

1 Article

2 Multifunctional Dynamic Voltage Restorer for Power 3 Quality Improvement

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10

11 **Abstract:** Power quality is a major concern in electrical power systems. The power quality
12 disturbances such as sags, swells, harmonic distortion and other interruptions have impact on the
13 electrical devices and machines and in severe cases can cause serious damages. Therefore it is
14 required to recognize and compensate all types of disturbances at an earliest to ensure normal and
15 efficient operation of the power system. To solve these problems, many types of power devices are
16 used. At the present time, one of those devices, Dynamic Voltage Restorer (DVR) is the most
17 efficient and effective device used in power distribution system. In this paper, design and modeling
18 of a new structure of multifunctional DVR for voltage correction is presented. The performance of
19 the device under different conditions such as voltage swell, voltage sag due to symmetrical and
20 unsymmetrical short circuit, starting of motors, and voltage distortion are described. Simulation
21 result shows the superior capability of proposed DVR to improve power quality under different
22 operating conditions. The proposed new DVR controller is able to detect the voltage disturbances
23 and control the converter to inject appropriate voltages independently for each phase and
24 compensate to load voltage through three single- phase transformers.

25 **Keywords:** compensation techniques; dynamic voltage restore; harmonic distortion; power quality;
26 short circuit; voltage sag; voltage swell

27

28 1. Introduction

29 With the increasing amount of sensitive devices (power electronic devices) that are quite
30 sensitive to power quality disturbances in the supply network, the problem of compensation of
31 power quality disturbances is ever increasing. Power quality disturbances are categorized into
32 voltage sags, voltage swells, transients, harmonics, interruptions. It can cause many technical
33 problems (such as extra heating, mis-operation, early aging of the devices etc.) and financial losses to
34 the power system operators and the customers. There are different ways for improvement of power
35 quality such as Distribution STATic synchronous COMPensator (DSTATCOM), Dynamic Voltage
36 Restorer (DVR), Active Filter (AF), Unified Power Quality Conditioner (UPQC), etc. Among these,
37 the DVR is one of the most effective and cost-efficient devices, which can used in power distribution
38 system.

39 Using DVR in the distribution system for power quality improvement has been analyzed and
40 proposed through many publications [1]-[18]. However, these research consider the solution for
41 each case, for example for mitigating voltage sags due to starting motors [9], or short circuits [4], [5],
42 [6], [13], mitigating balanced voltage sags and swells [6], compensating fluctuations and distortions
43 of voltage [2]. In this paper, the DVR is used for power quality improvement of any type
44 (multifunctional DVR), providing the solution for all cases above. The detailed configuration of DVR
45 is described in Section 3, and the multi-loop controller using PI (Proportional- Integral) controller

46 developed on the rotating coordinate system is presented in Section 4. A multifunctional DVR is
47 modeled using MATLAB-Simulink and tested for voltage swell, voltage sag due to starting motor,
48 symmetrical and unsymmetrical short-circuit and voltage distortions. Simulation results show the
49 capability of the DVR to control the fault and disturbance conditions of the distribution system.

50 **2. Most Common Power Quality Problems**

51 Although the problems described in this section are well known, for the sake of completeness,
52 we review shortly here the fundamentals of power quality problems. Power quality can be defined
53 as the ability of the power system to provide their customers with an uninterrupted flow of energy at
54 ideal sinusoidal waveform. Various power quality problems can be categorized as voltage sags,
55 swells, harmonics, transients, interruption considered are the most common power quality problems
56 in electrical distribution systems. Common Power quality problems are described briefly below,
57 following [2], [14], [15].

58 Voltage sag or a dip is short duration reduction of amplitude, it occurs when the RMS of voltage
59 decreases between 10 to 90 percent of nominal voltage for one-half cycle to one minute. It is one of
60 most frequent disturbance in the distribution system. It is caused by faults in the power system,
61 transformer energizing or by the starting of a large induction motors, among other causes..

62 Voltage swell is the opposite to voltage sag, it happens when the RMS of voltage increases
63 between 10 to 80 percent of nominal voltage for one-half cycle to one minute. It is not as common as
64 voltage sag. The main causes for voltage swells are switching of large capacitors or start/stop of
65 heavy loads, among other causes.

66 Interruption is defined as a reduction in voltage or current to less than 10 percent of nominal,
67 not exceeding 60 seconds in length. Sustained interruption happen when the supply voltage or
68 current falls to zero for more than 1 minute. These are the result of faults, equipment failure, control
69 malfunction or improper breaker tripping.

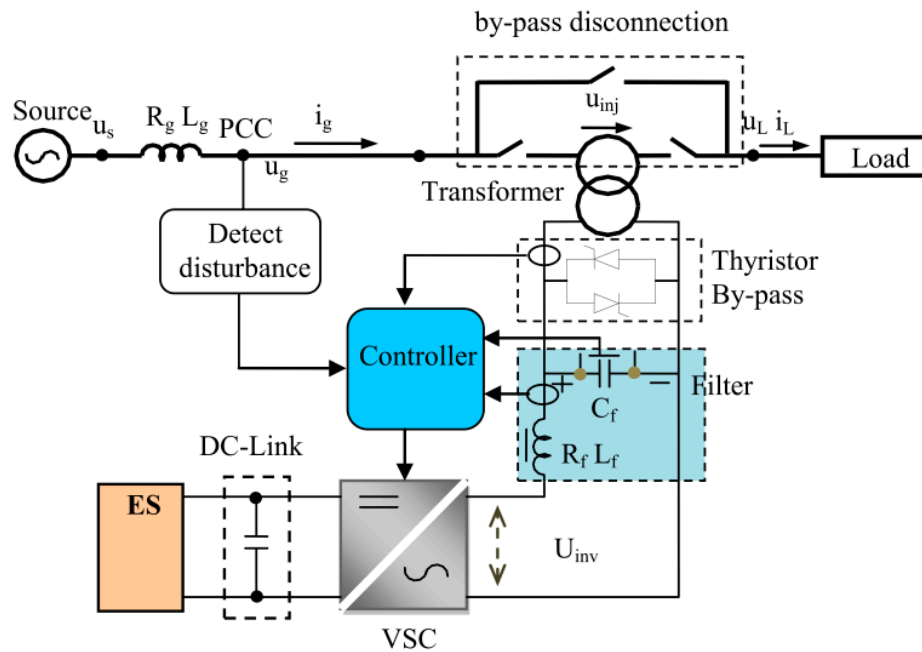
70 Harmonics are the waves with frequencies that are the integral multiple of the frequency of
71 reference wave (at which supply system is designed to operate).

