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2 **Validation of Airborne Sensor Photogrammetric Digital** 3 **Terrain and Global Digital Elevation Models around Mekelle** 4 **City, Ethiopia**

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12 **Abstract:** The quality of photogrammetric-based derived products like orthophotos, digital terrain
13 models (DTMs) and digital line maps as well as the global digital elevation models (DEM) are
14 rigorously dependent on the accuracy of image orientation. This paper evaluates the vertical accuracy
15 of aerial photogrammetric Digital Terrain Model (DTM), Shuttle Radar Topography Mission (SRTM),
16 Advanced Spaceborne Thermal Emission and Reflectance Radiometer (ASTER) and TerraSAR-X's
17 twin satellite of TanDEM-X (TDX) datasets against *in-situ* orthometric heights computed from
18 ellipsoidal heights and the 2008 Earth Gravitational Model (EGM2008) derived geoid heights in
19 Ethiopia. The quality of the four global digital elevation models was also validated against the aerial
20 photogrammetric DTM measurements. Besides, the accuracies of the photogrammetric DTM and the
21 four DEM products were checked for their compliance to the American Society for Photogrammetry
22 and Remote Sensing (ASPRS) standards as well as the Ethiopian national vertical data evaluation
23 standards. The study showed that the photogrammetric DTM is in a good agreement with the
24 reference orthometric heights compared to SRTM, ASTER and TDX datasets. More precisely, the
25 result has an absolute accuracy of 1.67 m at Linear Error (LE) 95% confidence level, while the absolute
26 accuracy of SRTM3 arc seconds (SRTM3) at LE 90% (11.91 m) is better than its product specification
27 (16 m). The absolute accuracy of SRTM1 arc second (SRTM1) (7.70 m at LE 90%) surpasses that of
28 SRTM3, whereas the absolute accuracy of ASTER DEM is somehow below its product specification.
29 TDX also has the same vertical accuracy (10.29 m at LE 90%) compared to its product specification
30 (10 m). Furthermore, the vertical accuracy of the photogrammetric DTM meets the 100 cm vertical
31 accuracy of the 2015 ASPRS standard. However, it does not meet the Ethiopian national vertical data
32 accuracy requirement standard, i.e., RMSEz of ± 0.45 m. In general, the photogrammetric DTM,
33 SRTM1 and TDX have been proven a superior product over the SRTM3 and ASTER DEMs, and better
34 to use these products for high-level precision and accuracy required applications.

35 **Keywords:** vertical accuracy; photogrammetric DTM; ASTER; SRTM; TanDEM-X; orthometric
36 height; geoid height

37 **1. Introduction**

38 A Digital Elevation Model (DEM) represents the deviation of the Earth's topography from the
39 global equipotential surface of the Earth that best fits to open oceans and seas, usually called the
40 geoid. Globally, the departure of the Earth's topographic surface (land surface only) and the geoid
41 varies between -418 m at the Dead Sea to 8,848 m at the summit of Mount Everest in Nepal, with a
42 mean value of 840 m. A DEM is realized by measuring the height of the ground points on the actual
43 topographic surface above or below the geoid [1-3]. With the advent of satellite technology, practical
44 computation of the DEM involves two independent measurements: the ellipsoidal heights of the

45 Earth's surface with respect to the 1984 World Geodetic System (WGS84) reference ellipsoid, and the
46 geoid heights (i.e., the vertical separation between the geoid and the WGS84 reference ellipsoid).
47 Today, ellipsoidal heights of the Earth's surface can be determined using satellite positioning system
48 based on navigation satellites, or from radar and stereoscopic photogrammetric remote sensing
49 techniques integrated with the satellite's own positioning system [4, 5]. On the other hand, the geoid
50 can be directly computed from a global gravity model, preferably refined using detailed local gravity
51 data [6-8]. Subtracting the geoid height from the ellipsoidal height gives a vertical distance above the
52 geoid called an orthometric height. A regular grid of orthometric heights defines a DEM. The
53 integration of satellite remote sensing or photogrammetric techniques with navigation satellite
54 positioning and the geoid can now provide a high resolution DEM accurate to within meter to
55 decimeter level. High resolution DEMs are an important data source particularly in regions that are
56 devoid of detailed topographic maps. The DEM products are important in determining
57 geomorphological parameters (e.g. slopes, curvature, terrain roughness and aspects) that are
58 essential for various applications in the geosciences, the environmental sciences and the spatial
59 sciences [9]. It is also very instrumental for studying glacial geomorphology and ice-sheet
60 reconstruction [10], volcano [11,12], landslides [13-16], seismicity [17], gravity field modelling [10,18-
61 21], ecological modelling [22], hydrological modeling [23], watershed management [24], floodplain
62 delineating and mapping [25], cadaster and land use planning [26], land suitability assessment for
63 agriculture and other developmental economic infrastructures [27].

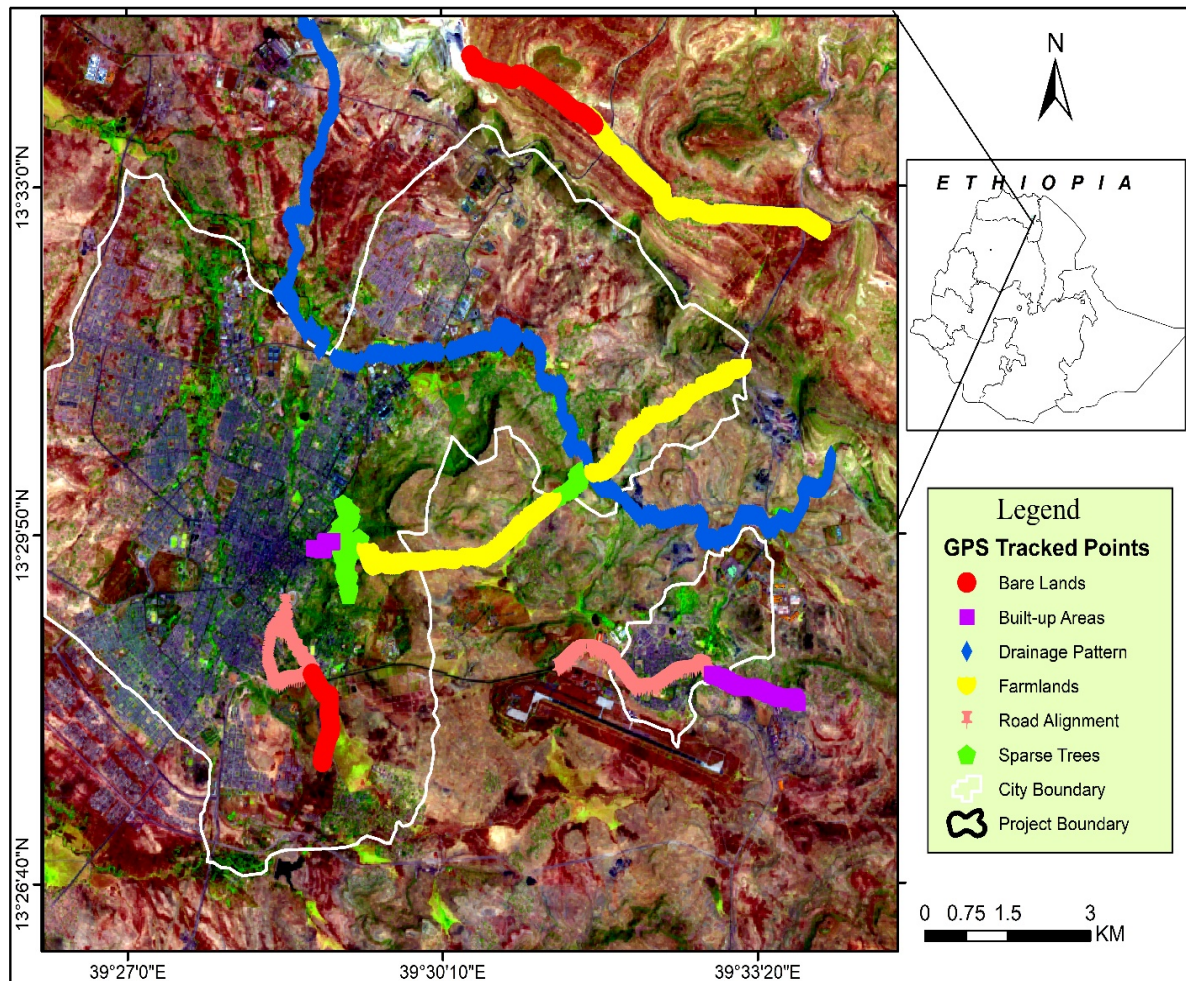
64 To realize these various applications, the DEMs are expected to have good accuracy and high
65 resolution. Thus, it is necessary to evaluate the level of accuracy of the DEMs prior to their practical
66 utilization. Based on their accuracy levels, DEMs shall be used in compliance with well-adopted
67 mapping standards such as those of the American Society for Photogrammetry and Remote Sensing
68 (ASPRS). In this connection, various elevation model products such as DEM derived from
69 Interferometric Synthetic Aperture Radar (InSAR) based global elevation models (i.e., ASTER, SRTM
70 and TDX [25, 28-34] and photogrammetric derived DEMs [11, 35] have been assessed to qualify their
71 accuracies before using for different applications.

