

1 Article

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Compact Inner-Wall Grating Slot Microring 3 Resonator for Label-Free Sensing

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13 **Abstract:** In this paper, we present and analyze a compact inner-wall grating slot microring
14 resonator (IG-SMRR) with the footprint of less than $13 \mu\text{m} \times 13 \mu\text{m}$ on the SOI platform for label-
15 free sensing, which comprises a slot microring resonator (SMRR) and inner-wall grating (IG). Its
16 detection range is significantly enhanced without the limitation of the free spectral region (FSR)
17 owing to the combination of SMRR and IG. Structural parameters of IG and SMRR are investigated
18 and optimized for favorable transmission properties. The simulation results shows that the IG-
19 SMRR has an ultra-large quasi-FSR of 84.6 nm, and the concentration sensitivities of sodium
20 chloride solutions and D-glucose solutions are up to 960.61 pm/% and 933.06 pm/%, respectively.
21 The investigation on the combination of SMRR and IG is a valuable exploration of label-free sensing
22 application for ultra-large detection range and ultra-high sensitivity in future.23 **Keywords:** microring resonator; inner-wall grating; slot waveguide; label-free; bulk sensing
2425

1. Introduction

26 Label-free optical sensors have been investigated extensively in many applications, such as
27 medical diagnostics, drug detection, food security, pesticide residue detection, environmental
28 monitoring, homeland defense, etc. In the optical sensing applications, two detection strategies, label-
29 based detection and label-free detection are implemented [1]. By comparison, the former suffers from
30 the complex labeling procedures and relatively long assay time, and the latter can be chosen as an
31 alternative for relatively easy and cheap sensing scenarios [2].32 In recent decades, a silicon-on-insulator (SOI) platform has been recognized as a favorable
33 candidate due to its compatibility with well-established complementary metal oxide semiconductor
34 (CMOS) manufacturing technology. SOI waveguide can offer high refractive index (RI) contrast that
35 permits strong light mode field confinement and compact bends (down to $1.5 \mu\text{m}$ bending radius
36 approaching the theory limit) [3]. The optical sensing devices based on the SOI platform have been
37 widely studied, such as Mach-Zehnder interferometer sensors [4], Fabry-Perot resonance sensors [5],
38 surface plasmon sensors [6,7], microring/microdisk resonator sensors [8-11] and grating sensors [12].
39 The MRR with high quality factor (Q-factor) enables lights to circle the rings scores of times before
40 being lost, which provides an equivalently long light-matter interaction distance. Therefore, the
41 attractive sensitivity of the optical MRR sensor can be achieved. In addition, the MRR sensor with
42 smaller footprints needs less amount of analyte and is easily integrated in the sensing arrays.43 For MRR sensor, two typical interrogation approaches, intensity interrogation and wavelength
44 interrogation [13], have been utilized. The detection range of the former is too small, which is suitable
45 for the relatively lower RI variation of analyte. The latter as the popular detection method can satisfy
46 the actual production demand. The low sensitivity of MRR sensor based on traditional strip

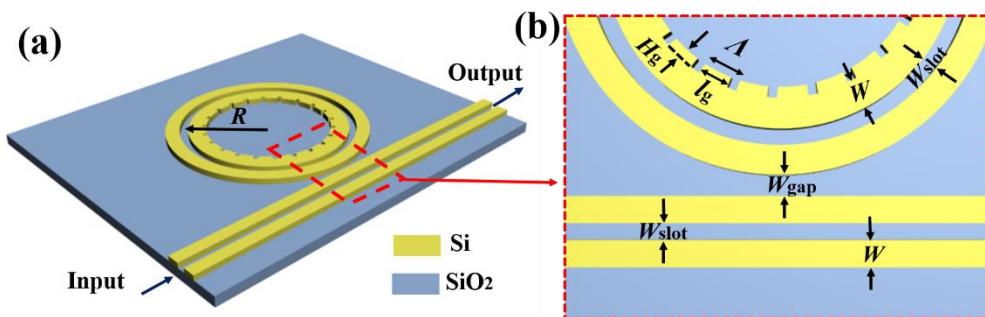
47 waveguide is around 70 nm/RIU [14], and the reason is that the lights trapped in the SOI waveguide
 48 cores cannot interact fully with the matter. The SMRR with much light in the slot can enhance the
 49 light-analyte interaction. Hence, the SMRR sensor has higher sensitivity. However, the detection
 50 range of MRR sensor based on the wavelength shift-dependent is severely constrained by the small
 51 FSR. In order to enlarge the detection range, some schemes, such as serially coupled double MRRs
 52 [15], the MRR with bent contra-directional couplers [16], Mach-Zehnder interferential couple MRR
 53 [17], grating-coupled silicon MRR [18] and angular grating MRR [19] are investigated to expand the
 54 FSR. These schemes can enlarge the FSR, but the sensitivities of the above schemes are relatively lower
 55 than the sensitivity of SMRR.