72 Transient is defined as a short duration surge of electrical energy in power system caused by a
73 sudden change of state. There are two types of transients: impulse and oscillatory. The main causes
74 for harmonic distortion are rectifiers and, in general, all non-linear loads.

75 **3. Multifunctional Dynamic Voltage Restorer**

76 *3.1. Configuration and components*

77 The DVR is a power-electronic-converter-based device capable of protecting sensitive loads
78 from most supply-side disturbances [11]. A DVR is installed in a distribution system between the
79 supply and a sensitive load feeder at the so-called point of common coupling (PCC). Its primary
80 function is to rapidly inject/absorb additional energy in the system in order to avoid any power
81 disruption to that load event of disturbances in the system. The general structure of a DVR consists
82 of a booster transformer, a harmonic filter, a voltage source converter (VSC), and an energy storage
83 (Fig. 1).



84

85 **Figure 1.** Configuration of DVR in the Power Distribution System.

86 3.1.1. Injection/booster Transformer

87 The injected voltage is supplied into the distribution system through an injection transformer. It
 88 connects the DVR to the distribution system via HV- winding and transforms the injected
 89 compensating voltage generated by the Voltage Source Converter (VSC) to the supply voltage after
 90 the detection of any disturbance by the controller. In addition, the injection transformer serves the
 91 purpose of isolating the DVR circuit from the system. For compensating unbalanced voltage sags,
 92 three single-phase transformers can be used, however, this increases the size and cost of the DVR. To
 93 select a suitable injection transformer into the DVR, the MVA rating, the primary winding voltage
 94 and current ratings, the turn-ratio and the short-circuit impedance values of transformers are
 95 required.

96 3.1.2. Harmonic Filter

97 The main task of the harmonic filter is to keep the harmonic voltage content generated by the
 98 VSC at the permissible level. The filter is placed to damp the switching harmonics generated by the
 99 PWM control of VSC.

100 3.1.3. DC-link and Energy Storage Unit

101 The main function of these energy storage units is to provide the desired real power during the
 102 voltage sag. Two types of systems are considered; the first where energy is taken from the incoming
 103 supply through a shunt converter, and the second where energy storage devices such as flywheels,
 104 batteries, superconducting magnetic energy storage (SMES) and super capacitors are used [3]. The
 105 energy storage devices have the advantage of fast response.

106 3.1.4. The Voltage Source converter

107 A VSC is a power electronic system that consists of a storage device and switching devices,
 108 which converts the dc voltage from the energy storage unit to a controllable three phase ac voltage.
 109 The inverter switches are normally fired using a sinusoidal Pulse Width Modulation (PWM) scheme.
 110 In multifunctional DVR, the VSC can be operated with unbalanced switching functions for three
 111 phases, and deal with each phase independently. Normally the VSC is not only used for voltage
 112 sag/swell compensation, but also for other power quality issues, e.g. flicker and harmonics [3].

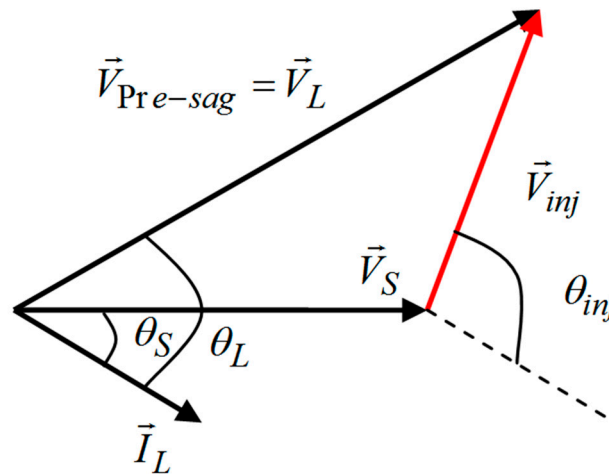
113 3.2. Compensation Techniques

114 For the proposed DVR, the pre-sag compensation method is chosen because it is the best
115 compensation strategy to restore controlled pre-sag magnitude without phase change. The
116 magnitude and the angle of the injected voltage are

$$117 \quad |V_{inj}| = \sqrt{V_L^2 + V_S^2 - 2V_L V_S \cos(\theta_L - \theta_S)} \quad (1)$$

$$118 \quad \theta_{inj} = \tan^{-1} \left(\frac{V_L \sin \theta_L - V_S \sin \theta_S}{V_L \cos \theta_L - V_S \cos \theta_S} \right) \quad (2)$$

119 However, the disadvantage of this method is that the injected active power is not controlled so
120 high capacity energy storage is required.



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122 **Figure 2.** Phasor diagram of the pre-sag compensation technique.

