

Discussion

# The Triangle Wave Versus the Cosine: How Classical Systems Can Optimally Approximate EPR-B Correlations

Richard David Gill <sup>1</sup> 

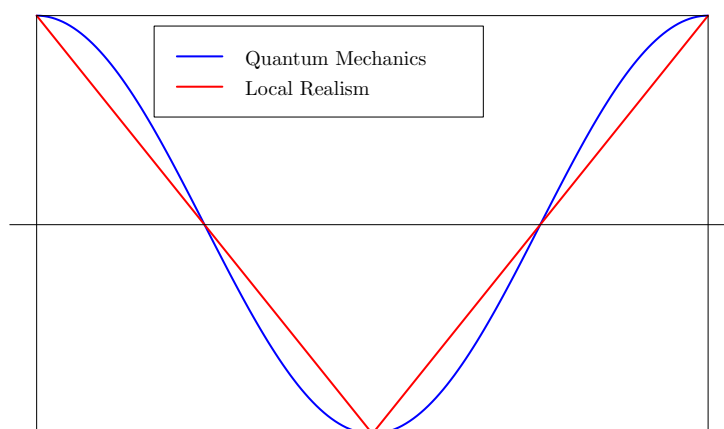
<sup>1</sup> Leiden University, Faculty of Science, Mathematical Institute; gill@math.leidenuniv.nl

1 **Abstract:** The famous singlet correlations of a composite quantum system consisting of two spatially  
2 separated components exhibit notable features of two kinds. The first kind are striking *certainty*  
3 *relations*: perfect correlation and perfect anti-correlation in certain settings. The second kind are a  
4 number of symmetries, in particular, invariance under rotation, as well as invariance under exchange  
5 of components, parity, or chirality. In this note I investigate the class of correlation functions that can  
6 be generated by classical composite physical systems when we restrict attention to systems which  
7 reproduce the certainty relations exactly, and for which the rotational invariance of the correlation  
8 function is the manifestation of rotational invariance of the underlying classical physics. I call such  
9 correlation functions *classical EPR-B correlations*. It turns out that the other three (binary) symmetries  
10 can then be obtained “for free”: they are exhibited by the correlation function, and can be imposed  
11 on the underlying physics by adding an underlying randomisation level. We end up with a simple  
12 probabilistic description of all possible classical EPR-B correlations in terms of a “spinning coloured  
13 disk” model, and a research programme: describe these functions in a concise analytic way.

14 **Keywords:** Singlet correlations, twisted Malus law, EPR-B experiments, local hidden variables,  
15 spinning coloured disk model, spinning coloured ball model, simulation models

## 16 1. The problem, in a picture

17 Just about every introduction to Bell’s theorem contains the following picture.



**Figure 1.** Correlation, between  $-1$  and  $+1$ , plotted against angle between measurement directions, from  $-\pi$  to  $\pi$

18 The accompanying text claims that the triangle wave is the prediction of local realism, the beautiful  
19 (negative) cosine curve is the prediction of quantum mechanics. However, the triangle wave is just one  
20 of many *possible* correlation functions allowed by local realism, but by no means the only one. In some  
21 sense it might be the best ... but in what sense? I am unaware of a decent mathematical answer to  
22 this question. The following notes make an attempt to describe concisely, all that local realism allows  
23 when some key features of the curve are insisted on. The picture shows the correlations obtained when  
24 two parties measure something called “spin”, each on one of two correlated (or entangled) particles;  
25 they can measure in any direction in a certain plane; their measurement outcome is binary (spin up  
26 or spin down in the chosen direction). The  $x$  axis of the graph represents the angle between the two  
27 measurement directions.

28 In theory one could also measure in directions in 3D space. One can clearly ask the corresponding  
29 new mathematical question. That question was formulated, and partially answered, by Kent and  
30 Pitalúa-García (2014) [1]. The present paper was first posted to arXiv in 2013, at the same time as an  
31 arXiv preprint of the Kent and Pitalúa-García paper. As far as I know, there have been no further  
32 developments since then!

