

Article

Holography Using Curved Metasurfaces

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Abstract: In this work we demonstrate non-flat metasurface holograms with applications in imaging, sensing, and anti-counterfeiting. In these holograms the image and its symmetry properties, with respect to the polarization of the light, depend on the specific shape of the substrate. Additionally, the sensitivity of the holographic image to the substrate shape can be engineered by distributing the phase information into determined areas of the metasurface.

Keywords: Metasurfaces; holography; curved; metamaterials; non flat optics; tunable; reconfigurable

1. Introduction

Photonic metasurface (MS) are one of the most successful platforms to realize computer-generated holograms. These devices utilize sub-wavelength pixels to create holographic images with high efficiency [1–5]. Holographic MS enable the multiplexing of information in various degrees of freedom, including for example wavelength [6,7], angle [8], polarization [9–13], and image dimensionality [14]. Applications of MSs include the manipulation and storage of information [15,16], security [10], and displays [17].

MSs offer the possibility to modulate the amplitude and phase of light with high resolution and negligible thickness. These properties make MSs easily exploitable in flexible designs. Examples of these applications include cloaking, lab-on-fiber, optically active, and filtering devices [18–23].

Flexibility has been previously exploited for MS holograms in devices controlled by the degree of substrate stretching, e.g. to vary the focus of a MS lens [24], or to alternate between multiple near-field images [25]. A theoretical exploration of flexible MS holograms has also enabled carpet cloaking, and spherical aberration correction for lensing applications [26]. Flexible MSs have also been used to decouple the shape of a lens from its optical function [27].

Traditional flat MS holograms produce identical holographic images when illuminated by left- (LCP) and right-handed circularly polarized light (RCP) but with the holographic image rotated 180 degrees around the zeroth order of the beam [10]. In this work we demonstrate that for non-flat MSs both the shape of the substrate and the polarization of the incident light contribute to determine the symmetry properties of the image. Here we also describe how the sensitivity to the MSs shape can be tailored to provide versatility for practical applications including in anti-counterfeiting and surface topology sensing.

2. Rayleigh-Sommerfeld light propagation

We designed our holograms using the Gerchberg-Saxton iterative phase reconstruction algorithm. To describe the general case of propagation between the non-flat MS and the image planes we adopted the full Rayleigh-Sommerfeld propagation method [28], as given by

$$U(x_I, y_I, z_I) = - \iint U(x_O, y_O, z_O) \frac{2(z_I - z_O)}{|\mathbf{r}_I - \mathbf{r}_O|} \times \left(ik - \frac{1}{|\mathbf{r}_I - \mathbf{r}_O|}\right) \times \frac{\exp(ik|\mathbf{r}_I - \mathbf{r}_O|)}{4\pi|\mathbf{r}_I - \mathbf{r}_O|} dx_O dy_O. \quad (1)$$

33 where the cartesian coordinates (x_j, y_j, z_j) relate to the position vectors \mathbf{r}_j , U is the complex light
 34 field, k is the wavevector of light, and the holographic MS object and imaging planes are denoted
 35 with the subscripts $j = O, I$ respectively. Here the coordinate system is aligned to the center of the
 36 undistorted MS. An illustration of this method can be seen in figure 1.

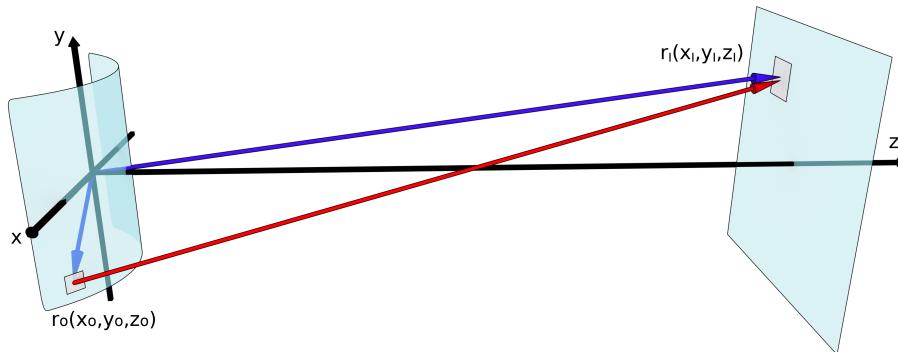


Figure 1. Light propagation from $\mathbf{r}_O(x_O, y_O, z_O)$ to $\mathbf{r}_I(x_I, y_I, z_I)$ using the Rayleigh-Sommerfeld equation. The holographic image originates from the MS and is projected onto the screen.

37 For flat MS, inverting the handedness of the polarization, for example from RCP to LCP, typically
 38 creates a holographic image rotated by 180 degrees around the zeroth order of the holographic image
 39 [10]. This occurs because each Pancharatnam-Berry element provides the same de-phasing, but with
 40 an opposite sign between the two polarizations $\phi_0(x_O, y_O, z_O) \rightarrow -\phi_0(x_O, y_O, z_O)$ [1,29]. With more
 41 complex meta-atoms a similar effect can be used to encode entirely different holographic images
 42 [30,31].

