

On the influence of center-Lipschitz conditions in the convergence analysis of multi-point iterative methods

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Abstract

The aim of this article is to extend the local as well as the semi-local convergence analysis of multi-point iterative methods using center Lipschitz conditions in combination with our idea, of the restricted convergence region. It turns out that this way a finer convergence analysis for these methods is obtained than in earlier works and without additional hypotheses. Numerical examples favoring our technique over earlier ones completes this article.

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1 Introduction

Let \mathcal{X}, \mathcal{Y} be Banach spaces and $\Omega \subset \mathcal{X}$ be a nonempty and open set. By $\mathcal{B}(\mathcal{X}, \mathcal{Y})$, we denote the space of bounded linear operators from \mathcal{X} into \mathcal{Y} . Let also $U(w, d)$, be an open set centered at $w \in \mathcal{X}$ and of radius $d > 0$ and $\bar{U}(w, d)$ be its closure.

Many problems from diverse disciplines such that Mathematics, Optimization, Mathematical Programming, Chemistry, Biology, Physics, Economics, Statistics, Engineering and other disciplines [?, ?], can be reduced to finding a solution x^* of the equation

$$\mathcal{H}(x) = 0, \quad (1.1)$$

where $\mathcal{H} : \Omega \rightarrow \mathcal{Y}$ is a continuous operator. Since, a unique solution x^* of equation (1.1) in a neighborhood of some initial data x_0 can be obtained only in special cases. Researchers construct iterative methods which generate a sequence converging to x^* .

The most widely used iterative method is Newton's defined for each $n = 0, 1, 2, \dots$ by

$$x_0 \in \Omega, x_{n+1} = x_n - \mathcal{H}'(x_n)^{-1} \mathcal{H}(x_n). \quad (1.2)$$

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The order of convergence is an important concern when dealing with iterative methods. The computational cost increases in general especially when the convergence order increases.

That is why researchers and practitioners have developed iterative methods that on the one hand avoid the computation of derivatives and on the other hand achieve high order of convergence.

We consider the following multi-step iterative method defined for each $n = 0, 1, 2, \dots$ by

$$\begin{aligned} u_n &= v_n^{(0)} \\ v_n^{(1)} &= v_n^{(0)} - \mathcal{H}'(v_n^{(0)})^{-1} \mathcal{H}(v_n^{(0)}) \\ v_n^{(2)} &= v_n^{(1)} - \mathcal{H}'(v_n^{(0)})^{-1} \mathcal{H}(v_n^{(1)}) \\ &\dots \\ u_{n+1} &= v_n^{(k)} = v_n^{(k-1)} - \mathcal{H}'(v_n^{(0)})^{-1} \mathcal{H}(v_n^{(k-1)}). \end{aligned} \quad (1.3)$$

The semi-local convergence of method (??) was given in [?]. It is well known that as the convergence order increases the convergence region decreases in general. To avoid this problem, we introduce a center-Lipschitz-type condition that helps us determine an at least as small region as before containing the iterates $\{u_n\}$. This way the resulting Lipschitz constants are at least as small. A tighter convergence analysis is obtained this way. The order of convergence was shown using Taylor expansions and conditions reaching up to the $k + 1$ order derivative of \mathcal{H} , although these derivatives do not appear in this method. As an academic example: Let $\mathcal{X} = \mathcal{Y} = \mathbb{R}$, $\Omega = [-\frac{5}{2}, \frac{3}{2}]$. Define φ on Ω by

$$\varphi(x) = x^3 \log x^2 + x^5 - x^4$$

Then

$$\begin{aligned} \varphi'(x) &= 3x^2 \log x^2 + 5x^4 - 4x^3 + 2x^2, \\ \varphi''(x) &= 6x \log x^2 + 20x^3 - 12x^2 + 10x, \\ \varphi'''(x) &= 6 \log x^2 + 60x^2 = 24x + 22. \end{aligned}$$

Obviously $\varphi'''(x)$ is not bounded on Ω . So, the convergence of methods (??) is not guaranteed by the analysis in [?, ?, ?].