123 3.3. Operation Modes of DVR

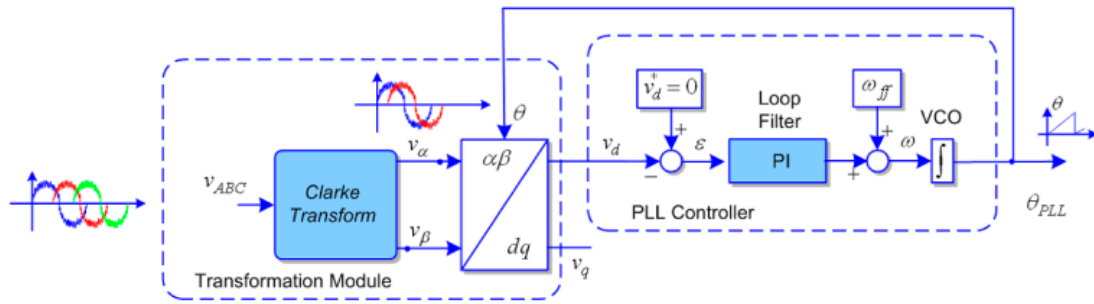
124 The DVR has three modes of operation: protection mode, standby mode (during steady state),
125 and injection/boost mode (during sag/swell). In Protection mode, the DVR is protected from the over
126 current on the load side due to short-circuit on the load or large inrush current. The DVR can be
127 isolated from the system by using the by-pass switches as shown in Figure 1. In standby mode, no
128 switching of semiconductors occurs and the load current will pass through the transformer primary
129 winding. In boost (Injection) mode, when the voltage disturbance occurs in the supply is detected,
130 the DVR will be injected a compensation voltage through the voltage injection transformer.

131 4. Control Techniques of DVR

132 In general, the process control of DVR includes 3 steps: 1. Detection of voltage sag/swell
133 occurrence in the system, 2. Comparison with the reference value and 3. Generation of gate pulses to
134 the voltage source inverter (VSI) to generate the DVR output voltages which compensates/absorbs
135 the voltage sag/swell.

136 4.1. Grid Synchronization Techniques

137 Synchronization to the supply voltages is very important in order to control the DVR. It keeps
138 an output signal synchronized with a reference input signal in frequency and phase.
139 Synchronization methods have been developed and presented in many publications [16]-[18]. The
140 most often used synchronization method in engineering applications, the phase-locked loop (PLL)
141 has been used in this paper.



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Figure 3. Phase locked loop to synchronize the DVR to the supply voltages.

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Figure 3 shows the block diagram of three phase PLL. The voltages measured at PCC bus (V_{abc}) is transformed from three phase frame to $\alpha\beta$ frame using Clarke's transform.

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$$\begin{bmatrix} V_\alpha \\ V_\beta \end{bmatrix} = \sqrt{\frac{2}{3}} \begin{bmatrix} 1 & -\frac{1}{2} & -\frac{1}{2} \\ 0 & \frac{\sqrt{3}}{2} & -\frac{\sqrt{3}}{2} \end{bmatrix} \begin{bmatrix} V_a \\ V_b \\ V_c \end{bmatrix} \quad (3)$$

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and transformed from $\alpha\beta$ frame to synchronously rotating dq frame using Park's transform

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$$\begin{bmatrix} V_d \\ V_q \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} V_\alpha \\ V_\beta \end{bmatrix} \quad (4)$$

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The Loop Filter is a low-pass filter, it is used to suppress high frequency components. The Loop Filter provides controlled signal to voltage controlled oscillator (VCO) which work as an integrator.

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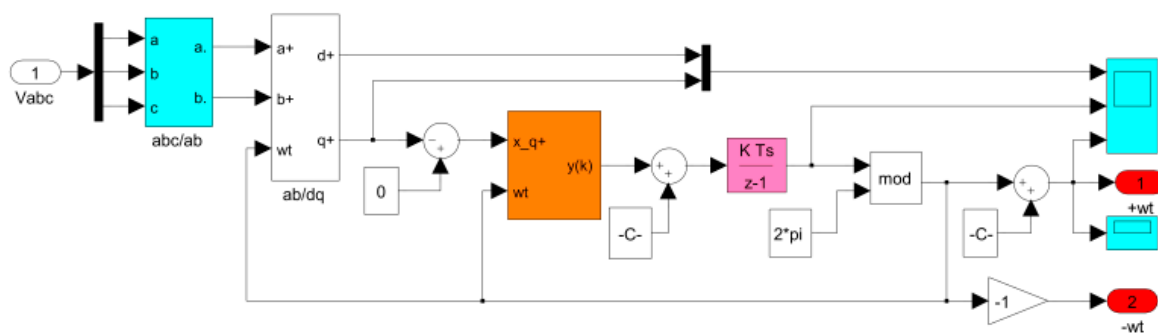
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Typically, this block is constituted of a first-order low-pass filter or a PI controller [16]. The output of the PI controller is the inverter output frequency that is integrated to obtain inverter phase angle θ . The PI regulator of the LF will set the angular position of the dq reference frame to make $V_d=0$ in the steady state, which means that the PLL will be active when the difference between grid phase angle and inverter phase angle is reduced to zero. The model of PLL in MATLAB-Simulink environment is present in Fig.4.



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Figure 4. The MATLAB-Simulink model of PLL.

