Effects of Channel Wall Twisting on the Mixing in a T-Shaped Micro-Channel

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Abstract: A new design scheme is proposed for twisting the walls of a microchannel, and its performance is demonstrated numerically. The numerical study was carried out for a T-shaped microchannel with twist angles in the range of 0 to 34\(\pi\). The Reynolds number range was 0.15 to 6. The T-shaped microchannel consists of two inlet branches and an outlet branch. The mixing performance was analyzed in terms of the degree of mixing and relative mixing cost. All numerical results show that the twisting scheme is an effective way to enhance the mixing in a T-shaped microchannel. The mixing enhancement is realized by the swirling of two fluids in the cross section and is more prominent as the Reynolds number decreases. The twist angle was optimized to maximize the DOM, which increases with the length of the outlet branch. The twist angle was also optimized in terms of the relative mixing. The two optimum twisting angles are generally not coincident. The optimum twist angle shows a dependence on the length of the outlet branch but it is not affected much by the Reynolds number.

Keywords: T-shaped microchannel; degree of mixing; twisting angle

1. Introduction

Micromixing is needed to homogenize reagents in many microfluidic systems, such as microreactors and micrototal analysis systems (\(\mu\)TASs). Applications include biological and chemical reactions, the dilution of drug solutions, and sequencing nucleic acids [1]. In these systems, the mixing is usually done in various types of microchannels. However, the fluid flows are extremely slow and have very low Reynolds numbers. Therefore, molecular diffusion is a major mechanism of mixing. It is very important to enhance the mixing for the design of microchannels [2].

The techniques to improve mixing in microchannels can be classified as passive, active, or combined techniques. One major difference is the usage of an external energy source other than the energy source that drives the flow. Active techniques use various types of external energy sources, such as electrokinetic [3], magneto-hydrodynamic [4], electroosmosis [2], ultrasound wave [5], and pulsed flow sources [6, 7]. In contrast, passive techniques use the channel geometry or wall modifications to agitate or generate secondary flow in microchannels. Therefore, passive techniques are much easier to integrate into microfluidic systems. Combined methods involve both passive and active techniques. For example, Chen et al. [8] used a pulsatile flow through wavy channel walls, while Lim et al. [9] combined a periodic osmotic flow with geometry modification.

Passive techniques can be categorized into several groups according to how the channel is modified. Many passive techniques modify the channel wall of the outlet branch, which is the portion of a microchannel after the junction where the two fluids merge. Some examples use recessed grooves in the channel wall [10] and a herringbone wall [11]. The second type of technique involves building structures inside the channel, such as indentations and baffles [12, 13], periodic geometric features [14], and a simple block in the junction [15].

The third type of technique involves rearranging the overall structure of THE microchannel instead of using a straight microchannel. For example, Kashid et al. [16] studied five different generic...
microchannel designs with focus on the region before the fluid merges. They tested five different layouts of inlet branches. Kockmann et al. [17] studied various mixer structures to obtain higher mixing in micromixers. Other examples are the AccoMix split-and-recombine technique by Panic et al. [18], the FAMOS multi-lamination micromixer by Keoschkerjan et al. [19], and the K-M collision micromixer by Schneider et al. [20]. These designs use complex elements such as multiple flow passages, 3-dimensional structures, and curved or non-straight channels.

Recently, a new concept of twisting the outlet branch has been studied to enhance the mixing in a microchannel. For example, Jafari et al. [21] studied a twisted channel with the Reynolds number ranging from 76.7 to 460.3. They coiled the outlet branch at a given twist angle. Sivashankar et al. [22] proposed a twisted 3D microfluidic mixer fabricated by a laser writing technique. They showed that a twisted channel enhances the mixing.

We propose a new twisted channel geometry that is easily fabricated. We also characterized the mixing performance in a T-shaped microchannel. The design has a channel with twisted walls along the outlet branch. The mixing performance was studied numerically, and the performance was analyzed by calculating the degree of mixing and relative mixing cost.

2. Microchannel with twisted channel walls

Fig. 1 shows the layout of a T-shaped microchannel with three branches. All three branches have a rectangular cross section that is 200 μm high and 120 μm deep. Inlet 1 and inlet 2 are both 1250 μm long. The branch after the junction of the inlets is the outlet branch, which was varied from 2950 to 4050 μm long. The channel walls of the outlet branch are twisted, as shown in Fig. 1(a). The twisting angle was varied from 0 to 34° (17 revolutions). The shape of the cross section remains unchanged along the outlet branch. Fig. 1(b) shows an example of 2π twisting (1 revolution).

