

1 *Article*

2 Path analysis of causal factors influencing marine 3 traffic accident via structural equation numerical 4 modeling

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10 **Abstract:** Many causal factors to marine traffic accidents (MTA) influence each other and have
11 associated effects. It is necessary to quantify the correlation path mode of these factors to improve
12 accident prevention measures and their effects. In the application of human factors to the accident
13 mechanisms, the complex structural chains on causes to MTA systems were analyzed combining
14 the Human Failure Analysis and Classification System (HFACS) with theoretical Structural
15 Equation Modeling (SEM). First, the accident causation model was established as a human error
16 analysis classification in sight of MTA, and the constituent elements of the causes of accident was
17 conducted. Second, a hypothetical model of Human factors classification was proposed applying
18 the practice of the structural model. Third, with the data resource from ship accident cases, this
19 hypothetical model was discussed and simulated, and as a result the relationship path dependency
20 mode between the latent independent variable of the accident was quantitatively analyzed based
21 on the observed dependent variable of human behaviors. Application examples show that
22 relationships in HFACS are verified and in line with the path developing mode, and resource
23 management factors have a pronounced influence and a strong relevance to the causal chain of the
24 accidents. Appropriate algorithms for the theoretical model can be used to numerically understand
25 the safety performance of marine traffic systems under different parameters through mathematical
26 analysis. Hierarchical assumptions in the HFACS model are quantitatively verified.

27 **Keywords:** maritime traffic; marine accident; accident causation theory; human factor; structural
28 equation modeling; HFACS; path dependency

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1. Introduction

31 Marine traffic safety is an important component of economics and trade between different
32 countries. The volume of ship transportation has, over time, become an important measurement of
33 the country's economic development. With the growth of China's national economy the shipping
34 industry has developed rapidly and the scale of transportation has been expanding. With that
35 growth, the marine traffic accidents (MTA) has consistently called attention to life safety, property
36 safety and environment protection. Therefore, as a basic issue of safety research, the symptomatic
37 problems of MTA always get attention by experts (Goerlandt and Montewka, 2015).

38 In order to reduce the incidence of MTA, many experts have conducted of research on the
39 causes of MTA. Marine traffic is a complex system that includes people, ships, and environmental
40 management. In the past, people focused on improving the safety of ships and equipment. Due to
41 the continuous development of technology, the safety of ships and equipment has reached a very
42 high level. Safety experts and scientists agree that the role and status of human factors and
43 management factors in accidents have been proven. Thus, at present, many scholars believe that the

44 root cause of accidents is management factors, i.e. the direct cause of accidents is the unsafe acts of
45 personnel(Yang et al 2013).

46 The development of accident causation theory shows that most accidents are not caused by a
47 single elementary event, but by a series of factors interacting with each other. Therefore, it is
48 necessary to study the relationship between the different causes of MTA, in order to help
49 decision-makers better understand the accident and thus fundamentally reduce the occurrence of
50 such accidents.The analyses of the causes of MTA and the research on the interrelationship of the
51 causes are being continuously developed. The complexity of the cause of the accident system has
52 been established, and the chain model associated with the cause of the accident has basically been
53 consistent(Xi et al, 2018).

54 However, it is still a difficult problem to explore the association pattern and intensity of the
55 generic causal chain quantitatively. It is possible to use new algorithms to study the interactions and
56 influence paths of the causes of accidents. In particular, the analysis of the causal chain path of big
57 data can help us understand the characterization mechanism of accidents and provide scientific
58 diagnosis of how those accidents occurred. To quantitatively analyze the relationships between the
59 causes of MTA and clarify the causal mechanism of human factors in an accident and analyze the
60 logical cause of the accident, this paper will combine with accident data, using the SEM method to
61 analyze the complex relationship between the causal structures of MTA system.

62 The rest of this paper will be organized as follows. In section 2, the most recent studies about
63 the cause of accidents and the mechanism of accident factors are reviewed. In section 3, our research
64 theory and research hypothesis are presented. In section 4, we present the model in causal factors
65 chain for MTA. In section 5 and 6 our research is applied to a specific case. The relevant data is
66 collected, analyzed and applied to the model, and the sensitivity of the model tested. In section 7, the
67 conclusions are drawn based on our research.

68 2. Literature Review

69 Increasing industry system safety through reducing infrequent events keeps a major challenge
70 to safety scientists. Accident causation methods were broadly applied in marine traffic field.To
71 study MTA occurrence mechanism, the first thing is to understand the causes of the accident and the
72 interaction of the factors that cause the accident. (Pidgeon et al., 2000; Grant et al., 2018). marine
73 accidents result from a combination of complex conditions. Japanese scholars proposed using the
74 marine information structure, holding that independent action and interaction of human and
75 maritime factors caused most accidents (Fukushima, 1976). The complexity of systems and the
76 environments in which human operate means the process of safety is not directly forward or linear,
77 but instead is driven by a complex network of relationships and behaviors between humans,
78 technology and their environment.In comparison to other accident analysis methods, STAMP
79 model uses a functional abstraction approach, to model the structure of a system and describe
80 the interrelated functions(Leveson, 2015). A new risk management framework is put forward to
81 solve a human control problem and modelling techniques are required to appreciate the direct
82 or indirect operational requirements of systems(Rasmussen,1997). According to this work-flow,
83 the structure of work systems is hierarchical which actors, objects and tasks are modeled across
84 levels of the complex system and their relationships to each other are linked to explain causal
85 connections. Dynamic work-flows are represented in the framework as inter-dependencies
86 between the vertical integration levels of the system (Grant et al,2018).The FRAM accident
87 model is different from the traditional model for analyzing accidents from the perspective of
88 internal system operation mechanism or event causal sequence(Hollnagel, 2012). It does not
89 stick to system structure decomposition and causal factor analysis, and avoids the analysis of
90 accidents into the orderly occurrence of a single associated event, or avoids the analysis on
91 hierarchical stacking of multiple potential factors. Combining Safety-I and Safety-II
92 perspectives broadened understanding of safety management(Hollnagel, 2014; Jones et al, 2018).

93 Reason (1990) put forward the Swiss Cheese Model, the latent and active failures model, and
94 pointed out, for the first time, that an accident is due to the latent defects or vulnerabilities in each
95 part of the system, and that when the defects on each part are lined up, the final cause of the accident
96 can be understood (Fan et al., 2015; Yang et al., 2013). The model has been criticized for being a
97 reductionist and linear model that fails to account for a holistic representation of systems as
98 dynamic and adaptive which forms the basis of systems theory (Grant et al., 2018). Maintaining
99 the notion of human error as a central concept in accident causation system disregards the basic
100 fact, which the relevant performance usually is carried out by human- organization factor
101 rather than by an individual. Furthermore, it can be shown that about 80% of MTA are related
102 to human factors (Hu et al., 2007). The applications driven by qualitative accident causation
103 models have been improved to investigate human factors in accidents. Subsequently, exploration
104 of the correlation between the causes of the MTA and the consequences of accidents has made
105 significant progress. The main qualitative research investigated the impact of different factors on the
106 outcome of accidents. The relationship among causal factors in accidents has also been studied.
107 Hänninen. (2014) used the directed acyclic graph of the Bayesian network to study the cause of
108 marine accidents. Dai and Wang. (2011) utilized goal structure notion to analyze the associated rules
109 of human factors to marine accidents. Graziano et al. (2016) used the tracer taxonomy to study
110 human errors in collision accidents. Sotiralis et al. (2016) focused on human centered design aspects
111 to incorporate human factors to ship collisions analysis. Lyu et al. (2018) studied the relationships
112 among safety climate, safety behavior, and safety outcomes in construction workers. The novel drift
113 into failure model (DFM) provides a set of philosophies that explain the nature of drift within a
114 complex system. These embody principles from complexity theory such as path dependence,
115 non-linearity and the impact of protective structures (Dekker et al., 2012).