72 This study intends to contribute to a continued global scientific endeavor in assessing the quality
73 of photogrammetric DTM and the four global DEMs. The specific aim of the paper is to evaluate the
74 accuracy of the photogrammetric DTM and the four global DEMs (two SRTMs, ASTER and TDX)
75 against *in-situ* orthometric heights derived from EGM2008 geoid heights and Real-Time-Kinematic
76 based Global Navigation Satellite System (GNSS) measurements in the surroundings of Mekelle city
77 (Northern Ethiopia). Besides, the quality of the four global digital elevation models were validated
78 against the aerial photogrammetric DTM measurements.

79 2. Materials and Methods

80 2.1. Site Description

81 The study area is located in the northern part of Ethiopia, particularly in the surroundings of
82 Mekelle and Qwiha Towns. The case study site located on the Nubian plate, approximately 780 km
83 (ground geodesic distance) from Addis Ababa. Geographically, the study area is bounded between
84 13° 25' 54" and 13° 35' 50" north latitudes and 39° 26' 10" and 39° 35' 6" east longitudes (Figure 1). The
85 landmass of the study area was formed as a part of widespread continental transgression from the
86 east to south that took place from Triassic to Cretaceous. Generally, the study area is characterized
87 by extremely undulating topography. The southern, south eastern, eastern and northeastern parts
88 are defined by highly elevated mountains with extremely rugged terrain. The central low-lying,
89 southwestern and western part of the area is almost flat, while the western part is dissected terrain.
90 In particular, the low-lying central depression and western regions are mostly characterized by river
91 systems that drain from SSE plateaus to NNW lowlands, and the drainage networks dominate the
92 northwestern part of the area. More specifically, the local topography varies from 1969.4 to 2410.6 m
93 with respect to the EGM2008 geoid model as inferred from aerial photogrammetric measurements
94 and the gradient of the local topography ranges from 0° to 60% (Figure 3).



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Figure 1. Location map of the study area. N.B: The background data is the false color composite of Sentinel-2A image, which was acquired in March 2020. Besides, GNSS Tracked Points were collected across six profiles. In this connection, Profile 1 represents sparse trees; Profile 2 represents Road alignment; Profile 3 represents Drainage pattern; Profile 4 represents Farmlands; Profile 5 represents Built-up areas and Profile 6 represents Bare lands.

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2.2. Data Sources

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2.2.1. Photogrammetric DTM

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We used an aerial photogrammetric DTM that has 10 m spatial resolution. These aerial photographs were acquired by the Ethiopian Information Network Security Agency (INSA) in April 2016 (Table 1). The aerial survey was performed as part of the rural land parcel registration and good land governance mission in Ethiopia. A high quality Charge Coupled Device (CCD) UltraCam Eagle camera with panchromatic, Red-Green-Blue (RGB) and Near-Infrared (NI) spectral bands was used to acquire aerial photos with Ground Sample Distance of 25 cm. The aerial photos were acquired at a nominal flight height of 2845 m above the Alexandria Mean Sea Level (AMSL) along six strips with 70% forward overlap and 30% side overlap. Aerial photos were processed with a tie to onboard aircraft navigation and attitude data as well as with reference to 4 Ground Control Points (GCPs). The GCPs (North, East and Up-coordinates of the checkpoints) were established with static GNSS observations taken for a session of 72 hours. Thus, using these aerial photographs, a very high resolution DTM was generated.

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117 **Table 1.** Detailed characteristics of input dataset used for DEM products evaluation.

Dataset	Resolution	Source
Photogrammetric DTM	10 m	INSA
Shuttle Radar Topography Mission (SRTM1)	1 arc second (~30 m)	http://earthexplorer.usgs.gov
Shuttle Radar Topography Mission (SRTM3)	3 arc seconds (~90 m)	http://earthexplorer.usgs.gov
Advanced Spaceborne Thermal Emission and Reflection Radiometer (ASTER)	3 arc seconds (~30 m)	http://earthexplorer.usgs.gov
TerraSAR-X's twin satellite (TDX)	3 arc seconds (~90 m)	https://tandemx-science.dlr.de
Validation Kinematic GPS tracked data collected across different land use and terrain features	Profile Point Data	Field Measurement

118 2.2.2. SRTM DEMs

119 In this study, we also used SRTM1 and SRTM3 DEMs. The SRTMv2.1 interferometric radar
 120 payload has collected elevation data covering almost 80% of the Earth's surface between 60°N and 54°S
 121 during its 11-days mission in February 2000. This DEM is relatively low spatial resolution of 3 arc
 122 seconds (~90 m) in the rest of the world outside of USA [36]. The DEM is defined in geographic datum
 123 with a tie to WGS84 for horizontal coordinates (latitude and longitude) and the EGM1996 geoid model
 124 for elevation or orthometric height. The final product of the DEM is reported to have an absolute vertical
 125 accuracy of ± 16 m and horizontal accuracy of ± 20 m at a 90% confidence level [37]. The second DEM
 126 is SRTMv3.0 (SRTM1) obtained by filling the data gaps in the SRTM DEM with elevations acquired
 127 from the USGS's Global Multi-resolution Terrain Elevation Datasets[38].

128 2.2.3. ASTER DEM

129 The other DEM used in this study is ASTER version 2, which was released for public use in October
 130 2011 and has a spatial resolution of 30 m. ASTER DEM is acquired from NASA Terra Satellite. With
 131 regard to accuracy, ASTER has an absolute vertical accuracy of 17 m at 95% confidence level [30]. The
 132 Terra Satellite has acquired elevation data across the landmass between 83° N and 83° S using
 133 correlation between stereo pair images acquired with 15 m spatial resolution from the visible and near
 134 infrared (VNIR) bands.

135 2.2.4. TanDEM-X

136 The German TDX 90 m DEM is the fourth global DEM product used in this study. As Wessel [39]
 137 clearly summarized, the German TDX 90 m DEM is acquired using Earth observation radar mission
 138 that consists of a SAR interferometer made up of two almost identical satellites flying in close formation
 139 for comparative analysis. The corresponding pairs of the TDX images were acquired by the twin
 140 satellites TerraSAR-X and TDX, which fly in a close helix formation with distances between 300 and 500
 141 m of each other to generate highly accurate global DEM with complete global coverage.

142 2.2.5. Real time Kinematic GPS tracked Datasets

143 For validating the different DEMs datasets, the study also used ground truth ellipsoidal heights,
 144 which were acquired from *in-situ* based real time Kinematic GPS tracks. Based on the base map
 145 prepared using satellite imagery, six major land use/land cover classes (profiles) were identified.
 146 Accordingly, the validation points were collected along these six major different land cover classes
 147 (profiles) representing sparse trees (Profile 1); road alignment (Profile 2); drainage pattern (Profile 3);
 148 farmlands (Profile 4); built-up areas (Profile 5) and bare lands (Profile 6) (Figures 1 and 3 and Table 2).

149 **Table 2:** Operational description of land use/land cover classes considered in this study.