For simplicity, we assume that the same aqueous solution flows into the two inlets. The fluid is assumed to have the properties found in many existing BioMEMS systems. Its diffusion constant is $D=10^{-10} \text{ m}^2\text{s}^{-1}$, and the kinematic viscosity of the fluid is $\nu=10^{-6} \text{ m}^2\text{s}^{-1}$ at room temperature. This diffusion constant is typical of small proteins in an aqueous solution. The Schmidt (Sc) number is $10^4$ (the ratio of the kinetic viscosity and the mass diffusion of fluid).

3. Governing equations and computational procedure

The fluid is assumed to be Newtonian and incompressible, and the equations of motion are the Navier-Stokes and continuity equations:

\[
(\bar{u} \cdot \nabla)\bar{u} = -\frac{1}{\rho} \nabla p + \nu \nabla^2 \bar{u}
\]

\[
\nabla \cdot \bar{u} = 0
\]

where $\bar{u}$ is the velocity vector, $p$ is the pressure, $\rho$ is the mass density, and $\nu$ is the kinematic viscosity. The evolution of the concentration is computed from the advection diffusion equation:

Figure 1 Diagram of a T-shaped micro-channel with twisting: (a) twisting scheme; (b) example of 2π twisting.
\[(\vec{u} \cdot \nabla)\phi = D \nabla^2 \phi \]  

(3)

where \( D \) is the diffusion constant, and \( \phi \) is the local concentration or mass fraction of a given species.

The governing equations (Eqs. (1)-(3)) were solved using the commercial software FLUENT 14.5. All of the convective terms in Eqs. (1) and (3) were approximated by the QUICK scheme (quadratic upstream interpolation for convective kinematics), which third-order theoretical accuracy. A uniform velocity profile was assumed at the two inlets, while the outflow conditions were specified at the outlet. For example, the fluid velocity at the inlets is 1 (mm/s) for a Reynolds number of 0.3. All of the other walls were treated as no-slip walls.

The pressure difference was computed DOM and \( \frac{\sum_{i=1}^{n} (\phi_i - \bar{\phi})^2}{\mu \bar{u}_{\text{mean}}} \) (4) where \( \bar{u}_i \) is the velocity in the \( i \)th cell, \( \mu \bar{u}_{\text{mean}} \) is the mean velocity at the outlet of the microchannel, \( \phi_i \) is the mass fraction in the \( i \)th cell, and \( n \) is the number of cells. \( \xi \) is specified as 0.5, which indicates equal mixing of the two solutions.

The relative mixing cost was also evaluated using the ratio of the mixing cost to the mixing cost obtained without any twist:

\[ MC = \frac{\frac{\sum_{i=1}^{n} (\phi_i - \bar{\phi})^2}{\mu \bar{u}_{\text{mean}}}}{\text{DOM}_{\text{twist}}} \]  \[ MC_{\text{no twist}} \]  

(5)

A smaller MC means that channel wall twisting is more effective. The fluid mixing, \( MF \), is defined as follows:

\[ MF = 1 - 2|0.5 - \phi| \]  

(6)

\( MF = 1 \) means that the fluid is completely mixed, while \( MF = 0 \) indicates an unmixed fluid of A or B.

The computational domain was meshed by structured hexahedral cells. All computational cells have equal size and are each 5 \( \mu \)m long. A detailed study of the grid independence of the numerical solutions was carried out previously [8]. According to the results, the total mass flow rate at the outlet has an accuracy of 0.1% when the cell sides are 10 \( \mu \)m long. Thus, 5 \( \mu \)m is small enough for the cell length. For the baseline design without twisting, the DOM was calculated at the section of x=3 mm as 0.12, which is the same value reported by Glasgow et al. [5].