116 The need to manage human error comes as no great revelation to anyone involved in
117 operations where the consequences of failure are big serious. Exploring the formation methods
118 and mechanism models of human error, and obtaining a generalized method for accident
119 investigation, it is a topic that the industry is constantly studying. Based on the Swiss Cheese
120 Model, the version of Human factors Analysis and Classification System (HFACS) was
121 established. HFACS addresses human error at all levels of the system, including the condition
122 of aircrew and organizational factors (Shappell and Wiegmann, 2000). This model is a general
123 human error framework originally developed and firstly tested within the U.S. as a tool for
124 investigating and analyzing the human causes of aviation accidents (Wiegmann et al., 2001). It
125 has been identified several key safety factors that require intervention and proved that the HFACS
126 framework can be a viable tool (Gaur, 2005). Krulak. (2004) proposed a maintenance extension of the
127 HFACS method (HFACS-ME), and proved that human factors have a significant relationship with
128 mishap frequency and severity in mishaps. Shappell et al. (2007) used HFACS put forward a logical
129 method to analyze the human factors in the causes of accidents to provide a logical analysis of how
130 accidents occur and how they can be prevented. Celik et al. (2007) sought to integrate those factors
131 into the HFACS system to discover design-based human factors in marine accidents.

132 A general accident model describes the unexpected failures caused by characteristics of a
133 system where interactions between factors behave in unpredictable ways and produce multiple and
134 unexpected failures. Celik and Cebi. (2009) applied HFACS to qualitative analysis of Human
135 Organizational factors (HOF) Structure in MTA. Chen. (2013) explored the structural relationship of
136 human factors combined with "why-because" graphs. HU et al. (2008) used a relative risks model to
137 analyze and evaluate ship navigation safety using Bayesian belief network. Chen et al. (2013)
138 successfully studied the application of HFACS in coal mines and flight safety, and produced a
139 qualitative list of human factors. Wang et al. (2013) first applied complexity theory to analyze the
140 mechanism of the accident. Within complex systems, the relationships between factors can be
141 described in terms of the interaction between them. Using multiple indicators to reflect latent
142 variables, and also estimating the relationship between the entire model factors, a way to deal with
143 measurement errors is necessary to be proposal which is more accurate and reasonable than

144 traditional regression methods and useful to explore the path in accident causation style. It is
 145 necessary to find the principle of path dependence from complexity theory, which has the
 146 non-linearity and the impact of protective structures.

147 Structural equation modeling is a method for testing the relationship between assumed latent
 148 variables by using real data collected by researchers, Seo. (2005) used the Structural Equation
 149 Modeling method to reveal the mechanisms through which the contributory factors of unsafe work
 150 behavior influence safety actions of individuals at their workplaces.

151 In this paper, we reviewed the research on the mechanism of MTA. HFACS provides a new
 152 method for the study of human factors in marine accidents, but the lack of quantitative analysis
 153 limits its use. SEM method makes it possible to quantitatively analyze the relationships among
 154 human factors in accidents. Additionally, the lack of a clear path to analyze the causes of MTA
 155 motivated this paper to propose a correlation model in the causal factors chain for MTA, which is
 156 expected to explore the impact of human interactions in the mechanism of accidents.

157 3. Theoretical and research hypothesis

158 3.1 HFACS in MTA

159 Heinrich classifies the causes of an accident as unsafe behavior of human, unsafe status of
 160 materials, and unsafe conditions of environment (Marshall et al, 2018). More and more researchers
 161 have begun to study the influence of human factors on accidents. Human factors refer to the harmful
 162 effects of human behavior on the normal function or successful performance of the system when
 163 completing a specific task.

164 HFACS describes human error at each of four levels: the actions of the operators (e.g.,
 165 bench-level scientists and field investigators in forensics); the preconditions for those actions
 166 (i.e., the conditions that influence human behavior); the middle management (i.e., the
 167 individuals whose role it is to assign work); and the organization itself (Shappell, et al. 2000). In
 168 the maritime field, here using HFACS for MTA to analyze human factors in marine accident
 169 (Chauvin et al., 2013; Wu et al., 2017), proposal the basic path of accident formation is described in
 170 Category I factors, which includes Organizational factors SL_4 - Unsafe Supervision SL_3 -
 171 Preconditions for Unsafe Acts SL_2 - Unsafe Acts SL_1 - Accident SL_0 . Meanwhile, establishing accident
 172 causal factors and the classification of those factors are defined as shown in Table 1 (Category II
 173 factors was described as $X_{i,i=1,2,\dots,17}$). Here the original framework and structure proposed by
 174 Shappell (1997) was reserved, such as SL_0 (X_{17}), SL_1 ($X_{13}, X_{14}, X_{15}, X_{16}$), SL_2 ($X_8, X_9, X_{10}, X_{11}, X_{12}$), SL_3
 175 (X_4, X_5, X_6, X_7), and SL_4 (X_1, X_2, X_3).

176 Based on CREAM and the theoretical basis for HFACS, a human structural cheese model can be
 177 constructed for a marine traffic accident. As shown in Figure 1, the following hypotheses were made:

178 Hypothesis H1: SL_3 has a significant effect on SL_4 ;

179 Hypothesis H2: SL_2 has a significant effect on SL_3 ;

180 Hypothesis H3: SL_1 has a significant effect on SL_2 .

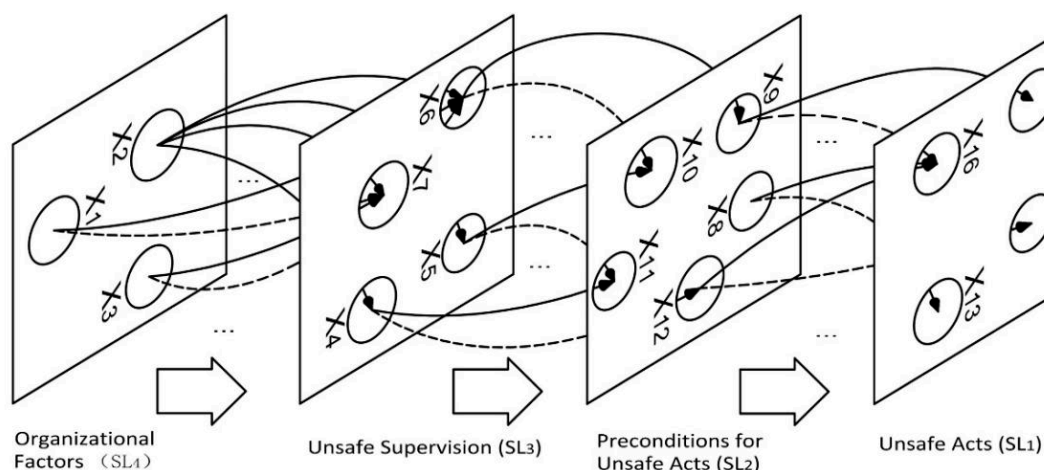
181 The quantitative relationship among human factors in maritime transportation is discussed
 182 thereafter.