Profiles	classes	Descriptions	GNSS Tracked points
Profile 1	Sparse Trees	These are group of trees interspersed with bare ground and low growing ground cover.	226 points
Profile 2	Road	This refers to a long or narrow stretch with a smoothed or paved surface made for traveling by motor vehicle.	272 points
Profile 3	Drainage pattern	These features are representing small rivers and streams courses in the study area.	660 points
Profile 4	Farmland	This is a portion of land surface used for crop cultivation or capable of being cultivated.	651 points
Profile 5	Built-up area	They are features including towns, small concentrated villages roofed with corrugated iron sheet and different infrastructures.	87 points
Profile 6	Bare land	A land with limited ability to support life and it is an area of thin soil, sand, or rocks.	234 points

150 In this regard, Geodetic Leica receivers were used for determining position coordinates for each
 151 field point. In total, 2130 ellipsoidal heights were collected across the study area during a field campaign
 152 in April 2017 (Tables 1 and 2). In essence, RTK-based ellipsoidal heights can capture accurate
 153 topographic information (~3-5 cm) and their transformation to orthometric height maintains high
 154 accuracy up to a few centimeters (~6-10 cm), the error in the EGM2008 geoid model over Ethiopia was
 155 estimated to vary between 3 and 5 cm [6]. This makes an *in-situ* ellipsoidal heights combined with
 156 EGM2008 geoid heights a standard reference for validating the accuracy of aerial photogrammetric and
 157 satellite-based DEM products.

158 2.3. Methods

159 The geometric accuracies of aerial images were evaluated by reducing uncertainty of the exterior
 160 orientation parameters through utilizing accurate Ground Control Points (GCPs) and attitude of aircraft
 161 in a block adjustment computation of aerial triangulation. We used 4 GCPs and 5 check-points in order
 162 to ensure the production of high quality photogrammetric measurements. GCPs were established using
 163 static Differential Global Navigation Satellite Systems (DGNSS) geodetic positioning using dual-
 164 frequency receivers. In essence, 3 GCPs are suffice to perform exterior orientation that transform images
 165 (defined in a camera coordinate system) to geodetic coordinate system. In the study area, the GCPs and
 166 checkpoints were designed in such a way that they tie overlapping aerial photos to ensure the overall
 167 quality of the photogrammetric measurements. Datasets from on-board GNSS and Inertial
 168 Measurement Unit were used to establish the absolute positions and orientations of each aerial photo
 169 in a block adjustment computation. After the direct georeferencing computation, the GCPs were used
 170 to adjust the final solution, while the checkpoints were used to evaluate the accuracy of triangulated
 171 images.

172 Finally, the vertical accuracies of photogrammetric DTM, ASTER, TDX, SRTM1 and SRTM3
 173 products were evaluated against the 2130 ground-based RTK GNSS measurements. Comparison was

174 made in terms of orthometric height, as it is a physical height system that can define level surfaces on
 175 the Earth's topography. In order to perform statistical comparison between elevation models and
 176 ground truth data, RTK GNSS based ellipsoidal heights were transformed to orthometric heights
 177 defined with reference to the EGM2008 geoid model. The five DEMs were adjusted to this geoid model
 178 to ensure statistical comparison among them.

179 2.3.1. Processing of the Photogrammetric DTM

180 The DTM was computed from aerial images using rigorous photogrammetric data reduction steps
 181 built into "Inpho DTMaster Version 7.0 software" [40]. The initial phase requires input of camera
 182 calibration parameters, flight information and aerial images. The second phase determines Exterior
 183 Orientation (EO) parameters from the onboard GPS-based camera position coordinates; Inertial
 184 Measurement Unit (IMU) derived from camera attitude (yaw, pitch, roll) and GCPs. The final phase
 185 employs a rigorous least-squares adjustment technique to compute EO parameters. Later, a regular grid
 186 of DEM was synthesized from a 3D point cloud data obtained from least-squares adjusted data.
 187 Furthermore, a DTM was generated at a spatial resolution of 10 m by removing natural and artificial
 188 features from the DEM. In this case, we edited and corrected height errors of the digging points
 189 (underestimated heights), floating points (overestimated heights), misrepresentation of terrain features
 190 such as gorges and rivers due to shadow on aerial photos, and height data of primary surfaces such as
 191 building and vegetation. This makes our photogrammetric DTM unique compared to the global DEMs
 192 that contain height errors corresponding to the primary surfaces such as built-up and vegetated areas.

193 2.3.2. Datum Transformation and Adjustment

194 Using a more accurate vertical datum is a prime importance to maintain the original vertical
 195 accuracy of the elevation models. In our case study, all the DEMs are defined with respect to the WGS84
 196 horizontal datum. In doing so, the photogrammetric DTM was transformed from the Clarke1880
 197 ellipsoid (Adindan Datum) to WGS84 using the following translational equation:

$$198 \quad D_x = -162 \text{ m}, D_y = -12 \text{ m}, D_z = 206 \text{ m} \quad (\text{Eq. 1})$$

199 With regard to vertical datum adjustment, all the elevation models are redefined with a tie to the
 200 EGM2008 geoid model. This involves the task of reducing SRTM and ASTER elevation datasets from
 201 the EGM1996 geoid to the EGM2008 geoid as well as reduction of TDX ellipsoidal heights from WGS84
 202 to the EGM2008 geoid. In practice, the reduction of SRTM and ASTER to the EGM2008 geoid will
 203 eliminate inherent errors in the EGM1996 geoid heights that reach from 0.5 to 1.0 m globally [41]. The
 204 EGM2008 geoid heights recover features from 40,000 km down to 18 km wavelengths, corresponding
 205 to a spatial resolution of 9 km and an accuracy of 15 cm globally [42]. In the territory of Ethiopia, the
 206 EGM2008 geoid model incorporates a detailed local airborne gravity data and it has better accuracy
 207 (~3.9 cm) compared to its global error budget [10]. In practice, it is highly recommended to reduce the
 208 DEMs to a more accurate vertical datum like the EGM2008 geoid in order to ensure effective utilization
 209 of the datasets for various applications.

210 The reduction of SRTM and ASTER to the EGM2008 geoid model involves a two-stage
 211 computation. The first phase synthesizes geoid heights from the spherical harmonic coefficients of the
 212 1996 Earth Gravity Model (EGM1996). EGM1996 geoid heights representing features with a spatial
 213 resolution of 55 km [43] are then added to SRTM and ASTER orthometric heights to give SRTM and
 214 ASTER-based ellipsoidal heights above WGS1984 (Equation 2).

$$215 \quad h_{\text{WGS84}} = H_{\text{egm96}} + N_{\text{egm96}} \quad (\text{Eq. 2})$$

216 Equation 3 gives the fundamental formula for computing the geoid using spherical harmonic
 217 synthesis. Various theories of geoid computation can be obtained from many literature sources [10, 44,
 218 45].

$$219 \quad N(\vartheta, \lambda) = \frac{GM}{a\gamma} \sum_{n=0}^N \left(\frac{a}{R(\vartheta)} \right)^{n+1} \sum_{m=0}^n (c_n^m \cos m\lambda + s_n^m \sin m\lambda) P_n^m(\cos\vartheta) \quad (\text{Eq. 3})$$

220 Where, G is Newton's Universal Gravitation constant; M is mass of the Earth; a is semi-major axis of the reference
 221 ellipsoid; ϑ is the geocentric colatitude; R is mean earth radius as a function of geocentric co-latitude; n is degree
 222 of spherical harmonics; m is order of spherical harmonics; λ is longitude; R is geocentric distance; $P_n^m(\cos\vartheta)$ is
 223 Associated Legendre function, γ is a mean normal gravity on the reference ellipsoid.

224 The second phase subtracts EGM2008 geoid heights from ellipsoidal heights as computed in
 225 equation 3 to give SRTM or ASTER derived orthometric heights that are defined with reference to the
 226 EGM2008 geoid model. Similarly, TDX was also reduced to EGM2008 geoid using Equation 4.

$$227 \quad H_{\text{egm2008}} = h_{\text{WGS84}} - N_{\text{egm2008}} \quad (\text{Eq. 4})$$

228 On the other hand, the photogrammetric DTM was originally defined with respect to leveled
 229 height that was in turn defined with a tie to a historical tide gauge station located at the Port of
 230 Alexandria; via the Blue Nile first order geodetic leveling project. The second order geodetic control
 231 point derived from the Blue Nile first order geodetic leveling network was used as a vertical reference
 232 height for defining orthometric heights of the photogrammetric DTM in the study area via static DGNS
 233 ellipsoidal heights of the Ground Control Points. This approach assumes constant vertical distance
 234 offset between WGS84 and the AMSL leveling datum-it ignores noticeable vertical separation between
 235 the geoid and the AMSL. In order to properly redefine the photogrammetric DTM rigorously from the
 236 AMSL to the EGM2008 geoid we first computed the difference between the ellipsoidal height of the
 237 second order geodetic control point (latitude 13.523958° N, longitude 39.553053° E, ellipsoidal height
 238 2348.088 m, the AMSL height 2348.572 m) and the leveled height. This gives a vertical distance
 239 separation of -0.484 m between the AMSL datum at the Port of Alexander as computed from the second
 240 order geodetic control point and the WGS84 reference ellipsoid. The negative sign indicates that the
 241 AMSL is below the reference ellipsoid as well as it is above the EGM2008 geoid by 0.323 m.