4. Results and discussion

Computations were carried out for given flow conditions to study how the twisting of the channel walls improves the mixing. The mean velocities at the two inlets are uniform in the range from 0.5 mm/s to 20 mm/s, and the corresponding Reynolds number is 0.15 to 6. Fig. 2 shows the computed DOM and the MC with respect to the twist angle \( \theta \). The DOM was calculated at the outlet. The pressure difference was measured between the two inlets and outlet, and the larger value was used to compute the MC. The DOM shows a significant improvement as the twist angle increases, regardless of the Reynolds number. For example, the DOM with a twist angle of 24\( \pi \) (12 revolutions) is 0.867 for \( Re = 0.3 \), which is about 5.2 times larger than that obtained without twisting.

There is an optimum twist angle where the maximum DOM occurs. However, the optimum angle is almost independent of the Reynolds number. The distribution of the DOM in Fig. 2(a) shows that the effects of the Reynolds number decrease as the Reynolds number increases. This suggests that the twisting of the channel walls becomes a dominant mixing mechanism when the Reynolds number is greater than about 6.

In contrast, the MC generally decreases as the twist angle increases. It also has an optimum value, as shown in Fig. 2(b). The optimum twist angle for the minimum MC is smaller than that of the maximum DOM. To examine how the twisting of channel walls improves the DOM, Fig. 3 shows the mass fraction contours at several cross sections along the outlet branch. The results were obtained with a twist angle of 18\( \pi \), where the minimum MC occurs. The Reynolds number is 0.3. The contours...
show that the fluids A and B rotate clockwise in the cross section as the channel walls twist in the counter clockwise direction. This swirling motion elongates the boundary between the fluids in the cross section, and the mixing is greatly enhanced along the boundary (green area in the figures).

The swirl motion is very slow compared with the rate of the channel wall twisting along the outlet branch. For example, fluid B (blue in Fig. 3(b)) moves circumferentially by about 0.5\pi in comparison to Fig. 3(a) when the cross section is twisted by \pi. Therefore, much greater twisting may hinder the swirling of fluids in the cross section. This suggests that there is an optimum twisting angle where the maximum DOM occurs.

**Figure. 2** Variation of the DOM and MC with the twist angle: (a) DOM; (b) MC.

**Figure. 3** Mass fraction contours at several cross sections along the outlet branch: (a) \theta=0; (b) \theta=\pi; (c) \theta=2\pi; (d) \theta=3\pi; (e) \theta=4\pi; (f) \theta=5\pi; (g) \theta=6\pi; (h) \theta=7\pi; (i) \theta=8\pi; (j) \theta=9\pi; (k) \theta=10\pi; (l) \theta=11\pi; (m) \theta=12\pi; (n) \theta=13\pi; (o) \theta=4\pi; (p) \theta=15\pi; (q) \theta=16\pi; (r) \theta=17\pi; (s) \theta=18\pi.
Figure 4 shows the contours of the mixed fluid at several cross sections along the outlet branch: (a) \( \theta = 0 \); (b) \( \theta = \pi \); (c) \( \theta = 2\pi \); (d) \( \theta = 3\pi \); (e) \( \theta = 4\pi \); (f) \( \theta = 5\pi \); (g) \( \theta = 6\pi \); (h) \( \theta = 7\pi \); (i) \( \theta = 8\pi \); (j) \( \theta = 9\pi \); (k) \( \theta = 10\pi \); (l) \( \theta = 11\pi \); (m) \( \theta = 12\pi \); (n) \( \theta = 13\pi \); (o) \( \theta = 14\pi \); (p) \( \theta = 15\pi \); (q) \( \theta = 16\pi \); (r) \( \theta = 17\pi \); (s) \( \theta = 18\pi \).

Fig. 5 compares the mass fraction and mixed fluid contours at the cross section of \( \theta = 8\pi \) for several twist angles: mass fraction contours for (a) \( \theta = 12\pi \), (b) \( \theta = 16\pi \), (c) \( \theta = 20\pi \) and (d) \( \theta = 24\pi \); mixed fluid contours for (e) \( \theta = 12\pi \), (f) \( \theta = 16\pi \), (g) \( \theta = 20\pi \) and (h) \( \theta = 24\pi \). The results confirm that the twisting causes vigorous mixing along the boundary. The red streak in the figures indicates the mixed fluid, which develops along the boundary. The length of the boundary increases with the twisting angle \( \theta \) of the cross section. The mixed fluid zone spreads out as the boundary impinges on the channel walls, which means that the channel walls slow down the swirling motion, and the mixed fluid spreads along the channel walls.