183 **Table 1 Relationship of Causal factors to Marine accident**

Symbol	Item of Causal factors	Symbol	Item of Causal factors
SL_0	Accident	X_7	Violation Monitoring
SL_1	Unsafe Acts	X_8	Team factors
SL_2	Preconditions for Unsafe Acts	X_9	Individual factors
SL_3	Unsafe Supervision	X_{10}	Material factors
SL_4	Organizational Influence	X_{11}	Natural Environment
X_1	Resource Management	X_{12}	Physical Environment
X_2	Organizational Climate	X_{13}	Slip

X ₃	Process Safety Control	X ₁₄	Lapse
X ₄	Inadequate Supervision	X ₁₅	Mistake
X ₅	Unsuitable Execution Plan	X ₁₆	Violation
X ₆	Error-Correction Parsing	X ₁₇	Accident Consequence

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Figure 1 Path model of causal factors chain to MTA based on HFACS

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3.2 Causal factors in MTA

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The maritime industry stakeholder believes that the human component is a complex, multidimensional proposition that affects maritime safety and marine environmental protection, and includes crew, shore-based management, legislative and law enforcement agencies, shipyards, authorized organizations, and a series of behavioral activities of other relevant parties (Xi et al, 2017). All marine accidents will be affected and controlled by human factors, ship factors, environmental factors and management factors. However, the manifestations of system factors vary greatly in different accidents. In order to assist in the implementation of accident case analysis, an accident analysis system needs to be designed to fully define the description and characterization of the cause of the accident. This step relies on historical data and subject-matter experts analysis from the latent sources, such as databases, experiments, simulations, webs and logical analytical models. Detail items are shown in Table 2.

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Table 2 Definition of Causal factors to Marine accident

No:	Item	Description and Observation character
X ₁	Resource Management	Ship resource allocation, the allocation of ship resources, including operators, equipment and facilities, information support and monitoring, embodied in the suitability of personnel, the seaworthiness of the ship, and the suitability and effectiveness of external supporter.
X ₂	Organizational Climate	The organizational climate can be shown that influence employees' events, activities, and procedures, as well as those that may be rewarded, supported, and expected. It can be divided into employees' internal perceptions and team climates
X ₃	Process Safety Control	Process safety refers to how to prevent accidental loss of control and possible traffic accidents caused by installations and facilities during navigation, berthing and operation process, resulting in damage to employees and ships, environmental damage and property loss. .
X ₄	Inadequate Supervision	No finding in operation arrangements or process issues Insufficient staff training time, VTS monitoring failure

X ₅	Unsuitable Execution Plan	Improper arrangement of berths and anchorages, Operation plan negligence, Operation plan rationality defect
X ₆	Error-Correction Parsing	Repeat the same nature accident
X ₇	Violation Monitoring	Limit cause from Draught, weather, ship scale, etc.
X ₈	Team factors	Crew member's mistake; Tug crew error; Communication and cooperation negligence
X ₉	Individual factors	Illness or bad physiological state; Alcoholic beverage; Continuous operation, fatigue etc.
X ₁₀	Material factors	Equipment defects, Structural defects, Cargo defects, latent defects, Overload
X ₁₁	Natural Environment	Natural disasters, Poor visibility, Wind currents, Tides, Surges, Navigational environments, Waterway bends, Navigation aids, Navigable waters, Fishing areas
X ₁₂	Physical Environment	Channel curvature; Obstacle (including dock or anchorage restrictions) Navigation aid; Navigation density; Navigable water depth; Navigable water width
X ₁₃	Slip	Precaution to the natural conditions of the fairway; Precaution on ship traffic conditions; Precaution to encountering ship behavior; Visual hope negligence; Navigation instrument not used correctly
X ₁₄	Lapse	Navigation operation; Avoidance collision behavior; Manipulation judgment
X ₁₅	Mistake	Emergency treatment; Manipulating behavior(an anchorage, by mooring)
X ₁₆	Violation	Violation operation (relevant ship); Violation operation (assisting tugboat);Violation operation (pilot);Deviation (pilot)
X ₁₇	Accident Consequence	Degree of the consequences of the accident, including near miss

200 3.3 Relationship of causal factors in MTA

201 The relationship of factors has many pieces. When studying the correlation of human factors in
202 the causes of MTA, the following aspects are mainly considered:

203 (1) Positive or negative factors of the correlation coefficient

204 If the correlation coefficient is positive, there is a positive correlation of the factors; if the
205 correlation coefficient is negative, then there is a negative correlation of the factors.

206 (2) Scale of the correlation coefficient

207 For correlation coefficient, the greater the absolute value, the stronger the correlation of the
208 factors is; if the minimum value is 0, at that time, in general, the factors do not depend on each other.

209 (3) Rank in Correlation of factors

210 The interaction of factors is reflected in the relationship of the factors, so some are directly
211 associated, indicating that the factors are direct and influential, but some are indirect showing
212 secondary effects.

213 The above associated accident analysis can form the path of the factors. The main content of
214 path analysis is to solve: (a) Path direction; (b) Variable relationships of indicators; (c) Path load
215 capacity; and (d) Whether the model hypothesis is actually matched.

216 3.4 Path analysis on causal factors of the MTA system

217 According to the complex network theory, the combination of accident factors and their
218 associated relationships is called the accident network SOBIESKI J S. (2006). The node characteristics
219 and associated characteristics in the accident network determine the main performance of the
220 accident network.

221 The occurrence of complex system safety incidents is not caused by a single risk factor, but is
222 the result of multiple risk causal factors. Corresponding to the accident network, the causal factors of
223 the MTA system are generally not a single node, but an accident chain composed of multiple

224 associated nodes, or an accident network consisting of an accident chain. Therefore, taking into
 225 account the dynamic nature of the risk, the accident is related to the accident path. However, the
 226 accident does not happen overnight, but needs to undergo a series of processes such as risk
 227 emergence, risk transfer, risk coupling, and accident emergence. In this process, there are many risk
 228 transfer paths, and the final accident path may be any one of them. One can analyze the risk
 229 transmission path of the complex accident system before the accident occurs, and identify the
 230 important parameters that affect the risk transfer. In an accident network, a path with more nodes is
 231 a critical path, and a path with fewer nodes is a non-critical path.

232 The causal path of the accident system includes two parts: the causes of the accident and the
 233 relationship of the causes. The path of the maritime causal system can show the beginning and
 234 ending of the MTA causal path, namely to express the direct and root causes in the MTA. It can show
 235 the causal path of a series of factors interacting with each other before the accident and help better
 236 explain the transmission process of the accident cause, reveal the evolution mechanism of the
 237 accident, and further help people to take effective measures based on the causal path of vulnerable
 238 defects.

