

1 Article

## 2 Effects of Channel Wall Twisting on the Mixing in a 3 T-Shaped Micro-Channel

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7 Received: date; Accepted: date; Published: date

8 **Abstract:** A new design scheme is proposed for twisting the walls of a microchannel, and its  
9 performance is demonstrated numerically. The numerical study was carried out for a T-shaped  
10 microchannel with twist angles in the range of 0 to  $34\pi$ . The Reynolds number range was 0.15 to 6.  
11 The T-shaped microchannel consists of two inlet branches and an outlet branch. The mixing  
12 performance was analyzed in terms of the degree of mixing and relative mixing cost. All numerical  
13 results show that the twisting scheme is an effective way to enhance the mixing in a T-shaped  
14 microchannel. The mixing enhancement is realized by the swirling of two fluids in the cross section  
15 and is more prominent as the Reynolds number decreases. The twist angle was optimized to  
16 maximize the DOM, which increases with the length of the outlet branch. The twist angle was also  
17 optimized in terms of the relative mixing. The two optimum twisting angles are generally not  
18 coincident. The optimum twist angle shows a dependence on the length of the outlet branch but it  
19 is not affected much by the Reynolds number.

20 **Keywords:** T-shaped microchannel; degree of mixing; twisting angle  
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### 22 1. Introduction

23 Microscale fluid mixing is needed to homogenize reagents in many microfluidic systems, such  
24 as microreactors and micrototal analysis systems ( $\mu$ TASs). Applications include biological and  
25 chemical reactions, the dilution of drug solutions, and sequencing nucleic acids [1]. In these systems,  
26 the mixing is usually done in various types of microchannels. However, the fluid flows are extremely  
27 slow and have very low Reynolds numbers. Therefore, molecular diffusion is a major mechanism of  
28 mixing. It is very important to enhance the mixing for the design of microchannels [2].

29 The techniques to improve mixing in microchannels can be classified as passive, active, or  
30 combined techniques. One major difference is the usage of an external energy source other than the  
31 energy source that drives the flow. Active techniques use various types of external energy sources,  
32 such as electrokinetic [3], magneto-hydrodynamic [4], electroosmotic [2], ultrasound wave [5], and  
33 pulsed flow sources [6, 7]. In contrast, passive techniques use the channel geometry or wall  
34 modifications to agitate or generate secondary flow in microchannels. Therefore, passive techniques  
35 are much easier to integrate into microfluidic systems. Combined methods involve both passive and  
36 active techniques. For example, Chen et al. [8] used a pulsatile flow through wavy channel walls,  
37 while Lim et al. [9] combined a periodic osmotic flow with geometry modification.

38 Passive techniques can be categorized into several groups according to how the channel is  
39 modified. Many passive techniques modify the channel wall of the outlet branch, which is the portion  
40 of a microchannel after the junction where the two fluids merge. Some examples use recessed grooves  
41 in the channel wall [10] and a herringbone wall [11]. The second type of technique involves building  
42 structures inside the channel, such as indentations and baffles [12, 13], periodic geometric features  
43 [14], and a simple block in the junction [15].

44 The third type of technique involves rearranging the overall structure of THE microchannel  
45 instead of using a straight microchannel. For example, Kashid et al. [16] studied five different generic

46 microchannel designs with focus on the region before the fluid merges. They tested five different  
 47 layouts of inlet branches. Kockmann et al. [17] studied various mixer structures to obtain higher  
 48 mixing in micromixers. Other examples are the AccoMix split-and-recombine technique by Panic et  
 49 al. [18], the FAMOS multi-lamination micromixer by Keoschkerjan et al. [19], and the K-M collision  
 50 micromixer by Schneider et al. [20]. These designs use complex elements such as multiple flow  
 51 passages, 3-dimensional structures, and curved or non-straight channels.

52 Recently, a new concept of twisting the outlet branch has been studied to enhance the mixing in  
 53 a microchannel. For example, Jafari et al. [21] studied a twisted channel with the Reynolds number  
 54 ranging from 76.7 to 460.3. They coiled the outlet branch at a given twist angle. Sivashankar et al. [22]  
 55 proposed a twisted 3D microfluidic mixer fabricated by a laser writing technique. They showed that  
 56 a twisted channel enhances the mixing.