242 Adding the vertical distance separation between the WGS84 and the AMSL (-0.484 m) to the
 243 leveled heights of the photogrammetric DTM that was initially determined with a tie to the AMSL
 244 reduces the DTM to the WGS84. In this stage, the photogrammetric DTM is defined in terms of
 245 ellipsoidal heights. The last stage, re-defined the ellipsoidal heights of the photogrammetric DTM to the
 246 EGM2008 geoid model by subtracting the geoid heights from it. This rigorous adjustment applied to
 247 the photogrammetric DTM allowed us to recover vertical distance separation of 0.323 m between the
 248 EGM2008 geoid and the AMSL as well as recovered unmodeled geoid undulations that were initially
 249 ignored in the computed DTM defined with reference to the AMSL. The modeled local variation of the
 250 EGM2008 geoid heights across the study area varies from -1.162 to -0.618 m with a mean and standard
 251 deviation of -0.944 m and 0.122 m, respectively. After the photogrammetric DTM data is adjusted to
 252 the EGM2008 geoid, EGM2008 geoid heights were subtracted from RTK-GNSS based ellipsoidal heights
 253 to give consistent orthometric heights that serve as ground truth data for evaluating the accuracies of
 254 the elevation models.

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257 2.3.3. Vertical Accuracy Assessment

258 Although different interpolation techniques and algorithms are available, the DEM products were
 259 compared with one another using bicubic interpolation technique [46]. This is because as argued by
 260 Ghandehari et al. [47], bi-cubic interpolation technique is much suitable in recovering the sub-pixel
 261 variations of elevation of a reference in-situ random points that will be located at an off-centroid of
 262 pixels specifically in rugged terrain. First, the five DEMs (the Photogrammetric DTM, SRTM1, SRTM3,
 263 ASTER and TDX) were compared against RTK-GNSS based ground truth data. Comparison was made
 264 along six height profiles representing the different land use and land cover types and the complex
 265 topographic nature of the area (Tables 5 and 6). Secondly, a pixel-by-pixel based statistical comparison
 266 was made between the SRTM1, SRTM3, ASTER and TDX DEMs products against the high-resolution
 267 photogrammetric DTM data. More specifically, a vertical accuracy assessment was made in terms of
 268 statistical minimum, maximum, mean difference (bias), standard deviation, RMSE and Linear Error at
 269 95% confidence interval (Equations 5-9). Finally, accuracies of the elevation models were examined
 270 against the ASPRS 2013 and 2015 standards [48, 49] and the Ethiopian standards and directives.

$$271 \quad \text{bias} = \frac{\sum_{i=1}^n (H_i^{\text{GPS}} - H_i^{\text{DEM}})}{n} \quad (5)$$

$$272 \quad \sigma = \sqrt{\frac{1}{n-1} \sum_{i=1}^n (H_i - H)^2} \quad (6)$$

$$273 \quad \text{RMSE} = \sqrt{\frac{n-1}{n} \sigma^2 + \text{bias}^2} \quad (7)$$

$$274 \quad \text{LE } 90\% = 1.6449 \times \text{RMSE} \quad (8)$$

$$275 \quad \text{LE } 95\% = 1.96 \times \text{RMSE} \quad (9)$$

276 Where bias is mean difference, σ is standard deviation, RMSE is root mean square error, LE 90%
 277 is Linear Error (LE) at 90% two-sided confidence level and LE 95% is Linear Error at 95% two-sided
 278 confidence level.

279 3. Results

280 3.1. Vertical Accuracy of Photogrammetric Measurements

281 The qualities of the photogrammetric DTM as well as the performance of the other four global
 282 DEMs (two SRTMs, ASTER and TDX) against GPS derived orthometric height are analyzed and
 283 presented. The output of the processed aerial photographs showed that the geometric accuracy of aerial
 284 photos is improved by reducing uncertainty in exterior orientation parameters through utilizing
 285 accurate Ground Control Points (GCPs) and attitude of aircraft in a block adjustment computation of
 286 aerial triangulation. The results of the block adjustment corrections from the GCPs were 0.021 m, 0.006
 287 m and 0.008 m, respectively, in the north, east and up-coordinates in terms of root mean square error
 288 (RMSE). The final photogrammetric datasets subjected to correction from the GCPs were accurate to
 289 decimeter level (as evaluated at 5 check points). The computed RMSE values are 0.537 m, 0.394 m and
 290 0.227 m, respectively, in the north, east and up-coordinates.

291 3.2. Point-based Validation of DEMs

292 In this section, we presented the output of point-based accuracy of a photogrammetrically derived
 293 DTM, 1 arc second and 3 arc seconds SRTM, ASTER and TDX DEM products against in-situ orthometric
 294 heights computed from EGM2008 geoid model and GNSS based ellipsoidal heights. Orthometric height
 295 is estimated from the five elevation models at the GNSS measurement points, and Table 3 presents the
 296 vertical accuracies of the five DEMs against orthometric heights derived from in-situ RTK GNSS tracked
 297 datasets and EGM2008 geoid model. The residuals between the orthometric heights (collected along six

298 GNSS height profiles) and five elevation models showed the relative accuracies of the models. Generally,
 299 the photogrammetric DTM agrees well with the ground truth reference datasets compared to ASTER,
 300 SRTM1, SRTM3 and TDX. The computed value of the photogrammetric DTM confirmed that it has the
 301 lowest RMSE (0.85 m); overestimating the ground truth heights with a bias of 0.69 m.

302 **Table 3.** Orthometric height difference between GNSS (H)-based orthometric height and five elevation models
 303 including A, S1, S3, P and TDX with reference to the 2008 geoid model (using 2130 point values, unit: m).

DEMs	Statistics				
	Mean	Stdev	RMSE	Min	Max
H	2213.32	137.36		1969.24	2409.57
A	2211.41	132.54		1957.35	2405.92
S3	2218.18	136.28		1969.51	2411.23
P	2214.01	137.45		1969.4	2410.62
S1	2214.62	135.95		1968.17	2410.40
TDX	2213.59	135.39		1969.57	2408.90
A – H	-1.91	14.65	14.77	-48.23	64.52
S3 – H	4.85	5.38	7.24	-25.97	33.37
S1 – H	3.45	3.16	4.68	-9.13	21.91
P – H	0.69	0.51	0.85	-2.24	5.28
TDX – H	1.30	6.12	6.26	-23.91	43.51

304 Legend: H = GNSS height values; A = ASTER DEM; P = Photogrammetric DTM; S3 = SRTM3 arc seconds; S1 =
 305 SRTM1 arc seconds; and TDX=TanDEM-X.

306 Similarly, the SRTM3 DEM agrees with the ground truth reference data compared to ASTER DEM
 307 (RMSE 14.77 m). The SRTM3 DEM has a RMSE of 7.24 m, while the vertical accuracy of the SRTM1
 308 DEM (RMSE of 4.68 m) exceeds that of ASTER (14.77m), SRTM3 (7.24 m) and TDX (6.26 m). In the study
 309 area, TDX is the second most accurate global DEMs next to SRTM1. It has better vertical accuracy than
 310 ASTER and SRTM3. The TDX DEM has a RMSE of 6.26 m when compared to the in-situ orthometric
 311 height computed from GNSS ellipsoidal height and EGM2008 geoid height. In general, SRTM1, SRTM3,
 312 ASTER DEM, TDX and the photogrammetric DTM statistically and systematically deviate from ground
 313 truth GNSS-based tracked points by 3.45 m, 4.85 m and -1.91 m, 1.30 m, and 0.69 m, in the same order.
 314 The statistical analysis in reference to *in-situ* data indicates highest performance of the photogrammetric
 315 DTM compared to SRTM1 and SRTM3, ASTER and TDX. In this regard, however, the photogrammetric
 316 DTM, the two SRTM models, and TDX overestimate the heights, while the ASTER DEM underestimates
 317 the elevation values (Table 3). In addition, in more practical terms, Table 4 shows the absolute vertical
 318 accuracy of the photogrammetric DTM and the four digital elevation models used in this study. In
 319 reference to in-situ orthometric heights, the absolute vertical accuracy of the photogrammetric DTM
 320 (1.67 m at LE 95%) is almost an order of magnitude better than that of TDX, SRTM3 and ASTER DEMs.
 321 With a better statistical rigorous and geographic completeness, the absolute vertical accuracies of the
 322 TDX, SRTM1 and SRTM3 in relation to the photogrammetric DTM perform better than their respective
 323 product specification accuracies. In contrast, the absolute vertical accuracy of the ASTER DEM does not
 324 meet its product specification accuracy in the study area.

