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# Age-Related Compensation: Neuromusculoskeletal Capacity, Reserve & Movement Objectives.

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21 **Abstract**

22 The prevention, mitigation and treatment of movement impairments, ideally, requires early diagnosis  
23 or identification. As the human movement system has physiological and functional redundancy,  
24 movement limitations do not promptly arise at the onset of physical decline. A such, prediction of  
25 movement limitations is complex: it is unclear how much decline can be tolerated before movement  
26 limitations start. Currently, the term 'homeostatic reserve' or 'physiological reserve' is used to refer  
27 to the redundancy of the human biological system, but these terms do not describe the redundancy  
28 in the muscle architecture of the human body. The result of functional redundancy is compensation.  
29 Although compensation is an early predictor of movement limitations, clear definitions are lacking and  
30 the topic is underexposed in literature. The aim of this article is to provide a definition of  
31 compensation and emphasize its importance. Compensation is defined as an alteration in the  
32 movement trajectory and/or altering muscle recruitment to complete a movement task.  
33 *Compensation for capacity* is the result of a lack in neuromusculoskeletal *reserve*, where reserve is  
34 defined as the difference between the *capacity* (physiological abilities of the neuromusculoskeletal  
35 system) and the task demand. *Compensation for movement objectives* is a result of a shift in weighting  
36 of movement objectives, reflecting changing priorities. Studying compensation in biomechanics  
37 requires altered protocols in experimental set-ups, musculoskeletal models that are not reliant on  
38 prescribed movement, and inclusion of alternative movement objectives in optimal control theory.

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41 **Keywords:** Mobility impairments, Neuromusculoskeletal models, Rehabilitation, optimal control  
42 theory, frailty, redundancy

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## 45           1. Introduction

46    By 2050, all regions except for Africa will have at least 25% of their population over 60 years old and  
47    the proportion of people aged 80 or over will have tripled by that time (UN 2019). Ageing is often  
48    accompanied by a decrease in mobility, which can lead to loss of independence, inability to work,  
49    social exclusion, and a reduced quality of life (Government office for Science 2014).

50    Ideally, movement limitations would be recognized and prevented at an early stage. Mechanisms that  
51    contribute to mobility impairments are therefore major research topics in the fields of physiology,  
52    biomechanics, and motor control. While the fields of biomechanics and motor control seek to  
53    understand the mechanisms of age-related mobility decline by understanding dynamics and control  
54    of biological systems, the field of physiology focusses on the biological processes. Combining the  
55    knowledge from these different fields is necessary to understand age-related movement impairments.  
56    Daily life activities such as walking, standing up from a chair, or ascending stairs are complex motor  
57    tasks which involve subtle muscle control and trajectory planning (Harper, Wilken, and Neptune 2018;  
58    Caruthers et al. 2016; Winter 1995). Movement limitations do not promptly arise at the onset of  
59    physical decline because the human body has redundancy (Lipsitz 2002). The *biological redundancy*  
60    available to compensate for age and disease-related changes has been referred to as the '*homeostatic*  
61    *reserve*' or '*physiological reserve*' (Clegg et al. 2013). These terms are also used to indicate frailty or  
62    whether a patient is likely to recover from an insult (Rockwood et al. 2005). However, these terms do  
63    not incorporate the redundancy in the muscle architecture of the human body, the *functional*  
64    *redundancy*. Terms such as '*physiological capacity*' (Oseid 1973), '*musculoskeletal reserve*' (Bull,  
65    Cleather, and Southgate 2008), and '*musculoskeletal capacity*' (Nygård et al. 1987) have been used,  
66    but a general understanding and definition of these terms in the fields of biomechanics and motor  
67    control is lacking.

68    Functional redundancy is key in understanding how much decline can be tolerated before movement  
69    limitations begin. The result of functional redundancy is what we will refer to as *compensation*. From  
70    the onset of physical decline until the moment that movement impairments arise, human movement  
71    strategies will include compensation. Compensation is therefore an early indicator of physical decline  
72    and as such of importance clinically.

73    Definitions and terminology on compensation as a result of functional redundancy are lacking and we  
74    feel that the topic is underexposed in literature. In this short communication we therefore propose  
75    definitions on compensation and emphasize the importance of including compensation in (age-  
76    related) biomechanics research.