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4.2. Sag/swell Detection Techniques

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The voltage sag/swell phenomena are necessary to detect the starting point, the end point, sag depth and phase shift. There are many different methods for detecting voltage sag, swell, such as peak value, root mean square (RMS), Fourier transform, Wavelet transforms and Space Vector method. In the number of methods, Space Vector control is the most effective method which is used widely in DVR applications. In this method, the three phase voltages V_{abc} are transformed into a two-dimensional voltage V_{dq} which in turn can be transferred into magnitude and angle. The

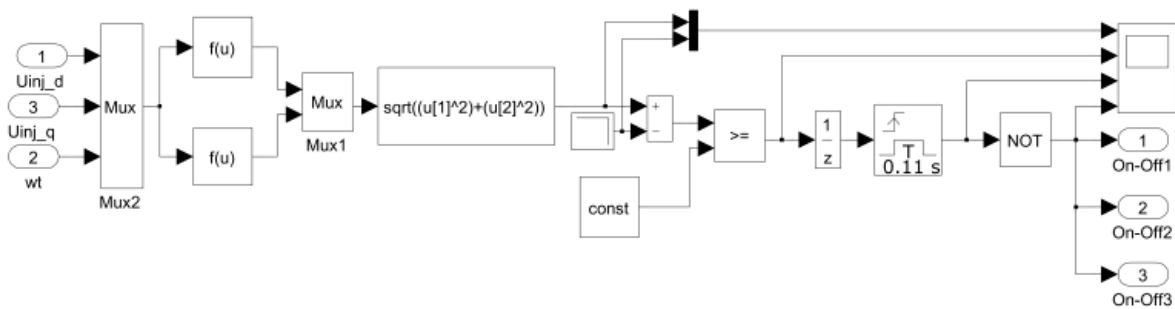
166 information of voltage magnitude and angle shift is compared with the reference value in the dq
 167 frame, which had to be transformed back to the three-phase frame.

$$169 \quad |V_{err,dq}| = \sqrt{(V_{ref,d} - V_{PCC,d})^2 + (V_{ref,q} - V_{PCC,q})^2} \quad (5)$$

$$170 \quad |V_{err,dq}| > V_{threshold} \quad (6)$$

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172 If the voltage dip contains a phase jump, it will lead to a reduction in both the d- and
 173 q-component. Details of this case are described in [17]. Figure 5 shows the voltage sag/swell detector
 174 model of DVR in MATLAB-Simulink environment. The proposed method can detect the change in
 175 the state of the supply (the start, end points, and phase jump) with low time delay.
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178 **Figure 5.** The MATLAB-Simulink model of the Detector.

179 4.3. Control Techniques

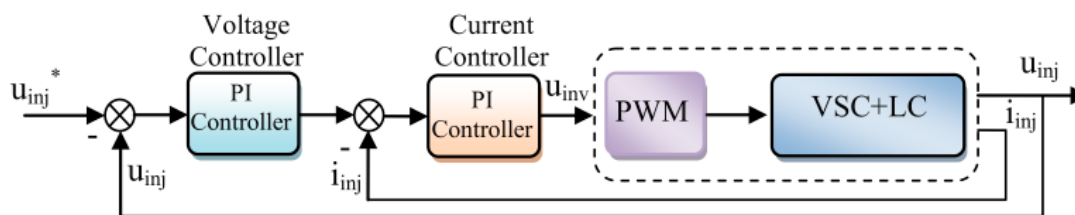
180 The control system is very important in DVR, with the requirements of fast response for of
 181 voltage sags and variations in the supplied load. The main purpose of the control system is to
 182 maintain the voltage magnitude of the sensitive load, where DVR is used, under system
 183 disturbances. There are three main voltage controllers used, the Feed-forward (open loop), Feedback
 184 (closed loop) and Multi-loop controller, and another controllers based on “artificial intelligence”,
 185 such as Artificial Neural Networks (ANN), Fuzzy Logic (FL) and Space Vector Pulse Width
 186 Modulation (SVPWM) for special conditions. The Feed-forward voltage controller is the primary
 187 option for the DVR, because of its simplicity and fast response. The disadvantage of the open loop
 188 controller is the high steady state error. The Feedback controller has the advantage of accurate
 189 response, but it is complex and causes time-delays. Multi-loop control is used with an outer voltage
 190 loop to control the DVR voltage and inner loop to control the load current. This method has the
 191 strengths of feed-forward and feedback control strategies, it can improve the system dynamic
 192 response rate, shortening the time of compensation significantly [1]-[3].

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194 The injected voltage that is needed to compensate by DVR is

$$195 \quad u_{inj}^* = u_L^* - u_g \quad (7)$$

196 The structure of the multi-loop controller is shown in Figure 6. In this method, the three-phase
 197 voltages of the grid are sensed and transformed to two-phase system (ab) in the stationary reference
 198 frame and in the rotating reference frame (dq). Then, the positive sequence and the negative
 199 sequence components are extracted. Positive sequence grid voltage vector is compared against the
 200 positive sequence load voltage command vector. The difference between them becomes the desired
 201 injected positive sequence voltage vector across the filter capacitor. The process of the negative
 202 sequence controller is similar.



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Figure 6. Block diagram of the multi-loop controller.

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5. Simulation

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5.1. Modeling and simulation

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The proposed multifunctional DVR is implemented in MATLAB-Simulink for mitigating of balanced, unbalanced voltage sag/swell, fluctuations and distortions voltage. The simulations are based on the real power system as shown in Figure 7 and the details of the system parameters are given below

Source:

115kV, 50Hz, $S_{sc}= 250\text{MVA}$.

Transmission line:

$R= 1.309 \Omega$, $L= 9.24 \text{ mH}$.

Transformers:

T1: 25MVA, 110/6.3kV, Y/D1, $U_k= 11.5\%$

T2: 2800kVA, 6.3/0.63kV, D/Yn11, $U_k=5.8\%$.

Load: 16.87MW, 11.24MVA_r

Sensitive load:

1975 kW motor, 0.63 kV, rated speed 1000 rpm.