33 I recently became aware of an interesting, much earlier, paper by Toner and Bacon (2003) [2]  
34 which actually rather satisfactorily solves a somewhat related problem: how many bits of classical  
35 communication are needed for two classical agents, Alice and Bob, to reproduce the 3D quantum  
36 correlations? The answer turns out to be just one bit (on average) and the required communication  
37 protocol is “simple” according to the authors. Now, making use of the *detection loophole* to classically  
38 simulate quantum correlations is also a case of using, in effect, classical communication, namely by  
39 rejecting some runs: Alice and Bob are allowed to “try all over again” if either experiences an adverse  
40 event. One wants protocols such that each of the two parties ends up with an outcome and moreover  
41 both know that the other has an outcome too. It seems to me that the various problems – faking *all* the  
42 singlet correlations (either with settings in  $S^1$  or with settings in  $S^2$ ) and doing it with the detection  
43 loophole, or with classical communication, or without any cheating at all but just optimising a sensible  
44 expression of the numerical quality of the approximation – are quite subtly related, and that it should  
45 be possible to convert solutions of one problem to a solution of another.

46 The original version of this paper was written in 2013 and appeared on arXiv as <https://arxiv.org/abs/1312.6403>. It has been resting, waiting for new ideas, for five years.

## 48 2. The problem, formalised

49 According to quantum mechanics, it is in principle possible to arrange the following experiment.  
50 Alice and Bob are in their respective laboratories at distant locations, but have set up all kinds of  
51 practical arrangements in advance. In particular, they are at rest with respect to the same inertial frame  
52 of reference and they have set up accordingly synchronised clocks. They both possess some kind of  
53 random number generators and are able to simultaneously and independently choose angles  $\alpha$  and  $\beta$   
54 in the interval  $[0, 2\pi)$  according to any desired probability distributions. They each input their chosen  
55 angle into a physical device in each of their laboratories and after a short time interval, the device  
56 responds with a binary output, which we shall code numerically as  $\pm 1$ . The length of time between  
57 initiating the choice of random angle and output of  $\pm 1$  is so short that a signal travelling at the speed  
58 of light and carrying Alice’s chosen angle from Alice’s to Bob’s lab could not arrive till after Bob’s  
59 output is fixed, and vice-versa. We call the inputs *settings* and the outputs *outcomes*.

60 This can now be repeated independently as many times as one likes, say  $N$  times, resulting in  
61 synchronised lists, all of length  $N$ , of settings (angles) and outcomes ( $\pm 1$ ) at the two locations. We call  
62 these  $N$  repetitions *runs*.

63 In an ideal experiment, the outcomes of each separate run (a pair of random numbers  $\pm 1$ )  
64 are statistically independent from those of other runs and distributed according to the following  
65 conditional probability law (conditional on the chosen settings  $\alpha$  and  $\beta$ ):

$$\Pr(++ ) = \Pr(-- ) = \frac{1}{4} \left( 1 - \cos(\alpha - \beta) \right),$$

$$\Pr(+ - ) = \Pr(- + ) = \frac{1}{4} \left( 1 + \cos(\alpha - \beta) \right).$$

66 These joint probabilities are a manifestation of the *twisted Malus law*.

67 Notice that these joint probabilities possess a large number of symmetries: they are symmetric  
68 with respect to rotation, parity switch (exchange of outcome values  $\pm 1$ ), exchange of the two parties  
69 (Alice and Bob), and chirality switch (exchange of clockwise and anti-clockwise). They also reflect two  
70 “certainty” relations: at exactly equal settings, outcomes are opposite with probability one; at exactly  
71 opposed settings, outcomes are equal with probability one. As a consequence of the symmetry in  
72 outcome values, we also have a “complete randomness” property: each outcome separately, whatever  
73 the setting, is a symmetric Bernoulli trial with outcomes  $\{-1, +1\}$ .

