow R_+$ is said to be a D -function provided $\Xi(0) = 0$.

Definition 2.8 An operator $T : E \rightarrow E$ is said to be a partial nonlinear D -contraction if there is a D -function such that

$$\|Tu - Tv\| \leq \Xi(\|u - v\|)$$

for $u, v \in E$, where $0 < \Xi(r) < r, \forall r > 0$. In particular, if $\Xi(r) = kr, \forall k > 0$, then T is called a partial Lipschitz operator with constant k and moreover, if $0 < k < 1$, then T is known as partial linear contraction on E .

Theorem 2.2 $(E, \preceq, \|\cdot\|)$ is a partially ordered, regular, a complete normalized linear space so that the norm $\|\cdot\|$ and the order relation \preceq in E are compatible in every compact chain C of E . Now $A, B : E \rightarrow E$ are two increasing operators such that

- (a) the operator A is partially nonlinear D -contraction and partially bounded,
- (b) the operator B is partially compact and partially continuous, and
- (c) there is an element $u_0 \in E$ such that $u_0 \preceq Au_0 + Bu_0$ or $u_0 \succeq Au_0 + Bu_0$.

Then the equation $Au + Bu = u$ has a solution u^* in E and the sequence $\{u_n\}$ of successive iterations introduced by $u_{n+1} = Au_n + Bu_n, n = 0, 1, \dots$, converges monotonically to u^* .

3 Existence of Solutions and Uniqueness

The equivalent integral form of *Non - HFID* (1) is considered in the function space $C(J, R)$ of continuous real-valued functions introduced on J . We define the order relation \preceq and a norm $\|\cdot\|$ in $C(J, R)$ by

$$\|u\| = \sup_{t \in J} |u(t)|, \quad (4)$$

and

$$u \leq v \Leftrightarrow u(t) \leq v(t), \text{ for all, } t \in J. \quad (5)$$

Obviously, $C(J, R)$ is a Banach space with respect to previous supremum norm and is also partially ordered with respect to the previous partially order relation \preceq . Further, it is also clear that Banach space of partially ordered $C(J, R)$ is regular and is a lattice, so each pair of elements in the space has an upper and a lower bound in the space.

The following lemma regarding the compatibility of sets in $C(J, R)$ followed by an application theorem of the Arzela-Ascoli.

Lemma 3.3 Let $(C(J, R), \preceq, \|\cdot\|)$ be a Banach space of partially ordered with the order relation \preceq and the norm $\|\cdot\|$ introduced by (4) and (5), respectively. Then, \preceq and $\|\cdot\|$ are compatible in each partially compact subset of $C(J, R)$.

We can see the proof of the lemma in [1]. Before to show our result, we need the following definition:

Definition 3.9 A differentiable function $z \in C^1(J, R)$ is a lower solution of the *Non - HFIDE* (1) if it fulfills

$$\begin{aligned} (D^\alpha z)(t) + \lambda z(t) &\leq f\left(t, z(t), \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} g(s, z(s)) ds\right) \\ z(t_0) &\leq B_0 \in R, \end{aligned} \quad (6)$$

for every t in J . Likewise, an upper solution $y \in C^1(J, R)$ to the *Non - HFIDE*(1) is introduced on J by inverting the previous inequalities.

Definition 3.10 A function $z \in C^1(J, R)$ is called a lower solution of the Non – HFIDE (19) if it fulfills

$$\begin{aligned} (D^\alpha z)(t) + \lambda u(t) &\leq f_1 \left(t, z(t), \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} g(s, z(s)) ds \right) \\ &+ f_2 \left(t, z(t), \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} g(s, z(s)) ds \right), \\ z(t_0) &\leq B_0, \end{aligned} \quad (7)$$

likewise, an upper solution y in $C^1(J, R)$ to the Non – HFIDE (19) is introduced on J by inverting the above inequalities.

3.1 Existence theorem

In the following hypothesis relating to our further discussion:

- (A₁) There is a constant $M_f > 0$ such that $|f(t, u, v)| \leq M_f$, $\forall t \in J$ and u in R .
- (A₂) The function $f(t, u, v)$ is monotone increasing in u and v for any t in J .
- (A₃) The function $g(t, u)$ is monotone increasing in u for any t in J .
- (A₄) The Non HFIDE (1) has a lower solution $z \in C^1(J, R)$.
- (A₅) There is a constant $L > 0$ such that

$$0 \leq g(t, u) - g(t, v) \leq L(u - v)$$

for every $t \in J$, $u, v \in R$, with $u \geq v$.