239 4. Correlation model in causal factors chain for MTA

240 Usually, to study the safety of complex systems, it is impossible to test the actual system to
 241 observe the accident behavior; therefore, one must construct a theoretical model of the complex
 242 system. By constructing the corresponding simulation model for the theoretical model, computer
 243 simulation can be used to gain an in-depth understanding of system performance under different
 244 parameters. Traditional multivariate analysis methods such as complex regression, factor analysis,
 245 multivariate analysis of variance, correlation analysis, etc. can only test the relationship between a
 246 single independent variable and dependent variable at the same time, and these analytical methods
 247 often have deficiency in theoretical assumptions and application. Factor analysis can reflect the
 248 relationship between multi-variables, but it can not further analyze the causal relationship between
 249 variables. While path analysis can analyze the causal relationship between variables, the actual
 250 situation is difficult to meet the basic assumptions that the measurement error between the
 251 variables is zero, the residuals are irrelevant, and the causality is one-way function. In this paper, a
 252 novel method to analysis the causal factors is introduced via the network structural equation.

253 The Structural Equation Model(SEM) is a statistical method that analyzes the relationship
 254 among different variables by using a co-variance matrix of variables. The structural equation model
 255 integrates path analysis, confirmatory factor analysis and general statistical test methods to analyze
 256 the causal relationship between variables, including the advantages of factor analysis and path
 257 analysis. At the same time, it makes up for the shortcomings of factor analysis, taking into account
 258 the error factors, and does not need to be limited by the assumptions of path analysis. Based on this,
 259 we propose the strong and weak associated path of accident cause to quantitatively describe the
 260 mechanism of the accident.

261 The purpose of this paper is to find the path to the causes of the accident by finding the
 262 relationship among the causes of the accident. This differs from traditional statistical methods
 263 because in addition to quantitatively analyzing the effect of a cause on the results, the structural
 264 equation model also can quantitatively analyze the relationship between causes, so this paper will
 265 use the structural equation modeling method to decipher the relationships in the causes of the
 266 accident.

267 4.1 Methods and Models

268 The Structural Equation Model includes both the measurement model and the structure model
 269 (Crowley and Fan, 1997; Zhang et al., 2016). The measurement equation is used to describe the
 270 relationship between the observed dependent variable and the latent independent variable. The
 271 equation matrices of the measurement model are:

$$272 \quad x = \lambda_x \xi + \delta \quad (1)$$

$$y = \lambda_y \eta + \varepsilon \quad (2)$$

Where among them,

x ---- Vector consisting of observed variables from exogenous latent variables

y ---- Vector consisting of observed variables from endogenous latent variables

λ_x ---- The strength of association from exogenous observed variables.

λ_y ---- The strength of association from endogenous observed variables

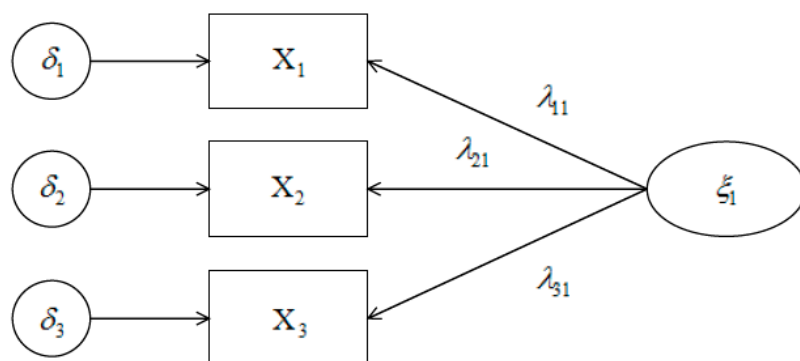
ξ ---- Unobserved exogenous latent variables

η ---- Unobserved endogenous latent variables

δ ---- The error items of the exogenous variables

ε ---- The error items of the endogenous variables

The measurement model is shown in Figure 2.



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Figure 2 The measurement model

286 Structure equations are used to describe the relationship among latent variables. Equation
287 matrix form of the structure model is:

$$\eta = \beta\eta + \gamma\xi + \zeta \quad (3)$$

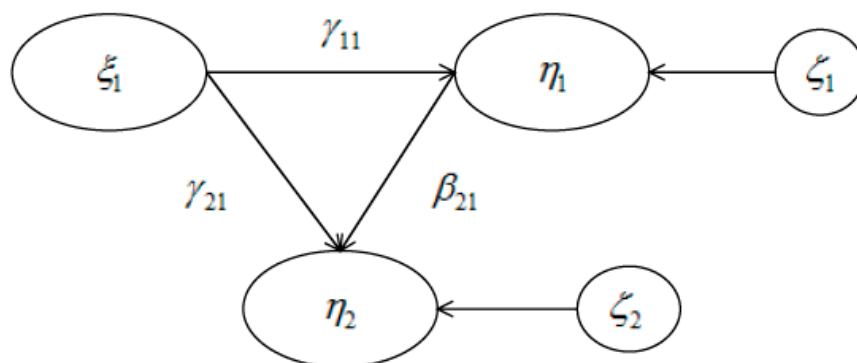
289 Where among them,

290 β ---- the relationship between endogenous latent variables

291 γ ---- the relationship between exogenous latent variables

292 ζ ---- the residual term of the equation, and it represents the portion of the endogenous latent
293 variable that is not interpreted in SEM.

294 The structural model is shown in Figure 3.



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Figure 3 The structural model

297 The above three equations can form a general structural equation model (Byrne, 2009; Seo et al.,
298 2015). Each line segment in the SEM has a path coefficient that characterizes the association between
299 the two variables connected by the limit. After the path coefficients have been normalized, the
300 values range from -1 to +1. In addition, the values by path factor can be divided into three categories:

301 (1) When $0 < \text{path coefficient} \leq 1$, it means that there is a positive correlation between variables or
 302 one variable has a positive effect on another variable, that is, the function between variables is
 303 monotonically increasing;