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## 79 2. Compensation

80 We define compensation as an alteration in movement strategy in relation to a baseline (e.g., previous  
81 state or a control group). Compensation in movement strategies originates from the redundancy in  
82 the muscle architecture of the human body. Humans compensate by altering their movement  
83 trajectory and/or altering the muscle recruitment to complete a task:

- 84 • Movement trajectory: people can complete tasks using a variety of strategies to retain  
85 mobility including upper limb to lower limb compensations and postural changes. This form  
86 of compensation is a variation in the planned movement trajectory and can be described by  
87 kinematics. Examples are using the handrail when climbing stairs, walking with a walking aid,  
88 widening the base of support in gait, running with shorter step lengths, or standing up from a  
89 chair using the armrests.
- 90 • Muscle recruitment: this form of compensation engages the altered selection of muscle  
91 recruitment. Due to muscle architecture redundancy, compensation by altered muscle  
92 recruitment could also occur without a change in trajectory. A possible need of altered  
93 recruitment in healthy ageing could be the relative difference in decline of muscle strength  
94 between muscle groups (Gross et al. 1998; Abe et al. 2011). An example of this form of  
95 compensation is also co-contraction, which is a strategy that can be executed to increase  
96 stability (increased co-contraction) or reduce muscle activity (decreased co-contraction)  
97 through changes only in muscle recruitment, rather than changes in kinematics.

98

99 Apart from the form of compensation, we propose also to distinguish the reasons for compensation.

100 There are two forms:

- 101 • Compensation for Capacity: We define **neuromusculoskeletal (NMSK) capacity** as the  
102 physiological abilities of the neuromusculoskeletal system. With this definition of capacity, we  
103 do not directly account for changes in the endocrine, immune, cardiovascular, respiratory,  
104 renal, or brain systems. NMSK capacity accumulates due to genetic and/or environmental  
105 factors up to a point at which age-related decline sets in (Fig. 1) (Kirkwood 2005). This decline  
106 is a result of structural changes of the neural, muscular, and skeletal (including soft tissues)  
107 systems (Fig. 2). A higher peak (or plateau) capacity mitigates the effects of decline caused by  
108 ageing or age-related diseases and the rate of decline can be adjusted through environmental  
109 factors (Warburton, Nicol, and Bredin 2006). Next, we define **NMSK reserve** as task specific  
110 and the difference between the capacity and the task demands (Fig. 1). Positive reserve  
111 enables the execution of a task. As task requirements vary over the duration of the task, so  
112 does reserve. Therefore, inability to achieve the activity may occur for only a portion of the

113 task but still results in task failure. For example, in standing up, the point of lift off from the  
 114 chair has the highest task demand and the reserve for this part of the task is therefore  
 115 smallest. It is likely that this part of the task execution will become impaired first. We define  
 116 **Compensation for capacity** as a changed recruitment of NMSK resources in response to a low  
 117 reserve (relatively high task demand) in any part (neural, muscular, skeletal) of the NMSK  
 118 capacity that can occur at any moment during task execution.

- 119 • Compensation for Movement Objectives: Within the redundancy of capacity and reserve,  
 120 humans both consciously and unconsciously decide on movement strategies. To achieve a  
 121 movement goal, there are several feasible strategies within the capacity each with their own  
 122 task demands. For example, some strategies might demand more from the neural than the  
 123 muscular system, and some strategies are less stable than others.

124 Energy-related costs are thought to be the primary driver for cyclic movements like standard  
 125 gait (Anderson & Pandy, 2001; Cavagna & Franzetti, 1986; Hoyt & Taylor, 1981; Kuo, 2001;  
 126 Minetti, Ardigo, Reinach, & Saibene, 1999), but there are other drivers (Malatesta et al. 2003;  
 127 Raynor et al. 2002). The applied motion strategy of humans is probably a consideration of  
 128 metabolic energy, velocity, stability (safety), and/or pain avoidance; these we jointly refer to  
 129 as the **movement objectives**. Especially in ageing and neuromuscular deficiencies, it is likely  
 130 that more emphasis is placed on alternative objectives, such as stability to minimise falling.  
 131 Therefore, strategy selection is critical in movement impairments, although the specific  
 132 objectives that are optimised in daily movements are not yet known. **Compensation for**  
 133 **movement objectives** manifests as altered movement strategies due to changes in the  
 134 weighting of movement objectives.