57 We propose a new twisted channel geometry that is easily fabricated. We also characterized the  
 58 mixing performance in a T-shaped microchannel. The design has a channel with twisted walls along  
 59 the outlet branch. The mixing performance was studied numerically, and the performance was  
 60 analyzed by calculating the degree of mixing and relative mixing cost.

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## 62 2. Microchannel with twisted channel walls

63 Fig. 1 shows the layout of a T-shaped microchannel with three branches. All three branches have  
 64 a rectangular cross section that is 200  $\mu\text{m}$  high and 120  $\mu\text{m}$  deep. Inlet 1 and inlet 2 are both 1250  $\mu\text{m}$   
 65 long. The branch after the junction of the inlets is the outlet branch, which was varied from 2950 to  
 66 4050  $\mu\text{m}$  long. The channel walls of the outlet branch are twisted, as shown in Fig. 1(a). The twisting  
 67 angle was varied from 0 to  $34\pi$  (17 revolutions). The shape of the cross section remains unchanged  
 68 along the outlet branch. Fig. 1(b) shows an example of  $2\pi$  twisting (1 revolution).

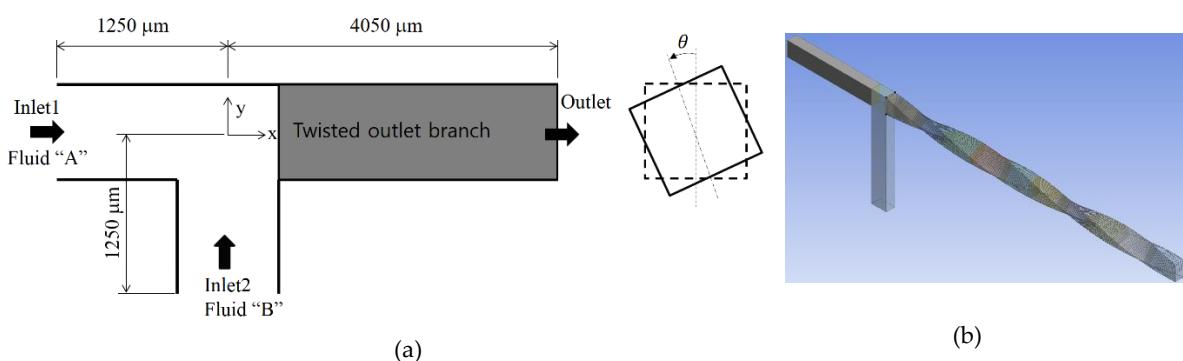
69 For simplicity, we assume that the same aqueous solution flows into the two inlets. The fluid is  
 70 assumed to have the properties found in many existing BioMEMS systems. Its diffusion constant is  
 71  $D=10^{-10} \text{ m}^2\text{s}^{-1}$ , and the kinematic viscosity of the fluid is  $\mu=10^{-6} \text{ m}^2\text{s}^{-1}$  at room temperature. This  
 72 diffusion constant is typical of small proteins in an aqueous solution. The Schmidt (Sc) number is  $10^4$   
 73 (the ratio of the kinematic viscosity and the mass diffusion of fluid).

## 74 3. Governing equations and computational procedure

75 The fluid is assumed to be Newtonian and incompressible, and the equations of motion are the  
 76 Navier-Stokes and continuity equations:

$$77 (\vec{u} \cdot \nabla) \vec{u} = -\frac{1}{\rho} \nabla p + \nu \nabla^2 \vec{u} \quad (1)$$

$$78 \nabla \cdot \vec{u} = 0 \quad (2)$$



91 **Figure. 1** Diagram of a T-shaped micro-channel with twisting: (a) twisting scheme; (b) example of  $2\pi$  twisting.  
 92

93 where  $\vec{u}$  is the velocity vector,  $p$  is the pressure,  $\rho$  is the mass density, and  $\nu$  is the kinematic  
 94 viscosity. The evolution of the concentration is computed from the advection diffusion equation:

95  $(\vec{u} \cdot \nabla)\phi = D\nabla^2\phi$  (3)

96 where D is the diffusion constant, and  $\phi$  is the local concentration or mass fraction of a given species.