### 74 3. Classical physical representation

75 If these outcomes were generated by a classical (i.e., local realist) physical model, we would  
76 be able to construct simultaneously defined random variables  $A(\alpha)$  and  $B(\beta)$ ,  $\alpha, \beta \in [0, 2\pi)$ , such  
77 that in one run of the experiment, all these random variables are realised simultaneously, and the  
78 actually observed outcomes are merely selected by the *independent* choice of settings  $\alpha, \beta \in [0, 2\pi)$ . It  
79 seems physically reasonable to assume that the joint probability distribution of the complete stochastic  
80 processes  $A, B$  satisfies the same symmetries: i.e., the symmetries observed in the twisted Malus law  
81 reflect underlying (physical, fundamental) model symmetries.

82 In fact, under measurability conditions, we can symmetrize a given model, converting a  
83 non-symmetric model to a fully symmetric one: this is because probabilistic mixing of stochastic  
84 processes with the same, given, marginal distributions, results in a new stochastic process with the  
85 same marginal distributions. I will only explicitly impose the symmetry under rotations. As we  
86 will see, because of the “certainty relations” which we also impose, the other symmetries in the  
87 correlation functions are automatically true. So whether or not the other symmetries are imposed  
88 on the underlying process makes no difference to the family of correlation functions which can be  
89 generated by the model.

90 I already used the difficult word measurability and I need now to pay this tricky topic some  
91 further attention. So far we have just assumed the existence of a single probability space on which  
92 are defined two indexed families of binary random variables  $A(\alpha)$  and  $B(\beta)$ . It follows that joint  
93 probability distributions of any finite number of these random variables are also well defined. The  
94 random function  $A(\alpha), \alpha \in [0, 2\pi)$  takes values in  $\{-1, +1\}$  but might in principle be extraordinarily  
95 irregular. However, I would like to argue that it can at least be approximated by a piece-wise constant  
96 function making only a finite number of changes of value: in other words,  $\{\alpha \in [0, 2\pi) : A(\alpha) = 1\}$  is  
97 a finite union of intervals, and so of course too is its complement  $\{\alpha \in [0, 2\pi) : A(\alpha) = -1\}$ ; and the  
98 same for  $B$ .

99 Here is one argument, heuristic to be sure. First of all, in my opinion there is no loss of *physical*  
100 generality in assuming that any realisation of the set  $\{\alpha \in [0, 2\pi) : A(\alpha) = 1\}$  is a Borel measurable  
101 subset of  $[0, 2\pi)$ . Here is a mathematical argument for this physical claim. If one is prepared to  
102 reject the axiom of choice, it is possible to axiomatically demand that all subsets of the real line are  
103 measurable. The mathematical existence of non-measurable sets is apparently a matter of mathematical  
104 taste, it refers to how large or small we want our abstract mathematical universe to be. Note that with  
105 the axiom of choice, though they exist mathematically, non-measurable sets cannot be constructed or  
106 computed or exhibited in any sense.

107 So let's assume the realisations of the just mentioned sets are at least nice enough that they are  
108 Borel measurable. Now, any bounded measurable subset of real numbers can be arbitrarily well  
109 approximated by finite unions of intervals in the following sense: for any  $\epsilon > 0$  one can find an

110 approximating set (a finite union of intervals) such that the set-theoretic difference between the set  
 111 being approximated and its approximation can be covered by a countable set of intervals the sum of  
 112 whose lengths is at most  $\epsilon$ .

113 These ideas lead to me to propose that (up to an arbitrarily good approximation, in a precise  
 114 mathematical sense which has yet to be determined), the sample paths of  $A$  and  $B$  are very regular  
 115 indeed: only a finite number of jumps between  $\pm 1$ .