135

136 When compensation no longer enables the execution of the task at hand, inability and mobility  
 137 limitations arise (Fig. 1). Capacity determines whether and which compensation strategies are  
 138 available. Compensation and capacity are therefore overlapping and interacting. Individuals with  
 139 greater capacity have more room to deploy effective compensation strategies. But compensation  
 140 strategies can also be detrimental when they result in a habitual over- or underuse of physiological  
 141 abilities. Elderly people can end up in a negative cycle (cycle of frailty), which accelerates decline of  
 142 capacity (Xue 2011). A similar mechanism is prevalent in the young after traumatic incidents (Schmitt,  
 143 Paterno, and Hewett 2012; Barenius et al. 2014; Cinque et al. 2018). The compensation applied after  
 144 a stressor, for example asymmetry in gait to unload the involved side, can permanently change  
 145 movement strategies. Such asymmetry could cause underuse of the involved side and overuse of the  
 146 non-involved side, thereby putting neuromuscular capacity into decline in the long-term.

147

### 148 **3. Selection of Compensation Strategies**

149 Compensation often occurs ahead of when the physical decline results in a lack of reserve. In other  
150 words, humans alter their kinematics before this seems physically necessary. Moreover, within the  
151 NMSK capacity and reserve there are several feasible movement strategies.

152 To account for this, the field of biomechanics and motor control mostly assumes that the selection of  
153 movement strategies is to occur through a continuous optimization of a cost function (*optimal control*  
154 *theory*) (Todorov and Jordan 2002). In this context, movement objectives and their relative weighting  
155 could be considered as a multi-objective function resulting in a weighted average. Often cost functions  
156 in this field minimize an energy objective, while there might be alternatives. The shift in weighting  
157 factors of multiple movement objectives may explain age-related differences in movement strategies.  
158 As an example, the relationship between oxygen consumption per unit distance and gait speed has a  
159 minimum which matches the preferred walking speed in adults (“optimal walking speed”) (Pearce et  
160 al. 1983; di Prampero 1986). In older adults, however, preferred walking speed declines and energy  
161 expenditure per unit distance increases (Malatesta et al. 2003). Part of this can be explained by  
162 biological changes (objectively lower efficiency), but part of this is due to the selection of a slower  
163 walking speed. Selecting a lower walking speed suggests a shift in the weighting of the movement  
164 objectives that results in a less energetically economic movement pattern (Malatesta et al. 2003). This  
165 has been postulated as the minimisation of muscular fatigue rather than the minimisation of  
166 metabolic cost of transport (Song and Geyer 2018). However, there is no study to date that has  
167 explored possible psychological reasons for this, such as an increased emphasis on stability or pain  
168 avoidance. Humans likely make comparative assessments of movement objectives based on the task  
169 goal, their capacity, and psychological reasons related to a fear of falling, pain, or an unknown  
170 environment (Papa and Cappozzo 2000); the emphasis on energy-cost alone is inadequate to  
171 characterize movement, particularly in an ageing population.

172

### 173 **4. Compensation in Biomechanics Research**

174 To summarize, NMSK capacity declines with healthy ageing. This decline is apparent in the neural,  
175 muscular, and skeletal systems and each influence the execution of complex motor tasks. For a specific  
176 task, humans have NMSK reserve, so that, if NMSK capacity reduces, the task can still be achieved.  
177 Humans compensate by altering their movement trajectory and/or altering the muscle recruitment to  
178 complete a task. Compensation can be a result of a lack of reserve, when capacity does not meet the  
179 task demands, or due to a shift in weighting of movement objectives, reflecting changing priorities.

180 Experimental design plays an important role in facilitating or constraining compensation strategies.  
181 Many studies impose standardisations on protocol, so the possibility of compensation is restricted.  
182 For example, most studies on sit-to-stand do not permit the participants to compensate using their  
183 arms, thus limiting their translation to characterising mobility of the elderly in their homes,  
184 communities, and clinic (van der Kruk & Bull, 2019). They therefore also do not provide insight into  
185 how much decline can be tolerated before movement limitations in daily life arise nor how humans  
186 select compensatory movement strategies for a task.

187

188 Musculoskeletal models and simulations are useful tools for estimating variables in human movement  
189 that are difficult to measure directly in human subjects. Models allow for simulations that cannot be  
190 performed with human subjects, such as studying site specific muscle weakness (e.g. Smith, Reilly, and  
191 Bull 2019). The conventional method in these modelling approaches, however, uses prescribed  
192 (measured) kinematics. Therefore, these simulations do not incorporate compensation. If wanting to  
193 model compensation, kinematics should be generated *de novo* (without tracking experimental data)  
194 using predictive simulations (Ong et al. 2017; Geijtenbeek 2019; Falisse et al. 2019). However, current  
195 state-of-the-state predictive models are too limited to simulate compensation strategies in daily life  
196 activities, as they have been simplified to upper or lower limb separately, mostly in two dimensions  
197 (Ong et al. 2017; Falisse et al. 2019; Song and Geyer 2018). In reality, people often use out-of-plane,  
198 asymmetric, and upper-lower-limb compensation strategies, like arm support in standing up or stair  
199 walking. These models therefore need further development before providing valid insights into  
200 compensation strategies of humans.