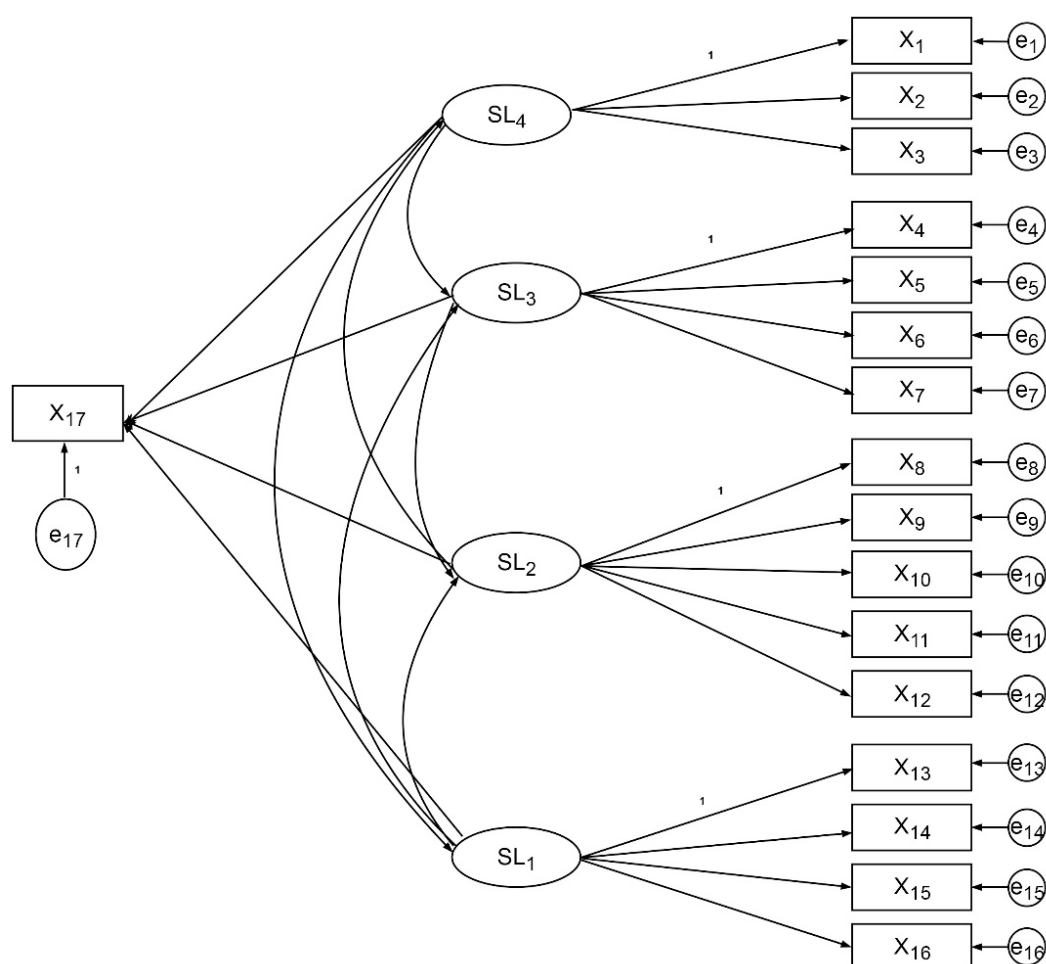
304 (2) When $-1 \leq \text{path coefficient} < 0$, it means that there is a negative correlation between variables
 305 or one variable has a negative effect on the other variable, that is, the function between variables is
 306 monotonously decreasing;

307 (3) When the path coefficient is equal to 0, it means that the variables are independent of each
 308 other and not related to each other.

309 4.2 Hypothesis Structure model for the human factors of MTA

310 Use Category I factors of the human factors in section 1 as latent variables (indicated by
 311 ellipses), and use the corresponding Category II factors as observation variables (indicated by
 312 boxes), drawing a hierarchical classification and hypothesis model of human factors. e_i is the
 313 observation error. As shown in Figure 4.

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315

316 **Figure 4 Structural Hypothetical Model of HFACS-MTA**

317 5. Case study

318 This paper uses the accident case database from 2000 to 2009 in a certain area as an analytic
 319 sample (Hu et al., 2012; Huang et al., 2018), through the screening and extraction of the database,
 320 combining with the SEM hypothesis model and algorithm to apply to the model.

321 5.1 Accident samples analysis

322 5.1.1 Accident sample scale

323 Taking the human error in the area of MTA as the research object, a total of 894 samples of
 324 accidents were introduced. X_{17} "Accident" as an observation variable is used to examine the effects of
 325 different factors on the consequences of the accident. Use of the score of consequences of the accident
 326 depends on the actual level of the collection, including five levels: incidents, minor accidents,
 327 general accidents, major accidents, and serious accidents. They correspond to different accident
 328 consequences scores, as shown in Table 3.

329 **Table 3 Accident consequence score table**

Rank	value	Description
incidents	1	_ Near miss
		_ hazard
		_ An event considered to be worthy of attention
minor accidents	2	_ Failure that can be readily compensated by the crew
		_ No significant harm to people, property or the environment
general accidents	3	_ Local damage to ship
		_ Marginal conditions for, or injuries to crew
major accidents	4	_ Major casualties excluding total loss
		_ Single fatality or multiple severe injuries
serious accidents	5	_ Total loss (actual loss and constructive total loss)
		_ Many fatalities

330 5.1.2 Formatting causal factors of the accident

331 Among these samples, there were all kinds of consequence which included 12 incidents, 520
 332 minor accidents, 148 general accidents, 123 major accidents, and 91 serious accidents. The cause
 333 analysis of the accidents is the process of determining the cause of the accident and measuring the
 334 impact of the accident.

335 As to HFACS, human factors are those factors related to people in the operation of the system.
 336 Human factors are beneficial to the safety side (such as people exert their own ingenuity, overcome
 337 the adverse effects of mechanical equipment or harsh environment, etc.), but also can have a
 338 negative effect. As a research object of human factors in MTA, the negative impact on human safety
 339 due to human factors, namely Human Error was more important. The detailed information about
 340 the observed characters in accident reports were structured and formatted(also shown in Table 2).

341 Each sample analysis for the causes of the accident is based on observed characters items, such
 342 as management software , ship (cargo) hardware, environment(including natural conditions,
 343 geographical conditions, traffic conditions), and liveware (Xi et al., 2017). In research of human
 344 factors in marine traffic safety, the following four interfaces should be analyzed:

345 1) Liveware- liveware interface (L-L): The interaction between people in the system, such as
 346 leadership, management, communication and cooperation between people.

347 2)Liveware-hardware interface (L-H): The relationship between people and ships, equipment
 348 and other hardware, such as whether the design or layout of the ship or equipment conforms to
 349 human characteristics, whether it is convenient for people to manage and maintain the hardware,
 350 use or operate the hardware.

351 3) Liveware-software interface (L-S): The relationship between people and software, such as
 352 whether the information is complete and easy to follow as well as the ease of the operation of the
 353 software.

354 4) Liveware-environment interface (L-E): The relationship between humans and the
 355 environment, such as whether working conditions limit human's behavior and whether external
 356 conditions affect people's judgments.

357 In the case of structured accidents' documents, the observed characters in causes of the
358 accidents are divided into the following 7 categories:

359 (1) Management items: maritime administration limit, company management limit;

360 (2) Natural items: natural disasters, poor visibility, wind, tides, surges;

361 (3) Channel or terminal items: navigation loops, channel bends, aids to navigation, navigable
362 waters, chart publications, fishing areas;

363 (4) Traffic items: navigation order, traffic accident, berth anchorage, navigation management;

364 (5) Ship cargo items: structural defects, equipment defects, cargo defects, latent defects, over
365 workload;

366 (6) Personnel involved items: the tugboat operator, the ship operator, and the outboard
367 operator.

368 (7) Crew items: violation operation, negligence of route planning, negligence of navigation
369 operation, negligence in avoidance of collision, negligent manipulation, emergency-handling,
370 communication and cooperation negligence.