116 An alternative approach would be to only consider a finite number of different angles altogether:  
 117 for instance, only angles which are expressed as a whole numbers of degrees, minutes, and seconds.  
 118 Instead of continuous rotational symmetry we have discrete rotational symmetry. There are now no  
 119 measurability or regularity issues at all. The analysis we are going to make in the regular, continuous  
 120 index case, can also be made in the discrete index case, subject to the obvious modifications. We will  
 121 remark later on how the results would be modified.

122 So let us suppose that (perhaps after an initial approximation), the stochastic processes  $A$  and  $B$   
 123 are such that the sets of angles where they take their possible values  $\pm 1$  are finite unions of intervals. It  
 124 can be shown from this that the angles at which the value jumps between  $\pm 1$ , and the number of those  
 125 angles, are random variables (they can be written as limits of functions of finitely many coordinates).

126 Think of the sample paths of  $A$  and  $B$  as two functions on the unit circle. Because of one of the  
 127 "certainty relations" between  $A$  and  $B$  it follows that the sample path of  $B$  is identical to the path of  $A$   
 128 after rotation through an angle  $\pi$ . It also follows from the other that the sample path of  $B$  is identical  
 129 to the negative of the path of  $A$ . Thus the two sample paths are determined completely by the path of  
 130  $A$  on the first half of the circle,  $[0, \pi)$ . The negative of the same path is repeated, for  $A$ , on  $[\pi, 2\pi)$ ; and  
 131 the path of  $B$  is the path of  $A$  shifted (rotated) a distance  $\pi$ .

132 Let us suppose that the joint probability distribution of  $A$  and  $B$  is invariant under rotation, just as  
 133 the correlation function is. We can write the joint probability distribution of the processes  $A$  and  $B$  as a  
 134 probabilistic mixture over the numbers of jumps of each process. It can be argued (details in a later to  
 135 be written appendix?) that any such probability distribution can be built up as follows, according to  
 136 what I call the randomised spinning coloured disk model.

#### 137 4. The randomised spinning coloured disk

138 Pick (at random) an even number  $k \geq 0$  and angles  $0 < \theta_1 < \dots < \theta_k < \pi$ . Colour the  $k + 1$   
 139 segments  $(0, \theta_1)$ ,  $(\theta_1, \theta_2)$ ,  $\dots$ ,  $(\theta_k, \pi)$  "black", "white",  $\dots$ , "black". If  $k = 0$  there is just one segment  
 140  $(0, \pi)$ , and it is coloured black. Colour  $(\pi, 2\pi)$  in complementary way:  $(\pi, \pi + \theta_1)$ ,  $\dots$ ,  $(\pi + \theta_k, 2\pi)$  are  
 141 coloured "white", "black",  $\dots$ , "white". The colour assigned to end-points does not matter. We have  
 142 now coloured the entire unit circle with our two colours "white" and "black" except that we didn't  
 143 determine the colours of the finitely many points on the boundaries between intervals of fixed colour.  
 144 Each point is opposite a point of the opposite colour, so the total length of white segments and the  
 145 total length of black segments are equal. Now give the coloured unit circle a random rotation chosen  
 146 uniformly between  $0$  and  $2\pi$ . Define  $A(\alpha) = \pm 1$  according to whether the colour of the randomly  
 147 rotated circle at point  $\alpha$  is black or white. Define  $B$  as the rotation of  $A$  through the angle  $\pi$ .  $A$  and  $B$   
 148 aren't defined at finitely many angles, but we don't have to worry about this. The probability is zero  
 149 that  $A$  is undefined at any particular given point.

150 If we choose  $k$  at random according to an arbitrary probability distribution over the even  
 151 non-negative integers, and then  $0 < \theta_1 < \dots < \theta_k < \pi$  according to an arbitrary joint distribution  
 152 given  $k$ , and finally choose a rotation of the coloured circle completely at random, we have defined  
 153 two stochastic processes  $A$  and  $B$ , except at finitely many points, such that the joint probability  
 154 distribution of  $A$  and  $B$  is invariant under rotation and possesses the desired "certainty relations". My  
 155 mathematical claim is that this recipe generates the class of all possible processes  $A$  and  $B$  subject to  
 156 rotation invariance, certainty relations, and regularity of sample paths (finitely many sign changes). It  
 157 therefore generates all of these process's correlation functions. By adding to these correlation functions

158 also all possible limits (in some precise sense) of such functions one also includes correlations of  
159 processes which can be obtained as limits (in some precise sense) of regular ones.