The rest of the article is organized as follows: Section 2 contains the conditions to be used in the semi-local convergence that follows in Section 3. Finally the numerical examples are given in the concluding Section 4.

2 Local convergence

Let $L_0 > 0, L > 0$ and $L_1 \geq 1$ be parameters. Define the scalar quadratic polynomial p by

$$p(t) = (2L_0 + L)L_0 t^2 - (4L_0 + 4L_0 L_1 + L)t + 2. \quad (2.1)$$

The discriminant D of p is given by

$$\begin{aligned} D &= (4L_0 + 4L_0L_1 + L)^2 - 8L_0(2L_0 + L) \\ &= 16(L_0L_1)^2 + L^2 + 32L_0^2L_1 + 8L_0L_1L > 0, \end{aligned}$$

so p has roots s_1 and s_2 with $0 < s_1 < s_2$ by the Descartes's rule of signs. Define also parameters

$$\gamma = \left(\frac{L}{2(1 - L_0s_1)} + \frac{2L_0L_1}{(1 - L_0s_1)^2} \right) s_1 \quad (2.2)$$

and

$$r_A = \frac{2}{2L_0 + L}. \quad (2.3)$$

Notice that $\gamma \in (0, 1]$, since $p(s_1) = 0$. The local convergence analysis of method (??) uses the conditions (A):

- (a1) $\mathcal{H} : \Omega \rightarrow \mathcal{Y}$ is a differentiable operator in the sense of Fréchet and there exists $x_* \in \Omega$ such that $\mathcal{H}(x_*) = 0$ and $\mathcal{H}'(x_*)^{-1} \in \mathcal{L}(\mathcal{Y}, \mathcal{X})$.
- (a2) There exists $L_0 > 0$ such that for each $x \in \Omega$

$$\|\mathcal{H}'(x_*)^{-1}(\mathcal{H}'(x) - \mathcal{H}'(x_*))\| \leq L_0\|x - x_*\|.$$

Set $\Omega_0 = \Omega \cap B(x_*, \frac{1}{L_0})$.

- (a3) There exist $L = L(L_0) > 0$ and $L_1 = L_1(L_0) \geq 1$ such that for each $x, y \in \Omega_0$

$$\|\mathcal{H}'(x_*)^{-1}(\mathcal{H}'(y) - \mathcal{H}'(x))\| \leq L\|x - y\|$$

and

$$\|\mathcal{H}'(x_*)^{-1}\mathcal{H}'(x)\| \leq L_1\|x - x_*\|.$$

- (a4) $\bar{B}(x_*, s_1) \subset \Omega$.

- (a5) There exists $s_3 \geq s_1$ such that $s_3 < \frac{2}{L_0}$. Set $\Omega_1 = \Omega \cap \bar{B}(x_*, \frac{2}{L_0})$.

Based on the preceding conditions and notations we can show a local convergence result for method (??).

THEOREM 2.1 *Under the conditions (A), further assume that $u_0 \in B(x_*, s_1) - \{x_*\}$. Then, $\lim_{n \rightarrow \infty} u_n = x_*$, and the following estimations hold*

$$\|v_n^1 - x_*\| \leq \frac{L\|v_n^0 - x_*\|^2}{2(1 - L_0\|v_n^0 - x_*\|)}, \quad (2.4)$$

$$\|v_n^i - x_*\| \leq \gamma^i\|v_n^0 - x_*\| \text{ for each } i = 2, \dots, k \quad (2.5)$$

and

$$\|u_{n+1} - x_*\| \leq \gamma^{k+n}\|u_0 - x_*\|. \quad (2.6)$$

Moreover, the point x_* is the unique solution of equation $\mathcal{H}(x) = 0$ in the set Ω_1 given in (a5).