- (A₆) There are D–functions Ξ_1 and Ξ_2 such that

$$0 \leq f(t, x_1, x_2) - f(t, y_1, y_2) \leq \Xi_1(x_1 - y_1) + \Xi_2(x_2 - y_2)$$

for all $u_1, u_2, v_1, v_2 \in R$ with $u_1 \geq v_1$ and $u_2 \geq v_2$. Furthermore

$$\frac{a^\alpha}{\Gamma(\alpha + 1)} (\Xi_1(r) + \Xi_2(Lar)) < r, \quad \text{for any, } r > 0$$

- (A₇) The Non – HFIDE (19) has a lower solution $z \in C^1(J, R)$.

The following lemma is important in our next work and its proof is clear by a direct verification (by using the definition Riemann & Liouville differential operator).

Lemma 3.4 Let $h : J \rightarrow R$, be an integrable function then $u \in C^1(J, R)$ is a solution of Non – HFIDE

$$\begin{aligned} (D^\alpha u)(t) + \lambda u(t) &= h(t), \quad t \in J \\ u(t_0) &= B_0 \in R \end{aligned}$$

if and only if it is a solution of the following nonlinear integral equation

$$u(t) = ce^{-\lambda \frac{t^\alpha}{\alpha!}} + e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} h(s) ds, \quad t \in J$$

where $c = B_0 e^{\frac{\lambda t_0^\alpha}{\Gamma(\alpha)}}$ is a constant.

Theorem 3.5 Let the conditions $(A_1 - A_4)$ be held. Then the Non - HFIDE (4) has a solution u^* on J and the sequence $\{u_n\}_{n=1}^\infty$ the successive approximations, defined by

$$\begin{aligned} u_1(t) &= y(t), \\ u_{n+1}(t) &= ce^{-\lambda \frac{t^\alpha}{\alpha!}} + e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds \end{aligned} \quad (8)$$

for all t in R , converges monotonically to u^* .

Proof. From Lemma 3.4, the Non - HFIDE (4) is equivalent to the nonlinear integral equation

$$u(t) = ce^{-\lambda \frac{t^\alpha}{\alpha!}} + e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds, \quad t \in J. \quad (9)$$

Set $E = C(J, R)$. Then, by Lemma 3.3 it follows that each compact chain in E has the property of compatibility with respect to the order relation \leq and the norm $\|\cdot\|$ in E . We introduce the operator T by

$$Tu(t) = ce^{-\lambda \frac{t^\alpha}{\alpha!}} + e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds, \quad t \in J. \quad (10)$$

Since Tu is continuous, then $Tu \in E$. That is, T maps E into itself. The Non - HFIDE (4) is then equivalent to the operator equation

$$Tu(t) = u(t), \quad t \in J. \quad (11)$$

Through a series of steps, we must prove that the operator T fulfills all the conditions of Theorem 2.1.

Step I: Let T be increasing on E . Let u, v in E with $u \leq v$. Then, from (A_2) , we get

$$\begin{aligned} Tu(t) &= ce^{-\lambda \frac{t^\alpha}{\alpha!}} + e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds, \\ &\leq ce^{-\lambda \frac{t^\alpha}{\alpha!}} + e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, v(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, v(\xi)) d\xi\right) ds \\ &= Tv(t) \end{aligned}$$

for all t in J . This proves that T is a increasing operator on E .

Step II: Let T be partially continuous on E . $\{u_n\}$ is a chain points sequences C in E such that $u_n \rightarrow u, \forall n \in N$. Then, by the controlled convergence theorem,

$$\begin{aligned} \lim_{n \rightarrow \infty} Tu_n(t) &= \lim_{n \rightarrow \infty} \left(ce^{-\lambda \frac{t^\alpha}{\alpha!}} + e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds \right) \\ &= ce^{-\lambda \frac{t^\alpha}{\alpha!}} + e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} \left(\lim_{n \rightarrow \infty} f\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds \right) \\ &= ce^{-\lambda \frac{t^\alpha}{\alpha!}} + e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds \\ &= Tu(t) \end{aligned}$$

for every t in J . This proves that $\{Tu_n\}$ converges to Tu point-wise on J . Therefore, we prove that $\{Tu_n\}$ is an equi-continuous sequence of functions in E . Let t_1, t_2 in J with $t_1 < t_2$. Then

$$\begin{aligned} |Tu_n(t_2) - Tu_n(t_1)| &\leq c|e^{-\lambda \frac{t_1^\alpha}{\alpha!}} - e^{-\lambda \frac{t_2^\alpha}{\alpha!}}| \\ &, + |e^{-\lambda \frac{t_2^\alpha}{\alpha!}} \int_{t_0}^{t_2} \frac{(t_2-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds \end{aligned}$$