325

326 **Table 4. A)** Linear error of the elevation models in reference to orthometric height derived from RTK GNSS
 327 ellipsoidal heights and EGM2008 geoid and **B)** Linear error of the global elevation models in reference to
 328 photogrammetric DTM at 95% and 90% confidence level (LE 95%=1.96x RMSEz, LE 90%=1.6449x RMSEz). LE are
 329 estimated according to the NSSDA and NAMS standards.

Elevation data	A) linear error of the elevation models in reference to RTK GNSS ellipsoidal heights		B) Linear error of the elevation models in reference to photogrammetric DTM	
	NSSDA (95%)	NAMS (90%)	NSSDA (95%)	NAMS (90%)
P	1.67	1.40	-	-
A	28.95	24.30	24.11	20.23
S1	9.17	7.70	5.86	4.92
S3	14.19	11.91	9.13	7.67
TDX	12.26	10.29	4.46	3.74

330 NB: Refer to the abbreviations in Tables 3.

331 3.3. Grid-based Comparison of the Global Elevation Models against Photogrammetric DTM

332 Vertical accuracies of the four global elevation models were presented in relation to that of the local
 333 photogrammetric DTM. Height differences between the elevation models were statistically analyzed on
 334 a pixel-by-pixel basis. Prior to grid based accuracy evaluation, SRTM1, ASTER and photogrammetric
 335 DTM were re-sampled to 90 m resolution (cell size) using bicubic interpolation techniques to make them
 336 consistent with the 90 m spatial resolution of SRTM3 and TDX [50]. In connection to this, the residual
 337 orthometric heights between the reference elevations model (derived from ultra-high resolution of re-
 338 sampled photogrammetric DTM) and re-sampled SRTM1 and ASTER, as well as the SRTM3 and
 339 TanDEN-X 90m are presented in Table 5.

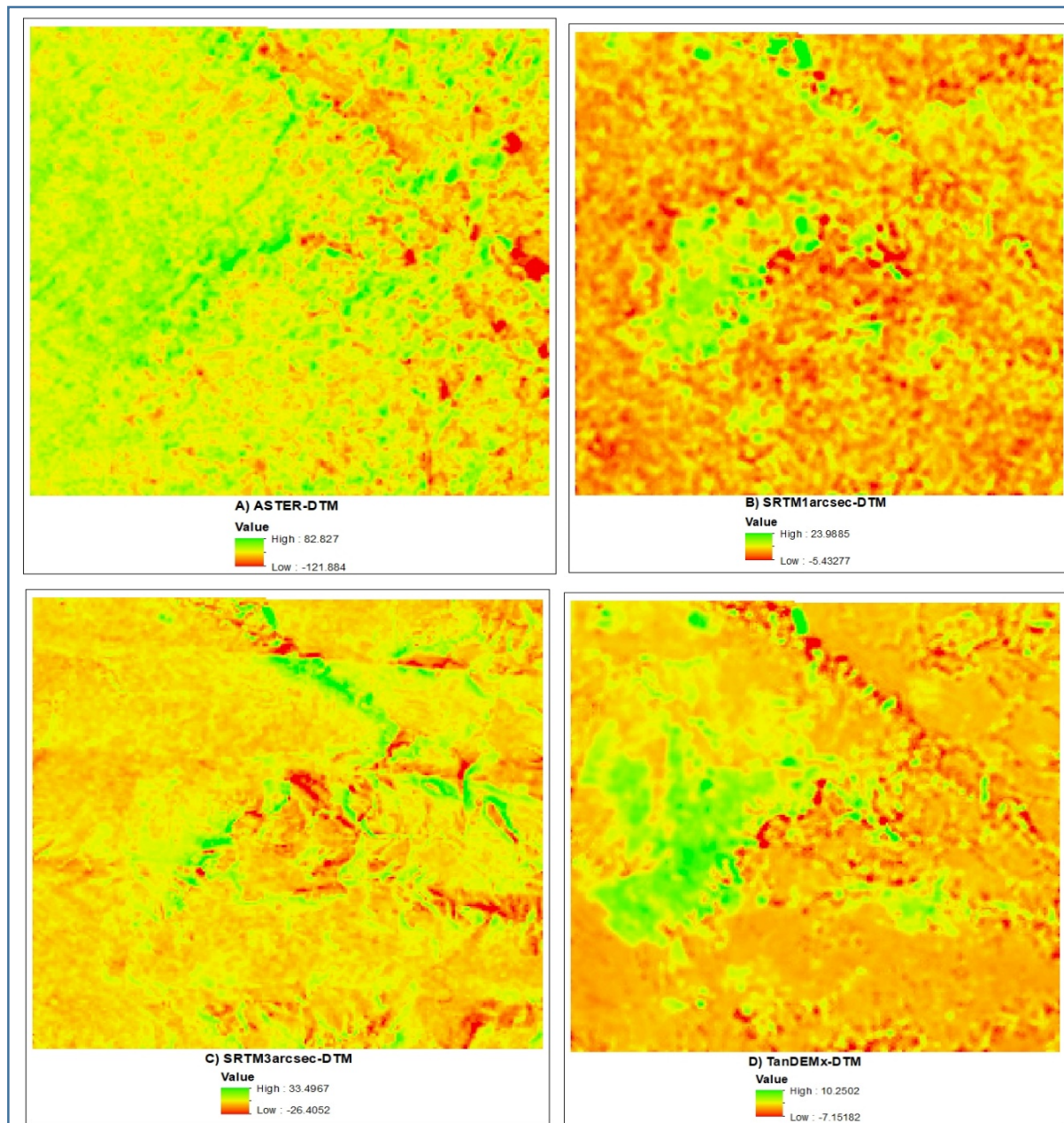
340 **Table 5.** Orthometric height differences between photogrammetric DTM and the four global elevation models with
 341 reference to the 2008 geoid model (using 36,000 point values), unit: m.

DEMs	Statistics				
	Mean	Stdev	RMSE	Min	Max
P	2179.16	135.22	-	1905.23	2516.33
A	2176.03	132.98	-	1890.27	2530.64
S3	2180.91	135.24	-	1907.38	2515.71
S1	2180.65	135.14	-	1905.53	2516.69
TDX	2178.27	134.88	-	1906.13	2513.62
A – P	-3.13	11.90	12.30	-149.35	110.65
S3 – P	1.75	4.32	4.66	-48.78	55.06
S1 – P	1.49	2.59	2.99	-34.69	46.5
TDX – P	-0.89	2.09	2.28	-34.20	34.95

342 NB: Refer to the abbreviations in Table 3.

343 The statistics in Table 5 are showing the difference among the four elevation models against the
 344 photogrammetric derived DTM. Our results indicated that a very good agreement is observed between
 345 photogrammetric DTM and TDX; and their difference has a RMSE of 2.28 m and bias of -0.89 m. In
 346 addition, the two SRTM elevation models have good agreement with the photogrammetric DTM. The

347 SRTM1 has a RMSE of 2.99 m and bias of 1.49 m, while the SRTM3 has a RMSE of 4.66 m and bias of
 348 1.75 m. On the other hand, the residuals between photogrammetric DTM and ASTER are significant
 349 across the whole study area (Figure 2). As clearly presented in Table 5, the residuals between the
 350 photogrammetric DTM and ASTER DEM have a RMSE of 12.30 m and the maximum value reaches up
 351 to -149.35 m. The residuals between the two models have a bias of -3.13 m, meaning ASTER
 352 underestimates heights compared to the photogrammetric DTM. In general, from the four global digital
 353 elevation models TDX has a very good agreement with photogrammetric DTM than other elevation
 354 models (Table 5).



385 Figure 2. (A) Presents pixel based deviation map of ASTER DEM from photogrammetric DTM (A – P); (B) presents
 386 pixel based deviation map of SRTM1 from photogrammetric DTM (S1 – P); (C) presents pixel based deviation map
 387 of SRTM3 from photogrammetric DTM (S3 – P) and (D) presents pixel based deviation map of TanDEM-X from
 388 photogrammetric DTM (TDX – P), Map (unit: m).