Proof. We use an induction based proof to show estimations (??)-(??). Let $x \in B(x_*, s_1) - \{x_*\}$. By (a1) and (a2), we obtain that

$$\|\mathcal{H}'(x_*)^{-1}(\mathcal{H}'(x) - \mathcal{H}'(x_*))\| \leq L_0\|x - x_*\| < L_0s_1 < 1. \quad (2.7)$$

It follows from the Banach lemma on invertible operators [?] and (??) that $\mathcal{H}'(x_*)^{-1} \in \mathcal{L}(\mathcal{Y}, \mathcal{X})$ and

$$\|\mathcal{H}'(x)^{-1}\mathcal{H}'(x_*)\| \leq \frac{1}{1 - L_0\|x - x_*\|}. \quad (2.8)$$

Then, $x_0 = v_0^0, v_0^1, \dots, v_0^k$ are well defined by method (??) for $n = 0$. We can write

$$v_0^1 - x_* = v_0^0 - x_* - \mathcal{H}'(v_0^0)^{-1}\mathcal{H}(v_0^0). \quad (2.9)$$

Then, by using (a1), (a3), (??) and (??), we get in turn that

$$\begin{aligned} \|v_0^1 - x_*\| &= \|v_0^0 - x_* - \mathcal{H}'(v_0^0)^{-1}\mathcal{H}(v_0^0)\| \\ &\leq \|\mathcal{H}'(v_0^0)^{-1}\mathcal{H}'(x_*)\| \\ &\quad \int_0^1 \|\mathcal{H}'(x_*)^{-1}[\mathcal{H}'(x_* + \theta(v_0^0 - x_*)) - \mathcal{H}'(v_0^0)]d\theta\| \|v_0^0 - x_*\| \\ &\leq \frac{L\|v_0^0 - x_*\|^2}{2(1 - L_0\|v_0^0 - x_*\|)} \\ &< \frac{Ls_1}{2(1 - L_0s_1)}\|v_0^0 - x_*\| \\ &< \|v_0^0 - x_*\| < s_1, \end{aligned} \quad (2.10)$$

which shows (??) for $n = 0$ and $v_0^1 \in B(x_*, s_1)$. Similarly by the second substep for $n = 0, k = 2$ we also get

$$\begin{aligned} v_0^2 - x_* &= v_0^1 - x_* - \mathcal{H}'(v_0^1)^{-1}\mathcal{H}(v_0^1) \\ &= v_0^1 - x_* - \mathcal{H}'(v_0^1)^{-1}\mathcal{H}(v_0^1) \\ &\quad + \mathcal{H}'(v_0^1)^{-1}[(\mathcal{H}'(v_0^0) - \mathcal{H}'(x_*)) + (\mathcal{H}'(x_*) - \mathcal{H}'(v_0^1))] \\ &\quad \times \mathcal{H}'(v_0^0)^{-1}\mathcal{H}(v_0^0), \end{aligned} \quad (2.11)$$

so by (a3), the definition of s_1 and (??) (for $x = v_0^1, v_0^0$), we get in turn that

$$\begin{aligned} \|v_0^2 - x_*\| &\leq \frac{L\|v_0^1 - x_*\|^2}{2(1 - L_0\|v_0^1 - x_*\|)} \\ &\quad + \frac{L_0(\|v_0^1 - x_*\| + \|v_0^0 - x_*\|)}{(1 - L_0\|v_0^1 - x_*\|)(1 - L_0\|v_0^0 - x_*\|)} \\ &\leq \left(\frac{L}{2(1 - L_0s_1)} + \frac{2L_0L_1}{(1 - L_0s_1)^2} \right) s_1\|v_0^1 - x_*\| \\ &\leq \gamma s_1\|v_0^1 - x_*\| < s_1, \end{aligned} \quad (2.12)$$

which shows (??) for $n = 0$ and $k = 2$. Similarly, from

$$\begin{aligned} v_0^i - x_* &= v_0^{i-1} - x_* - \mathcal{H}'(v_0^0)^{-1}(\mathcal{H}(v_0^{i-1})) \\ &= v_0^{i-1} - x_* - \mathcal{H}'(v_0^{i-1})\mathcal{H}(v_0^{i-1}) \\ &\quad + \mathcal{H}'(v_0^{i-1})^{-1}[(\mathcal{H}'(v_0^0) - \mathcal{H}'(x_*)) \\ &\quad + (\mathcal{H}'(x_*) - \mathcal{H}'(v_0^{i-1}))]\mathcal{H}'(v_0^0)^{-1}\mathcal{H}(v_0^{i-1}) \end{aligned} \quad (2.13)$$