97 The governing equations (Eqs. (1)-(3)) were solved using the commercial software FLUENT 14.5.  
 98 All of the convective terms in Eqs. (1) and (3) were approximated by the QUICK scheme (quadratic  
 99 upstream interpolation for convective kinematics), which third-order theoretical accuracy. A uniform  
 100 velocity profile was assumed at the two inlets, while the outflow conditions were specified at the  
 101 outlet. For example, the fluid velocity at the inlets is 1 (mm/s) for a Reynolds number of 0.3. All of the  
 102 other walls were treated as no-slip walls. The mass fraction of the fluid was set to  $\phi=1$  at inlet 1  
 103 and  $\phi=0$  at inlet 2.

104 The performance of the bridge design was evaluated by calculating the DOM. The DOM defined  
 105 by Glasgow et al. [5] is used in the following form:

106  $DOM = 1 - \frac{1}{\xi} \sqrt{\sum_{i=1}^n \frac{(\phi_i - \xi)^2}{n} \frac{u_i}{u_{mean}}}$  (4)

107 where  $u_i$  is the velocity in the  $i^{th}$  cell,  $u_{mean}$  is the mean velocity at the outlet of the microchannel,  $\phi_i$  is  
 108 the mass fraction in the  $i^{th}$  cell, and n is the number of cells.  $\xi$  is specified as 0.5, which indicates equal  
 109 mixing of the two solutions.

110 The relative mixing cost was also evaluated using the ratio of the mixing cost to the mixing cost  
 111 obtained without any twist:

112  $MC = \frac{\left(\frac{DOM}{\Delta p}\right)_{twist}}{\left(\frac{DOM}{\Delta p}\right)_{no\ twist}}$  (5)

113 A smaller MC means that channel wall twisting is more effective. The fluid mixing, MF, is defined as  
 114 follows:

115  $MF = 1 - 2|0.5 - \phi|$  (6)

116 MF=1 means that the fluid is completely mixed, while MF=0 indicates an unmixed fluid of A or B.

117 The computational domain was meshed by structured hexahedral cells. All computational cells  
 118 have equal size and are each 5  $\mu\text{m}$  long. A detailed study of the grid independence of the numerical  
 119 solutions was carried out previously [8]. According to the results, the total mass flow rate at the outlet  
 120 has an accuracy of 0.1% when the cell sides are 10  $\mu\text{m}$  long. Thus, 5  $\mu\text{m}$  is small enough for the cell  
 121 length. For the baseline design without twisting, the DOM was calculated at the section of  $x=3$  mm  
 122 as 0.12, which is the same value reported by Glasgow et al. [5].

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#### 124 4. Results and discussion

125 Computations were carried out for given flow conditions to study how the twisting of the  
 126 channel walls improves the mixing. The mean velocities at the two inlets are uniform in the range  
 127 from 0.5 mm/s to 20 mm/s, and the corresponding Reynolds number is 0.15 to 6. Fig. 2 shows the  
 128 computed DOM and the MC with respect to the twist angle  $\theta$ . The DOM was calculated at the outlet.  
 129 The pressure difference was measured between the two inlets and outlet, and the larger value was  
 130 used to compute the MC. The DOM shows a significant improvement as the twist angle increases,  
 131 regardless of the Reynolds number. For example, the DOM with a twist angle of  $24\pi$  (12 revolutions)  
 132 is 0.867 for  $Re=0.3$ , which is about 5.2 times larger than that obtained without twisting.