389 Moreover, the computed results of SRTM elevation models and TDX mimic to the
 390 photogrammetric DTM almost across highlands and low lands, situated in the central depression,
 391 northern and southern plateaus of the study site. It is also observed that the vertical accuracy of the
 392 three elevation models (SRTM1, SRTM3 and TDX) models agreed well with photogrammetric DTM
 393 across the central and northeastern parts of the study area (Figure 2), which is being characterized by
 394 extremely rugged terrain. However, this study showed significant deviation of each of the four elevation
 395 models from the photogrammetric DTM, specifically in areas that are characterized by high slopes and
 396 extremely undulating terrain (Figure 3). The differences are strongly correlated with escarpments,
 397 tributaries, dissected topography and gullies. Particularly, the differences are noticeable in north eastern,
 398 central and eastern, and southern parts of the study area (Figure 2). In these areas, the difference
 399 between the SRTM elevation models (SRTM1 and SRTM3) and photogrammetric DTM are significant,
 400 and the orthometric height values of SRTM elevation models are greater than those of photogrammetric
 401 DTM mainly along the escarpment. The reverse is true in areas that are characterized by river or
 402 drainage systems and dissected topography. This may be related to limitations of the interferometric
 403 technique to acquire accurate data over extremely rugged topography that is characterized by high
 404 slopes, and height variations.

405 3.4. Vertical Accuracy across Different Land Use and Land Cover Types

406 In theory, the accuracy of the elevation models are also sensitive to the characteristics of ground
 407 targets or land use/land cover types. In this regard, comparison was made using GNSS survey profiles
 408 (Figure 3 1 and 3) to observe how the accuracies the different digital elevation models' are sensitive to
 409 the different land use land cover types.

410 Table 6. The minimum and maximum values of the five DEMs against GNSS derived orthometric height profiles
 411 surveyed across different land use land cover types (vertical datum is geoid2008 and unit: m).

Land use Types	P	A	S3	S1	Tx	P	A	S3	S1	Tx
	Min	Min	Min	Min	Min	Max	Max	Max	Max	Max
Sparse trees	-5.28	-36.17	-29.66	-16.74	-19.85	1.72	38.56	25.97	9.06	20.03
Road alignment	-2.42	-37.36	-19.87	-17.00	-11.21	1.06	24.24	2.74	2.29	5.96
Drainage pattern	-2.8	-64.52	-33.37	-21.91	-33.13	2.24	43.04	7.26	9.23	3.13
Farm land	-2.75	-14.73	-26.19	-13.01	-12.19	1.65	48.23	20.27	5.43	16.27
Built-up areas	-1.42	-30.96	-10.81	-6.99	-3.86	0.18	16.92	8.67	2.08	5.74
Bare lands	-1.6	-16.02	-7.48	-6.64	-2.82	-0.07	33.47	1.38	1.74	1.96

412 NB: Refer to the abbreviations in Table 3 and Figure 1.

413 Accordingly, we found that the agreement between elevation models and ground truth reference
 414 datasets vary from profile to profile depending on variation in land use/land cover types. Tables 6 and
 415 7 show the quantitative comparison of the five elevation models against orthometric heights acquired
 416 along six GNSS survey profiles representing different land use and land cover types. The statistical
 417 analysis in reference to GNSS tracked dataset indicates highest performance of the photogrammetric
 418 DTM compared to SRTM1, SRTM3, ASTER and TDX. The RMSE of the SRTM1 and SRTM3, ASTER
 419 and TDX also showed noticeable variation across the six elevation profiles. The mismatch between
 420 photogrammetric and GNSS tracked dataset varies from 0.49 m (in farmlands) to 0.89 m (in sparse tree
 421 areas) in terms of RMSE. Moreover, as clearly indicated in Table 7, the RMSE of SRTM1 and SRTM3,
 422 ASTER and TDX, ranges from 2.65 (in bare lands) to 6 m (along drainage patterns), 1.76 m (in farm
 423 lands) to 2.93 m (sparse tree areas), 2.81m (in farm lands) to 15.6m (in bare lands) and 0.91 m (in bare

424 lands) to 6.19 m (in drainage pattern areas), respectively. In general, along every GNSS survey profile,
 425 photogrammetric DTM showed strong correlation with the ground-truth data as compared to
 426 SRTM1 and SRTM3, ASTER and TDX.

427 **Table 7.** Descriptive Statistics for vertical error for the five DEMs by land cover (vertical datum is geoid2008 and
 428 unit: m).

Land use Types	P	A	S3	S1	TX	P	A	S3	S1	Tx
	Mean					RMSE				
Sparse Trees	-0.63	-10.00	-9.65	-4.15	0.04	0.89	3.67	2.93	5.73	5.46
Road alignment	-0.56	-4.75	-4.53	-3.45	-1.27	0.59	3.87	2.10	4.70	3.18
Drainage Pattern	-0.60	-3.36	-6.51	-4.66	-3.76	0.81	5.54	2.35	6.00	6.19
Farm land	-0.79	10.19	-2.83	-2.50	0.68	0.49	2.81	1.76	3.14	1.97
Built Up Areas	-0.59	2.54	-3.08	-3.00	-0.08	0.54	3.10	1.91	3.63	1.86
Bare Lands	-0.86	13.16	-2.15	-2.04	0.41	0.88	15.60	2.65	2.65	0.91

429 NB: Refer to the abbreviations in Table 3.

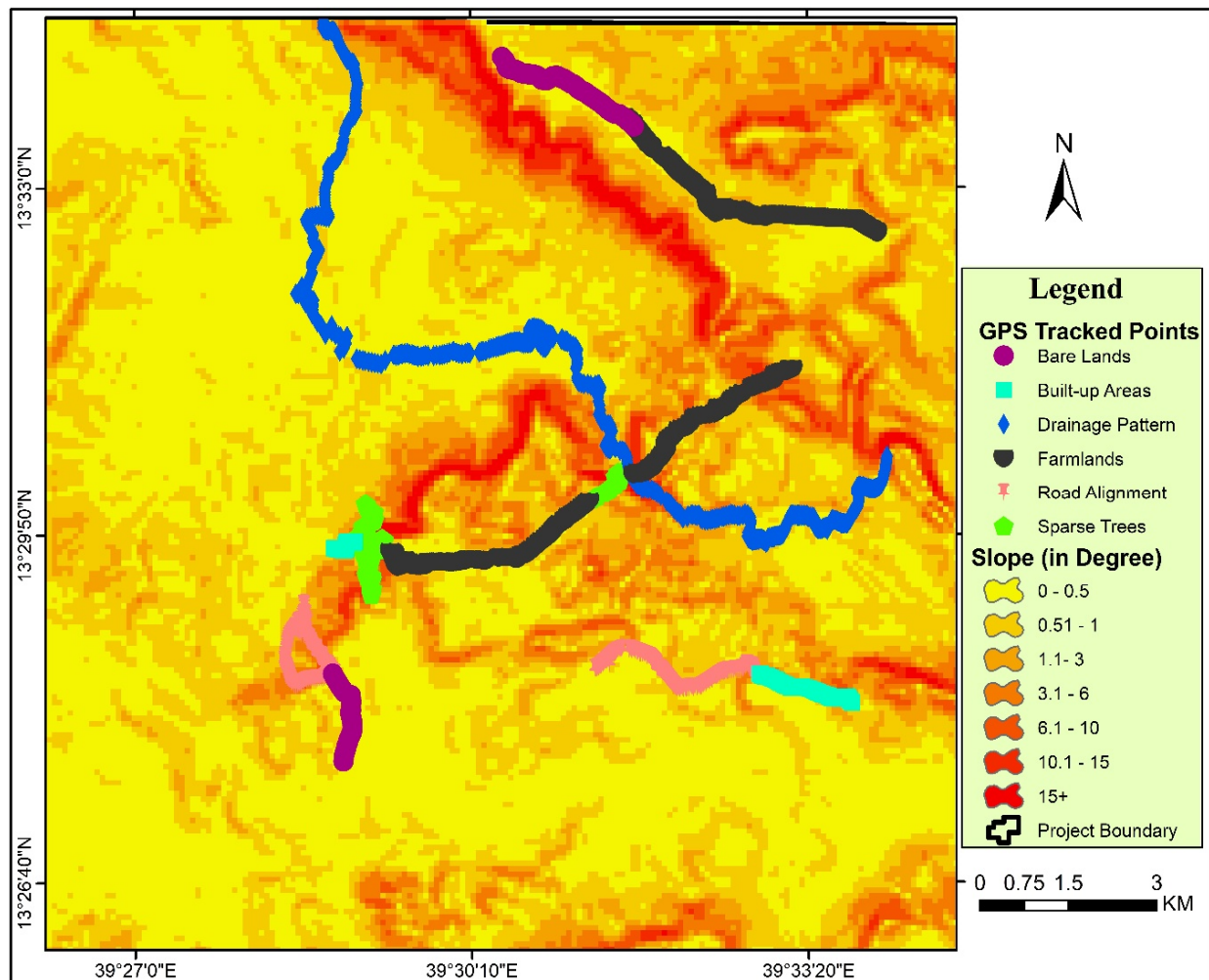
430 3.5. Vertical Accuracy across Different Slope Classes