so

$$\|v_0^i - x_*\| \leq \gamma \|v_0^{i-1} - x_*\| \leq \gamma^i \|v_0^0 - x_*\| < s_1, \quad (2.14)$$

and

$$\|x_1 - x_*\| \leq \gamma^{k+1} \|x_0 - x_*\| < s_1, \quad (2.15)$$

which show (??) and (??) for $n = 1, i = 2, 3, \dots, k$ and $v_0^i, x_1 \in B(x_*, s_1)$. Similarly, by induction we have in turn (as in (??))

$$\begin{aligned} \|v_j^1 - x_*\| &= \|v_j^0 - x_* - \mathcal{H}'(v_j^0)^{-1}\mathcal{H}(v_j^0)\| \\ &\leq \frac{L\|v_j^0 - x_*\|^2}{2(1 - L_0\|v_j^0 - x_*\|)} < s_1, \\ \|v_j^i - x_*\| &= \|v_j^{i-1} - x_* - \mathcal{H}'(v_j^0)^{-1}\mathcal{H}(v_j^1) \\ &\quad + \mathcal{H}'(v_j^{i-1})^{-1}[(\mathcal{H}'(v_j^{i-1}) - \mathcal{H}'(x_*)) \\ &\quad + (\mathcal{H}'(x_*) - \mathcal{H}'(v_j^0))]\mathcal{H}'(v_j^0)^{-1}\mathcal{H}(v_j^{i-1})\| \end{aligned} \quad (2.16)$$

leading to (as in (??))

$$\|v_j^i - x_*\| \leq \gamma^i \|v_j^0 - x_*\| < s_1 \quad (2.17)$$

and (as in (??))

$$\|u_{n+1} - x_*\| = \|v_n^k - x_*\| \leq \gamma^{k+n} \|u_0 - x_*\| < s_1, \quad (2.18)$$

which completes the induction for (??)-(??) and also show that $u_{n+1} \in B(x_*, s_1)$. It also follows from (??) that $\lim_{n \rightarrow \infty} u_n = x_*$, since $\gamma \in [0, 1)$. Let $x_{**} \in \Omega_1$ with $\mathcal{H}(x_{**}) = 0$. It then follows from the definition of Ω_1 , (a2) and $T = \int_0^1 \mathcal{H}'(x_{**} + \tau(x_* - x_{**}))d\tau$ that

$$\|\mathcal{H}'(x_*)^{-1}(T - \mathcal{H}(x_*))\| \leq \frac{L_0}{2} \int_0^1 \|x_* - x_{**}\|d\tau \leq \frac{L_0}{2} s_3 < 1,$$

so $T^{-1} \in \mathcal{L}(\mathcal{Y}, \mathcal{X})$. Then, from the estimate

$$0 = \mathcal{H}(x_*) - \mathcal{H}(x_{**}) = T(x_* - x_{**}), \quad (2.19)$$

we get $x_* = x_{**}$.

□

REMARK 2.2 (a) In view of (a2), we can write

$$\begin{aligned}\|\mathcal{H}'(x_*)^{-1}\mathcal{H}'(x) &= \|\mathcal{H}'(x_*)^{-1}[(\mathcal{H}'(x) - \mathcal{H}'(x_*)) + \mathcal{H}'(x_*)]\| \\ &\leq 1 + \|\mathcal{H}'(x_*)^{-1}(\mathcal{H}'(x) - \mathcal{H}'(x_*))\| \\ &\leq 1 + L_0\|x - x_*\|,\end{aligned}\quad (2.20)$$

so the second condition in (a3) can be dropped, and we choose $L_1 = 2$, since $\|x - x_*\| \leq s_1 < \frac{1}{L_0}$.