The DVR is designed to protect the sensitive loads at voltage level 6.3 kV and its parameters are below:

Energy storage:

Power rating: 1400kVA, $V_{DC}= 700\text{V}$

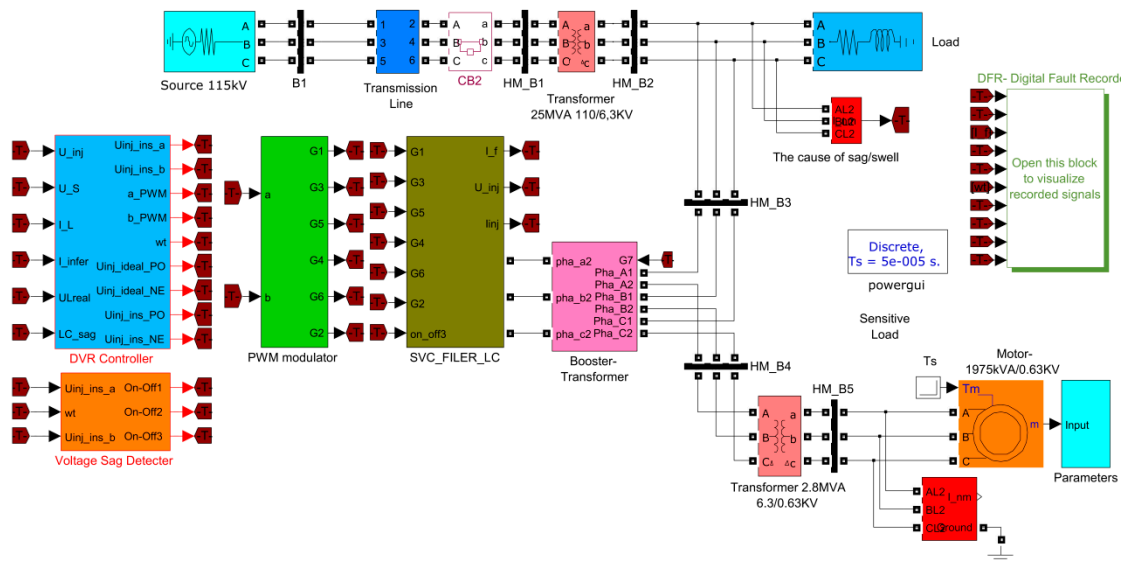
Injection transformer: 3 single-phase transformers, 1500kVA, 0.63/6.3kV, $U_k=5\%$.

Filter:

$L_f= 7,109 \text{ mH}$, $C_f= 6,942 \mu\text{C}$.

Switches: IGBT

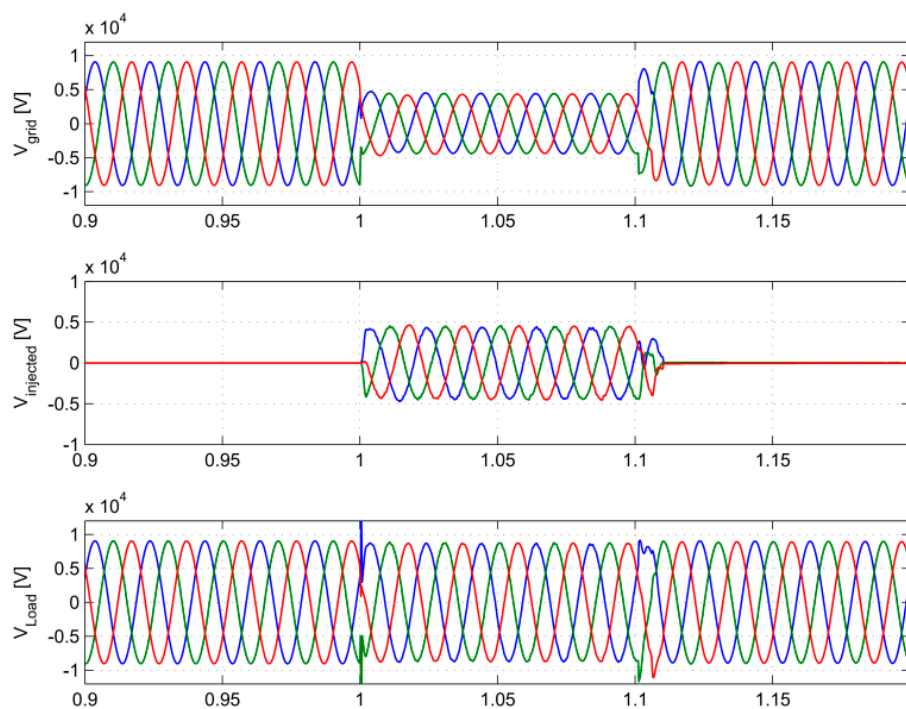
Switching frequency: 5 kHz.



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246 **Figure 7.** The MATLAB-Simulink model of test system.247 *5.2. Results and Discussion*248 *5.2.2. Case 1: Three phase balanced voltage sag.*

249 The balanced voltage sag at PCC due to three phase short circuit happens in the power system,
 250 the voltage decreased to 50% from 1.00s to 1.10s. Figure 8 shows the simulated waveforms for the
 251 grid voltages, the injection voltages of DVR and the load voltages during the sag event. Before the
 252 sag, the DVR is in the standby state waiting for the sag detection. It can be observed that the DVR
 253 compensates the balanced sag rapidly when the grid-side voltage sag happens. By this simulation,
 254 the perfect performance of the grid synchronization algorithm and the control strategy is shown.



