

## Article

# Analysis and Application of a Novel Layered Bidirectional Equalizer for Series Connected Battery Strings

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**Abstract:** To eliminate the influence of the inconsistency on the cycle life and the available capacity of the battery pack, and improve the balancing speed, a novel inductor-based layered bidirectional equalizer (IBLBE) is proposed. The equalizer is composed of the bottom balancing circuits and the upper balancing circuits, and the two layer circuits both consist of a plurality of balancing sub-circuits, which allow the dynamic adjustment of equalization path and equalization threshold. The battery string is modularized by layered balancing circuits to realize fast active equalization, especially for long battery strings. By controlling the bottom balancing circuits, the individual cells can be balanced in each module. At the same time, the equalization between battery modules can be realized by controlling the upper balancing circuits. Simulation and experimental results demonstrate that the proposed equalizer can achieve fast active equalization for a long battery string, and has the characteristics of multi balancing path, large balancing current and high accuracy. The advantages of the proposed equalizer are further verified by a comparison with existing active equalizer.

**Keywords:** series connected battery string; layered bidirectional equalizer; power inductor; dynamic adjustment of equalization path

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## 1. Introduction

Since the individual cell has limited voltage and capacity, power batteries require a variety of series or parallel combinations to achieve the voltage or capacity level for various applications [1][2].

However, due to the manufacturing inconsistency and unique performance characteristic of every single cell, the cells in series connected may suffer from serious imbalance between cell voltages or state of charge (SOCs) after several charging or discharging cycles, which can cause some of the cells to be overcharged or over discharged. This degrades the performance of battery strings, shortens its lifetime, and even poses a safety hazard (e.g., explosion or fire.etc.). Equalization for battery strings could be realized to prevent these phenomena and prolong the battery strings lifetime.

Numerous equalization topology and balancing method have been proposed and they are well summarized in [1][6][16]. The equalization topologies can be categorized as passive equalization and active equalization. The passive methods remove the excess energy from the fully charged cells through dissipative elements [3][4].

The passive equalization is the most straightforward and the cheapest one. However, the excess energy is converted into heat rather than be stored, which leads to the energy waste and thermal management problems.

The active cell balancing methods transfer energy from higher energy individual cell to lower energy cells. These active equalization circuits can generally be categorized as capacitors, converters or transformers circuits, each of which has its own advantages and disadvantages in terms of speed, accuracy, cost, and efficiency.

Daowd [1], Ye [5], Shang [6], and others have proposed several equalization circuit topologies based on switched-capacitors or LC quasi-resonant circuits, which charge or discharge capacitors to realize energy transfer. These equalization circuits can realize zero-voltage gap. However, these circuits suffer from a longer balancing time, especially with a small difference in cells voltages. Transformer-type equalization circuits have the basic structure of a fly-back transformer [1][14], which can be divided into a variety of types, such as single magnetic cores, multiple magnetic cores, single vice sides, and multiple vice sides. Transformer-type equalization circuits have the characteristics of high level of integration and high balancing speed but poor expandability and large transformer magnetic flux leakage.

Finally, converter-type equalization circuits use DC-DC converters for energy transfer, including buck, boost and Ćuk. The equalization circuits proposed by Lee [7], Yarlagadda [8], Phung [9], Lu [10], Chen [11], and Guo [12] belong to this type. Converter equalization circuits can realize bidirectional energy flow with higher balancing efficiency, but they often require a complex switch array and a precise control algorithm. Two of the most common inductor-based equalization circuits are the adjacent equalizer proposed in [9] and the single switched inductor equalizer proposed in [8]. As shown in figure 1(a), the inductor-based adjacent equalizer (IBAE) senses the voltage difference of the two neighboring cells, and transfers energy from the higher one to the lower one. Multiple balancing sub-circuits can operate at the same time, but it takes a relatively long time for transferring energy from the first one to the last one especially in the long battery string. Figure.1 (b) presents the single switched inductor equalizer (SSIE). The SSIE can achieve the direct cell-to-cell energy transfer between any two cells in the battery string. However, this equalizer has a complex switch matrix which needs to operate 4 switches in each switching period, and it takes a long time to serve all cells in a long battery string with only one balancing bypass.

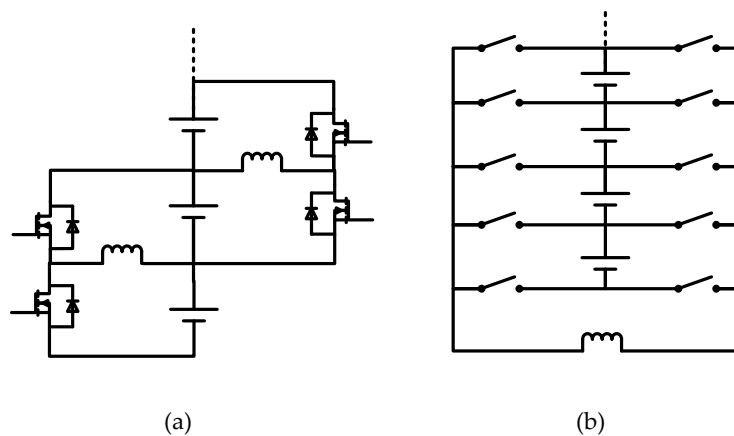


Figure.1 Two traditional inductor-based equalizers. (a) The inductor-based adjacent equalizer (IBAE); (b) The single switched inductor equalizer (SSIE).

In consideration of the advantages and disadvantages of the equalization methods discussed above, a novel inductor-based layered bidirectional equalizer (IBLBE) with the advantages of more balancing path and large balancing current is proposed. The main idea of the IBLBE is modularizing the battery string with layered balancing circuits based on power inductors to realize fast active equalization, especially for long battery strings. The IBLBE reduces the charging current of the higher energy cells in the charging process, and decreases the discharging current of the

lower energy cells in the discharging process. The proposed equalizer realizes dynamic equalization and preventing over-charge and over-discharge.

In this paper, the IBLBE is proposed and analyzed. Its circuit structure and equalization principle are introduced in Section 2. The models and calculation of the key parameters are derived in Section 3. In Section 4, the simulation results are presented. The experimental results and the advantages of IBLBE compared with the inductor-based adjacent equalizer are presented in Section 5, followed by the conclusion in Section 6.

## 2. Proposed Equalizer Scheme

### 2.1 Structure of the Proposed Equalizer

Figure 2 shows the system configuration of the proposed equalizer. Figure 2 (a) is the structure of the equalizer; figure 2 (b) is the schematic diagram of the bottom balancing circuit; figure 2 (c) is the schematic diagram of balancing sub-circuit.

The battery string connected in series is subdivided into  $N$  modules, and each module contains  $n$  individual cells. The  $N$  battery modules are divided into two parts with cutoff point  $K$ . If  $N$  is an even number,  $n=2*K$ ; if  $N$  is an odd number,  $n=2*K-1$ . Every battery module  $M_i$  is equipped with a balancing sub-circuit  $E_i$ , which controls the charge transfer between  $M_i$  and other modules. Each battery module is divided into two parts with cutoff point  $k$ . If  $n$  is an even number,  $n=2*k$ ; if  $n$  is an odd number,  $n=2*k-1$ . Every individual cell is equipped with a balancing sub-circuit  $S_j$ , which controls the charge transfer between  $B_i$  and other individual cells in this module.