Fig. 5 compares the mass fraction and the mixed fluid contours at the cross section of \( \theta = 8\pi \) for several twist angles. For a given length of the outlet branch, a larger twist angle results in a greater rate of twisting along the outlet branch. Figs. 5(a)-(d) show how the twisting rate affects the swirl motion in the cross section. As the twisting rate increases, a stronger swirl motion is observed in the cross section with the same twist of \( \theta = 8\pi \). A stronger swirl motion results in a longer boundary of the fluids A and B, as shown in Fig. 5(e)-(h). This eventually enhances the mixing of the two fluids along the boundary.

Fig. 6 shows the mass fraction and the mixed fluid contours at the mid-section in the z-direction. The contours of the mass fraction show that the positions of fluids A and B move up and down successively as they flow downstream, which indicates the swirl motion in the cross section. The contours of the mixed fluid confirm that the mixing greatly enhanced along the boundary between fluids A and B. The mixing occurs along the centerline from the junction of the fluids and is greatly enhanced along the boundary.

Figure 5 Mass fraction and mixed fluid contours at the cross section of \( \theta = 8\pi \) for several twist angles: mass fraction contours for (a) \( \theta = 12\pi \), (b) \( \theta = 16\pi \), (c) \( \theta = 20\pi \) and (d) \( \theta = 24\pi \); mixed fluid contours for (e) \( \theta = 12\pi \), (f) \( \theta = 16\pi \), (g) \( \theta = 20\pi \) and (h) \( \theta = 24\pi \).
enhanced near the channel wall as the fluids flow downstream. This enhancement is due to the swirl motion.

The DOM was optimized, and the corresponding twist angle remained almost constant for the range of Reynolds numbers studied. This suggests that the mixing enhancement mechanism is mostly affected by the twist angle. However, the swirl motion is very slow compared with the rate of, so excessive twisting may hinder the fluid swirling.

Figure 6 Contours at the mid-section in the z-direction: (a) mass fraction of fluid “A”; (b) mixed fluid; the same colour scale is used as in Fig. 3.

Figure 7 Effects of length of the outlet branch on mixing: (a) DOM; (b) MC.

Fig. 7 shows the effects of the length of the twisted outlet branch on the mixing. The DOM shows a strong dependence on the length of the outlet branch. The maximum DOM decreases as the length of the outlet branch decreases. The twist angle where the maximum of DOM occurs increases with the length of the outlet branch. For example, the angles are 10π, 12π, and 14π for L_out = 2950, 3950, and 4950 μm, respectively. Similarly, the minimum of MC is obtained at a larger twist angle as the length of the outlet branch increases (8π, 9π, and 12π for L_out = 2950, 3950, and 4950 μm, respectively). However, the ratio of the twist angle to the length of the outlet branch decreases as the length of the outlet branch increases. This means that greater twisting is required as the length of the outlet branch decreases.
5. Conclusions

This study numerically examined the effects of channel wall twisting on the mixing performance of a T-shaped microchannel. The performance was evaluated by examining the DOM and the MC. The channel walls were twisted continuously from the junction of the two inlet branches to the outlet, and the twist angle of the cross section increases continuously. This twisting scheme is easy to fabricate and very effective for improving the DOM.

The simulation results showed that the twisting significantly enhances the mixing due to the swirl motion of the fluids in the cross section along the outlet branch. In general, increasing the twist angle increases the swirl motion, which elongates the boundary between fluids A and B and enhances the DOM. But the swirl motion is very slow compared with the rate of the channel wall twisting along the outlet branch. Excessive twisting hinders the swirl and decreases the DOM, so there is an optimum twist angle where the maximum of DOM occurs. This optimum twist angle increases with the length of the outlet branch but is almost independent of the Reynolds number.

The twisting angle was also optimized in terms of the relative mixing cost. This twist angle is different from that where the maximum DOM occurs and shows a dependency on the length of the outlet branch. Greater twisting is required as the length of the outlet branch decreases. As the Reynolds number increases, the twisting becomes dominant in mixing the fluids, and its effects on the DOM is limited. But the relative mixing cost is improved further as the Reynolds number increases, which suggests that the twisting is a useful passive design concept for a wide range of Reynolds numbers.

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Conflicts of Interest

The authors declare no conflict of interest.

References