$$\begin{aligned}
& -e^{-\lambda \frac{t_1^\alpha}{\alpha!}} \int_{t_0}^{t_1} \frac{(t_1-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds \\
\leq & c|e^{-\lambda \frac{t_1^\alpha}{\alpha!}} - e^{-\lambda \frac{t_2^\alpha}{\alpha!}}| + |e^{-\lambda \frac{t_2^\alpha}{\alpha!}} \int_{t_0}^{t_2} \frac{(t_2-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds \\
& - e^{-\lambda \frac{t_1^\alpha}{\alpha!}} \int_{t_0}^{t_2} \frac{(t_1-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds \\
& + |e^{-\lambda \frac{t_1^\alpha}{\alpha!}} \int_{t_0}^{t_2} \frac{(t_1-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds \\
& - e^{-\lambda \frac{t_1^\alpha}{\alpha!}} \int_{t_0}^{t_1} \frac{(t_1-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds \\
& \leq c|e^{-\lambda \frac{t_1^\alpha}{\alpha!}} - e^{-\lambda \frac{t_2^\alpha}{\alpha!}}| \\
+ & |e^{-\lambda \frac{t_2^\alpha}{\alpha!}} - e^{-\lambda \frac{t_1^\alpha}{\alpha!}}| \left| \int_{t_0}^{t_2} \frac{(t_2-s)^{\alpha-1} - (t_1-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds \right| \\
& + e^{-\lambda \frac{t_1^\alpha}{\alpha!}} \left| \int_{t_0}^{t_2} \frac{(t_1-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, x_n(\xi)) d\xi\right) ds \right. \\
& \left. - \int_{t_0}^{t_1} \frac{(t_1-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds \right| \\
& \leq c|e^{-\lambda \frac{t_1^\alpha}{\alpha!}} - e^{-\lambda \frac{t_2^\alpha}{\alpha!}}| + |e^{-\lambda \frac{t_2^\alpha}{\alpha!}} - e^{-\lambda \frac{t_1^\alpha}{\alpha!}}| \\
& \left| \int_{t_0}^{t_0+a} \frac{(t_2-s)^{\alpha-1} - (t_1-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds \right| \\
& \left| \int_{t_1}^{t_2} \frac{(t_1-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds \right| \\
\leq & |e^{-\lambda \frac{t_1^\alpha}{\alpha!}} - e^{-\lambda \frac{t_2^\alpha}{\alpha!}}| \left(c + \frac{M_f}{\Gamma(\alpha)} \int_{t_0}^{t_0+a} (t_2-s)^{(\alpha-1)} - (t_1-s)^{\alpha-1} e^{\lambda \frac{s^\alpha}{\alpha!}} ds \right) \\
& + \frac{M_f}{\Gamma(\alpha)} \left| \int_{t_1}^{t_2} -(t_1-s)^{\alpha-1} e^{\lambda \frac{s^\alpha}{\alpha!}} ds \right| \\
\leq & |e^{-\lambda \frac{t_1^\alpha}{\alpha!}} - e^{-\lambda \frac{t_2^\alpha}{\alpha!}}| \left(c + \frac{M_f}{\Gamma(\alpha)} \int_{t_0}^{t_0+a} ((t_2-s)^{(\alpha-1)} - (t_1-s)^{\alpha-1}) e^{\lambda \frac{s^\alpha}{\alpha!}} ds \right) + \frac{M_f}{\Gamma(\alpha)} |p(t_1) - p(t_2)| \\
\leq & |e^{-\lambda \frac{t_1^\alpha}{\alpha!}} - e^{-\lambda \frac{t_2^\alpha}{\alpha!}}| \left(c + \frac{M_f \cdot e^{\lambda(t_0+a)^{\alpha-1}}}{\Gamma(\alpha)} \right) + \frac{M_f}{\Gamma(\alpha)} |p(t_1) - p(t_2)|
\end{aligned}$$

where, $p(t) = \int_{t_0}^t \frac{(t_0+a-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} ds$, $t \in J$.