The balancing sub-circuits  $E_i$  and  $S_i$  are implemented by buck-boost converters, which allow the bidirectional energy flow. The balancing sub-circuits  $E_i$  compose the upper balancing circuits, which are used to achieve the equalization between battery modules. The balancing sub-circuits  $S_i$  compose the bottom balancing circuits which are used for equalization between cells in each module.

The proposed equalizer IBLBE can achieve the dynamic adjustment of equalization path and equalization threshold, described as follows:

(1) Dynamic adjustment of the equalization path.

In the equalization process, the balancing sub-circuit  $E_i$  provides equalization path for module  $M_i$ , and the balancing sub-circuit  $S_j$  provides equalization path for individual cell  $B_j$ . Furthermore, the equalizer can extend the equalization path by operating  $E_i$  and  $S_j$  concurrently.

(2) Dynamic adjustment of equalization threshold.

The equalization circuits have two equalization threshold; one for the battery modules and the other for the individual cells in the same module. If the two thresholds are not met, the balancing circuits stop working.

The working condition for  $E_i$  is  $V(M)_{\max} - V(M)_{\min} > 5mV$ ,  $V(M)$ s are the modules terminal voltages.

In every battery module, the working condition for  $S_j$  is  $V(B)_{\max} - V(B)_{\min} > 3mV$ ,  $V(B)$ s are the terminal voltages of cells in the same module.

The equalization threshold could be adjusted according to the system require and the accuracy of sampling circuits [15].

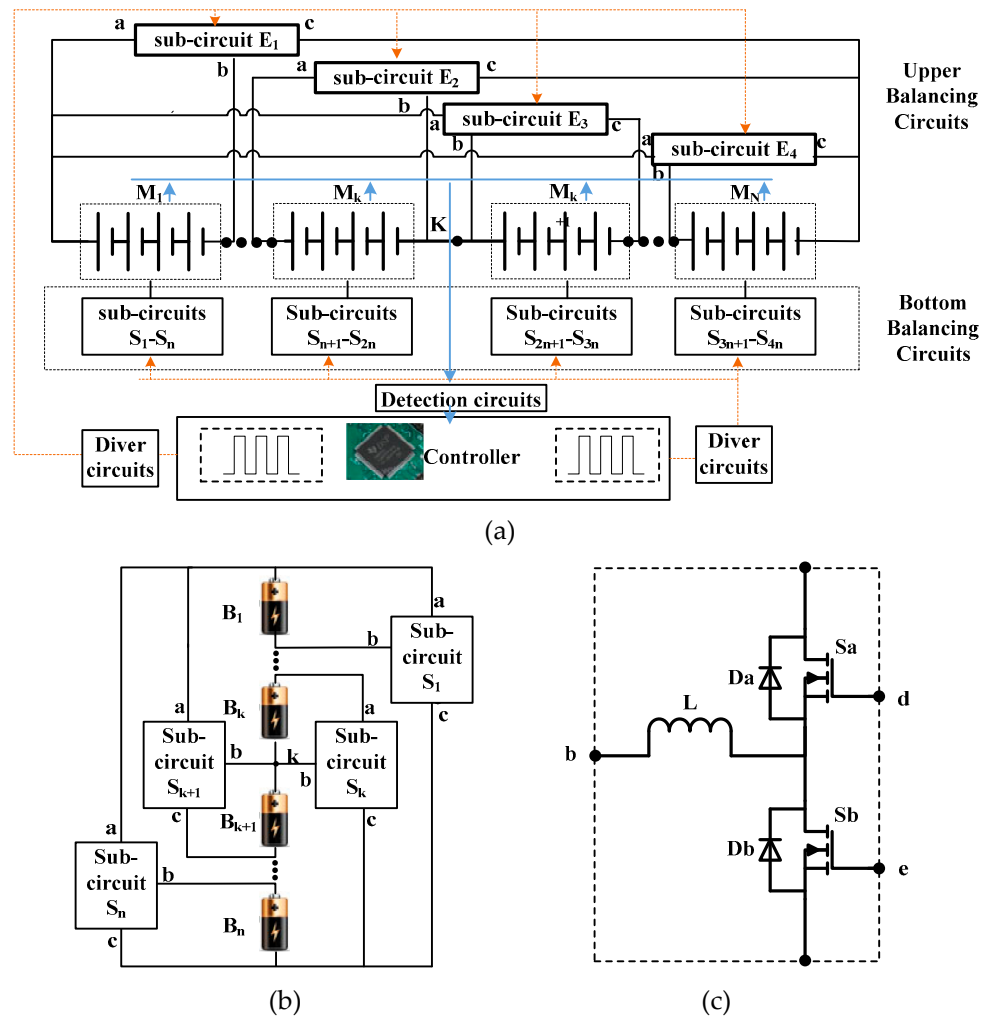


Figure 2. System configuration of the proposed equalizer (a) Structure of the proposed equalizer (b) Schematic diagram of bottom balancing circuit (c) Schematic diagram of balancing sub-circuit

## 2.2 Equalization principle

The battery strings have four different working states: charging state, discharging state, the idle state after charging and the idle state after discharging. The equalization principles of charging state and the idle state after charging are the same; the equalization principles of discharging state and the idle state after discharging are the same.

Cell balancing based on voltage inconsistency is more easily implemented and more common [13]. In this paper, the cells terminal voltages are employed as the index of inconsistency. A balancing circuit shown in figure 3 for 16 cells in series subdivided into 4 modules is used as the example to introduce the principles of the proposed equalizer.

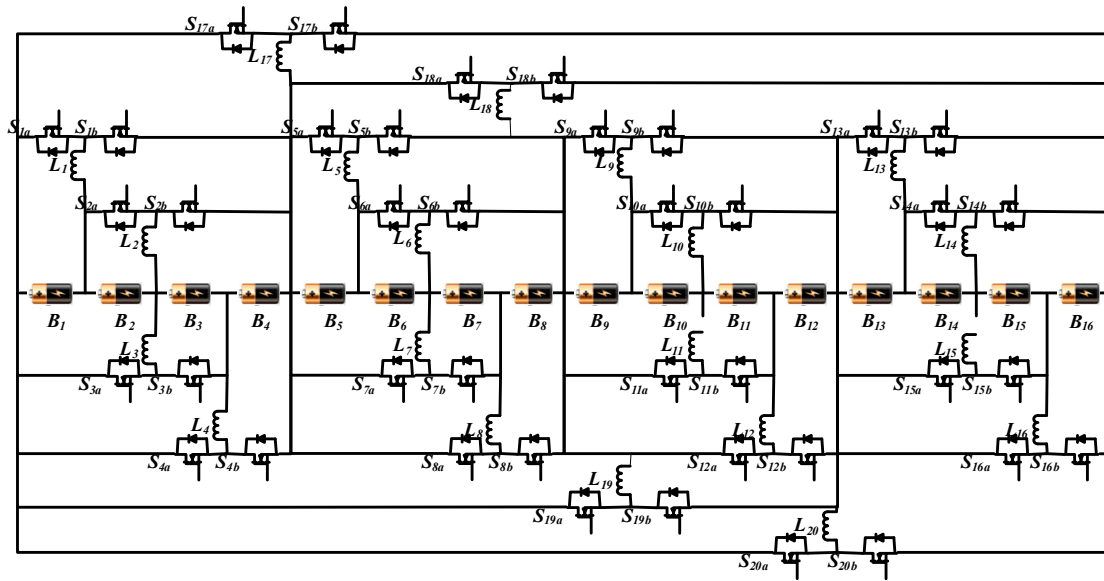


Figure 3. Proposed equalizer for 16 cells in series

### 2.2.1 The equalization principles of charging state

In the charging state or the idle state after charging, firstly, identify the highest cell voltage; secondly control the corresponding sub-circuit  $S_j$  to transfer energy from highest cell to the other cells (in the same module). Suppose that the cell voltage of  $B1$  is higher than the others in the module  $M1$ . The equalization principle can be divided into the following two stages:

#### Stage 1: $L_1$ charging

As shown in figure 4 (a), the individual cell  $B1$  charges the inductor  $L_1$  when the switch  $S_{1a}$  is turned ON. The inductor  $L_1$  stores energy with the current  $i_{L1}$  gradually increasing. Some of the electrical energy is transferred into magnetic energy stored in the inductor.

$$V_{B1} = R_{on}i_{L1} + L \frac{di_{L1}}{dt} \quad 0 < t \leq t_{on} \quad (1)$$

in which  $R_{on}$  the circuit total resistance when  $S_{1a}$  is turned ON, including the DC resistance of  $L_1$ , the turn-on resistance of  $S_{1a}$ , and the internal resistance of cell  $B1$ .  $i_{L1}$  is the current of inductor  $L_1$ ,  $t_{on}$  is the turn-on time of  $S_{1a}$ .

The general solution of  $i_{L1}$  is:

$$i_{L1} = \frac{V_{B1}}{R_{on}} - \frac{V_{B1}}{R_{on}} e^{-t \frac{R_{on}}{L}} = \frac{V_{B1}}{R_{on}} \left( 1 - e^{-t \frac{R_{on}}{L}} \right) \quad 0 < t \leq t_{on} \quad (2)$$

The turned-on time  $t_{on}$  of  $S_{1a}$  determines the peak value of inductor current  $i_p$ , which is a key parameter to calculate the average current of inductors and the average balancing current of balancing sub-circuits.

$$i_p = \frac{V_{B1}}{R_{on}} \left( 1 - e^{-t_{on} \frac{R_{on}}{L}} \right), \quad t = t_{on} \quad (3)$$

In this process,  $L_1$  stores energy and the balancing sub-circuit  $S1$  decreases the charging current of  $B1$ .

$$i_{B1} = I_{ch} - i_{c1} \quad (4)$$

In which  $i_{B1}$  is the current through  $B1$ ,  $I_{ch}$  is the charging current of battery string,  $i_{c1}$  is the equalization current of balancing sub-circuit  $S1$ .

#### Stage 2: $L_1$ discharging

As shown in figure 4 (b), the inductor  $L_1$  charges cell  $B_2$ ,  $B_3$  and  $B_4$  in  $M1$  through the flywheel diode of  $S_{1b}$  when the switch  $S_{1a}$  is turned OFF, realizing the energy transfer from cell  $B_1$  to the other cells.

This is a first order full response circuit, and the inductor current response is:

$$i_{L1} = i_p e^{-(t-t_{on})\frac{R_{off}}{L}} - \frac{V_B + V_D}{R_{off}} \left(1 - e^{-(t-t_{on})\frac{R_{off}}{L}}\right) \quad t_{on} < t \leq t_d \quad (5)$$

$$i_{L1} = \left(i_p + \frac{V_B + V_D}{R_{off}}\right) e^{-(t-t_{on})\frac{R_{off}}{L}} - \frac{V_B + V_D}{R_{off}} \quad t_{on} < t \leq t_d \quad (6)$$

$V_D$  is the forward voltage of the  $D_{1b}$  (body diode of  $S_{1b}$ ),  $R_{off}$  is the loop total resistance,  $V_B$  is the total terminal voltage of  $B_2, B_3$  and  $B_4$ ,  $t_d$  is the stop time of  $L_1$  discharging.

In this process, the inductor  $L_1$  charges  $B_2$ ,  $B_3$ ,  $B_4$  through the flywheel diode of switch  $S_{1b}$  and the balancing sub-circuit increases the charging current of  $B_2$ ,  $B_3$ ,  $B_4$ .

$$i_{B2} = i_{B3} = i_{B4} = I_{ch} + i_{d1} \quad (7)$$

$i_{B2}$ ,  $i_{B3}$ ,  $i_{B4}$  are the current through  $B_2$ ,  $B_3$ ,  $B_4$  respectively,  $i_{d1}$  is the equalization current of balancing sub-circuit  $S_1$ .

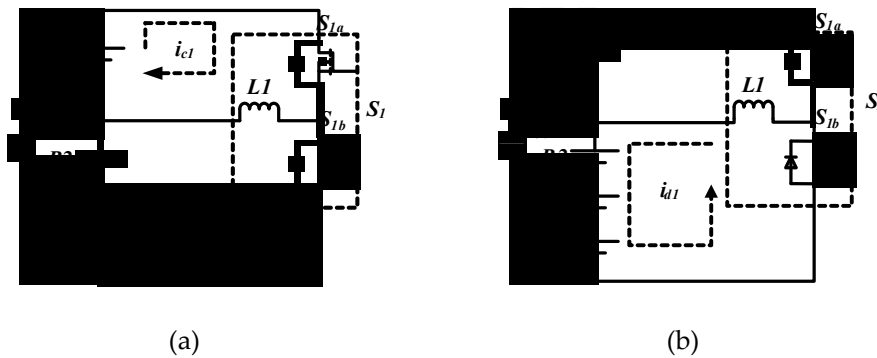


Figure 4. Equalization principles of proposed equalizer in charging state or the idle state after charging (a)Cell  $B1$  charges inductor  $L1$  (b)Inductor  $L1$  charges the cell  $B2, B3$  and  $B4$ .