431 The vertical accuracies of the elevation models are further assessed by slope to examine the
 432 sensitivity of vertical errors across to different terrain (slope) characteristics across the study area. The
 433 slope is derived from the re-sampled photogrammetric DTM at 90 m spatial resolution, and classified
 434 into 7 slope categories and Hawker et al. [25] proposed slope classification scheme was adopted (Figure
 435 3).

436 **Table 8.** Vertical error in RMSE of the DEMs in reference to in-situ-based measured orthometric heights against by
 437 different slope classes (Unit: m).

Slope (°)	0-0.5	0.5-1	1-3	3-6	6-10	10-15	15+
Description	Flat	Nearly flat	Very gentle slope	Gentle slope	Moderate slope	Steep slope	Very steep slope
ASTER	12.83	9.89	12.60	15.17	13.91	20.34	19.62
SRTM3	6.03	4.32	4.39	5.35	7.44	10.42	15.50
SRTM1	4.05	3.75	3.69	4.00	4.99	6.60	7.65
TDX	4.35	2.39	2.33	3.06	4.46	7.03	8.58
Photogrammetric DTM	0.80	0.78	0.82	0.85	0.81	0.86	1.09
No. of GNSS tracked points	49	89	887	531	224	166	190

438 Table 8 presents the distribution of vertical errors of the elevation models as compared to in-situ
 439 orthometric heights. Overall, in reference to the orthometric heights, the photogrammetric DTM has a
 440 better vertical accuracy for all slope categories as compared to ASTER, SRTM3, SRTM1 and TDX DEMs.
 441 In connection to this, the vertical errors of all DEMs computed in relation to the orthometric heights
 442 increase linearly as a function of slope. Some of DEMs have lower RMSE for flat to gentle slopes and
 443 largest values for the steepest slopes. In particular, the RMSE values of ASTER and SRTM3 DEMs
 444 increase considerably for 'moderate slopes', 'steep slopes' and 'very steep slopes'.



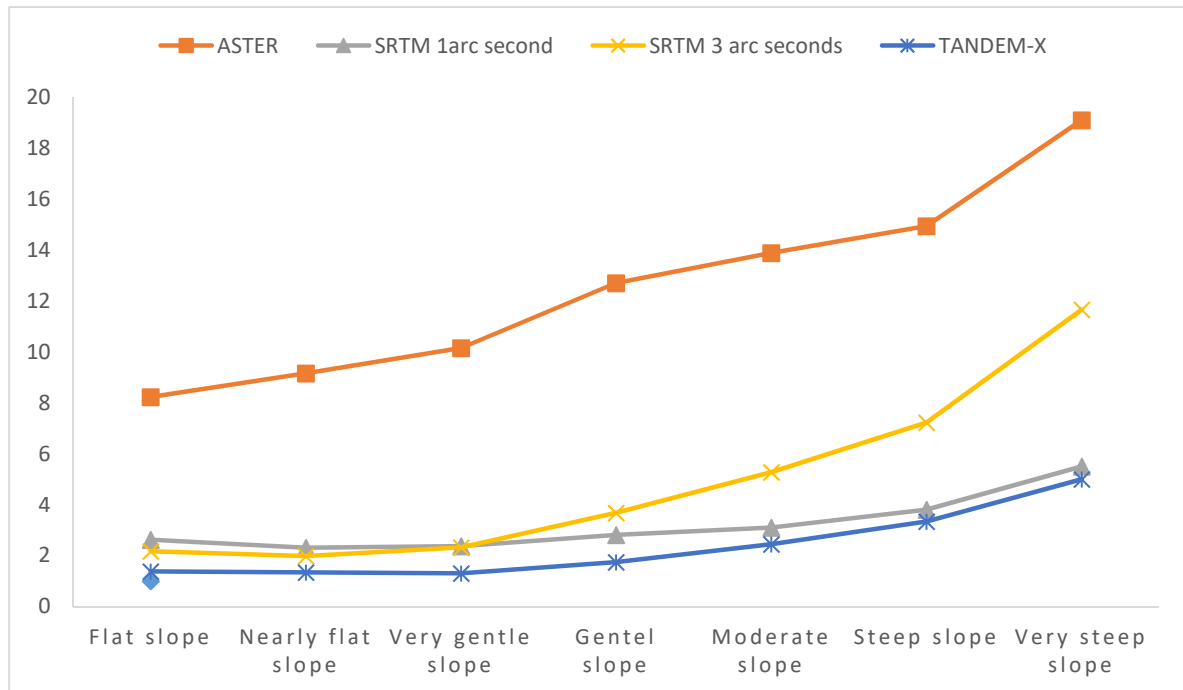
445

446 **Figure 3.** Routes and profiles of the surveyed elevation data located across the study area, and detailed
 447 description of the profiles are presented in Table 2.

448 While the vertical error of the photogrammetric DEM is lowest (Table 8 and Figure 3) for all slope
 449 classes and this is due to the removal of natural and man-made features from the photogrammetric
 450 DEM during DTM editing process. TDX and SRTM1 have almost the same level of vertical accuracies
 451 across different slope categories. On the contrary, SRTM1 slightly performs better accuracy than TDX
 452 product in 'flat', 'steep' and very steep slopes', while TDX has the lowest RMSE for the remaining slope
 453 categories. In general, for all slope categories, both SRTM1 and TDX are more accurate than SRTM3 and
 454 ASTER DEMs. The vertical errors of SRTM3 and ASTER increase considerably for slope values larger
 455 than 10°. As a whole, our results show that the vertical accuracy of the elevation models are strongly
 456 associated with terrain slope.

457 Similarly, the vertical accuracies of the global DEMs (i.e. SRTM1 and SRTM3, ASTER and TDX) are
 458 evaluated against photogrammetric DTM as a function of terrain slope, and accuracy assessment was
 459 made across the study area using different slope classes. Figure 4 shows the vertical errors (RMSE)
 460 distribution of the global DEMs (i.e., SRTM1, SRTM3, ASTER and TDX) by slope classes as evaluated
 461 against the photogrammetric DTM. TDX has the lowest values of RMSE than SRTM1, SRTM3 and
 462 ASTER products for all slope classes, demonstrating its superiority across the study area terrain
 463 characteristics. In this regard, Rexer and Hirt [51] also argued that also the quality of SRTM is superior
 464 to the global ASTER elevation model. Besides, the vertical accuracy of SRTM1 is almost equivalent to

465 that of TDX DEM. In addition, SRTM3 data is slightly better than SRTM1 for 'flat', 'nearly flat' and 'very
 466 gentle' slopes, while SRTM1 surpasses SRTM3 for 'gentle', 'moderate', 'steep' and 'very steep' slopes.
 467 The vertical errors of ASTER and SRTM3 increase considerably for slope values larger than 3°.
 468 Altogether, our results show that the vertical accuracies of the elevation models are strongly associated
 469 with terrain slopes. They have linear relationships in which the vertical errors of the elevation data
 470 increase as the values of the terrain slope increase.
 471



472 Figure 4. Density plot of RMSE of the global DEMs against the photogrammetric DTM by slope category.
 473

474 4. Discussion

475 The accuracy of SRTM, ASTER, TDX and the photogrammetric DTM were evaluated, and the
 476 residuals between the orthometric heights and five elevation models clearly showed the relative
 477 accuracies of the models. As evidently indicated in the result section, it is understandable that the
 478 vertical accuracy of the photogrammetric data (0.23 m) meets the ASPRS standard of 49.0 cm for non-
 479 vegetated areas and 75.0 cm for vegetated areas [48, 49]. We also have evaluated the vertical
 480 accuracies of the SRTM1 and SRTM3, ASTER and TDX that shows Linear Error (LE) computed based
 481 on ASPRS standards for the five topographic models against RTK-GNSS based orthometric heights
 482 at the 90 and 95 two-sided percentiles of confidence interval (Table 4). Based on these standards, the
 483 absolute vertical accuracy of the photogrammetric DTM is 1.67 m (LE 95%). Our analysis showed that
 484 the photogrammetric DTM best qualify the ASPRS standard [48, 49], and more specifically, based on LE
 485 95%, the photogrammetric DTM is conformal to a 100 cm vertical accuracy class. In relation to the
 486 ground truth, the accuracy of the photogrammetric DTM (an absolute error of 1.67 m or 1 m vertical
 487 accuracy class) is lower than the quality of original data (RMSE of 0.227 m or 0.2 m vertical accuracy
 488 class) as estimated by five checkpoints and four GCPs. The increase in the absolute error comes from
 489 both photogrammetric data and ground truth data as well as limitations related to statistical
 490 rigorosity of adjustment analysis derived from few checkpoints and GCPs.