Step III: Let T be a operator of partially compact on E and C is an arbitrary chain in E . Then we prove that $T(C)$ is a equi-continuous an uniformly bounded set in E . Firstly, we prove that $T(C)$ is uniformly bounded. We put $u \in C$ is arbitrary. Then,

$$\begin{aligned}
|Tu(t)| & \leq |ce^{-\lambda \frac{t^\alpha}{\alpha!}}| + |e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds| \\
& \leq |c| + \frac{a^\alpha M_f}{\Gamma(\alpha+1)} = r
\end{aligned}$$

for every t in J . We are taking the supremum over t , we get $\|Tu\| \leq r$ for every $u \in C$. Thus $T(C) \prec E$ is a uniformly bounded. Therefore, we will prove that $T(C)$ is an equicontinuous set in E . We put $t_1, t_2 \in J$ is arbitrary with $t_1 < t_2$. Then

$$\begin{aligned}
& |Tu(t_2) - Tu(t_1)| \leq c|e^{-\lambda \frac{t_1^\alpha}{\alpha!}} - e^{-\lambda \frac{t_2^\alpha}{\alpha!}}| \\
& + |e^{-\lambda \frac{t_2^\alpha}{\alpha!}} \int_{t_0}^{t_2} \frac{(t_2 - s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda s} f\left(s, u(s), \int_{t_0}^s \frac{(s - \xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds \\
& - e^{-\lambda \frac{t_1^\alpha}{\alpha!}} \int_{t_0}^{t_1} \frac{(t_1 - s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s - \xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds| \\
& \leq c|e^{-\lambda \frac{t_1^\alpha}{\alpha!}} - e^{-\lambda \frac{t_2^\alpha}{\alpha!}}| + |e^{-\lambda \frac{t_2^\alpha}{\alpha!}} \int_{t_0}^{t_2} \frac{(t_2 - s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s - \xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds \\
& - e^{-\lambda \frac{t_1^\alpha}{\alpha!}} \int_{t_0}^{t_2} \frac{(t_1 - s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s - \xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds| \\
& + |e^{-\lambda \frac{t_1^\alpha}{\alpha!}} \int_{t_0}^{t_2} \frac{(t_1 - s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s - \xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds \\
& - e^{-\lambda \frac{t_1^\alpha}{\alpha!}} \int_{t_0}^{t_1} \frac{(t_1 - s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s - \xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds| \\
& \leq c|e^{-\lambda \frac{t_1^\alpha}{\alpha!}} - e^{-\lambda \frac{t_2^\alpha}{\alpha!}}| \\
& + |e^{-\lambda \frac{t_2^\alpha}{\alpha!}} - e^{-\lambda \frac{t_1^\alpha}{\alpha!}}| \left| \int_{t_0}^{t_2} \frac{(t_2 - s)^{\alpha-1} - (t_1 - s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s - \xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds \right| \\
& + e^{-\lambda \frac{t_1^\alpha}{\alpha!}} \left| \int_{t_0}^{t_2} \frac{(t_1 - s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s - \xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds \right. \\
& \quad \left. - \int_{t_0}^{t_1} \frac{(t_1 - s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s - \xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds \right| \\
& \leq c|e^{-\lambda \frac{t_1^\alpha}{\alpha!}} - e^{-\lambda \frac{t_2^\alpha}{\alpha!}}| + |e^{-\lambda \frac{t_2^\alpha}{\alpha!}} - e^{-\lambda \frac{t_1^\alpha}{\alpha!}}| \\
& \left| \int_{t_0}^{t_0+a} \frac{(t_2 - s)^{\alpha-1} - (t_1 - s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s - \xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds \right| \\
& \left| \int_{t_1}^{t_2} \frac{(t_1 - s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s - \xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds \right| \\
& \leq |e^{-\lambda \frac{t_1^\alpha}{\alpha!}} - e^{-\lambda \frac{t_2^\alpha}{\alpha!}}| \left(c + \frac{M_f}{\Gamma(\alpha)} \int_{t_0}^{t_0+a} (t_2 - s)^{(\alpha-1)} - (t_1 - s)^{\alpha-1} e^{\lambda \frac{s^\alpha}{\alpha!}} ds \right) \\
& \quad + \frac{M_f}{\Gamma(\alpha)} \int_{t_1}^{t_2} (t_1 - s)^{\alpha-1} e^{\lambda \frac{s^\alpha}{\alpha!}} ds \\
& \leq |e^{-\lambda \frac{t_1^\alpha}{\alpha!}} - e^{-\lambda \frac{t_2^\alpha}{\alpha!}}| \left(c + \frac{M_f}{\Gamma(\alpha)} \int_{t_0}^{t_0+a} \left((t_2 - s)^{(\alpha-1)} - (t_1 - s)^{\alpha-1} \right) e^{\lambda \frac{s^\alpha}{\alpha!}} ds \right) + \frac{M_f}{\Gamma(\alpha)} |p(t_1) - p(t_2)|
\end{aligned}$$

where, $p(t) = \int_{t_0}^t (t_0 + a - s)^{\alpha-1} e^{\lambda \frac{s^\alpha}{\alpha!}} ds$, $t \in J$.