56 In this paper, we present a compact optical label-free sensor based on IG-SMRR to acquire the
 57 ultra-large detection range and ensure the high sensitivity. The sensor adopts all-pass filter SMRR, in
 58 the inner-wall of which integrated by a grating on an SOI platform. Lumerical MODE Solutions is
 59 utilized to simulate the related parameters and sensing performance of the device. The relations
 60 between the side mode suppression ratio (SMSR), the extinction ratio (ER), the Q-factor and the
 61 structural parameters are investigated. Taking the sodium chloride solutions and D-glucose solution
 62 as the top cladding layer, the sensing characteristics of the optical label free sensor are demonstrated.

63 2. Structure Design and Operation Principle

64 2.1 Structure design

65 The 3D schematic of the proposed sensing device is shown Figure 1 (a). The SOI wafer is adopted
 66 as the waveguide material with 220 nm Si on a 2 μ m SiO₂ substrate. Homogeneous sensing is
 67 implemented in this paper, so the sensor device is immersed in aqueous solutions. Naturally, pure
 68 water is chosen as the top cladding in the process of determining the geometric parameters of
 69 waveguides. This homogeneous sensing case can be easily extended to surface sensing applications
 70 by covering thin adsorbed analyte for the top cladding in the calculation. The bent radius (R) of the
 71 SMRR is designated as the distance between the center of the rings and the middle of the slot, and set
 72 to 5.8 μ m. The gap width between the bus and the ring waveguide is denoted as W_{gap} . Other geometric
 73 parameters are depicted in Figure (a) and Figure (b). The ring and bus waveguide have the same slot
 74 width (W_{slot}). The strip waveguide width W and the slot width W_{slot} are set to 210 nm and 100 nm
 75 respectively, which enables an extremely strong restriction of the electric field with the mode
 76 confinement factor of over 30% [20]. The etched IG have the azimuthal period (Λ) of about 964 nm,
 77 azimuthal width (l_g) and the duty cycle (F) (ratio of silicon block to the period). The structure of the
 78 gratings is achieved by etching quasi-rectangular region ($l_g \times H_g$) from the inner-wall of the ring
 79 waveguide. Here, H_g is radial height of the etched fragment of the grating.



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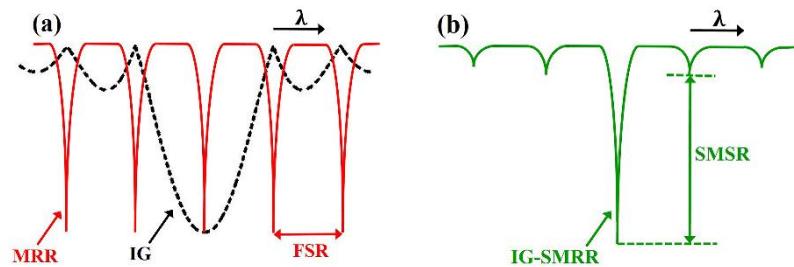
81 **Figure 1.** (a) 3D Schematic of the proposed device. (b) Top view of the IG-MRR in the coupling
 82 region.