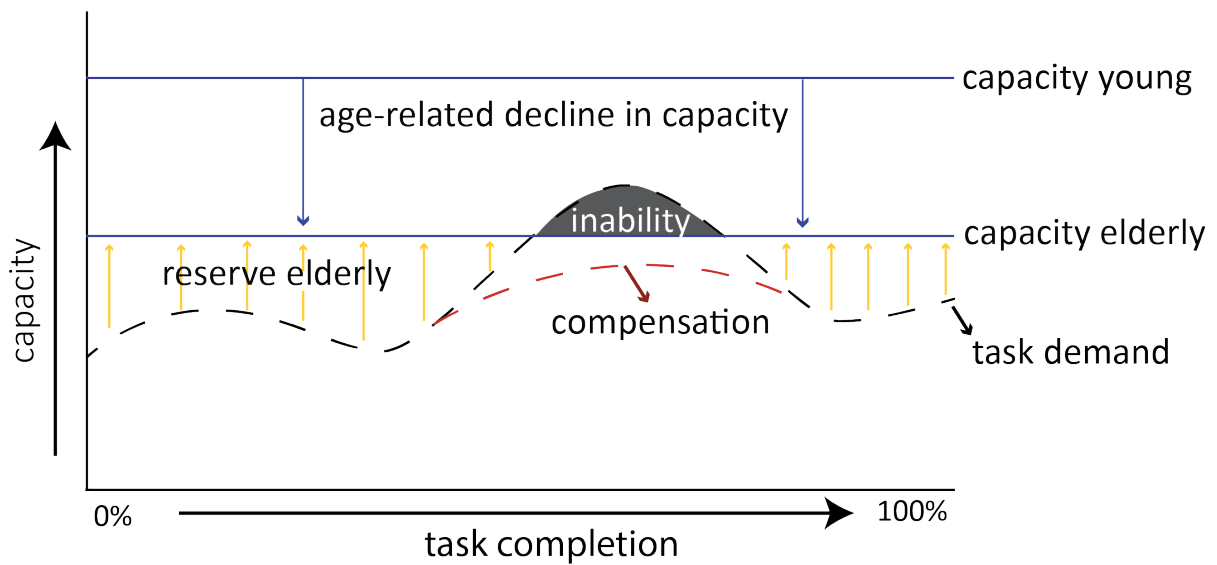
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206 **FIGURE 1:** Capacity, Reserve & Compensation

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208 *Figure 1: Reserve is the difference between the capacity and the task demands. Capacity is defined as the*  
 209 *physiological abilities of the neuromusculoskeletal system, in this case available for this task. If the reserve*  
 210 *cannot meet the task demands, compensation will occur which changes the task demands while achieving the*  
 211 *same goal.*