Since the functions $t \rightarrow (t - s)^{\alpha-1}$ and $t \rightarrow p(t)$ are uniformly continuous on compact $J = [t_0, t_0 + a]$, we have that $|Tu(t_2) - Tu(t_1)| \rightarrow 0$ as $t_2 \rightarrow t_1$, uniformly for every $u \in C$. This proves that $T(C)$ is an equi-continuous set in E . Thus $T(C) \prec E$ is compact and consequently T is a operator of partially compact on $E \rightarrow E$.

Step IV: z fulfills the operator inequality $z \leq Tz$.
from the supposition (A_4) Achieves, y is a lower solution of *Non – HFIDE* (4) introduced on J . Thus

$$(D^\alpha z)(t) + \lambda z(t) \leq f \left(t, z(t), \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} g(s, z(s)) ds \right), \quad (12)$$

and

$$z(t_0) \leq B_0 \in R. \quad (13)$$

for every t in J . The integrating (12) from t_0 to t , we have

$$z(t) \leq ce^{-\lambda \frac{t}{\alpha!}} + e^{-\lambda \frac{t}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s}{\alpha!}} f \left(s, z(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, z(\xi)) d\xi \right) ds \quad (14)$$

for every t in J . This prove that z is a lower solution of the operator equation $u = Tu$.
Thus T satisfies all the conditions of Theorem 2.1, and Remark 2.1 and we can deduce which the operator equation $Tu = u$ contain of a solution. Therefore, the integral equation and *Non – HFIDE* (4) have a solution u^* introduced in J . Moreover, the sequence $\{u_n\}$ of successive approximations introduced by Eq. (8) converges monotonically to u^* . Thus we have completed the proof.

Remark 3.2 *The inference of theorem 3.5 also still true if we substitute condition (A_4) with (B_4) The *Non – HFIDE* (4) contain a upper solution $v \in C^1(J, R)$.*

Example 3.1 *The interval $J = [0, 1]$ is a closed and bounded, we consider the *Non – HFIDE**

$$(D^{\frac{3}{2}}u)(t) + u(t) = \tan hu(t) + \tan h \int_0^t \frac{(t-s)^{\frac{1}{2}}}{\Gamma(\frac{3}{2})} \sin hu(s) ds, \quad (15)$$

$$u(0) = 1.$$

We applied the theorem 3.5, we get $\lambda = 1$, $c = 1$, $g(t, u) = \sinh u$ and $f(t, u, v) = \tanh u + \tanh v$.
Obviously, the functions f and g are continuous on $J \times R$, and f achieves (A_1) with $M_f = 2$. Furthermore, $g(t, u)$ is increasing in u for any t in J , and $f(t, u, v)$ is increasing in u and v for any t in J , thus conditions (A_2) and (A_3) are achieved. Finally, the *Non – HFIDE*(15) has a lower solution z defined by

$$z(t) = \frac{2}{\Gamma(\frac{3}{2})} \left(e^{\frac{-t}{\Gamma(\frac{3}{2})}} - 1 \right)$$

on J . Hence, all the assumption of Theorem 2.1 are achieved, and thus *Non – HFIDE*(15) has a solution u^* introduced on J , and the sequence $\{u_n\}$, introduced by

$$u_1(t) = y(t),$$

$$\begin{aligned} u_{n+1}(t) &= e^{-\frac{t}{\alpha!}} + e^{-\frac{t}{\alpha!}} \int_0^t \frac{(t-s)^{\frac{1}{2}}}{\Gamma(\frac{3}{2})} e^{\frac{s}{\alpha!}} \tan hu_n(s) ds \\ &+ e^{-\frac{t}{\alpha!}} \int_0^t \frac{(t-s)^{\frac{1}{2}}}{\Gamma(\frac{3}{2})} e^{\frac{s}{\alpha!}} \tan h \left(\int_0^s \frac{(s-\xi)^{\frac{1}{2}}}{\Gamma(\frac{3}{2})} \sinh u_n(\xi) d\xi \right) ds \end{aligned}$$

for all $t \in J$ and where $\Gamma(\frac{3}{2}) = \frac{3\sqrt{\pi}}{2}$, converges monotonically to u^* .

3.2 Uniqueness theorem

In this section, we investigate a uniqueness theorem for the *Non – HfIDE* (4) by using the weaker partially Lipschitz condition.