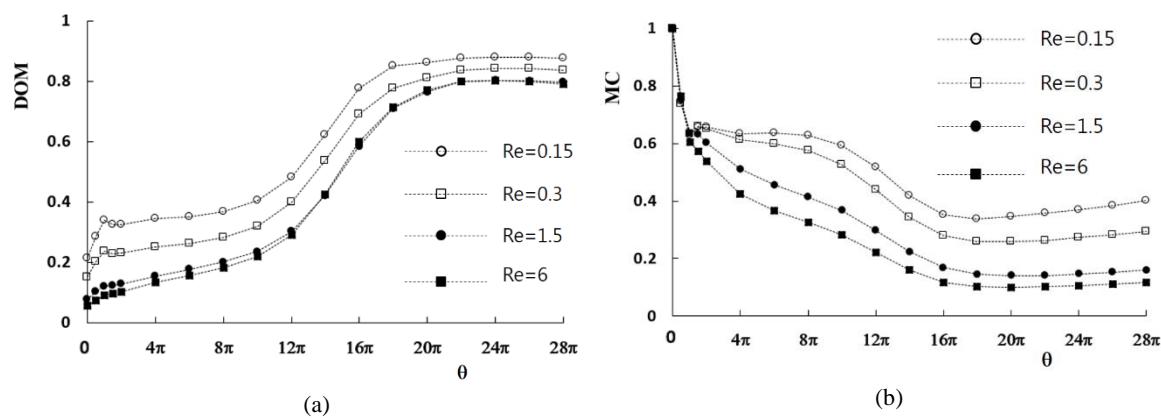
133 There is an optimum twist angle where the maximum DOM occurs. However, the optimum  
 134 angle is almost independent of the Reynolds number. The distribution of the DOM in Fig. 2(a) shows  
 135 that the effects of the Reynolds number decrease as the Reynolds number increases. This suggests  
 136 that the twisting of the channel walls becomes a dominant mixing mechanism when the Reynolds  
 137 number is greater than about 6.

138 In contrast, the MC generally decreases as the twist angle increases. It also has an optimum  
 139 value, as shown in Fig. 2(b). The optimum twist angle for the minimum MC is smaller than that of  
 140 the maximum DOM. To examine how the twisting of channel walls improves the DOM, Fig.3 shows  
 141 the mass fraction contours at several cross sections along the outlet branch. The results were obtained  
 142 with a twist angle of  $18\pi$ , where the minimum MC occurs. The Reynolds number is 0.3. The contours

143 show that the fluids A and B rotate clockwise in the cross section as the channel walls twist in the  
 144 counter clockwise direction. This swirling motion elongates the boundary between the fluids in the  
 145 cross section, and the mixing is greatly enhanced along the boundary (green area in the figures).

146 The swirl motion is very slow compared with the rate of the channel wall twisting along the  
 147 outlet branch. For example, fluid B (blue in Fig. 3(b)) moves circumferentially by about  $0.5\pi$  in  
 148 comparison to Fig. 3(a) when the cross section is twisted by  $\pi$ . Therefore, much greater twisting may  
 149 hinder the swirling of fluids in the cross section. This suggests that there is an optimum twisting  
 150 angle where the maximum DOM occurs.

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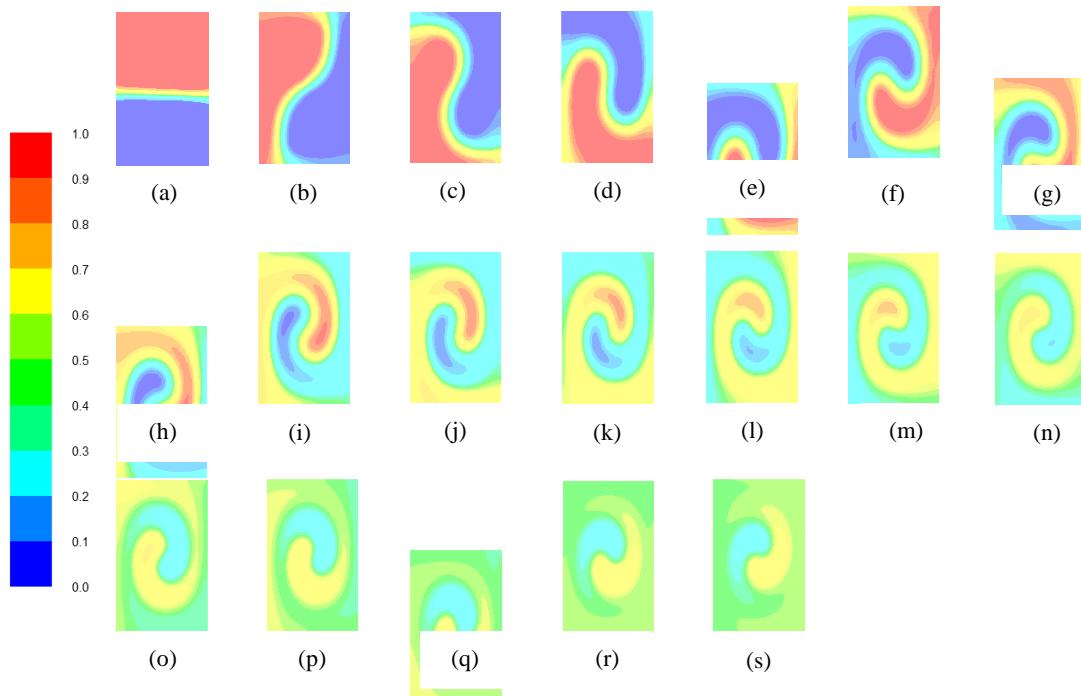


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158 **Figure. 2** Variation of the DOM and MC with the twist angle: (a) DOM; (b) MC.