83 2.2 Operation principle

84 The resonance equation of SMRR can be expressed:

$$85 \quad 2\pi R n_{\text{eff}} = m \lambda_{\text{res}}, m = 1, 2, 3, \dots \quad (1)$$

86 where, R is the ring radius, n_{eff} is effective RI, m (positive integer) is the azimuthal resonant order,
87 and λ_{res} is the resonant wavelength.



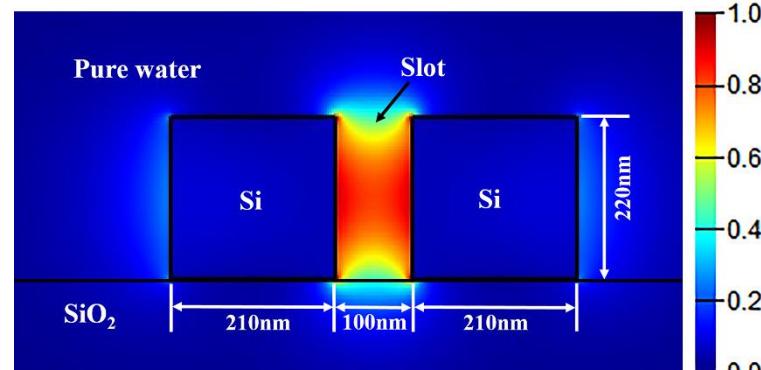
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89 **Figure 2** Demonstration of the operating principle. (a) The spectral responses of the SMRR and the IG.
90 (b) The spectral response of the IG-SMRR.

91 The operating principle of the designed sensor is demonstrated in Figure 2, in which the spectral
92 responses of SMRR, IG and IG-SMRR are described. Obviously, the detection range of sensor is
93 severely restricted by the FSR. The SMRR is filtered by IG with the wavelength-selective characteristic.
94 The detection range of the sensor gets broadened due to the side-mode suppression. The side-mode
95 suppression ratio (SMSR) is optimized by optimizing the etching depth of the IG.

96 3. Results and Discussion

97 Mode Solutions software of Lumerical Inc. [21] is utilized to construct the device model and
98 calculate the spectral responses of the sensor. A tunable laser of TE-polarization (the fundamental
99 mode, TE_0) is injected into the bus waveguide. The mode field distribution is calculated by using
100 Finite Difference Eigenmode (FDE) solver as shown in Figure 3. The varFDTD solver collapses a 3D
101 geometry into a 2D set of effective indices that can be solved with 2D FDTD (usually regarded as
102 2.5D), which ensures the high calculation accuracy and saves much memory and simulation time.
103 The spectral responses of the proposed sensor are carried out by the varFDTD solver. In the process
104 of the following parameter optimization, pure water is acted as the top cladding.



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106 **Figure 3** Mode field distribution of the slotted waveguide

107 The output spectra can be expressed as:

$$108 \quad T = 10 \lg \frac{P_{\text{out}}}{P_{\text{in}}} \quad (2)$$

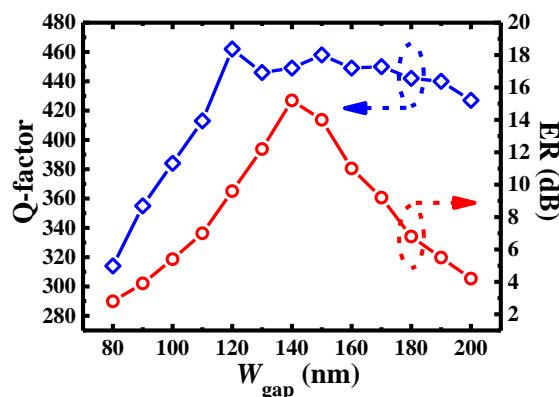
109 where P_{in} and P_{out} are the power flow integrals at the input and output ports, respectively. Q-
110 factor can be calculated from the expression:

$$111 \quad \text{Q - factor} = \frac{\lambda_{\text{res}}}{3 \text{dB bandwidth}} \quad (3)$$

112 where λ_{res} is resonant wavelength of MRR.