Theorem 3.6 *A suppose that conditions (A₄) – (A₆) achieve. Then the Non – HfIDE (4) contain of an unique solution u^* introduced on J , and the sequence $\{u_n\}$ of successive approximations introduced by the Eq. (8) converges monotonically to u^* .*

Proof. Set $E = C(J, R)$. Obviously, E is a lattice with respect to the order relation \leq and thus upper and lower bounds there is for all pair of elements in E . We introduce the operator T by (10). Then, the *Non – HfIDE* (4) is equivalent to the operator equation (11). We must prove that T fulfills all the conditions of Theorem 2.1.

Obviously, T is a increasing operator from $E \rightarrow E$. We want to prove that the operator T is a partially nonlinear D–contraction on E , thus let $u, v \in E$ with $u \geq v$. Then, by (A₅) and (A₆)

$$\begin{aligned}
 |Tx(t) - Tv(t)| &\leq |e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, u(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds \\
 &\quad - e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f\left(s, v(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, v(\xi)) d\xi\right) ds| \\
 &\leq e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} |f\left(s, u(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) \\
 &\quad - f\left(s, v(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, v(\xi)) d\xi\right)| ds \\
 &\leq e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} \left(\xi_1(u(s) - v(t)) + \xi_2\left(c \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi - g(\xi, v(\xi))\right)\right) ds \\
 &\leq e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\frac{-\lambda}{\alpha!}(t^\alpha - s^\alpha)} \left(\xi_1(u(s) - v(s)) + \xi_2 \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} L(u(\xi) - v(\xi)) d\xi\right) ds \\
 &\leq \frac{1}{\Gamma(\alpha)} \int_{t_0}^t (t-s)^{\alpha-1} e^{\frac{-\lambda}{\alpha!}(t^\alpha - s^\alpha)} \left(\xi_1(\|u - v\|) + \xi_2 \frac{b^\alpha}{\Gamma(\alpha+1)} La\|u - v\|\right) ds \\
 &\leq \xi \|u - v\|
 \end{aligned} \tag{16}$$

for every $t \in J$, where $\xi(r) = \frac{a^\alpha}{\Gamma(\alpha+1)} \left(\xi_1(r) + \xi_2(Lar)\right) < r$, $r > 0$.

Taking the supremum over t , we get

$$\|Tu - Tv\| \leq \xi(\|u - v\|)$$

for every $u, v \in E$, with $u \geq v$. Consequently, T is a partially nonlinear D–contraction in E . In addition, as in the proof of Theorem 3.5, we can show that the function z given in condition (A₄) achieves the inequality of the operator $z \leq Tz$ in J . Now, we apply direction of Theorem 2.1 gives that the *Non – HfIDE* (4) has a unique solution u^* , and the sequence $\{u_n\}$ of successive approximations introduced by Eq.(10) converges monotonically to u^* .

Remark 3.3 *The inference of theorem 3.6, also still true if we substitute condition (A₄) with (B₄).*

Example 3.2 *The interval $J = [0, 1]$ is a closed and bounded, we consider the HFIDE*

$$(D^{\frac{3}{2}}u)(t) + x(t) = \frac{1}{2} \left(\tan^{-1} u(t) + \tan^{-1} \int_{t_0}^t \frac{(t-s)^{\frac{1}{2}}}{\Gamma(\frac{3}{2})} g(s, u(s)) ds \right) \tag{17}$$

$$u(0) = 1$$

where $g : J \times R \rightarrow R$ is the function introduced by

$$g(t, u) = \begin{cases} 1 & \text{if } u \leq 0 \\ 1 + \frac{u}{1+u} & \text{if } u > 0 \end{cases}$$

Hence, $\lambda = 1, c = 1, f(t, u, v) = \frac{1}{2} (\tan^{-1} u + \tan^{-1} v)$. Obviously, the functions f and g are continuous on $J \times R \times R$ and $J \times R$, consecutively. The function f achieves (A_1) with $M_f = \frac{\pi}{2}$ and it is easy to prove that g achieves (A_5) with $L = 1$. Further, $f(t, u, v)$ is increasing in u and v for any t in J . To prove that f fulfills (A_6) on $J \times R \times R$, let $u_1, u_2, v_1, v_2 \in R$ be such that $u_1 \geq v_1$ and $u_2 \geq v_2$. Then,

$$\begin{aligned} 0 &\leq f(t, u_1, u_2) - f(t, v_1, v_2) \leq \frac{1}{2} (\tan^{-1} u_1 - \tan^{-1} v_1 + \tan^{-1} u_2 - \tan^{-1} v_2) \\ &\leq \frac{1}{2} \frac{u_1 - v_1}{1 + \eta_1^2} + \frac{1}{2} \frac{u_2 - v_2}{1 + \eta_2^2} \\ &\leq \Xi_1(u_1 - v_1) + \Xi_2(u_2 - v_2) \end{aligned}$$