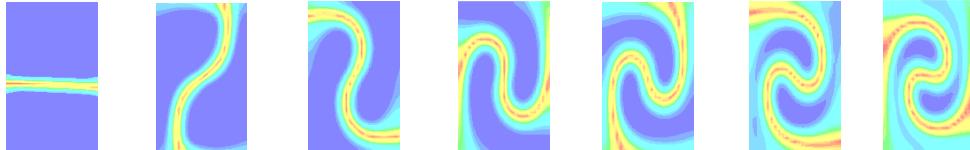
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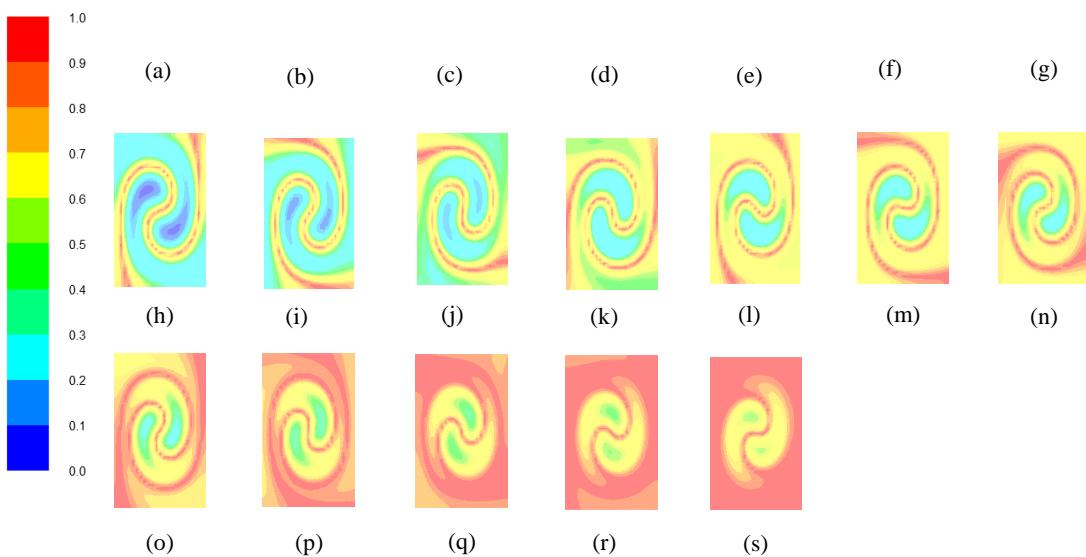


172 **Figure. 3** Mass fraction contours at several cross sections along the outlet branch: (a)  $\theta=0$ ; (b)  $\theta=\pi$ ; (c)  $\theta=2\pi$ ; (d)  
 173  $\theta=3\pi$ ; (e)  $\theta=4\pi$ ; (f)  $\theta=5\pi$ ; (g)  $\theta=6\pi$ ; (h)  $\theta=7\pi$ ; (i)  $\theta=8\pi$ ; (j)  $\theta=9\pi$ ; (k)  $\theta=10\pi$ ; (l)  $\theta=11\pi$ ; (m)  $\theta=12\pi$ ; (n)  $\theta=13\pi$ ; (o)  
 174  $\theta=14\pi$ ; (p)  $\theta=15\pi$ ; (q)  $\theta=16\pi$ ; (r)  $\theta=17\pi$ ; (s)  $\theta=18\pi$ .