113 3.1 Optimization of Parameters

114 High sensitivity of the optical label-free sensor is vital in the practical measuring application.
 115 Extinction ration (ER) and Q-factor are two key parameters, which determine the transmission
 116 spectrum properties of IG-SMRR, and further influence the sensitivity. Intrinsic propagation loss and
 117 coupling loss are main loss resources of the IG-SMRR. SOI waveguide can neglect radiation loss
 118 bending loss for $R > 3 \mu\text{m}$ owing to high index contrast [22]. The scattering power loss is mainly
 119 caused by IG (less than 13%) [23]. In this case the coupling loss dominates the total loss, and a small
 120 W_{gap} (less than 200 nm) can effectively decrease coupling loss [24]. Fig. 4 plots the Q-factor and ER as
 121 a function of coupling distance W_{gap} ($F=90\%$, $H_g=30 \text{ nm}$). ER increases first, then decreases with the
 122 increase of W_{gap} , and reach the peak as $W_{\text{gap}}=140 \text{ nm}$. Q-factor increases rapidly, then tend to be
 123 saturated and fluctuate slightly. In this process, the operating states of MRR transit from over
 124 coupling to critical coupling with the increase of ER, and then transit from critical coupling to under
 125 coupling with the decrease of ER. $W_{\text{gap}}=140 \text{ nm}$ is favorable to gain the maximum of ER and high Q-
 126 factor.

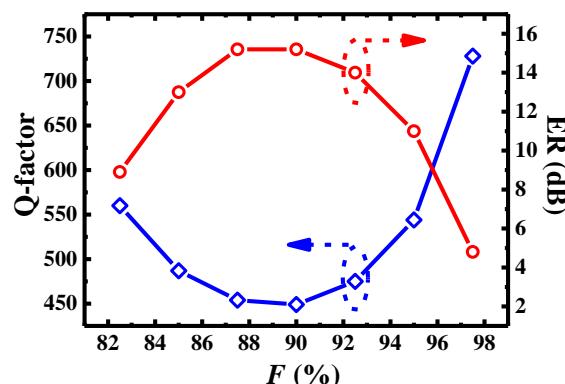


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Figure 4 Q-factor and ER as a function of coupling distance W_{gap}

129 The dependence of Q-factor and ER on the duty cycle F are shown in Figure 5. Variation trend
 130 of Q-factor and ER is in the opposite direction. Considering the trade-off between Q-factor and ER, F
 131 is set to 95%, and the corresponding Q-factor and ER are 544 and 11dB, respectively.

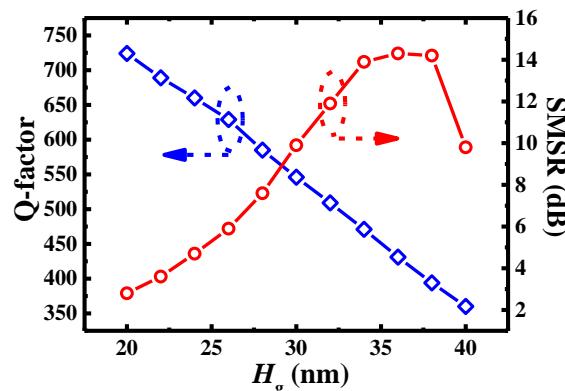


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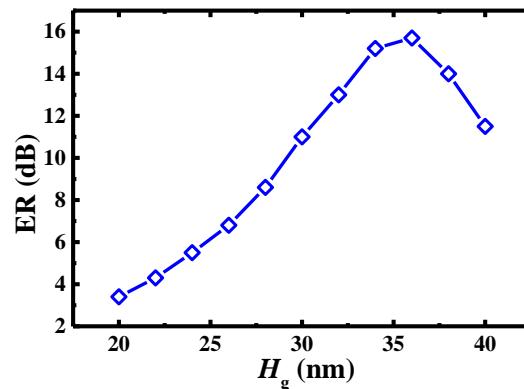
Figure 5 Q-factor and ER as a function of duty cycle F