for all $t \in J$ and for some $u_1 > \eta_1 > v_1$ and $u_2 > \eta_2 > v_2$, where Ξ_1 and Ξ_2 are D–functions introduced by

$$\Xi_1(r) = \frac{r}{1 + \eta_1^2}, \quad \text{and} \quad \Xi_2(r) = \frac{r}{1 + \eta_2^2}$$

for $0 < \eta_1, \eta_2 < r$. Furthermore,

$$\frac{1}{2} \frac{a^\alpha}{\Gamma(\alpha + 1)} (\Xi_1(r) + \Xi_2(ar)) = \frac{r}{1 + \eta^2} < r$$

where $\eta = \min\{\eta_1, \eta_2\}$.

In the end, the *Non – HFIDE* (4) has a lower solution $z(t) = \frac{2}{\Gamma(\frac{3}{2})} \left(e^{\frac{-t}{\Gamma(\frac{3}{2})}} - 1 \right)$ introduced on J .

Thus, all the supposition of Theorem 3.6 are fulfilled and thus we conclude that the *Non – HFIDE* (17) has a unique solution u^* introduced on J . Moreover, the sequence $\{u_n\}$, introduced by

$$u_0(t) = z(t)$$

$$\begin{aligned} x_{n+1}(t) &= e^{-\frac{t}{\alpha!}} + \frac{1}{2} e^{-\frac{t}{\alpha!}} \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\frac{s}{\alpha!}} \tan^{-1} u_n(s) ds \\ &\quad + \frac{1}{2} e^{-\frac{t}{\alpha!}} \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\frac{s}{\alpha!}} \tan^{-1} \left(\int_0^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi \right) ds \end{aligned} \quad (18)$$

for every t in J , converges monotonically to u^* .

3.3 The first type linear perturbations

At times, it is conceivable that the non-linearity of those involved in *Non – HFIDE* (1) does not fulfill either the supposition of theorem 3.5 or the supposition of theorem 3.6. In spite of, from incising the functions f_1 and f_2 of f in the form $f = f_1 + f_2$ fulfill the conditions of Theorems (3.5 and 3.6). Consecutively, in Dhage's terminology [1], the resulting equation is said to be the hybrid integro-differential equation with the first type linear disturbance. The objective of this section is to get an

existence result for such an equation.

Given above notations in the sections, we consider the nonlinear hybrid *Non – HFIDE*

$$\begin{aligned} D^\alpha u(t) + \lambda u(t) &= f_1\left(t, u(t), \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} g(s, u(s)) ds\right) \\ &+ f_2\left(t, u(t), \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} g(s, u(s)) ds\right) \\ u(t_0) &= B_0, \end{aligned} \quad (19)$$

for every t in J , where $f_1, f_2 : J \times R \times R \rightarrow R$ and $g : J \times R \rightarrow R$ are continuous functions.

From a solution of the *Non – HFIDE* (19), we denote a function $u \in C^1(J, R)$ that fulfills equation (19), where $C^1(J, R)$ is the habitual space of continuously differentiable real-valued functions introduced on J .

The *Non – HFIDE* (19) is called the hybrid fractional integrodifferential equation with a the first type linear perturbation [12, 16].

The *Non – HFIDE* (19) is well recognized in the literature and discussed of the existence and other properties. herein, we prove that existence of solutions by using partially compactness type conditions and the mixed partially Lipschitz.

Theorem 3.7 Assume that $(A_1) - (A_3)$ fulfilled with f and replaced by f_2 , and further let $(A_1), (A_5)$, and (A_6) fulfilled with f and replaced by f_1 . If (A_7) satisfied, then the *Non – HFIDE* (19) has a solution u^* introduced on J and the sequence $\{u_n\}$ of successive approximations, introduced by

$$\begin{aligned} u_1(t) &= z(t), \\ u_{n+1}(t) &= ce^{-\lambda \frac{t^\alpha}{\alpha!}} + e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f_1\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds \\ &+ e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f_2\left(s, u_n(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u_n(\xi)) d\xi\right) ds, \end{aligned} \quad (20)$$

for $t \in J$, converges monotonically to u^* .

Proof. Set $E = C(J, R)$. Then, from Lemma 3.4 it follows that each compact chain C in E has the property of compatibility with respect to the order relation \preceq and the norm $\|\cdot\|$ in E .