### 2.2.2 Equalization principles of discharging state

In the discharging state or the idle state after discharging, firstly, identify the lowest cell voltage; secondly control the corresponding sub-circuit  $S_j$  to transfer energy from the other cells (in the same module) to the lowest voltage cell. Suppose that the cell voltage of  $B3$  is lower than the others in the module  $M1$ . The equalization principle can be divided into the following two stages:

#### Stage 1: $L_3$ charging

As shown in figure 5 (a), the individual cell  $B1$  and  $B2$  charge the inductor  $L_3$  when the switch  $S_{3a}$  is turned ON. The inductor  $L_3$  stores energy with the current  $i_{L3}$  increasing. Some of the electrical energy is transferred into magnetic energy stored in the inductor. The balancing sub-circuit  $S3$  increases the discharging current of cell  $B1$  and  $B2$ .

$$i_{B1} = i_{B2} = I_{dis} + i_{c3} \quad (8)$$

#### Stage 2: $L_3$ discharging

As shown in figure 5 (b), the inductor  $L_3$  charges cell  $B3$  in  $M1$  through the flywheel diode of switch  $S_{3b}$  when the switch  $S_{3a}$  is turned OFF, realizing the energy transfer from cells  $B1$  and  $B2$  to the cell  $B3$ . The balancing sub-circuit  $S3$  decreases the discharging current of cell  $B3$ .

$$i_{B3} = I_{dis} - i_{d3} \quad (9)$$

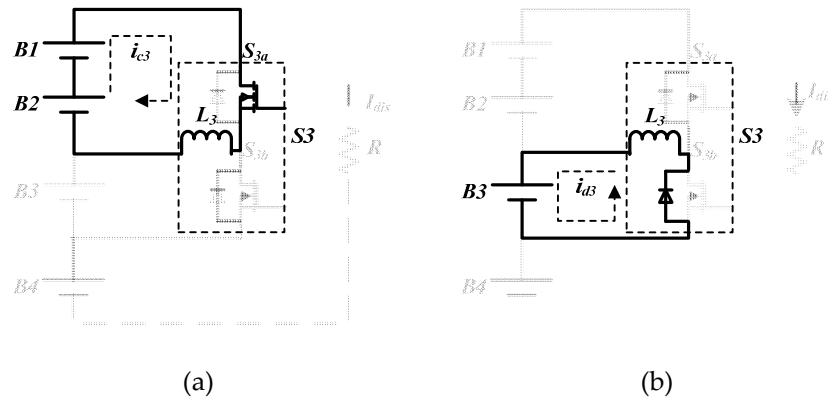


Figure 5. Principle of proposed equalizer in discharging or the idle period after discharging (a) B1 and B2 charge inductor L3 (b) L3 charges the cell B3.

### 2.3 Module equalization principle

In a long battery string, it needs more equalization path working simultaneously to improve the balancing speed.

The proposed equalizer modularizes the battery string with layered bidirectional balancing circuits. The balancing sub-circuits  $E_i$  in upper layer circuits are operated simultaneously with the sub-circuits  $S_j$  in the bottom layer, which extends the balancing path and can achieve the fast equalization between modules.

In the charging state or the idle state after charging, the energy is transferred from the highest voltage module to the others. When the voltage of module M4 is higher than the others, the operation can be divided into two stages.

As shown in figure 6 (a), the M4 charges the inductor  $L_{20}$  when the switch  $S_{20b}$  is turned ON. Then, the inductor  $L_{20}$  charges the module M1, M2 and M3 though the flywheel diode of  $S_{20a}$  when the switch  $S_{20b}$  is turned OFF, shown in figure 6 (b).

In the discharging state or the idle state after discharging, the energy is transferred from the other modules to the lowest voltage one. When the voltage of module M2 is lower than the others, the operation can be divided into two stages.

As shown in figure 6(c), the module M3 and M4 charge the inductor  $L_{19}$  when the switch  $S_{19b}$  is turned ON. Then, the inductor  $L_{19}$  charges the module M2 though the flywheel diode of  $S_{19a}$  when the switch  $S_{19b}$  is turned OFF, shown in figure 6 (d).

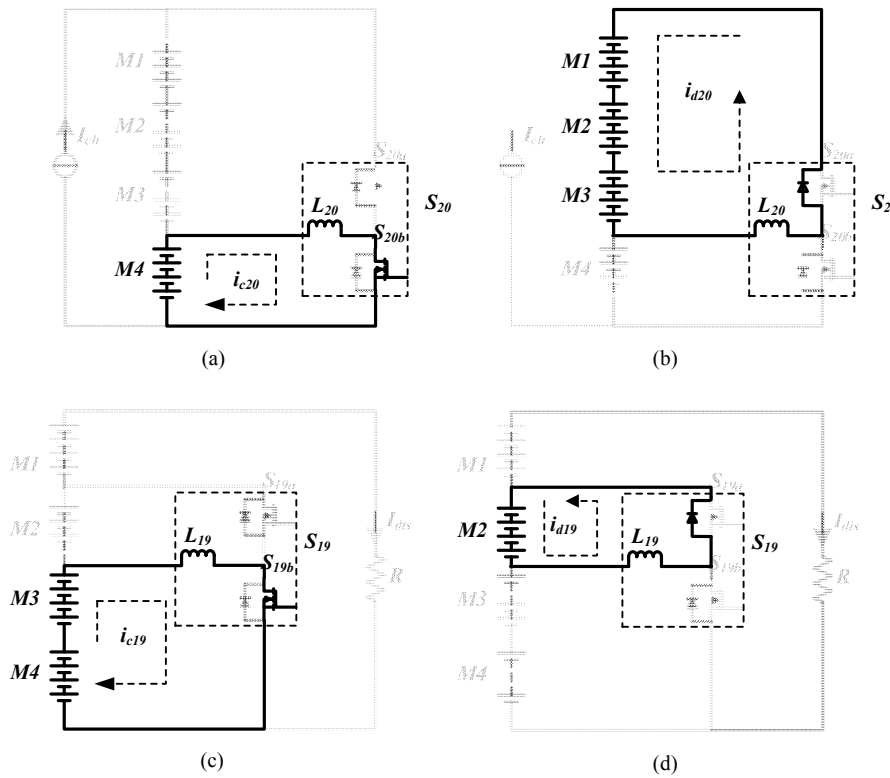


Figure 6. Modules equalization principles. (a) M4 charges  $L_{20}$ . (b)  $L_{20}$  charges modules M1, M2 and M3. (c) M3 and M4 charge  $L_{19}$  (d)  $L_{19}$  charges module M3.

### 3. Modeling, Analysis and calculation of the key parameters

In this section several key parameters are analyzed including the balancing speed, the balancing current, the inductors current, the duty cycle of switch waveform, the switching frequency and the inductances.

#### 3.1 Modeling of inductor current and duty cycle of driving waveform

DC-DC converters have two working modes: continue current mode (CCM) and discontinuous current mode (DCM), shown in figure 7. Considering the magnetic saturation and safety allowance, DC-DC converters have to work in the DCM, where the inductors can release all absorbed energy in the off-time of the switches.

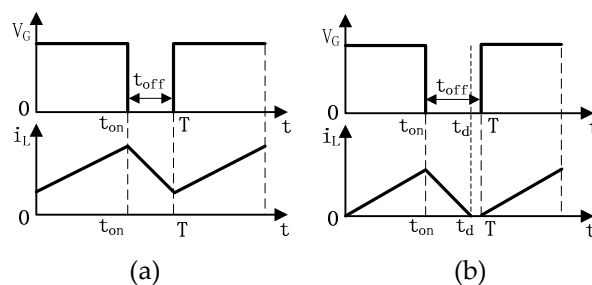


Figure 7. Two operating mode of DC-DC converter (a) Continuous current mode (CCM) (b) Discontinuous current mode (DCM)

During the energy transfer process of the inductor  $L_i$ , denote the voltage across  $L_i$  by  $V_c$  when the switch is turned ON, namely the total cells voltage charging  $L_i$ ; denote the voltage across  $L_i$  by  $V_d$  when the switch is turned OFF, namely the total cells voltage discharging by  $L_i$ .