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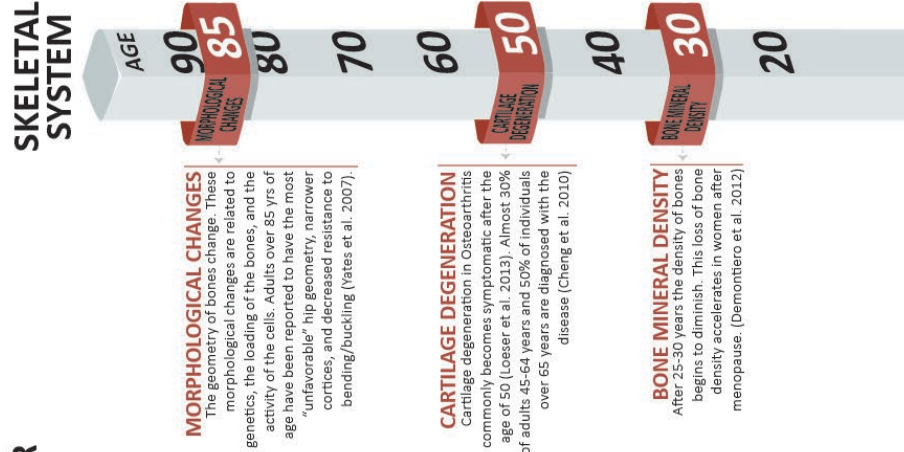
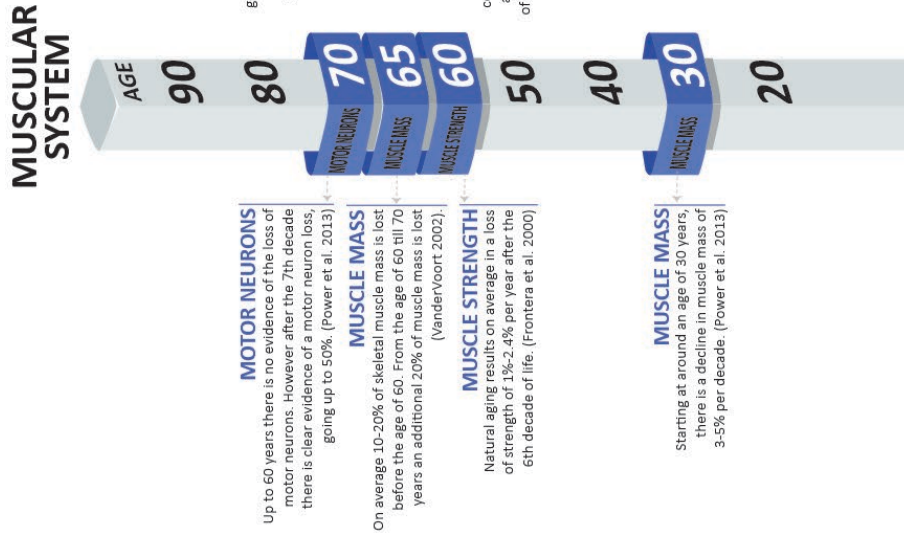
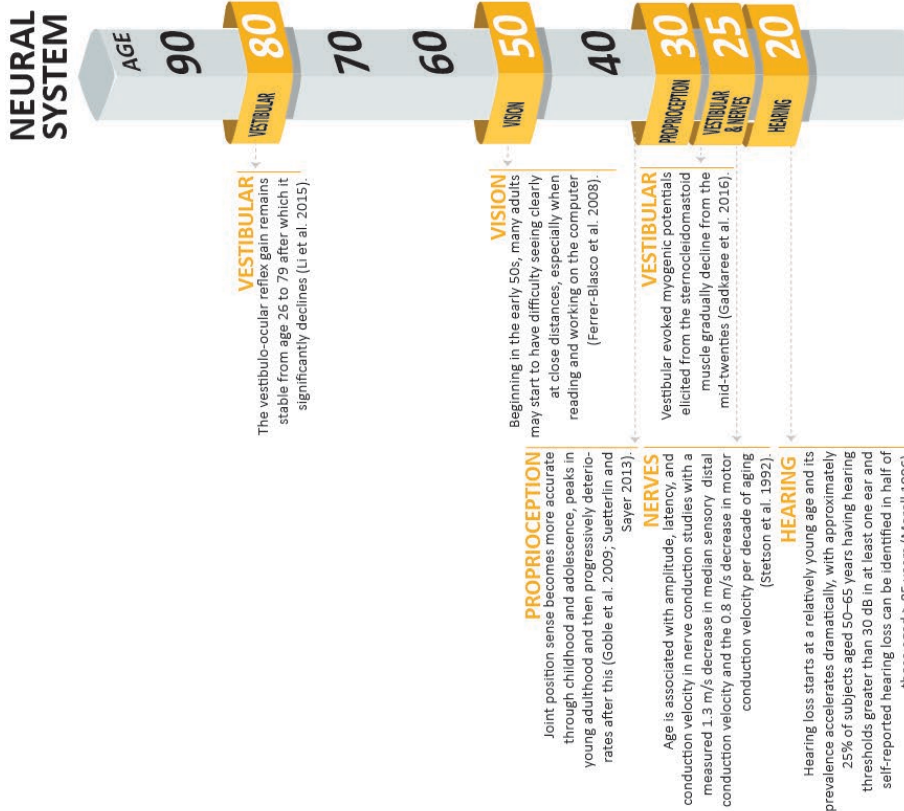
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217 **[ Next page: FIGURE 2:** General onset of decline in the adult neural, muscular and skeletal  
 218 **system (Goble et al. 2009; Suetterlin and Sayer 2013; Gadkaree et al. 2016; Cheng et al.**  
 219 **2010).]**

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