160 Marginally, each  $A(\alpha)$  and  $B(\beta)$  represents a symmetric Bernoulli trial, each is a symmetric  
161 Rademacher random variable. The joint distribution of the two stochastic processes  $A, B$  is not  
162 necessarily invariant under any of chirality switch, parity switch, or component exchange. However,  
163 the joint distribution of  $A(\alpha), B(\beta)$  for any fixed pair of angles  $(\alpha, \beta)$  does possess all these invariances.  
164 This joint probability distribution consists of four probabilities adding to one. Since its two margins  
165 are symmetric Bernoulli trials, the joint distribution is completely determined by the single number  
166  $\Pr(A(\alpha) = B(\beta)) = \Pr(A(\alpha) \neq A(\beta))$  which is the probability that the number of colour switches on  
167 the randomly rotated coloured unit circle between angles  $\alpha$  and  $\beta$  is odd. This probability can only  
168 depend on the *absolute value* of the difference between these angles, hence is invariant under parity,  
169 party and chirality switch.

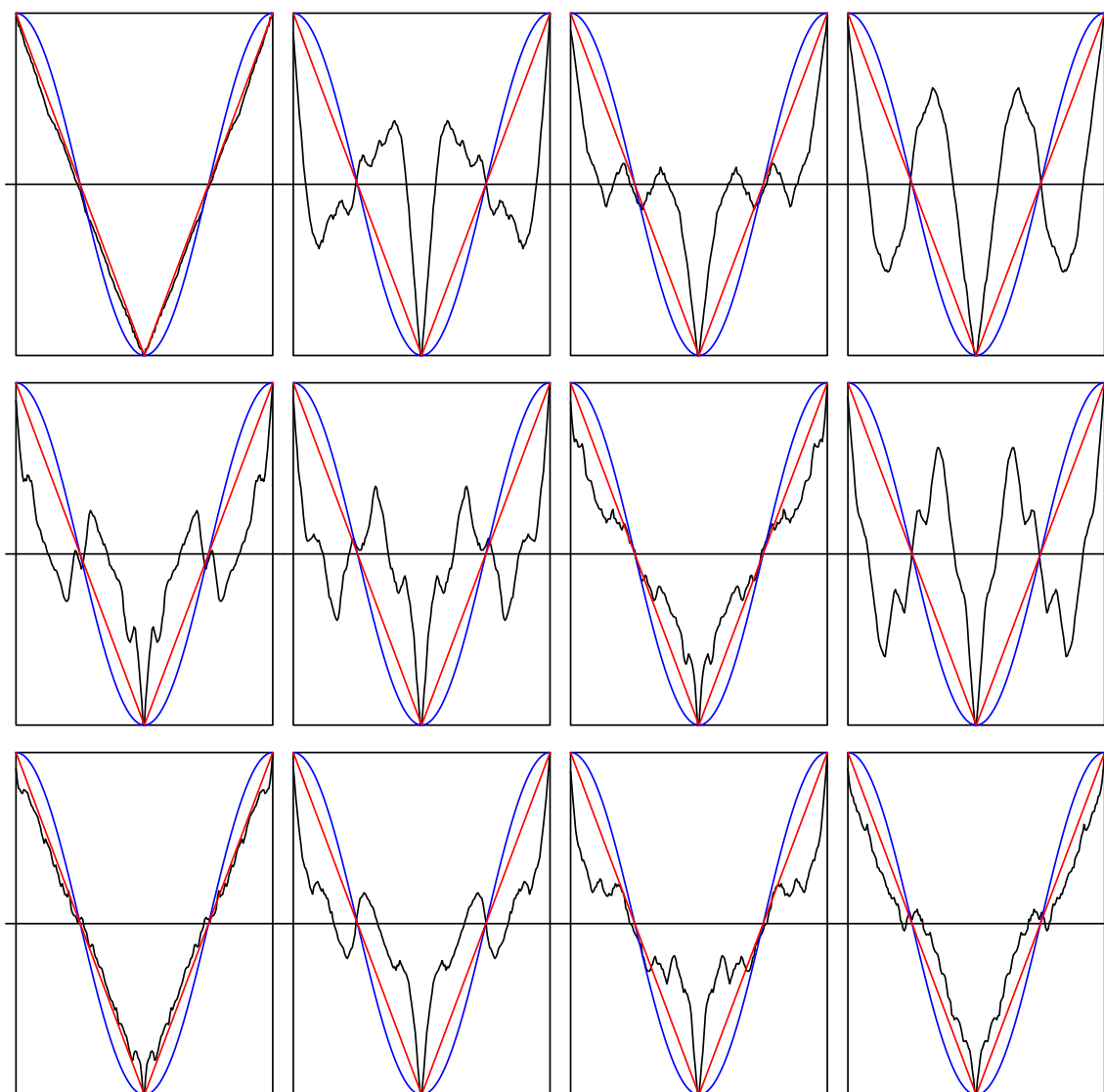
170 The raw product moment between  $A(\alpha)$  and  $B(\beta)$  is the expectation of its product, and is easily  
171 seen to be equal to  $2\Pr(A(\alpha) = B(\beta)) - 1$ . Within our local realist model,  $B(\beta) = -A(\beta)$  so that is  
172 the same as  $2\Pr(A(\alpha) \neq A(\beta)) - 1$ . If we write  $\delta = \beta - \alpha$  then we obtain from this the correlation  
173 function  $\rho(\gamma) = 2\Pr(A(\gamma) \neq A(0)) - 1$ .