134 Q-factor, SMSR and ER as a function of etched depth H_g of the IG are shown in Figure 5 and
 135 Figure 6. Here, coupling distance W_{gap} and duty cycle F are fixed at 140 nm and 95%, respectively. Q-
 136 factor decreases linearly with the increase of H_g , which is due to the increasing of scattering loss
 137 caused by IG. SMSR and ER have similar variation trend. Therefore, considering the trade-off of Q-
 138 factor and SMSR, H_g is chosen as 30 nm. The corresponding Q-factor, ER and SMSR are 546, 11 dB
 139 and 9.9 dB, respectively. The value of SMSR can fully meet practical needs.



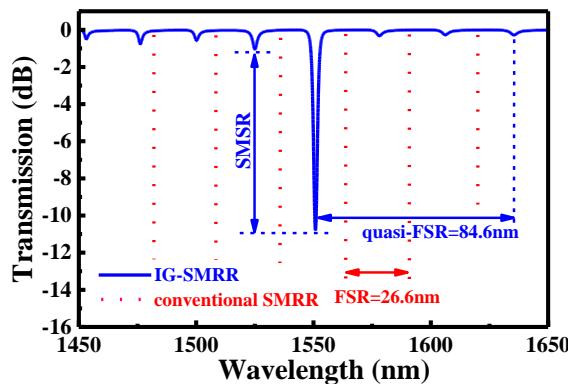
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Figure 6 Q-factor and SMSR as a function of etched depth H_g of IG

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Figure 7 ER as a function of etched depth H_g of IG

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Figure 8 Transmission spectrum of the IG-SMRR (blue solid line) and conventional SMRR (red dashed line)

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From the above optimization, several structural parameters of the sensor are determined: coupling distance $W_{\text{gap}}=140$ nm, duty cycle $F=95\%$ and etched depth $H_g=30$ nm. And the Q-factor of 546, the ER of 11 dB and the SMSR of 9.9 dB are achieved. As shown in Figure 8, the only one main resonant peak is at 1550.84 nm within the wavelength range from 1450 nm to 1650 nm. The first side mode to the left of main resonant peak has the greatest influence on the spectral characteristic, so it is evaluated by SMSR. The distances between the main resonant peak and its right third suppressed peak is denoted as the quasi-FSR. In the spectrum, the quasi-FSR of the IG-SMRR is 84.6 nm, and the FSR of conventional SMRR is 26.6 nm. Apparently, quasi-FSR is over 3 times of the FSR. Hence, the operating range of the proposed IG-SMRR gets effectively expanded.