$$V_c = R_{on}i_{L_i} + L \frac{di_{L_i}}{dt} \quad 0 < t \leq t_{on} \quad (10)$$

$$V_d = R_{off}i_{L_i} + L \frac{di_{L_i}}{dt} - V_D \quad t_{on} < t \leq t_d \quad (11)$$

Ignore the resistance  $R_{on}$  since its value is very small. Then the inductor current increases linearly when the switch is turned ON:

$$i_{L_i} = \frac{V_c \cdot t}{L} \quad (0 < t < t_{on}) \quad (12)$$

When the switch is turned OFF, ignore the resistance  $R_{off}$  and forward voltage  $V_D$  of flywheel diode, the inductor current decreases linearly:

$$i_{L_i} = i_p - \frac{V_d \cdot (t - t_{on})}{L} \quad (t_{on} < t < t_d) \quad (13)$$

$$i_p = \frac{V_c \cdot t_{on}}{L} = \frac{V_c \cdot D \cdot T}{L} \quad (14)$$

$$i_{L_i} = \begin{cases} \frac{V_c}{L_i} t, & 0 \leq t < t_{on} \\ \frac{V_c}{L_i} t_{on} - \frac{V_d}{L_i} (t - t_{on}), & t_{on} \leq t < t_d \\ 0, & t_d \leq t \leq T \end{cases} \quad (15)$$

in which D represents duty cycle, and T represents switching period.

To make the DC-DC converters working in the DCM, the inductor current need drop to 0 in the off-time of switch. The conditions that the duty cycle need satisfy are derived as follows:

$i_{L_i} = 0$  when  $t = t_d$ ; since  $T > t_d$ , when  $t = T$

$$\frac{V_c}{L} t_{on} - \frac{V_d}{L} (T - t_{on}) < 0 \quad (16)$$

Furthermore,

$$D < \frac{V_d}{V_c + V_d} = \frac{1}{1 + \frac{V_c}{V_d}} \quad (17)$$

In the equalization process, the duty cycle of driving waveforms for balancing sub-circuits Ei and Sj are the same.

In the equalization for charging state or the idle state after charging, the balancing circuits transfer energy from the individual cell with highest voltage to the others, so:

$$V_c = V_{Bi} \quad (18)$$

$$V_d = \begin{cases} \sum_{j=i+1}^n V_{Bj}, & 1 \leq i \leq k \\ \sum_{j=0}^{i-1} V_{Bj}, & k < i \leq n \end{cases} \quad (19)$$

$$\left\{ \begin{array}{ll} D < \frac{1}{1 + \frac{V_{B1}}{V_{B2} + V_{B3} + V_{B4}}} , & i = 1 \\ D < \frac{1}{1 + \frac{V_{B2}}{V_{B3} + V_{B4}}} , & i = 2 \\ D < \frac{1}{1 + \frac{V_{B3}}{V_{B1} + V_{B2}}} , & i = 3 \\ D < \frac{1}{1 + \frac{V_{B4}}{V_{B1} + V_{B2} + V_{B3}}} , & i = 4 \end{array} \right. \quad (20)$$

In the equalization for discharging state or the idle state after discharging, the balancing circuits transfer energy from the other cells to the lowest voltage cells, so:

$$V_c = \begin{cases} \sum_{j=i+1}^n V_{Bj} , & 1 \leq i \leq k \\ \sum_{j=0}^{i-1} V_{Bj} , & k < i \leq n \end{cases} \quad (21)$$

$$V_d = V_{Bi} \quad (22)$$

$$\left\{ \begin{array}{ll} D < \frac{1}{1 + \frac{V_{B2} + V_{B3} + V_{B4}}{V_{B1}}} , & i = 1 \\ D < \frac{1}{1 + \frac{V_{B3} + V_{B4}}{V_{B2}}} , & i = 2 \\ D < \frac{1}{1 + \frac{V_{B1} + V_{B2}}{V_{B3}}} , & i = 3 \\ D < \frac{1}{1 + \frac{V_{B1} + V_{B2} + V_{B3}}{V_{B4}}} , & i = 4 \end{array} \right. \quad (23)$$

### 3.2 Inductance, switching frequency and equalization speed

There is a key indicator for equalizer need to be considered: the cell-balancing time. This problem can be solved by increasing the balancing current. This is because the amount of charges transferred from one cell to others in unit time is proportional to the average value of current through the cell [5].

$$\Delta Q = i_{B_{iavr}} \cdot T \cdot f \quad (24)$$

In which,  $\Delta Q$  is the energy transferred from one cell to the others in one second,  $i_{B_{iavr}}$  is the average current through  $B_i$ ,  $T$  is the switching period and  $f$  is the switching frequency.

In equalization process, the current in balancing circuit is derived as follows:

The peak value of inductor current

$$i_p = \frac{V_c}{L} DT = \frac{V_c D}{Lf} \quad (25)$$

The average value of inductor current

$$i_{L_{iavr}} = \frac{1}{2} \frac{V_c D}{Lf} \quad (26)$$

In equalization for charging state or the idle state after charging, the average value of current through cell  $B_i$  and module  $M_i$  are:

$$i_{B_{iavr}} = \frac{1}{2} \frac{V_{B_i} D^2}{L f} \quad (27)$$

$$i_{M_{iavr}} = \frac{1}{2} \frac{V_{M_i} D^2}{L f} \quad (28)$$

The average current value of cells/modules are proportional to the product of  $D^2$  and  $V_{B_i}/V_{M_i}$  and is inversely proportional to the product of  $L$  and  $f$ . The values of  $D^2$  and  $V_{B_i}/V_{M_i}$  cannot adjust at will, in that case, the selection of  $L$  and  $f$  can achieve different effects on the balancing current and balancing speed.

#### 4. Simulation Result

The simulation model of the proposed equalizer is built in PSIM9.0.

In order to reduce the balancing time, sixteen 1F capacitors are employed to substitute cells with initial voltage shown in table 1. The switching frequency is set as 10 kHz. The inductances in  $S_i$  are 100uH, and the inductances in  $E_i$  are 330uH. It is assumed that the capacitors, inductors and switches are all lumped element. Moreover, the influence of parasitic inductance and parasitic capacitance and the deviation generated by AD transfer are ignored. The active condition set for balancing sub-circuit  $E_i$  is  $V(M_i) = V(M)_{\max} > V(M)_{\min} + 5\text{mV}$ ,  $i = 1, 2, 3, 4$ . The active condition set for balancing sub-circuit  $S_j$  is  $V(B_j) = V(B)_{\max} > V(B)_{\min} + 3\text{mV}$ ,  $j = 1, 2, \dots, 16$ , where  $V(B)_{\max}$  and  $V(B)_{\min}$  are the cells voltage in the same module.

Table 1 Initial voltage of 16 cells.

Modules	$V_{M1}$		$V_{M2}$		$V_{M3}$		$V_{M4}$	
Voltage(V)	15.027		15.153		15.201		15.301	
Cells	$V_{B1}$	$V_{B2}$	$V_{B3}$	$V_{B4}$	$V_{B5}$	$V_{B6}$	$V_{B7}$	$V_{B8}$
Voltage(V)	3.771	3.833	3.698	3.725	3.849	3.834	3.751	3.719
Cells	$V_{B9}$	$V_{B10}$	$V_{B11}$	$V_{B12}$	$V_{B13}$	$V_{B14}$	$V_{B15}$	$V_{B16}$
Voltage(V)	3.738	3.803	3.807	3.723	3.834	3.850	3.795	3.822

$V_{B\max}=3.850\text{V}$ ,  $V_{B\min}=3.698\text{V}$ , maximum voltage gap is 0.152V.  $V_{M\max}=15.301\text{V}$ ,  $V_{M\min}=15.027\text{V}$ , maximum voltage gap is 0.274V.