According to Lemma 3.4, the *Non – HFIDE* (19) is equivalent to the nonlinear integral equation

$$\begin{aligned} u(t) &= ce^{-\lambda \frac{t^\alpha}{\alpha!}} + e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f_1\left(s, u(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds, \\ &+ e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f_2\left(s, u(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds, \quad t \in J. \end{aligned} \quad (21)$$

Set $E = C(J, R)$ and introduce the operators A and B on E by

$$Au(t) = e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f_1\left(s, u(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds, \quad t \in J \quad (22)$$

and

$$Bu(t) = ce^{-\lambda \frac{t^\alpha}{\alpha!}} + e^{-\lambda \frac{t^\alpha}{\alpha!}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\lambda \frac{s^\alpha}{\alpha!}} f_2\left(s, u(s), \int_{t_0}^s \frac{(s-\xi)^{\alpha-1}}{\Gamma(\alpha)} g(\xi, u(\xi)) d\xi\right) ds, \quad t \in J. \quad (23)$$

Obviously, $A, B : E \rightarrow E$. In addition, *Non – HFIDE* (19) is equivalent to the operator equation

$$Au(t) + Bu(t) = u(t), \quad t \in J. \quad (24)$$

Following similar arguments to those used in the proofs of Theorems 3.5 and 3.6, we can show that operator A is a nonlinear D contraction and partially bounded and B is a partially compact operator and partially continuous in E . From the direct application of Theorem 2.2 gives that the operator equation $u \leq Au + Bu$ has a solution u^* . Thus, *Non-HFIDE* (19) has a sequence $\{u_n\}_{n=1}^\infty$, and the solution u^* introduced by (20) monotonic converges to u^* . This completes the proof.

The inference of Theorem 3.7 residues true if we substitute (A_7) with (B_7) . The *Non-HFIDE* (19) has a upper solution $y \in C^1(J, R)$.

Example 3.3 *The interval $J = [0, 1]$ is closed and bounded, we consider the Non-HFIDE,*

$$D^{\frac{1}{2}}u(t) + u(t) = \tan^{-1}u(t) + \tan h\left(\int_0^t \frac{(t-s)^{-\frac{1}{2}}}{\Gamma(\frac{1}{2})} \sin hu(s)ds\right), \quad (25)$$

$$u(0)=1.$$

We applied the Theorem 3.7, we get $\lambda = 1$, $c = 1$, $f_1(t, u, v) = \tan^{-1}u$, $f_2(t, u, v) = \tanh v$ and $g(t, v) = \sinh v$. Therefore the function f_1 fulfills (A_1) with $M_{f_1} = \frac{\pi}{2}$ and also fulfills (A_6) with $\Xi_1(r) = \frac{r}{1+\xi^2}$, $0 < \xi < r$ and $\Xi_2(r) = 0$. Now f_2 fulfills (A_1) with $M_{f_2} = 1$ and it is increasing in v , thus (A_2) fulfills. Likewise, g fulfills (A_3) . In the end, $z(t) = 3(e^{-t} - 1)$, for every $t \in J$, is a lower solution of the *Non-HFIDE* (25) on J , and thus (A_7) is fulfilled. Next, by Theorem 3.7, the *Non-HFIDE* (25) possesses a solution u^* on J , and the sequence $\{u_n\}_{n=1}^\infty$, introduced by

$$\begin{aligned} u_1(t) &= 3(e^{-t} - 1), \\ u_{n+1}(t) &= e^{-\frac{t}{\alpha}} + e^{-\frac{t}{\alpha}} \int_{t_0}^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\frac{s}{\alpha}} \tan^{-1} u_n(s) ds \\ &\quad + e^{-\frac{t}{\alpha}} \int_0^t \frac{(t-s)^{\alpha-1}}{\Gamma(\alpha)} e^{\frac{s}{\alpha}} \tanh \left(\int_0^s \sinh u_n(\xi) d\xi \right) ds, \end{aligned} \quad (26)$$

for $t \in J$, converges monotonically to x^* .

Remark 3.4 *We observe that if the Non-HFIDE ((1) or (19)) have a upper y solution, in addition to a lower solution z such that $y \geq z$, then the congruous solutions u_* and u^* of the Non-HFIDE ((1) or (19)) fulfills $u_* \leq u^*$, and these are the maximum and minimum solutions in the vector segment $[z, y]$ of the Banach space $E = C(J, R)$. In fact, the order relation \leq introduced by Eq. (5) is equivalent to the order relation introduced by the order etcher*

$$K = \{u \in c(J, R) \mid u(t) \geq 0, \text{ for every } t \in J\}$$

that is a closed set in $C(J, R)$.

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