## 174 5. Computation

175 The arguments given so far show that the set of all possible correlation functions  $\rho$  is the set of all  
176 convex combinations (including continuous combinations) of correlation functions corresponding to  
177 some even number  $k \geq 0$  and some  $0 < \theta_1 < \dots < \theta_k < \pi$ . To each  $k$  and  $\theta_1, \dots, \theta_k$  there corresponds a  
178 colouring of the unit circle. This colouring determines stochastic processes  $A$  and  $B$ . Their correlation  
179 function  $\rho$  can be described in terms of the colouring of the unit circle as follows: pick a point uniformly  
180 at random on the unit circle. Then  $\rho(\gamma)$  is the probability that the uniform random point has the  
181 opposite colour (black or white) to that of the point at a distance  $\gamma$  clockwise around the circle from  
182 the first chosen point.

183 The following R script calculates (by Monte Carlo integration) and graphs a sample of 12 such  
184 correlation functions, all with  $k = 4$ , but with various values of  $\theta_1$  to  $\theta_4$ .

```
185
186 1 oneplot <- function() {
187 2   if (nswitch%%2 == 0) times <- c(times,1)
188 3   timesplus <- c(times, times+1, times+2, times+3)
189 4   count <- function(t,d) sum(timesplus > t & timesplus <= t+d)
190 5   points <- seq(from=0, to=1, by=0.01)
191 6   numbers <- outer(data, points, Vectorize(count))
192 7   corr <- 2*(apply(numbers%%2, 2, sum)/1000)-1
193 8   correlation <- c(corr[100:1], corr)
194 9   difference <- pi*(c(points, 1+points[2:101]))
19510  plot(difference, correlation,
19611      type="l", bty="n", ann=FALSE, xaxt="n", yaxt="n")
19712  lines(c(0, 2*pi, 2*pi, 0, 0), c(+1, +1, -1, -1, +1))
19813  abline(h=0)
19914  lines(difference, cos(difference), col="blue")
20015  lines(c(0, pi, 2*pi), c(+1, -1, +1), col="red")
20116 }
20217 nswitch <- 4
20318 set.seed(11091951)
20419 par(mfrow=c(3,4), oma=c(0,0,0,0), mar=c(0,0,0,0))
20520 for(i in (1:12)) {
20621   times <- sort(runif(nswitch))
20722   data <- 2*runif(1000)
20823   oneplot()
20924 }
```



**Figure 2.** 12 random classical EPR-B correlations (in black), with coloured disks of 10 segments. Notice that some exceed the triangle wave (red) at some points where the triangle wave is positive.