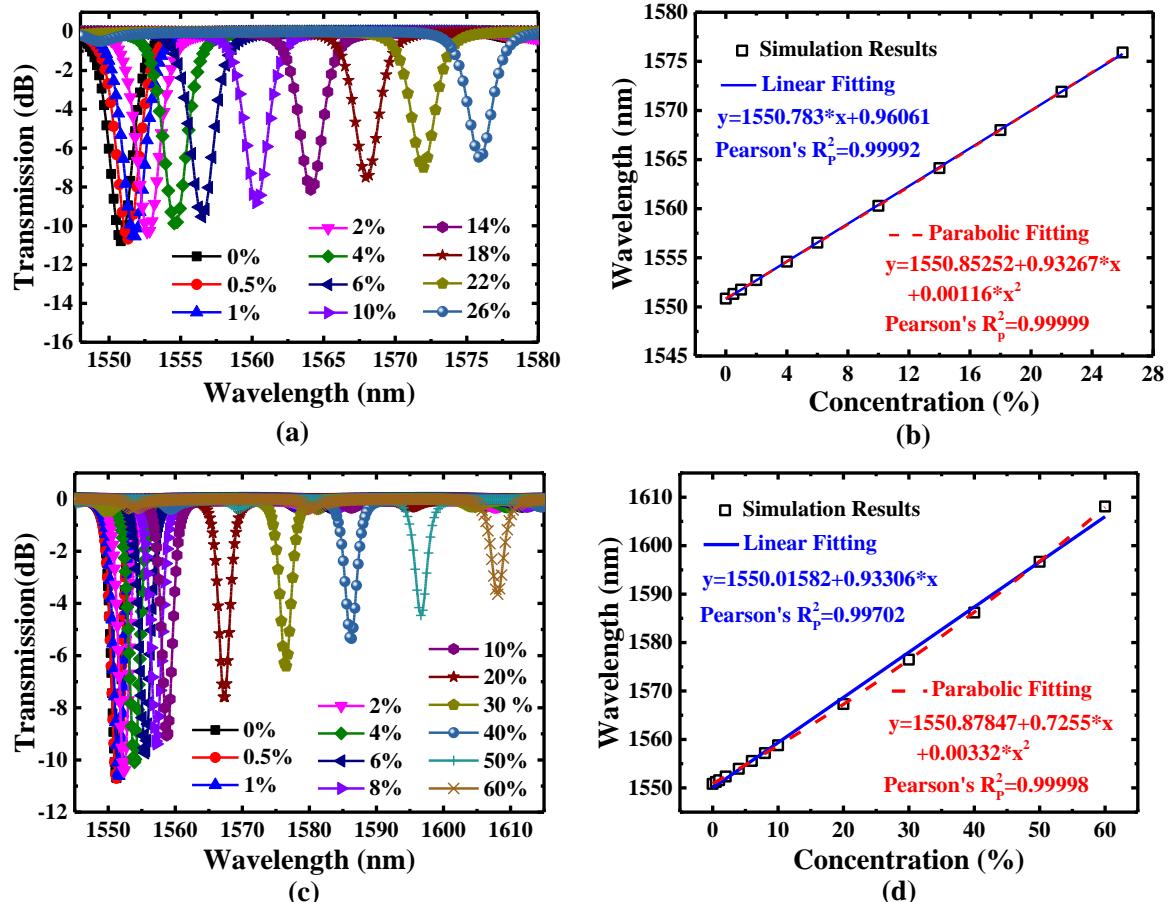
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3.2 Bulk Sensing Analysis

157 The sensing principle of IG-SMRR is similar to the optical waveguides. The aqueous solution
 158 concentrations as the top cladding are proportional to their RI. The RI variations of aqueous solution
 159 influences the mode optical field interacting the surrounding samples in the slot of the IG-SMRR,
 160 which can result in the resonant effective RI variations. Here, the slot plays a crucial role in the sensing
 161 process due to the much resonant optical field in it. According to the resonant equation of MRR, the
 162 effective RI variations can induce the resonant wavelength shifts. Therefore, the relationship between
 163 the solution concentration change and the resonant wavelength shift can be built. The concentration
 164 sensitivity [25] of the optical sensor can be defined as:

165
$$S_C = \Delta\lambda_{res} / \Delta C \quad (4)$$

166 where ΔC and $\Delta\lambda_{res}$ are the variations of the aqueous solution concentration and resonant
 167 wavelength, respectively. This sensitivity means the resonant wavelength shift induced by 1(mass) %
 168 concentration.



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 170
 171 Figure 9 Transmission spectrum of the IG-SMRR for (a) sodium chloride solution, (c) D-glucose
 172 solution with different concentrations, and for (b) and (d) corresponding relationships between the
 173 resonant wavelength and the solution concentration, respectively.

174 Table 1. RI of the Samples (at a temperature of 20°C).

Sample	Concentration (%)	RI
Pure water		1.333
Sodium chloride	0.5-26	1.3339-1.3795
D-glucose	0.5-60	1.3337-1.4394

175 To demonstrate the bulk sensing characteristic of the IG-SMRR, sodium chloride (NaCl) and D-
 176 glucose (C₆H₁₂O₆) are designated as samples. Their RI with different aqueous solution
 177 concentrations (mass %) are listed in Table 1 [26].