43 The rotation of the holographic image around the zeroth order can be described through the
 44 equation

$$I'(x_I, y_I) = I(-x_I, -y_I) \quad (2)$$

45 where I' and I are the intensity distributions in the holographic image plane for the rotated and
 46 non rotated holographic images respectively. x_I and y_I refer to the position in the holographic image
 47 plane in the x and y directions respectively, and the z coordinate is constant.

48 For the non-flat MS case, equation 2 only holds true when both the phase contribution from
 49 the polarization $\phi_0(x_O, y_O, z_O) \rightarrow -\phi_0(x_O, y_O, z_O)$, and the phase contribution from the MS shape
 50 $\phi_c(x_O, y_O, z_O) \rightarrow -\phi_c(x_O, y_O, z_O)$ are both inverted [32].

51 As such, equation 2 for the non-flat MS case is true when

$$\phi_c(x_O, y_O, z_O) + \phi_0(x_O, y_O, z_O) \rightarrow -\phi_c(x_O, y_O, z_O) - \phi_0(x_O, y_O, z_O) \quad (3)$$

52 Conversely, for a flat MS the phase contribution $\phi_c(x_O, y_O, z_O)$ is necessarily 0 and changing the
 53 handedness of the polarization leads to the rotation of the holographic image by 180 degrees.

54 Results and discussion

55 When we design non-flat MS holograms using the Gerchberg-Saxton algorithm, the recovered
 56 phase holograms are specific to the surface profile. Changing the MS shape will then result in
 57 a distorted holographic image. Our chosen holographic MS design uses as Pancharatnam-Berry
 58 de-phasing elements a regular array of gold nanorods, sitting on a polymeric spacing layer deposited
 59 on a reflective gold backplane [32,33]. Each unit cell, comprising a nanorod separated by the thin

60 dielectric layer from the gold backplane, can be approximated as an isotropically emitting Huygen's
 61 source. This three-layer structure is realized on a free-standing and flexible 2 μm thick polymeric
 62 membrane. To define the nanorods on the top surface we used a standard electron beam lithography
 63 procedure [33] followed by dry back etching of the unmasked superficial gold layer. The quality of the
 64 MS after lift-off is illustrated in figure 2(a) with an SEM image. Figure 2(b) shows a typical flexible
 65 holographic MS applied to a non-flat surface.

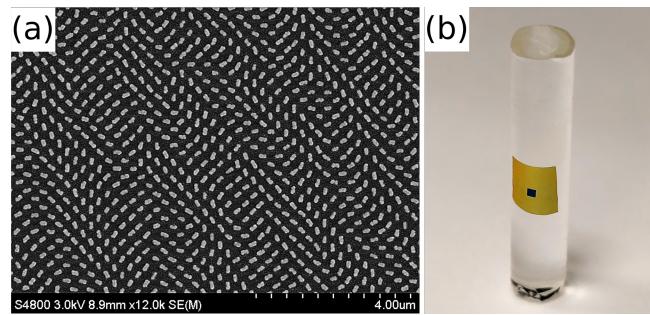


Figure 2. (a) The nanorods comprising the MS and imaged with an SEM after the membrane was lifted from the rigid initial substrate. (b) An experimental image displaying a MS conformed to a non-flat surface. The MS itself can be seen as the green square central on the gold membrane.

66 As described through equations 1-2, to obtain a correctly rotated holographic image it is necessary
 67 to change the symmetry of the substrate with respect to the xy plane (e.g. change z into $-z$), as well as
 68 the handedness of the polarization. The experimental demonstration of this statement is displayed in
 69 figure 3.

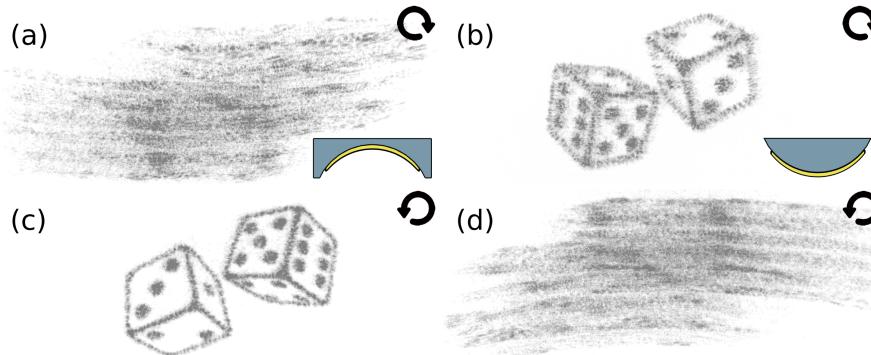


Figure 3. Experimental holographic images where (a,b) and (c,d) were illuminated with right handed, and left handed circular polarizations respectively. (a,c) used a concave substrate with a radius of curvature of 6 mm, (b,d) used a convex substrate with the same radius of curvature. The LCP images are rotated 180 degrees in the holographic image plane compared to the RCP images.