211 The reader is invited to replace the assignment `nswitch <- 4` (“nswitch gets the value 4”) by  
 212 assignments of other even numbers and look at the results.

## 213 6. Conclusion: what next?

214 This note is a research proposal rather than a report of definitive results. There are two main  
 215 directions to explore, mathematically. One direction concerns the investigation of regularity conditions  
 216 and approximation. I think it is mathematically important to tidy up the details but I do not think this  
 217 direction is physically or metaphysically interesting. Suppose we only considered measurement angles  
 218 which were whole numbers of degrees, minutes and seconds. Then there are no regularity issues at all  
 219 and the representation of all classical physical EPR-B models through a random spinning disk model  
 220 is mathematically precise: the lengths of the segments of the disk of different colours are restricted to  
 221 be whole numbers of seconds; and at the end, we only investigate the correlation functions at whole  
 222 numbers of seconds. Thus we finish up looking at a slightly smaller class of correlation functions, and  
 223 we only look at them at on the very fine lattice of “whole second” angles.

224 The other direction is more interesting. Let’s accept the class of correlation functions arising from  
 225 the spinning disk model. Can we analytically describe this class of functions, or the topological closure

226 of this class of functions (according to a convenient but meaningful topology) in an alternative succinct  
227 way? For instance, is there an elegant description of the characteristic functions of these correlation  
228 functions?

229 An intriguing possible direction involving indeed the Fourier transform is suggested by some  
230 lecture slides by Steve Gull, going back now 35 years. On his “MaxEnt 2009” web-page [http://www.  
231 mrao.cam.ac.uk/~steve/maxent2009/](http://www.mrao.cam.ac.uk/~steve/maxent2009/), under the heading *Quantum Acausality and Bell’s Theorem*, Steve  
232 writes

233 Many years ago (about 1984), I used to give a Mathematical Physics course to the Part II  
234 students. I illustrated the quantum paradox covered by Bell’s theorem by showing that  
235 you can’t program two independently running computers to mimic the results of spin  
236 measurements on two spin-1/2 particles in a singlet state. I believe this demonstration is  
237 actually better than Bell’s original argument.

238 His slides can be found at <http://www.mrao.cam.ac.uk/~steve/maxent2009/images/bell.pdf>. They  
239 sketch a lovely proof of Bell’s theorem using the fact that the Fourier transform of the correlation  
240 function  $\rho$  has to equal the expected squared absolute value of the Fourier transform of the random  
241 function  $A$ . The actual correlation function only has three non-zero Fourier coefficients. However  
242 the Fourier transform of any realisation of  $A$  must have infinitely many non-zero coefficients, since  
243 otherwise it could not have any jumps. Since their absolute values get squared before averaging, there  
244 is no way that all but three can vanish.

245 I have two ideas where to go next. Firstly, if we insist that the correlation function not only has the  
246 symmetries we want, but is also monotone decreasing (between 0 and  $\pi$ ) that will further narrow the  
247 possibilities. Maybe there is only one left – the triangle wave of my first picture? Classical correlations  
248 can exceed quantum correlations but, it seems, only at the cost of oscillations. Secondly, we can express  
249 the  $L_2$  distance between two curves in terms of the  $L_2$  distance between their Fourier transforms: might  
250 that give us a way to show that the triangle wave is the closest approximation to the cosine?

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252 **Conflicts of Interest:** The author declares no conflict of interest

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