- (b) It follows from the definition of s_1 and r_A that $s_1 < r_A$. That is the radius of convergence s_1 cannot be larger than the radius of convergence r_A of Newton's method obtained by us [?, ?, ?, ?, ?].
- (c) The local convergence of method (??) was not studied in [?]. But if it was call; \bar{s}_1 the smallest positive solution of $\bar{p}(t) = 0$, where

$$\bar{p}(t) = (2L_0 + \bar{L})L_0t^2 - (4L_0 + 4L_0\bar{L}_1 + \bar{L})t + 2, \quad (2.21)$$

where \bar{L} and \bar{L}_1 are the constants for the conditions in (a3) holding on Ω . But, we have

$$L \leq \bar{L} \quad (2.22)$$

$$L_1 \leq \bar{L}_1 \quad (2.23)$$

and

$$\gamma \leq \bar{\gamma}, \quad (2.24)$$

since $\Omega_0 \subset \Omega$. Hence, we have

$$\bar{s}_1 \leq s_1. \quad (2.25)$$

Moreover, if strict inequality holds in (??) or (??), then, we have $\bar{s}_1 < s_1$. Furthermore, by (??), our error bounds are more precise than the ones using L_0, \bar{L}, \bar{L}_1 and $\bar{\gamma}$. Hence, we have expanded the applicability of method (??) in the local convergence case.

In a similar way, we improve the semi-local convergence analysis of method (??) given in [?]. The work is given in the next section.

3 Semi-local convergence

We need the following auxiliary result on majorizing sequences for method (??).

LEMMA 3.1 Let $K_0 > 0, K > 0$, and r_0^1 be parameters. Denote by δ the unique root in the interval $(0, 1)$ of the polynomial φ given by

$$\varphi(t) = 2K_0t^{k+1} + K(t^k + t^{k-1} - 2).$$

Define the sequence $\{q_n\}$ for each $n = 0, 1, 2, \dots$ and $i = 1, 2, \dots, k-1$ by

$$r_0^0 = 0, r_n^0 = r_n, r_{n+1}^1 = q_{n+1} + \frac{K(q_{n+1} - q_n + r_n^{k-1} - q_n)(q_{n+1} - r_n^{k-1})}{1 - 2K_0q_{n+1}} \quad (3.1)$$

and

$$r_n^k = q_{n+1}, r_n^{i+1} = r_n^i + \frac{K(r_n^i - q_n + r_n^{i-1} - q_n)(r_n^i - r_n^{i-1})}{1 - 2K_0q_n}.$$

Moreover, suppose that

$$0 < \frac{K(q_1 + r_0^{k-1})}{1 - 2K_0q_1} \leq \delta < 1 - 2K_0r_0^1. \quad (3.2)$$

Then, the sequence $\{q_n\}$ is increasing, bounded from above by $q_{**} = \frac{r_0^1}{1-\alpha}$ and converges to its unique least upper bound q_* satisfying $q_1 \leq q_* \leq q_{**}$,

$$r_n^1 - r_n^{i-1} \leq \delta(r_n^{i-1} - r_n^{i-2}) \leq \delta^{kn+i-1}r_0^1, \quad (3.3)$$

$$r_{n+1}^1 - r_n^k \leq \delta(r_n^k - r_n^{k-1}) \leq \delta^{k(n+1)}r_0^1 \quad (3.4)$$

and

$$q_n = r_n^0 \leq r_n^1 \leq r_n^2 \leq \dots \leq r_n^{k-1} \leq r_n^k = q_{n+1}. \quad (3.5)$$

Proof. Replace $t_n, s_n^i, L_0, L, \alpha$ in [?] by $q_n, r_n^i, K_0, K, \delta$.

Next, we present the semi-local convergence analysis of method (??).