##### 4.1 Equalization simulation for charging state or the idle state after charging.

Figure 8 shows the equalization simulation results of charging state with a 0.5A charging current. The equalization between modules is achieved at 0.035s and the cell-balancing stops at 0.234s, with the final voltage gap 4mV.

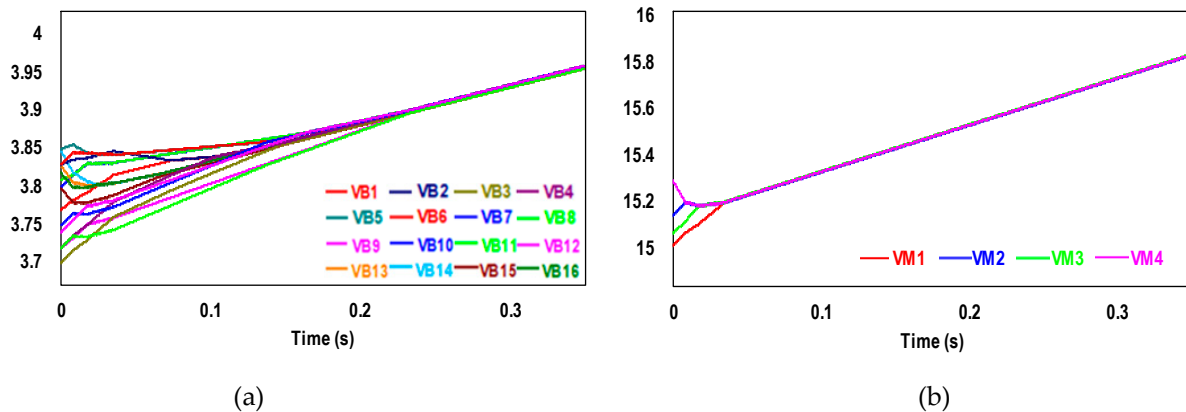


Figure 8. Equalization simulation results of proposed equalizer for 16cells during charging process.(a)16cells voltage trajectories (b) 4 modules voltage trajectories.

Figure 9 shows the simulation result of equalization for the idle state after charging. Firstly, the equalization between modules is achieved at about 0.113s. Then, the equalization stops at 0.238s, and the final voltage gap is 4mV.

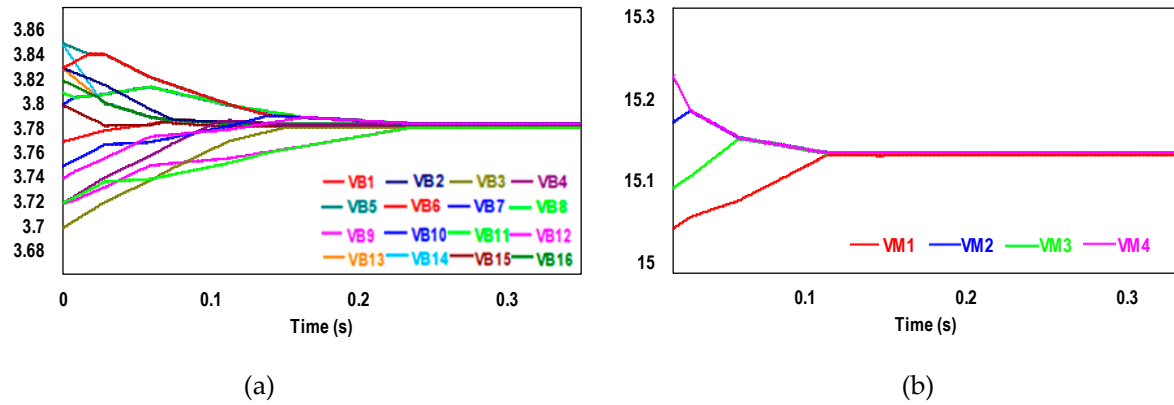


Figure 9. Equalization simulation results of proposed equalizer for 16cells during idle period after charging (a)16cells voltage trajectories (b) 4 modules voltage trajectories.

#### 4.2 Equalization simulation for charging state or the idle state after charging.

Figure 10 shows the equalization simulation results of discharging state with a 0.5A discharging current. The module equalization is achieved at about 0.213s and the cell balancing stops at 0.267s, with the final voltage gap 4mV.

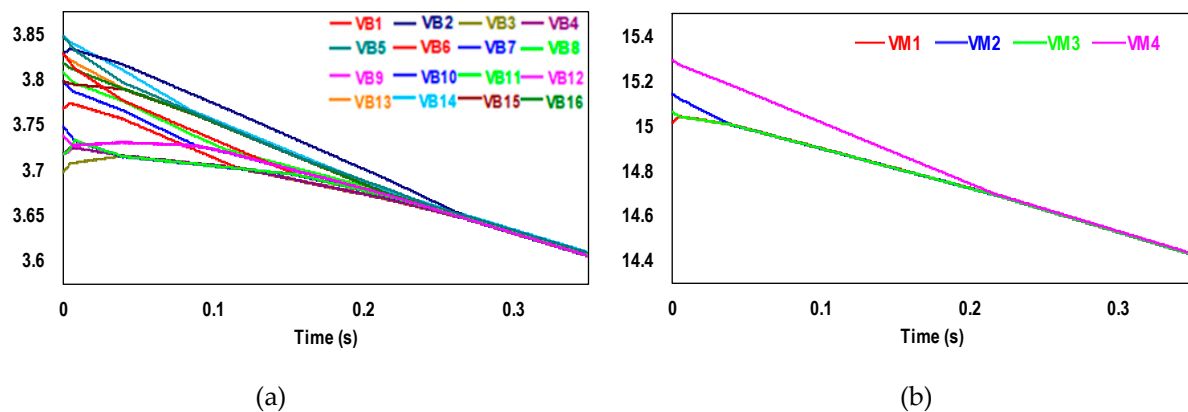


Figure 10. Equalization simulation results of proposed equalizer for 16cells during discharging process (a)16cells voltage trajectories (b) 4 modules voltage trajectories.

Figure 11 shows the equalization simulation result of the idle state after discharging. The module balancing stops at about 0.217s. The cells balancing stops at about 0.262s, and the final voltage gap is 4mV.