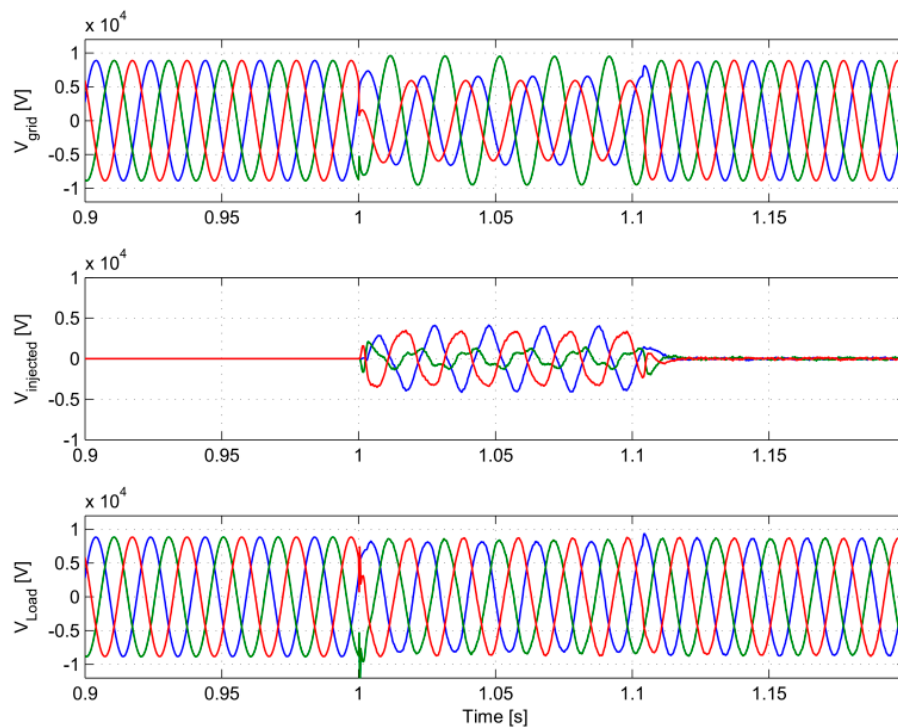
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257 **Figure 8.** Case 1- Balanced voltage sag: grid voltage, injected voltage of the DVR and load voltage.

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259 5.2.3. Case 2: The unbalanced voltage sag.



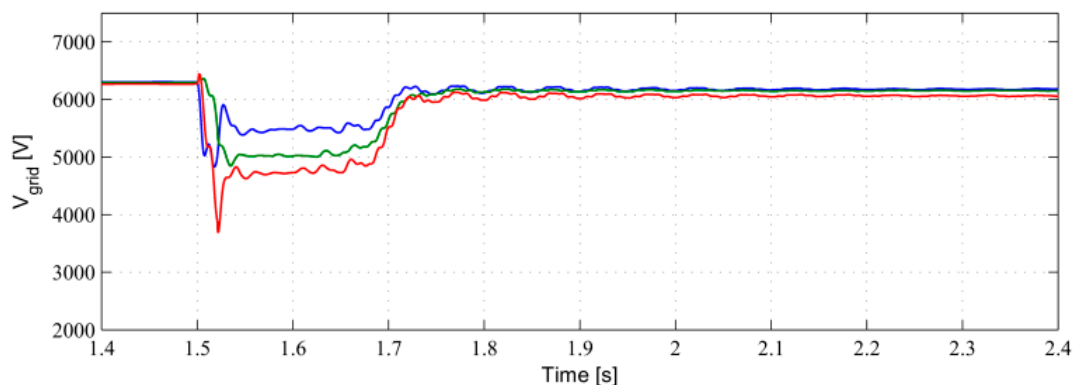
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261 **Figure 9.** Case 2- Unbalanced voltage sag: grid voltage, injected voltage of the DVR and load voltage.

262 In this case study, from 1.00s to 1.10s, a phase to phase short circuit (between phase A and C)
 263 occurred in power system, the voltage at PCC reduced to 35% in phase A, and to 28% in phase C and
 264 increased slightly by 10% in phase B respectively to the reference pre-sag voltage and the phase
 265 angle jump of grid voltage. The results of this simulation are shown in Figure 9. Observe that the
 266 DVR quickly injects the necessary voltage components, with correct both magnitude and phase
 267 angle to maintain balanced load voltages. It is shown that the DVR can detect and mitigate the
 268 voltage sag in different phases independently and inject the compensation energy through 3
 269 single-phase transformers to correct the grid voltage.

270 5.2.4. Case 3: Voltage sags due to starting of a motor.

271 A typical cause of voltage sags is caused by starting a large three-phase motor. The
 272 characteristics of voltage sags depend on various factors, such as motor rating, the method of
 273 starting and system's power supply capacity. In this paper, the test system is simulated in the case of
 274 starting 1975kW induction motor. The motor is started at 1,50 s by closing motor starting contactor.
 275 The three phase voltage sag RMS waveform of grid voltage is shown in Figure 10. Voltage sag
 276 caused by starting motor is unbalanced and drops down to 20% of its nominal value.