371 According to the different effects of the observed character on the outcome of these accidents,
372 the factors influence level are divided into four grades:

373 Level I, the factor may not impact the accident outcome, *no effect*

374 Level II, the factor may partly impact the accident outcome, *involved*

375 Level III, the factor may mainly impact the accident outcome, *mainly*

376 Level IV, the factor may apparently impact the accident outcome, *directly*.

377 5.2 Data acquisition and reliability analysis

378 In order to enable the fitting of the collected data into the hypothesis model, the collected
379 accident factors must be quantified according to the level of impact on the consequences of the
380 accidents. In this paper, to evaluate and synthesis the samples collected, a workshop was conducted
381 with subject-matter experts in accident analysis and systems thinking. Furthermore the data in
382 accident causation are measured by the "Likert scale", using a five-level scale.

383 First, quantitative data assignment is used for the extent of each factor's effect. According to the
384 Level of impact, the rating is separately defined. Such as *no effect*, 5; *involved*, 4; *mainly*, 2; *directly*, 1.
385 As to how the accident is described, for example, those which are described as a general accident,
386 the detail influence factors which result to a certain accident includes observed characters such as
387 "non finding in operation arrangements or process issues", "Insufficient staff training time" and
388 "VTS monitoring failure" (variable in Table 2). These factors effect the accident at different levels of
389 influence as discussed above, namely, "directly", "involved" and "no effect" respectively. That
390 means the score is 1, 4, 5 respectively. Each accident sample can be described by the influence factors.

391 Second, the score of the $x_i(i=1,2,\dots,16)$ accident causal factors depends on the minimum score
392 among the corresponding observed characters collected. As to the case stated above, those 3
393 observed characters involved "Inadequate Supervision" were numerical analyse, and the lowest
394 score is measured as 1, which means "directly". Therefore, x_i "Inadequate Supervision" is measured
395 as 1. All the structured observed characters in accident reports were formatted to numerical analysis
396 data. The tested data statistics are shown in Table 4.

397 **Table 4 Tested data from accident database**

Case No	X1	X2	X3	X4	X5	X6	X7	X8	X9	X10	X11	X12	X13	X14	X15	X16	X17
1	5	4	4	5	1	5	1	1	1	4	2	4	1	4	4	1	3
2	4	4	5	5	5	5	5	5	1	5	2	4	1	4	4	5	5
3	4	5	5	5	4	4	4	1	1	5	4	5	1	4	4	5	4
4	4	4	4	5	5	4	5	5	5	5	5	4	5	4	5	5	4
5	5	5	4	4	5	5	4	1	1	5	5	4	1	4	5	4	4

6	4	4	5	4	5	4	4	1	1	5	2	4	1	4	5	4	4
7	4	5	4	5	5	4	5	4	5	5	5	5	5	5	4	4	4
8	5	4	5	4	5	4	5	5	1	4	2	5	1	4	4	4	5
9	5	5	5	5	1	5	1	1	1	4	5	5	1	4	5	1	3
10	5	5	5	4	1	4	1	1	1	5	4	5	1	5	4	1	3

891	4	5	4	4	5	5	5	1	1	2	4	4	1	4	4	4	2
892	4	5	4	5	5	5	5	1	1	2	5	5	1	4	5	4	2
893	4	4	4	4	1	5	1	1	1	5	2	4	1	5	5	1	1
894	4	5	5	5	1	4	1	1	1	5	4	4	1	4	5	1	1
μ	4.1	4.2	4.1	4.2	4.0	4.1	2.7	2.9	2.3	4.1	3.7	4.4	2.1	4.5	4.5	4.0	4.3
σ	0.8	0.7	0.7	0.7	1.3	0.8	1.3	1.7	1.7	0.9	1.1	0.4	1.6	0.4	0.4	1.3	1.1

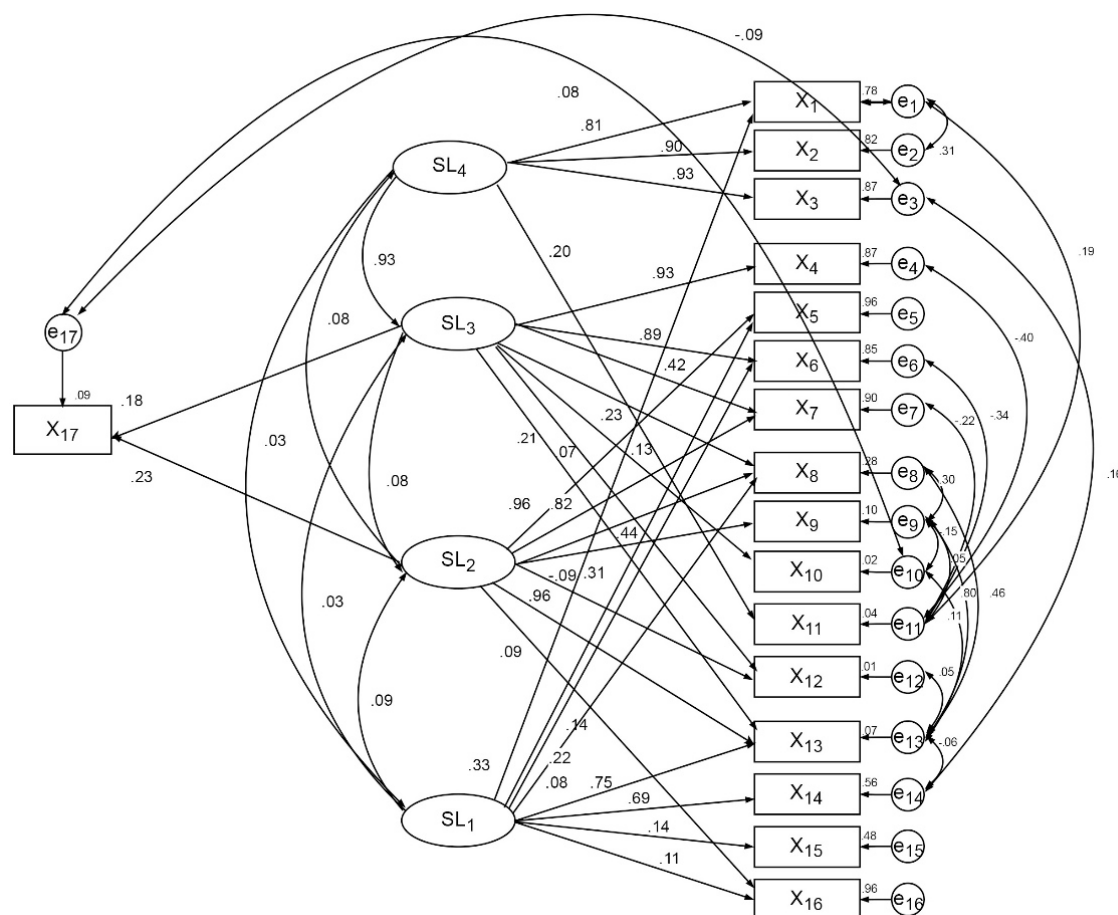
398 The collected accident factors were categorized according to the literature (Celik and Cebi,
399 2009), and finally the data was integrated into the 16 major accident factors. Thereby, a scoring of the
400 16 accident factors (variable in Figure 6) depends on the corresponding minimum score among the
401 accident factors collected.