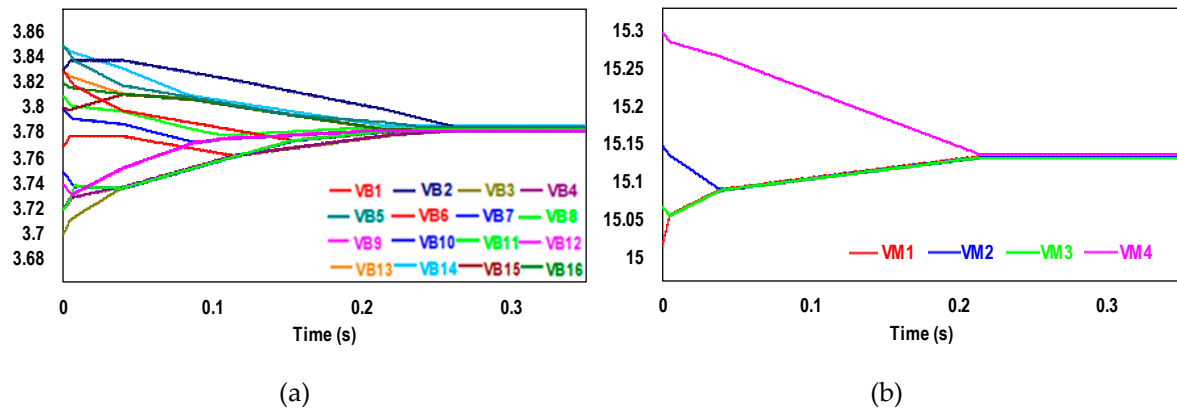


Figure 11. Equalization simulation results of proposed equalizer for 16 cells during idle period after discharging. (a) 16 cells voltage trajectories (b) 4 modules voltage trajectories.

#### 4.3 Comparative study with typical inductor-based equalizers

In order to validate the advantages in balancing speed of the proposed equalizer, comparative studies with traditional inductor-based adjacent equalizer (IBAE) and single switched inductor equalizer (SSIE) are implemented. In the comparative simulation, the initial cells voltages are the same with previous simulation shown in table 1; the inductances are 100uH; the switching frequency is 10 kHz; the duty cycle is 48%.

The topologies of IBAE and SSIE are shown in figure 1.

The equalization simulation results of traditional inductor-based equalizers (IBAE and SSIE) for 16 cells during idle state is given in figure 12. When the IBAE achieves the same 4mV voltage gap, its balancing time is 0.347s. The SSIE achieves the same 4mV voltage gap at about 0.851s.

The proposed equalizer achieves cells balancing at about 0.238s in the idle state after charging. It reduces the balancing time by 31.4% compared with the IBAE (0.347s) and reduces the balancing time by 72% compared with SSIE (0.851s).

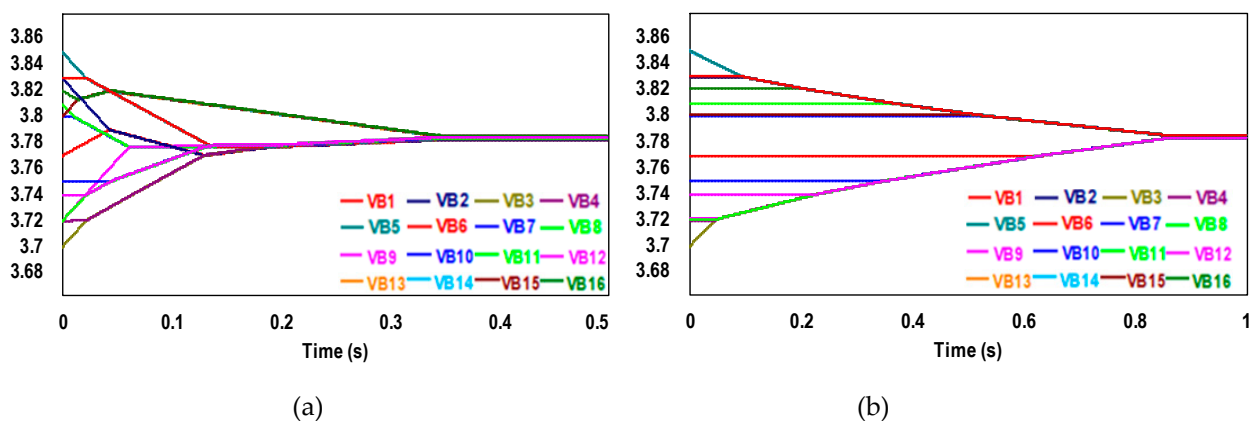


Figure 12. 16 cells voltage trajectories in static equalization of contrast experiment (a) IBAE (b) SSIE

## 5. Experimental results

In order to further verify the equalization principles and show the balancing performance of the proposed equalizer, a balancing system is implemented and tested for sixteen 2.6 Ah Sanyo ternary lithium batteries.

Table 2 summarizes the parameters of IBLBE. The inductances and the resistances in Table 2 are measured by a TH2810D LCR Meter.

This paper adopts the traditional fuzzy logic control algorithm (FLC) [6]. In every equalization cycle, the equalization time  $t_{eq}=10s$ , and the standing time  $t_{sd}=30s$ .

The standing time in every equalization cycle is aimed at eliminating the polarization voltage of cells. Therefore, it is more accurately to test the real open-circuit voltages (OCVs) of cells, and issue the balancing instructions.

Table 2 Component Values used for the equalizer

Parameters	Values			
Battery string	Sanyo ternary lithium batteries	B1-B16	2.6Ah	
Equalizer	MOSFET	S <sub>1a</sub> , S <sub>1b</sub> -S <sub>20a</sub> , S <sub>20b</sub>	IRF530	R <sub>DS(on)</sub> <0.090Ω
	Diode	D <sub>1a</sub> , D <sub>1b</sub> -D <sub>20a</sub> , D <sub>20b</sub>		V <sub>D</sub> <0.6V
	Inductance	L <sub>1</sub> -L <sub>16</sub>	99.1-101.5μH	R<0.1450 Ω
		L <sub>17</sub> -L <sub>20</sub>	328.2-332.4μH	R<0.3022 Ω

### 5.1 Equalization for charging state

The battery string charging current is 0.5A. The initial voltage of cells and modules is shown in table 1. The balancing circuits S2, S5, S11, S14 and E4 operate in the beginning.

Figure 13 (a) shows the experimental waveforms of inductor current  $i_{L11}$  and  $i_{L20}$ . The duty cycle of PWM is 65%. The inductor current is discontinuous and varies in saw-tooth waveform. The peak value of  $i_{L11}$  comes to 1.7A, and the peak value of  $i_{L20}$  is 1.8A.