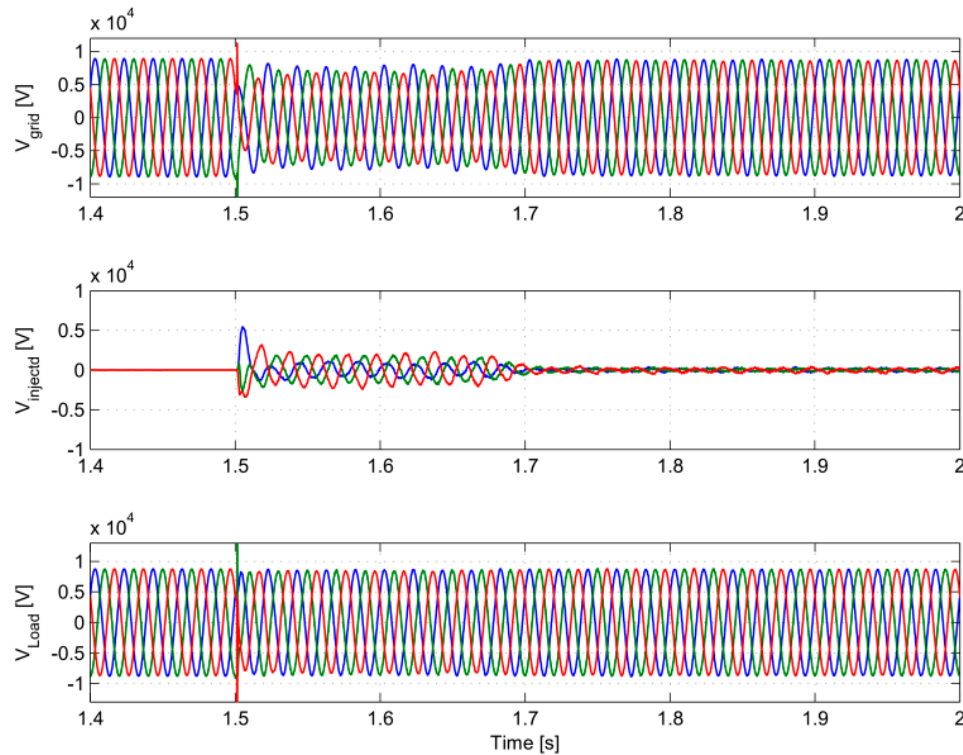


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Figure 10. The RMS waveform of grid voltage due to starting motor.

279 Figure 11 shows the simulated wave form of the grid voltage, injected voltage of the DVR and
 280 load voltage when starting motor. The DVR generated unbalanced three phase voltages for each
 281 phase to compensate grid voltage unbalance. As a result, the voltage sag is fully compensated, the
 282 load voltage is maintained balanced and constant.
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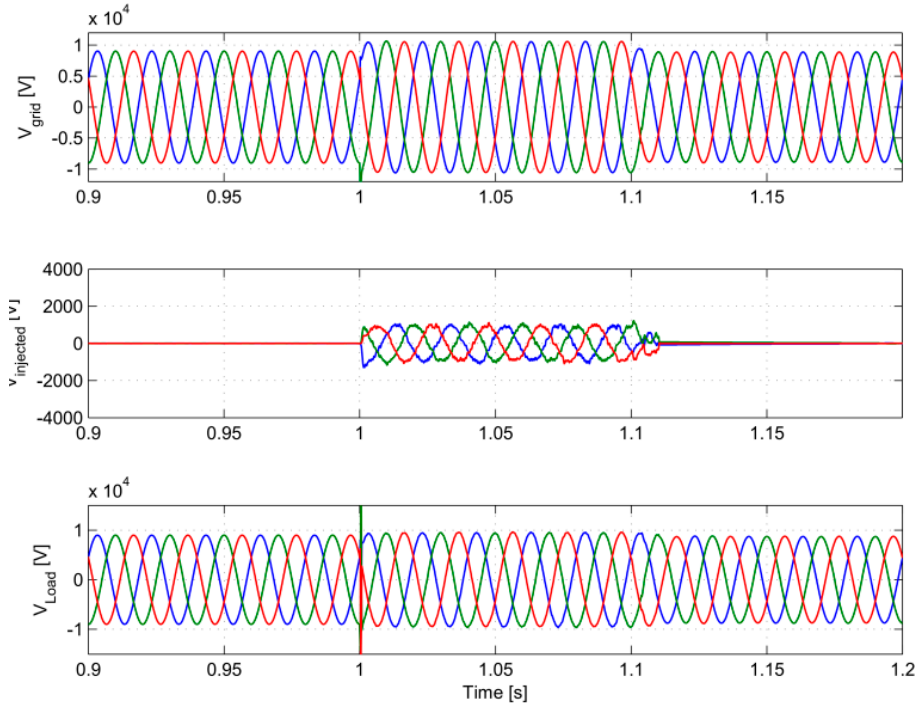


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285 **Figure 11.** Case 3- Voltage sag due to starting motor: grid voltage, injected voltage of the DVR and load
 286 voltage.

287 5.4.5. Case 4 and Case 5: Balanced and unbalanced voltage swells.

288 From the technical point of view, the DVR should mitigate voltage swells in the same way it
 289 mitigates voltage sags. The detection technique is based on the difference between the magnitude
 290 and phase angle of grid voltage and load voltage. The VSC generates the missing voltage through
 291 the transformer for compensation. However, it is completely different from the viewpoint of the
 292 energy handling capability. In the case of voltage sags, the DVR supplies an active power to the load
 293 but in the case of voltage swells, the DVR must absorb the power from the grid.



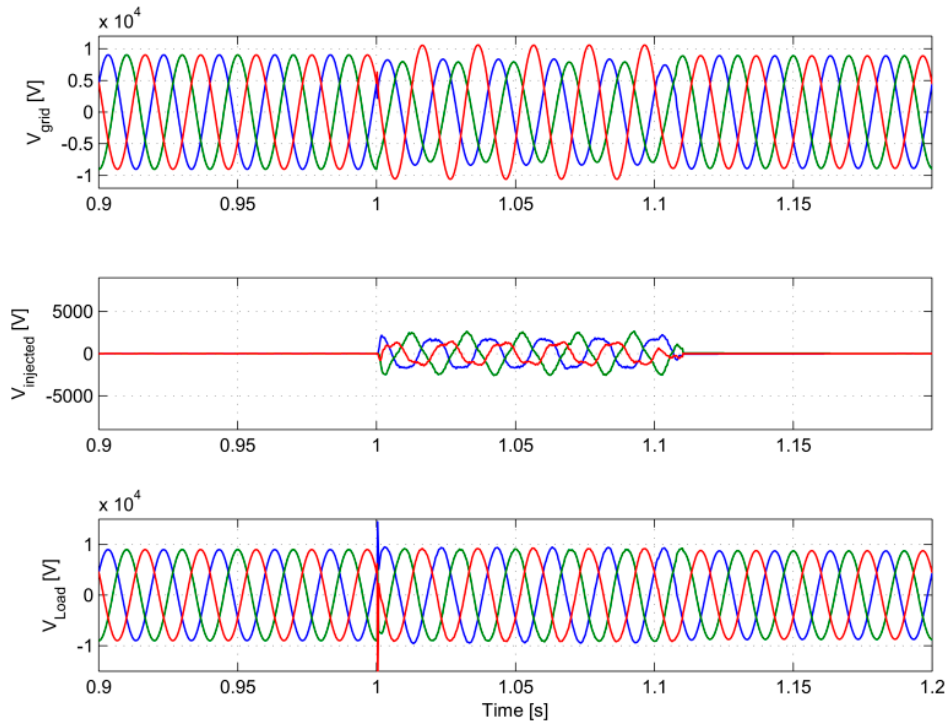
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295 **Figure 12.** Case 4: Balanced voltage swell: grid voltage, injected voltage of the DVR and load voltage.