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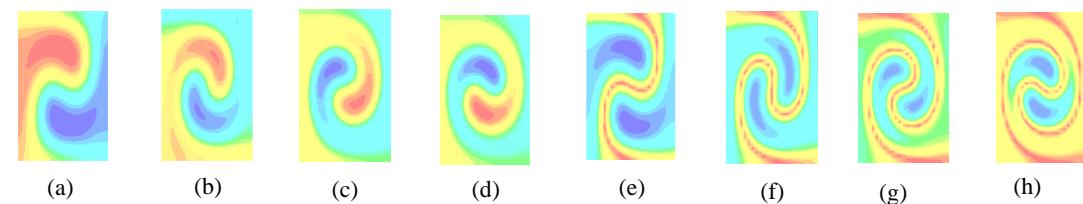
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**Figure 4** Distribution of the mixed fluid at several cross sections along the outlet branch: (a)  $\theta_i = 0$ ; (b)  $\theta_i = \pi$ ; (c)  $\theta_i = 2\pi$ ; (d)  $\theta_i = 3\pi$ ; (e)  $\theta_i = 4\pi$ ; (f)  $\theta_i = 5\pi$ ; (g)  $\theta_i = 6\pi$ ; (h)  $\theta_i = 7\pi$ ; (i)  $\theta_i = 8\pi$ ; (j)  $\theta_i = 9\pi$ ; (k)  $\theta_i = 10\pi$ ; (l)  $\theta_i = 11\pi$ ; (m)  $\theta_i = 12\pi$ ; (n)  $\theta_i = 13\pi$ ; (o)  $\theta_i = 14\pi$ ; (p)  $\theta_i = 15\pi$ ; (q)  $\theta_i = 16\pi$ ; (r)  $\theta_i = 17\pi$ ; (s)  $\theta_i = 18\pi$ .

**Figure 5** Mass fraction and mixed fluid contours at the cross section of  $\theta_i = 8\pi$  for several twist angles: mass fraction contours for (a)  $\theta = 12\pi$ , (b)  $\theta = 16\pi$ , (c)  $\theta = 20\pi$  and (d)  $\theta = 24\pi$ ; mixed fluid contours for (e)  $\theta = 12\pi$ , (f)  $\theta = 16\pi$ , (g)  $\theta = 20\pi$  and (h)  $\theta = 24\pi$ ; the same colour scale is used as in Fig. 3.

Fig. 4 shows the contours of the mixed fluid at the same planes as in Fig. 3. The results confirm that the twisting causes vigorous mixing along the boundary. The red streak in the figures indicates the mixed fluid, which develops along the boundary. The length of the boundary increases with the twisting angle  $\theta_i$  of the cross section. The mixed fluid zone spreads out as the boundary impinges on the channel walls, which means that the channel walls slow down the swirling motion, and the mixed fluid spreads along the channel walls.

Fig. 5 compares the mass fraction and the mixed fluid contours at the cross section of  $\theta_i = 8\pi$  for several twist angles. For a given length of the outlet branch, a larger twist angle results in a greater rate of twisting along the outlet branch. Figs. 5(a)-(d) show how the twisting rate affects the swirl motion in the cross section. As the twisting rate increases, a stronger swirl motion is observed in the cross section with the same twist of  $\theta = 8\pi$ . A stronger swirl motion results in a longer boundary of the fluids A and B, as shown in Fig. 5(e)-(h). This eventually enhances the mixing of the two fluids along the boundary.

Fig. 6 shows the mass fraction and the mixed fluid contours at the mid-section in the z-direction. The contours of the mass fraction show that the positions of fluids A and B move up and down successively as they flow downstream, which indicates the swirl motion in the cross section. The contours of the mixed fluid confirm that the mixing greatly enhanced along the boundary between fluids A and B. The mixing occurs along the centerline from the junction of the fluids and is greatly

221 enhanced near the channel wall as the fluids flow downstream. This enhancement is due to the swirl  
 222 motion.

223 The DOM was optimized, and the corresponding twist angle remained almost constant for the  
 224 range of Reynolds numbers studied. This suggests that the mixing enhancement mechanism is mostly  
 225 affected by the twist angle. However, the swirl motion is very slow compared with the rate of , so  
 226 excessive twisting may hinder the fluid swirling.