402 In addition to the correlation of factors in different MTAs, the impact of different factors on the
403 consequences of the MTA is also analyzed. Therefore, the observation variable "Accident
404 Consequence" (X_{17}) is added to examine the influence of different factors on the consequences of
405 accidents.

406 5.3 Model fitting and correction

407 The paths that do not conform to the SEM hypothesis are as follows: (a) the path of the error
408 term of the observed variable to the latent variable; (b) the path of the observed variable to other
409 observed variables; (c) the error term of the observed variable for other observations The path of
410 influence of the variable; (d) the path of the error term of the observed variable to the error term of
411 other observed variables.

412 When the model is changed, the researcher should add new paths one by one instead of adding
413 multiple paths all at once. The processed data are fitted with the hypothetical model, and modify the
414 model with the output of the modification indices. The resulting path dependency is shown in
415 Figure 5.



416

417

Figure 5 Path Diagram of MTA Forming using SEM simulation

418 5.4 Reliability analysis in path dependency

419 An analysis of the reliability of the sample data table should be performed before fitting the
 420 sample data to the hypothetical model (Byrne, 2009). Cronbach's Alpha coefficient (CA) is a measure
 421 of the intrinsic consistency of a set of data used to determine whether the set of data represents the
 422 same attitude tendencies and whether it can form an attitude measurement index.

423 The Cronbach's Alpha test was performed on observation variables to measure a set of
 424 hypothetical "internal consistency" coefficients (Byrne, 2009), so as to judge whether this group of
 425 hypotheses represents the same tendency of attitude and whether it can constitute an attitude
 426 measurement index.

427 In general, if the CA is greater than 0.7, this indicates that the data has good reliability. When
 428 the CA is below 0.7, the entries in the data may represent different dimensions and need to be
 429 filtered.

430 The results show that after deleting some of the items, the check coefficient values of the
 431 observed variables are all above 0.7, and the overall reliability value reaches 0.797, indicating that
 432 this figure has good reliability.

433 Data statistics are shown in Tab 4, which is shown mean and standard variation of each
 434 variable.

435 Since the modified model used in this paper has some differences with the theory, it is
 436 necessary to test the sensitivity of the model in order to verify whether the modified model used in
 437 this paper is applicable to different types and sizes.

438 The critical ratio (C.R.) is used to test the significance of evaluation of the parameter in the
 439 model (Crowley and Fan, 1997). The critical ratio is the proportion of the evaluation of the parameter
 440 estimate to its standard deviation. When the significance level is 0.05, it means that the parameter

441 evaluation is not equal to 0 significantly, and the null hypothesis can be rejected if the absolute value
 442 of C.R. is greater than 1.96. The calculation results are presented in Table 5.

443 **Table 5 Statics data of critical ratio on variable**

Hypothesis	Estimate value	Critical ratio	Conclusion
H1: SL ₃ ->SL ₄	0.944	33.727	Exist significant influences , defined hypothesis is true
H2: SL ₂ ->SL ₃	0.077	2.175	Exist significant influences , defined hypothesis is true
H3: SL ₁ ->SL ₂	0.125	2.921	Exist significant influences , defined hypothesis is true

444 The goodness-of-fit index of the amended model was shown in Table 6. From Tables 5 and 6, it
 445 is shown that the goodness-of-fit index of the model meets the criteria, indicating that the model and
 446 the data fit well.

447 **Table 6 Statics data of variable via SEM simulation**

Evaluation index	Estimate Value	Adaptation standard
<i>Absolute index</i>		
χ^2 Significant probability value	0.281	>0.05
Goodness-of-fit index (GFI)	0.989	>0.90
Adjusted goodness-of-fit index (AGFI)	0.980	>0.90
Root mean square residual (RMR)	0.031	<0.05
Root mean square error of approximation (RMSEA)	0.010	<0.05
<i>Relative index</i>		
Normal fit index (NFI)	0.993	>0.90
Relative fitness index (RFI)	0.988	>0.90
Incremental fit index (IFI)	0.999	>0.90
Tracker – Lewis index (TLI)	0.999	>0.90
Comparative-fit index (CFI)	0.999	>0.90
<i>Parsimony index</i>		
Parsimony goodness-of-fit Index (PGFI)	0.552	>0.50
Parsimony-adjusted (PNFI)	0.629	>0.50
χ^2/df (NC) indicating the degree of minimalist fit	1.088	1<NC<3

448 It can be seen from Table 5 that the path coefficient of SL₄->SL₃ is 0.94 and the *t*-check value is
 449 33.727; the path coefficient of SL₃->SL₂ is 0.08 and the *t*-check value is 2.175; the path coefficient of
 450 SL₂->SL₁ is 0.13 and the *t*-check value is 2.921. These indicate that the H1, H2, and H3 hypotheses are
 451 true and have a significant positive relationship. This proves the correctness of the HFACS-MTA
 452 framework from a quantitative point of view.

453 *5.5 Sensitivity analysis of HFACS-MTA based on SEM model*

454 Sensitivity analysis is used to qualitatively or quantitatively analyze changes in model results
 455 when model parameters or samples change. It classifies the collected documented cases according to
 456 different types of accidents (such as collisions, grounding, fires, etc.), which fit different types of
 457 accident data to the revised model of Figure 5, and carry out model analysis of the changes in the
 458 goodness-of-fit index and estimated parameters, in order to test the reliability and stability of the
 459 model. The post-test data prove that: although the significance level of the chi-square value obtained
 460 by fitting the modified model with the test sample did not reach the goodness-of-fit index, other
 461 fitness indexes met the requirements, and most of the path coefficients shown by the model were
 462 consistent. Therefore, the modification model of the MTA cause path is stable and suitable to be
 463 applied to samples under different conditions, and can provide guidance in those situations.

464 There are some differences between the model results and HFAC-MTA in the corresponding
 465 relationship of the Category I factors and Category II factors, as presented in Table 7.

466 **Table 7 factors correlation characters via SEM simulation**

Correlation Mode			Standardized path coefficient
SL ₄	->	X ₁₁	0.24
SL ₃	->	X ₅	No significant effect
		X ₁₃	0.21
SL ₂	->	X ₅	0.94
		X ₇	0.82
SL ₁	->	X ₁	0.27
		X ₅	0.16
		X ₆	0.23
		X ₈	0.08
		X ₁₀	0.09

467 Table 7 shows that:

468 (1) Organizational factors SL₄ are not only related to the three types of human factors in the
 469 theory, but also related to the Natural Environment.

470 (2) There is no significant correlation between Unsafe Supervision SL₃ and Unsuitable
 471 Execution Plan in HFACS theory, but there is a correlation with Slip.

472 (3) The Preconditions for Unsafe Acts SL₂ are related to Unsuitable Execution Plan and
 473 Violation Monitoring.

474 (4) There are correlations between Unsafe Acts SL₁ and Resource Management, Unsuitable
 475 Execution Plan, Error-Correction Parsing, Team factors, and Material factors.