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Table 1. RMS Voltage of Case 4- Balanced Voltage Swell.

Voltage at PCC before swell (V)	Balanced voltage swell at PCC (V)	Load voltage during swell (V)
6320	7450	6580



297

298 **Figure 13.** Case 5- Unbalanced voltage swell: grid voltage, injected voltage of the DVR and load voltage.

299 In the case of balanced and unbalanced voltage swell, swell has occurred at 1,00 s of the
 300 duration 0,1s. Figures 12 and 13 present the simulation results of the grid voltage, injected voltage
 301 of the DVR and load voltage. The information on the voltage at PCC and load voltage is presented in
 302 Tables 1 and 2. When voltage swell occurs, the grid voltage increased by 18%, the DVR compensates
 303 so the load voltage increased below 4%. In such way the swell doesn't influence the operation of the
 304 load. We can see, that the DVR has successfully maintained the load voltage is spite of balanced or
 305 unbalanced swells.

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Table 2. RMS Voltage of Case 5- Unbalanced Voltage Swell.

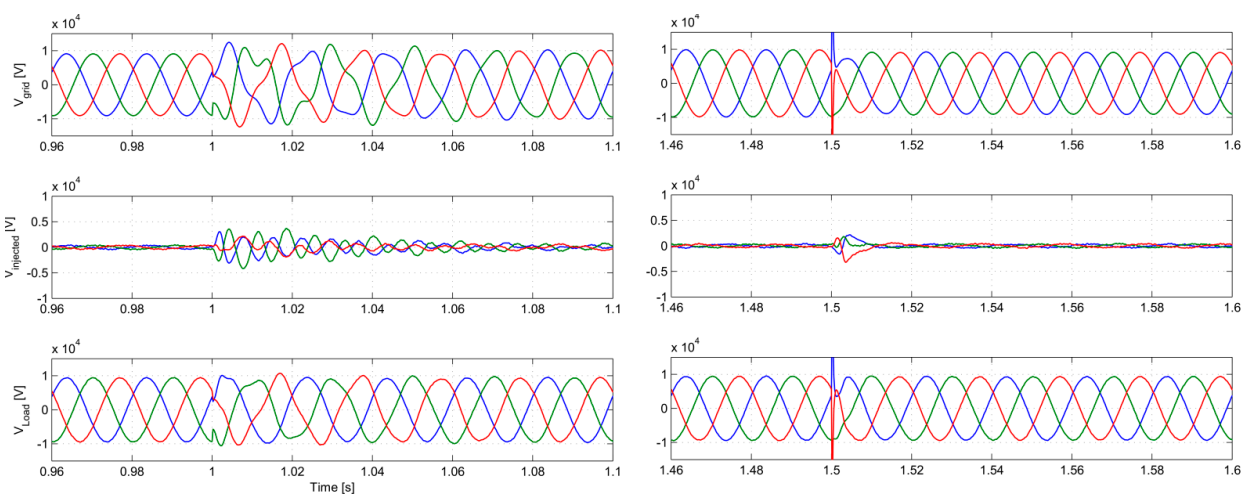
Voltage at PCC before swell (V)	Balanced voltage swell at PCC (V)	Load voltage during swell (V)
6320	7450 5950 5550	6500

307 5.4.6. Case 6: Fluctuations and distortions of voltages

308 In this simulation, the fluctuations and distortions of voltages caused by switching on and off
 309 the capacitor at HV side of the distribution transformer, were created for the duration of 1,0 s to 1,5 s.
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311 The voltage waveform of grid voltage, injected voltage of the DVR and load voltage are shown
 312 in Figure 14. The THD (Total Harmonic Distortion) of the voltage at PCC is 2.86% (measured for 10
 313 cycles' interval after switching on the capacitor) and decreased to 0.94% at load side. It can be
 314 observed that the load side voltages are maintained and sinusoidal waveforms are kept almost
 315 intact.



316

317 **Figure14.** Case 6- Fluctuations and distortions voltages: grid voltage, injected voltage of the DVR
 318 and load voltage.

319 5. Conclusions

320 In this paper it was presented a DVR which can compensate balanced and unbalanced voltage
 321 sags and swells and other utility voltage disturbances. The DVR is described in detail, configuration,
 322 and its sag/swell detection voltage technique, grid synchronization techniques and control
 323 technique. The simulation results under several conditions, balanced and unbalanced voltage sags
 324 and swells, fluctuations and distortions are presented. The results demonstrate that the proposed
 325 DVR is capable of compensating efficiently most of power quality problems, as well as harmonics in
 326 the grid voltage. It provides fast dynamic response and has the advantage of simple structure and
 327 high .

328

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332 performed the experiments; Zbigniew Leonowicz designed simulation algorithms and wrote the paper

333 **Conflicts of Interest:** The authors declare no conflict of interest. The founding sponsors had no role in the
334 design of the study; in the collection, analyses, or interpretation of data; in the writing of the manuscript, and in
335 the decision to publish the results.

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