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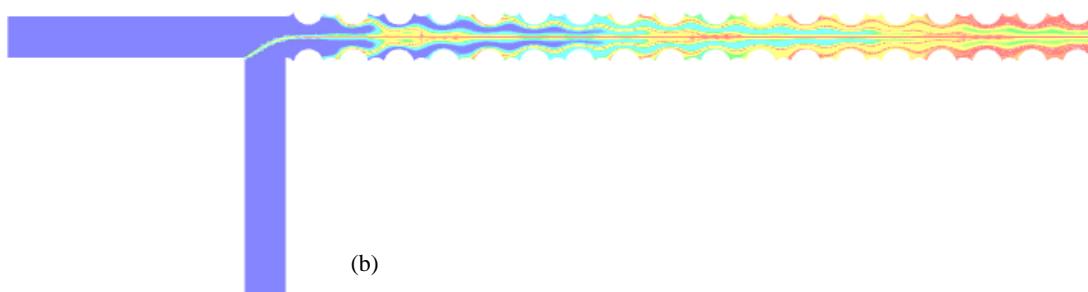
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(a)



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262 **Figure. 6** Contours at the mid-section in the z-direction: (a) mass fraction of fluid "A"; (b) mixed  
 263 fluid; the same colour scale is used as in Fig. 3.

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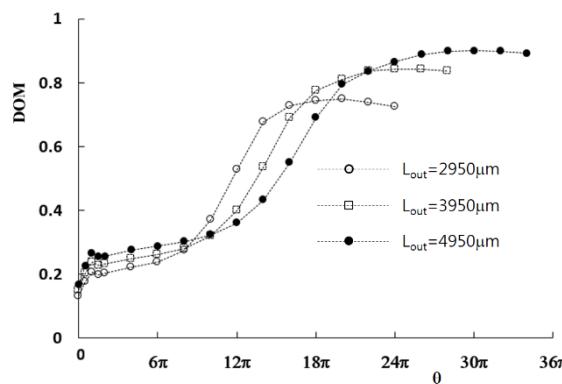
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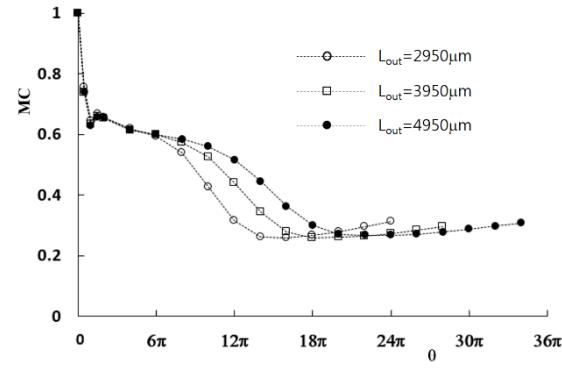
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274 **5. Conclusions**

275 This study numerically examined the effects of channel wall twisting on the mixing performance  
276 of a T-shaped microchannel. The performance was evaluated by examining the DOM and the MC.  
277 The channel walls were twisted continuously from the junction of the two inlet branches to the outlet,  
278 and the twist angle of the cross section increases continuously. This twisting scheme is easy to  
279 fabricate and very effective for improving the DOM.

280 The simulation results showed that the twisting significantly enhances the mixing due to the  
281 swirl motion of the fluids in the cross section along the outlet branch. In general, increasing the twist  
282 angle increases the swirl motion, which elongates the boundary between fluids A and B and enhances  
283 the DOM. But the swirl motion is very slow compared with the rate of the channel wall twisting along  
284 the outlet branch. Excessive twisting hinders the swirl and decreases the DOM, so there is an  
285 optimum twist angle where the maximum of DOM occurs. This optimum twist angle increases with  
286 the length of the outlet branch but is almost independent of the Reynolds number.

287 The twisting angle was also optimized in terms of the relative mixing cost. This twist angle is  
288 different from that where the maximum DOM occurs and shows a dependency on the length of the  
289 outlet branch. Greater twisting is required as the length of the outlet branch decreases. As the  
290 Reynolds number increases, the twisting becomes dominant in mixing the fluids, and its effects on  
291 the DOM is limited. But the relative mixing cost is improved further as the Reynolds number  
292 increases, which suggests that the twisting is a useful passive design concept for a wide range of  
293 Reynolds numbers.

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296 **Acknowledgments**

297 This work was supported by the 2018 Yeungnam University Research Grant.

298 **Conflicts of Interest**

299 The authors declare no conflict of interest.

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