THEOREM 3.2 Let $\mathcal{H} : \Omega \rightarrow \mathcal{Y}$ be a continuously differentiable operator in the sense of Fréchet and $[\cdot, \cdot; \mathcal{H}] : \Omega \rightarrow \mathcal{L}(\mathcal{X}, \mathcal{Y})$ be a divided difference of order one of \mathcal{H} . Suppose there exist $x_0 \in \Omega$ and $K_0 > 0$ such that

$$\mathcal{H}'(x_0)^{-1} \in \mathcal{L}(\mathcal{Y}, \mathcal{X}). \quad (3.6)$$

$$\|\mathcal{H}'(x_0)^{-1}\mathcal{H}(x_0)\| \leq r_0^1, \quad (3.7)$$

$$\|\mathcal{H}^{-1}(x_0)([x, y; \mathcal{H}] - \mathcal{H}'(x_0))\| \leq K_0(\|x - x_0\| + \|y - x_0\|). \quad (3.8)$$

Set $\Omega_2 = \Omega \cap B(x_0, \frac{1}{2K_0})$. Moreover, suppose that for each $x, y, z, w \in \Omega_2$

$$\|\mathcal{H}'(x_0)^{-1}([x, y; \mathcal{H}] - [z, w; \mathcal{H}])\| \leq K(\|x - z\| + \|y - w\|), \quad (3.9)$$

and the hypotheses of Lemma ?? hold. Then, $\{u_n\} \in B(v_0, q_*)$, $\lim_{n \rightarrow \infty} u_n = u_* \in \bar{B}(v_0, q_*)$, $\mathcal{H}(u_*) = 0$. and

$$\|u_* - u_n\| \leq q_* - v_n. \quad (3.10)$$

Moreover, u_* is the unique solution of equation $\mathcal{H}(x) = 0$ in $\bar{B}(v_0, q_*)$.

Proof. Replace $x_n, y_n, s_n^i, t_n, \alpha, L_0, L$ in [?] by $u_n, v_n, r_n^i, q_n, \delta, K_0, K$. □

REMARK 3.3 The condition

$$\|\mathcal{H}'(x_0)^{-1}([x, y; \mathcal{H}] - [z, w; \mathcal{H}])\| \leq L(\|x - z\| + \|y - w\|) \quad (3.11)$$

for each $x, y, z, w \in \Omega$, some $L > 0$ is used in [?] instead of (??). But we have

$$K_0 = L_0 \quad (3.12)$$

$$K \leq L, \quad (3.13)$$

and

$$\delta \leq \alpha, \quad (3.14)$$

since $\Omega_2 \subseteq \Omega$. Denote by \bar{q}_n, \bar{r}_n^i the majorizing sequences used in [?] and defined as sequences q_n, r_n^i but with $K_0 = L_0$ and K replaced by L . Then, we have by a simple induction argument, that

$$q_n \leq \bar{q}_n \quad (3.15)$$

$$r_n^i \leq \bar{r}_n^i \quad (3.16)$$

$$0 \leq r_n^i - q_n \leq \bar{r}_n^i - \bar{q}_n \quad (3.17)$$

$$0 \leq r_n^i - r_n^{i-1} \leq \bar{r}_n^i - \bar{r}_n^{i-1} \quad (3.18)$$

$$0 \leq q_{n+1} - r_n^{k-1} \leq \bar{q}_n - \bar{r}_n^{k-1} \quad (3.19)$$

and

$$q_* \leq \bar{q}_*. \quad (3.20)$$

Moreover, if $K < L$, then (??-??) hold as strict inequalities. Let us consider the set $\Omega_3 = \Omega \cap B(x_1, \frac{1}{2K} - r_0^1)$ provided that $r_0^1 < \frac{1}{2K}$. Moreover, suppose for each $x, y, z, w \in \Omega_3$

$$\|\mathcal{H}^{-1}(x_0)([x, y; H] - [z, w; H])\| \leq \lambda(\|x - z\| + \|y - w\|). \quad (3.21)$$

Notice that $\Omega_3 \subseteq \Omega_2$, so $\lambda \leq K$. Then, Ω_3 , (??), λ can replace Ω_2 , (??), and K respectively in Theorem ???. Clearly, the corresponding to $\{t_n\}$ majorizing sequence call it $\{\bar{t}_n\}$ is even tighter than $\{t_n\}$. Hence, we have extended the applicability of method (??) in the semi-local convergence analysis too. These improvements are derived under the same conditions as in [?], since the computation of L is included in the computation of K as a special case. Examples where the new constants are smaller than the older ones can be found in the numerical section that follows and in [?, ?, ?, ?, ?].