178 The conventional MRR can only detect the lower concentration range (<20%) [27] restricted by
 179 the small FSR. The IG-SMRR with the wide quasi-FSR can detect the higher concentration (>20%) of
 180 the solution due to the large quasi-FSR. The transmission spectra for different concentrations of
 181 sodium chloride solutions and D-glucose solutions are shown in Figure 9 (a) and (c), respectively.
 182 Figure 9 (b) and (d) illustrates the function relationship between the resonant wavelength and the
 183 solution concentration. We utilize the linear and parabolic fittings of the simulation results to discuss
 184 the sensing sensitivity and linearity. As shown in Figure 9 (b) and (d), the blue solid and red dashed
 185 lines represent the linear and parabolic fittings for the simulation results. A redshift of the resonant
 186 wavelength can be observed with the increase of solution concentration. In addition, with the increase
 187 of the RIs of samples, the lower index contrast between the solution and the waveguide interfaces
 188 results in the smaller intrinsic loss of the waveguide, which induces the decrease of ER [2].

189 The slope of linear fitting represents the concentration sensitivity of the sensor. The coefficient
 190 of determination (R_p^2) is utilized to evaluate the quality of the fitted lines. The sensitivity and R_p^2 are
 191 listed in Table 2.

192 **Table 2. Performance of the Sensor with Different Samples for Sensing Application.**

Sample	S_c (pm/%)	R_p^2 for Linear Fit	R_p^2 for Parabolic Fit
Sodium Chloride	960.61	0.99992	0.99999
D-glucose	933.06	0.99702	0.99998

193 As concluded in Table 2, the concentration sensitivities of the sensor for sodium chloride
 194 solutions and D-glucose solutions are 960.61 pm/% and 933.06 pm/%, respectively. Compared with
 195 [19], both solution concentrations are about 10 times than that of 95.27 pm/% and 95.33 pm/%,
 196 respectively. The R_p^2 for linear fit is less than the R_p^2 for parabolic fit, which illustrates that the 2 order
 197 parabolic fitting can depict the function relationship between the resonance wavelength and solution
 198 concentration more precisely than linear fitting [19,27,28-30]. For the low concentration variations of
 199 sodium chloride solutions, R_p^2 for linear fit is 0.99992, which shows the relationship between the
 200 resonance wavelength and solution concentration is nearly linear. However, for high concentration
 201 range of D-glucose solution, parabolic fitting can be considered. Therefore, a conclusion can be drawn
 202 that the linear fitting and parabolic fitting are suitable for the smaller range and larger range
 203 concentration detections, respectively.

204 **4. Conclusions**

205 In this work, the SOI IG-SMRR with an ultra-large detection range and a high sensitivity is
 206 proposed for label-free sensing. It combines SMRR with IG to enlarge the operating range due to
 207 good suppression of side modes. The related parameters are simulated and optimized to get the
 208 favorable transmission spectrum. The sensing device based on IG-SMRR has an ultra-large detection
 209 range. The concentration sensitivities of sodium chloride solutions and D-glucose solutions are up to
 210 960.61 pm/% and 933.06 pm/%. The numerical analysis shows the linear and parabolic fitting are
 211 suitable for low concentration and high concentration detections, respectively. The proposed sensing
 212 device with a compact footprint of less than $13\text{ }\mu\text{m} \times 13\text{ }\mu\text{m}$ is easily integrated with other SOI devices
 213 and enables integrated sensor arrays. Therefore, the SOI IG-SMRR combining the benefits of both
 214 SMRR and IG is a valuable exploration for micro/nano optical sensing applications in future.

215 **Author Contributions:** H.G. (first author) and H.G. (second author) simulated the device and wrote the original
 216 draft. C.W. and X.S. conceived the main idea and collected the related literatures. X.W. and Y.Y. analyze the
 217 simulation results and directed the simulation work. C.C. and F.W revised the paper. D.M. proofread and
 218 submitted the paper.

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