70 To evaluate the specificity of the holographic image to a particular substrate shape we designed
 71 and fabricated holographic MS for a flat surface, and convex cylinders with radii of curvature of 6 mm
 72 and 4 mm. We then compared the images obtained by these three MSs when applied to a cylinder
 73 with a radius of curvature of 6 mm. As can be seen in figure 4 the agreement between simulation
 74 and experiment is good. The greater the disparity between the surface shape that the MS hologram
 75 was designed for and the actual MS shape, the greater the distortion of the holographic image. A
 76 quantitative analysis of the distortion of the images was completed by evaluating the correlation
 77 coefficient of the simulated holographic images compared to the ideal target image. Here a correlation
 78 coefficient of 1 means that the two images are identical, and a coefficient close to 0 means no correlation.
 79 Even in simulation we do not expect a correlation coefficient of 1 because the number of iterations we
 80 perform during the phase retrieval is finite, and because we are encoding only the phase and not the
 81 amplitude information into the MS. Our analysis, as seen in the numbers in figure 4, demonstrates that

82 the correlation coefficient for holographic images where the MS has the correct surface shape is close
 83 to 1, but that the correlation coefficient drops to below half of this value when the MS has the incorrect
 84 shape [32].

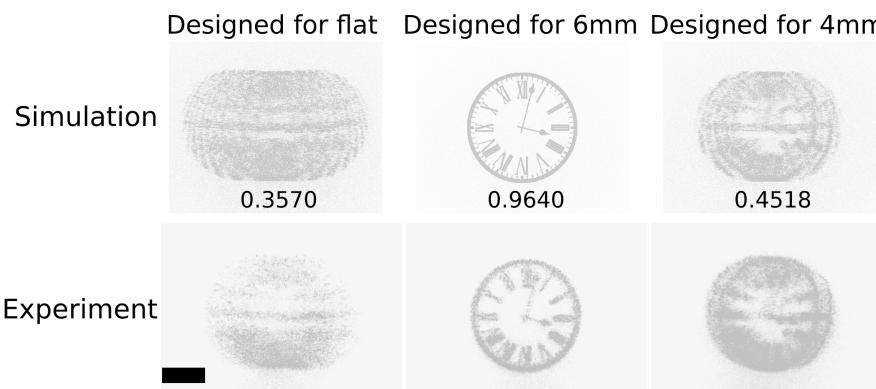


Figure 4. Simulated and experimental holographic image results, comparing MS designed for various convex cylinders with differing radii of curvature. In each case the MS was analyzed as being applied to a convex cylinder with a radius of curvature of 6 mm. For the experimental results the scale bar represents 10 mm. The numbers correspond to the correlation coefficient where 1 is perfect correlation.

85 The sensitivity of the MS holograms to the surface shape can also be increased by carefully
 86 distributing the holographic phase information in the MS. For the specific example of cylindrical
 87 substrates with different radii of curvature, the gradient and position of the phase elements in the
 88 central region along the long axis of the cylinder are changed the least. As shown in detail in ref. [32],
 89 MSs with no phase information encoded in the central region maintained the peak holographic image
 90 quality, while increasing their sensitivity to the MS shape.

91 2. Materials and Methods

92 To fabricate our samples we first spin coat a polymeric sacrificial layer onto a silicon substrate.
 93 Next we spin a 2 μ m thick polymer (SU-8, Microchem) on top, which acts as flexible substrate. Next
 94 we deposit a 100 nm thick layer of gold to act as a backplane mirror. Next we spin on another layer
 95 of SU-8 with a thickness of 90 nm and crosslink it with a flood UV exposure. Next we deposit an
 96 additional 40 nm of gold for the nanorods. Next we spin on another layer of SU-8 with a thickness of
 97 90 nm as an electron beam resist. Next we pattern the nanorod using a top-down standard electron
 98 beam lithography approach. Next we use a reactive ion etch to remove unmasked gold. Lastly we
 99 remove the sacrificial layer to leave a free-floating membrane.

100 3. Conclusions

101 We demonstrate a holographic MS where the holographic image has a strong dependence on
 102 the MS shape. Next, we describe the additional symmetry condition that MS Pancharatnam-Berry
 103 holograms exhibit compared to their flat counterparts. We also show how the holographic information
 104 in the MS can be encoded to tailor the sensitivity of the resulting holographic image to the MS shape.
 105 This work could be applied in fields ranging from sensors to anti-counterfeiting devices and lenses.

106 4. Patents

107 Holographic device patent application. UK patent application number GB1719588.4.

108 **Author Contributions:** J.B. designed, fabricated and characterized the MSs. Both authors wrote the manuscript.
 109 ADF directed the project.

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