476 6. Path analysis and discussion

477 Path analysis is used to test the hypothesis relationship of observation variables or indicator
 478 variables. The purpose of path analysis is to check the accuracy and reliability of the hypothetical
 479 model and analyze the relation intensity of different variables. Figure 5 mainly shows the path
 480 diagrams of latent variables and latent variables with their corresponding observed variables.
 481 However, the relationship among observed variables cannot be obtained, and there is a correlation
 482 in measurement error items of the model. The correlation between the two measurement error items
 483 indicates that there is a certain degree of latent correlation between the corresponding two
 484 measurement variables. From this, the MTA causal system path diagram can be as shown in Figure 7
 485 (Only select the part that normalized path coefficients greater than 0.2 between Category I factors
 486 and Category II factors).

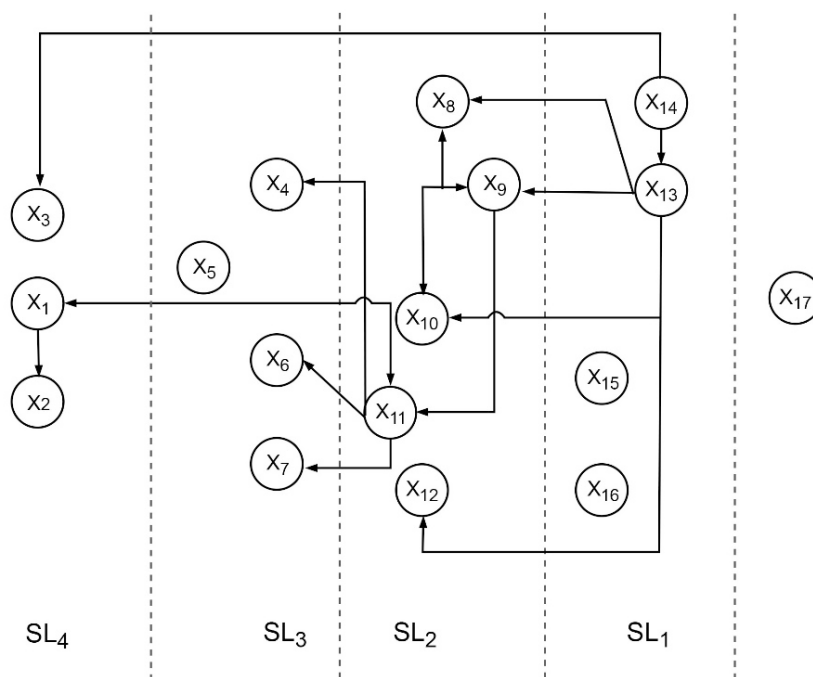


Figure 6 Path and trace representation of MTA network

487

488

489 Figure 6 presents some path dependencies that may lead to accident, such as:

490 Path dependency I (PD-I): Resource Management - Natural Environment - Individual factors -
491 Slip;

492 Path dependency II (PD-II): Organizational Climate - Resource Management -Natural
493 Environment - Error-correction Parsing.

494 Decision-makers can find the influence and mode of action in the causes of MTA based on these
495 path dependencies. For example, PD-I link indicates that there is interaction between the "Resource
496 Management" & "Natural Environment", "Natural Environment" & "Individual factors", "Individual
497 factors" & "Slip" and these interactions eventually result in accidents.

- 498 ● The "Natural Environment" is the important reason for the entire accident system, and it is
499 the key link between the previous factor and the next.
- 500 ● "Resource Management" has a prominent position in the Organizational factors level (root
501 cause) and is highly relevant.
- 502 ● "Process Safety Control" directly affects the "Slip" of human unsafe acts.

503 Therefore, the decision-maker can strengthen the control and management of the four
504 structural factors for the causal path to avoid interaction and ultimately prevent the accident from
505 occurring. It is also possible to intervene in only some of the key items, so as to cut off the
506 progression of the causal path and eventually avoid the accident.

507 (1) The Organizational factors SL_4 corresponding to Category II human factors are Resource
508 Management, Organizational Climate, Process Safety Control, and Natural Environment. Category
509 II human factors corresponding to Inadequate Supervision are: Error-Correction Parsing, Inadequate
510 Supervision, Violation Monitoring, Team factors, and Slip.

511 (2) The Preconditions for Unsafe Acts SL_2 corresponding to Category II human factors are
512 Violation Monitoring, Team factors, Unsuitable Execution Plan, Individual factors, and Violation.

513 (3)The Unsafe Acts SL_1 corresponding to Category II human factors are Resource Management,
514 Error-Correction Parsing, Lapse and Mistake. Among them, Resource Management,
515 Error-Correction Parsing, Team factors, and Violation Monitoring distribution are related to two
516 Categories I human factors.

517 **7. Conclusion**

518 The formation of MTA is complex, but the degree of influence and the mode of action of factors
519 in the cause system are different. The strength of the correlation of the factors determines the path of
520 the accident. Example verification shows that there are different correlations of various factors in
521 HFACS, and the observed variables manifest form conforms to the path dependency mode.
522 Resource management factors in the sub-hierarchy of organizational factors have a prominent
523 position in the accident formation and a strong correlation to same.

524 (1) The HFACS-MTA generic texture hypothesis paradigm based on the SEM can develop
525 system pathway maps between the latent (independent) variable and observed (dependent) variable
526 , which could quantitatively study the interrelationships in the various causes. The hypothesis
527 model application shows that the relationship of human factors in the MTA is consistent with
528 HFACS, and the direction of human error in the MTA is in the order of Organizational factors,
529 Inadequate Supervision, and Preconditions for Unsafe Acts, and finally passed on to Unsafe Acts.
530 The mutual influences in factors of the accident causes are obviously different.

531 (2) Structural equation modeling is a powerful research tool in the field of safety sciences, but
532 the establishment of related models relies on the knowledge of relevant scientific fields. The setting
533 of the implicit variables of the structural equations of accident causation theory and the setting of
534 the relationship between hidden variables have the theoretical knowledge base of the maritime field.
535 The setting and measurement of the measured variables corresponding to the hidden variables also
536 have their theoretical basis. The structural equation model is only a mathematical expression of the
537 theoretical knowledge base of the relevant scientific field, and it provides a tool for us to study
538 related safety sciences.

539 (3) We have seen that in recent times, the theory of accident causation based on system theory
540 has greatly changed and developed the understanding of traditional accidents forming. In
541 particular, the characteristics of safety is seen as the emergence of systems, with safety issues as a
542 matter of control. The cause of the accident is not only to describe the components in system
543 structure, but also to explain the interaction and coupling between the causal factors. This paper
544 believes that a certain mathematical algorithm is used to analyze the degree of cross-linking between
545 factors, describe the process of action between factors, and then determine the path of accident
546 formation. This is a quantitative demonstration of the cheese model, revealing the path dependence
547 of management defects in the field of marine safety affecting human behavior.

548 We also see that, to study the safety problems of the complex marine traffic system, it constructs
549 a theoretical model of a complex system and proposes an accident cause structural hypothesis.
550 Appropriate algorithms for the theoretical human-machine-control model can be used to
551 understand the safety performance of marine traffic systems under different parameters through
552 mathematical analysis. Combined with big data ideas and intelligent prediction theory, it provides
553 an important basis for risk pre-warning and accident prevention. This will be a problem that will
554 require further research.

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