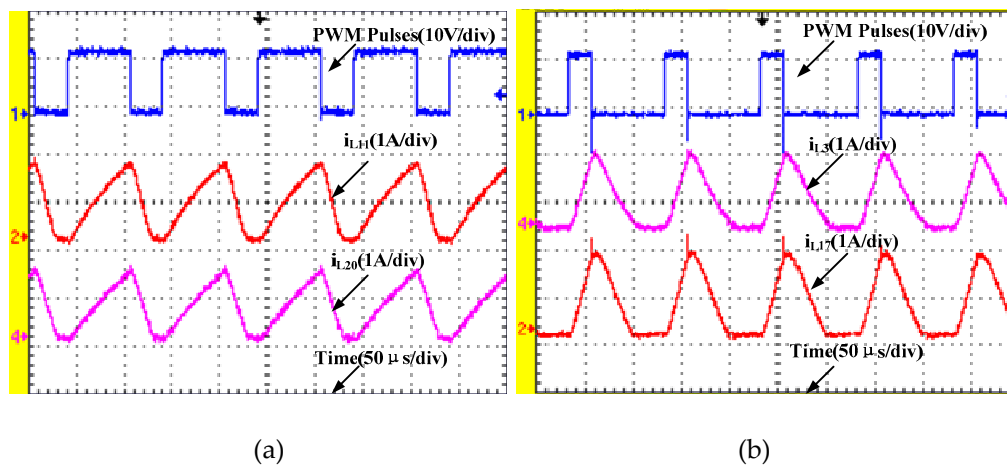


Figure 13. Experimental waveform of inductors current (a)  $i_{L11}$  and  $i_{L20}$  in equalization for charging state (b)  $i_{L3}$  and  $i_{L17}$  in equalization for discharging state

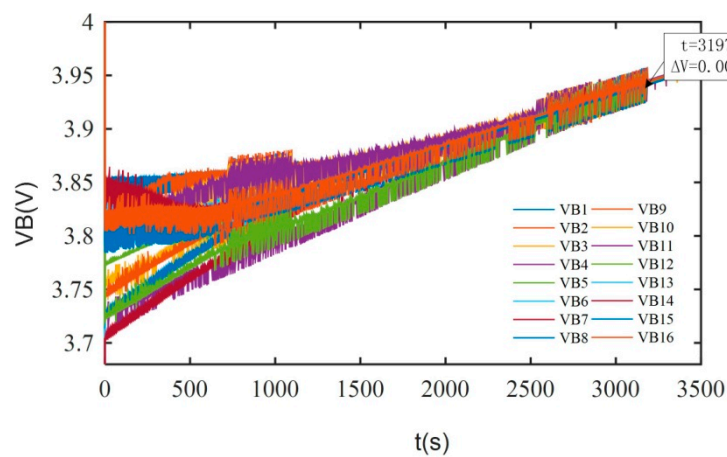
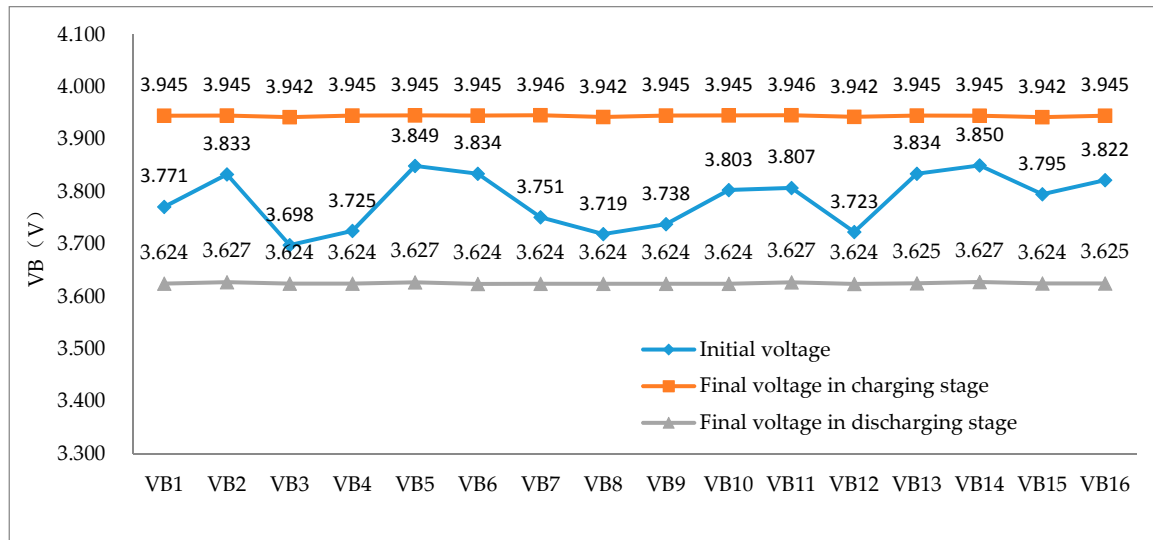


Figure 14. 16 cells voltage trajectories in equalization during charging process.

Figure 14 shows the 16 cells voltage trajectories in equalization during charging process. The initial voltage gap shown in table 1 is 152mV, and it decreases to 3mV at about 3197s.

Table 3 presents 16 cells voltage before and after equalization in charging and discharging state.

Table 3. 16cells voltage before and after equalization in charging and discharging state



## 5.2 Equalization for discharging state

In discharging process, the discharging resistor is 150Ω. The balancing sub-circuits *S3*, *S8*, *S12*, *S15* and *E1* operate in the beginning. Figure 13 (b) presents the experimental waveforms of inductors current  $i_{L3}$  and  $i_{L17}$ . The duty cycle of PWM is 24%. The inductor current is discontinuous and varies in saw-tooth waveform. The peak value of  $i_{L3}$  comes to 1.8A, and the peak value of  $i_{L17}$  is 1.9A.

Figure 15 shows the 16 cells voltage trajectories in equalization during discharging process. The initial voltage gap shown in table 1 is 152mV, and it decreases to 3mV at about 3098s. The final voltages of 16 cells after equalization are shown in table 3.

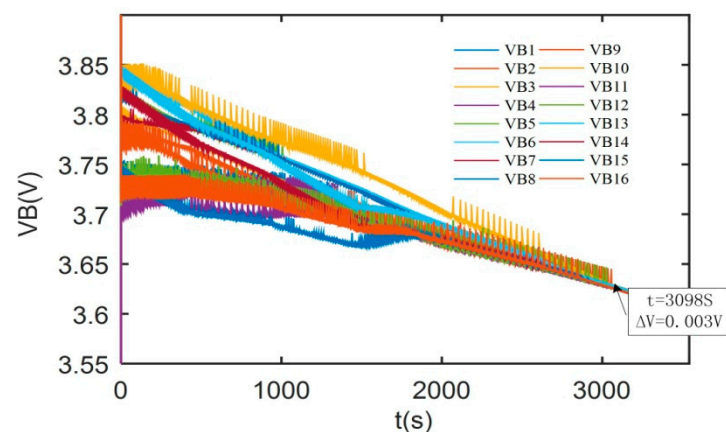


Figure 15. 16 cells voltage trajectories in equalization for discharging state

## 6. Conclusion

In this paper, a novel inductor-based layered bidirectional equalizer for series connected battery strings is proposed. The equalization principle, modeling of balancing current, the 16 cells-balancing performance and the comparative studies are presented. Adjusting the product  $f^*L$



of switching frequency and inductance can achieve the different levels of balancing current and balancing speed. Comparative simulations with two typical inductor-based equalizers (IBAE and SSIE) are implemented. The proposed equalizer reduces the balancing time by 31.4% compared with the IBAE and reduces the balancing time by 72% compared with SSIE. The simulation and experimental results show that the proposed equalizer can decrease the charging current of higher voltage cells during charging process and reduce the discharging current of lower voltage cells during discharging process; the equalizer can transfer energy from higher voltage cells to the lower voltage cells in the idle period after charging or discharging. Moreover, the layered balancing circuits extend the balancing path and increase the balancing current, which allow fast and active equalization especially for a long battery string. As a future work, the proposed topology will be used in battery strings in energy storage and EVs.

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**Conflicts of Interest:** The authors declare no conflicts of interest.

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