4 Numerical examples

We present the following examples to test the convergence criteria. Define the divided difference by

$$[x, y; \mathcal{H}] = \int_0^1 \mathcal{H}'(\tau x + (1 - \tau)y) d\tau.$$

EXAMPLE 4.1 Let $\mathcal{X} = \mathcal{Y} = \mathbb{R}^3$, $\Omega = U(0, 1)$, $x^* = (0, 0, 0)^T$ and define \mathcal{H} on Ω by

$$\mathcal{H}(x) = \mathcal{H}(x_1, x_2, x_3) = (e^{x_1} - 1, \frac{e-1}{2}x_2^2 + x_2, x_3)^T. \quad (4.1)$$

For the points $u = (u_1, u_2, u_3)^T$, the Fréchet derivative is given by

$$\mathcal{H}'(u) = \begin{pmatrix} e^{u_1} & 0 & 0 \\ 0 & (e-1)u_2 + 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

Using the norm of the maximum of the rows and (a_3) - (a_4) and since $\mathcal{H}'(x^*) = \text{diag}(1, 1, 1)$, we can define parameters for method (??) by $L_0 = e - 1$, $L_1 = L = e^{\frac{1}{e-1}}$, $\bar{L} = \bar{L}_1 = e$. Then, $s_1 = 0.0997$ The old radius is $\bar{s}_1 = 0.0727$.

EXAMPLE 4.2 Let $\mathcal{X} = \mathcal{Y} = \mathbb{R}$, $\Omega = \bar{U}(x_0, 1 - \xi)$, $x_0 = 1$ and $\xi \in [0, \frac{1}{2}]$. Define function \mathcal{H} on Ω by

$$\mathcal{H}(x) = x^3 - \xi.$$

Then, we get by (??)-(??) and (??) that for

(i) $k = 1$, $q_1 = r_0^1 = \frac{1}{3}(1 - \xi)$, $L_0 = K_0 = \frac{1}{2}(3 - \xi)$, $L = 2 - \xi$, and $K = 1 + \frac{1}{2K_0}$. Notice that $L_0 < K < L$. The conditions of Lemma ?? are satisfied for $\xi \in I_1 = [0.434523, 0.5)$ but the earlier conditions in [?] are satisfied for $\xi \in I_2 = [0.464523, 0.5)$, and $I_2 \subset I_1$. Moreover, if $\lambda = \frac{1}{3(3-\xi)}(-2\xi^2 + 5\xi + 6)$ then conditions of Lemma ?? are satisfied for $\xi \in I_3 = [0.3720452, 0.5)$.

(ii) For $k = 2$, the conditions of Lemma ?? are satisfied for $\xi \in I_1 = [0.6161045, 0.7)$ but the earlier conditions in [?] are satisfied for $\xi \in I_2 = [0.6266523, 0.7)$, and $I_2 \subset I_1$. Moreover, if $\lambda = \frac{1}{3(3-\xi)}(-2\xi^2 + 5\xi + 6)$ then conditions of Lemma ?? are satisfied for $\xi \in I_3 = [0.5966523, 0.7)$.

5 Conclusion

Our idea of the convergence region in connection to the center Lipschitz condition were utilized to provide a local as well as a semilocal convergence analysis of method (??). Due to the fact that we locate a region at least as small as in earlier works [?] containing the iterates, the new Lipschitz parameters are also at least as small. This technique leads to a finer convergence analysis (see also Remark ??, Remark ?? and the numerical examples). The novelty of the paper not only lies in the introduction of the new idea but also obtained using special cases of Lipschitz parameters appearing in [?]. Hence, no additional work to [?] is needed to arrive at these developments. This idea can be used to extend the applicability of other iterative methods appearing [?, ?] along the same lines.

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