491 The photogrammetric products also qualify for the ASPRS [49, 52] vertical accuracy assessment
 492 standards of: i) a 33.3 cm vertical accuracy class, ii) a 65.3 cm Non-vegetated Vertical Accuracy (NAV),

493 iii) a 99.9 cm Vegetated Vertical Accuracy (VVA), and iv) equivalent class 1 (99.9cm) and class 2 (50
494 cm) contour interval (Appendix I). Although our results well substantiated the accuracy of airborne-
495 based photogrammetric DTM and meets the well-known standards, the vertical accuracy (RMSE_z =
496 0.85 m) of the photogrammetric DTM is slightly poorer than the expected vertical accuracy
497 corresponding to three pixels (± 0.75 m) as per the ASPRS standard [48]. This level of DEM vertical
498 accuracy is good enough for photogrammetric data to meet many applications like rural cadaster,
499 natural resource management, digital soil mapping, watershed management, floodplain mapping,
500 natural disaster and risk management, infrastructure management, aviation safety, etc. However, the
501 photogrammetric DTM produced at a spatial resolution of 10 m does not qualify for urban cadaster
502 application that requires vertical accuracy in the order of ± 0.45 m, as per the Ethiopian standard [53].

503 At large, the accuracy of the photogrammetric DTM best complies with in-situ-based Real-Time
504 Kinematic GNSS tracked points compared to the other global ASTER, SRTM1, SRTM3 and TDX
505 elevation models. In the study area, the vertical accuracy of the two SRTM elevation models surpass
506 that of ASTER DEM. In this regard, the findings of this study coincide with previous studies that
507 correspondingly reported the superiority of SRTM (30 m and 90 m resolution) over ASTER global
508 elevation model [54].

509 In reference to in-situ orthometric heights, the SRTM product showed a better performance in
510 our study area compared to its product specification. SRTM3 has an absolute vertical accuracy of
511 11.91 m (LE at 90% confidence level) that is much better than its product specification, RMSE of 9.73m
512 (16 m absolute accuracy at 90% confidence level) [4]. This indicates that 92.02% of the SRTM3 data
513 has an absolute error in height information smaller than 16m. This observed vertical accuracy of the
514 SRTM in Ethiopia is better as compared to its performance reported in Polish Tatra Mountains. In
515 Poland, SRTM3 showed conformity to its product specification accuracy of 16 m with 82% [55]. Besides,
516 the absolute vertical accuracy of SRTM3 has significantly improved when it is compared to a regular
517 grid of photogrammetric DTM, 7.67 m at LE 90% and 9.13 m at LE 95% (Table 4). The absolute vertical
518 accuracy of SRTM1 (7.70 m and 9.17 m, respectively at LE 90% and LE 95%) in reference to in-situ
519 orthometric heights is remarkably better than that of the SRTM3 data.

520 The SRTM1 product showed noticeable improvement when compared to the accuracy of the
521 SRTM3 product specification. Most of the errors (96.2%) in the height values of the SRTM1 DEM are
522 smaller than RMSE of 9.73 m (SRTM product specification absolute vertical accuracy of 16 m) as
523 compared to 92.02% of the SRTM3. In contrast to SRTM, the absolute accuracy of ASTER is lower than
524 the accuracy reported in its product specification. The absolute accuracy of ASTER-GDEM version 2
525 in reference to *in-situ* orthometric heights (28.95 m at LE 95% confidence level) is low compared to its
526 design goal of 17 m absolute accuracy at LE 95%, which is equivalent to RMSE of 8.67 m [54]. This
527 corresponds to larger error budget in the ASTER elevation model. In the study area, only 48.5% of
528 the elevation values of the ASTER DEM has smaller error budget than the SRTM3 product
529 specification vertical accuracy, demonstrating its low performance. The observed accuracies of
530 SRTM3 and ASTER DEMs in our study area have showed slightly better accuracies (SRTM 13.73 m,
531 ASTER 20.07m at LE 95%, Table 4) than the findings of the study conducted in Tokyo [28]. The difference
532 may be caused by variation in topography.

533 On the other hand, the vertical accuracy of the TDX DEM is comparable to that of SRTM1 when
534 compared in reference to in-situ orthometric heights. In this comparison, the absolute vertical
535 accuracy of the TDX at LE 90% (10.29 m) is almost equivalent to its product specification of 10 m. As

536 clearly indicated in the results section, it has also even better absolute vertical accuracy of 3.74m at
537 LE 90% when compared to the photogrammetric DTM (Table 4B). Overall, in reference to the
538 photogrammetric DTM (Table 4B), the quality of TDX data is slightly better than SRTM1 and
539 remarkably better than SRTM3 [28, 49]. Moreover, the accuracy of ASTER with respect to
540 photogrammetric data covering in the study area is also relatively lower (24.11 m at LE 95%) than its
541 product specification (i.e., an absolute vertical accuracy of 17 m) [30, 31]. Largely, our findings
542 confirmed a better performance of TDX, SRTM1 and SRTM3 than ASTER. While other previous
543 studies asserted that, the photogrammetric DTM has shown an extraordinary accuracy (1.67 m at LE
544 95% and 1.40 m at LE 90%) compared to the findings of other global digital elevation models [45]. In
545 addition to vertical accuracy, the photogrammetric data also agree with the ASPRS's horizontal
546 accuracy requirements and it has a horizontal accuracy of 0.54 m and 0.39 m in the northing and
547 easting, respectively, in terms of RMSE compared to the ASPRS desired accuracy of 0.613 m
548 (2.45xGSD at 95% confidence level, with the photogrammetric data has a ground sampling distance
549 of 25 cm) [48, 49].

550 The quality of digital elevation models also varies across the different land use/land cover types
551 and terrain characteristics. These findings also supported by Gdulová et al. [56] conclusive argument.
552 The RMSE of the SRTM1 and SRTM3, ASTER and TDX showed noticeable variation across the six
553 land use land cover types. Our results showed higher errors in areas that are characterized by a
554 drainage pattern land cover (Profile-3), sparse tree areas (Profile-1) and in bare land topography
555 (Profile-6). The accuracy of ASTER is lower in the drainage patterns and bare lands, while that of
556 SRTM is low in sparse tree areas and along bare lands. This is probably because the C-band radar
557 used by the SRTM is not fully capable to penetrate through vegetation canopy. In this regard, studies
558 like Tachikawa et al. [54] showed the low accuracy of satellite stereoscopic observation in areas where
559 covered with thick vegetation canopy. Wessel et al. [39] also indicated low accuracy of TDX across
560 vegetated areas, which is in agreement with our results. Besides, in line with the digital elevation
561 model vertical accuracy assessment in vegetation areas, our finding is complemented with the
562 findings of Hawker et al.[25], and they argued that TDX is the most accurate global DEM in all land
563 cover types tested except short vegetation and tree-covered areas.

564 With regard to validation analysis of the different DEMs across topographic (slope)
565 characteristics, the two elevation models (SRTM1 and TDX) agreed well with photogrammetric DTM
566 for all slope classes. The error of TDX is marginally lower than SRTM 1arcsecond for all slope
567 categories. The SRTM3 conforms well to the photogrammetric DTM across topographic landmasses
568 characterized by lower slope angles. In contrast to other elevation models, ASTER DEM significantly
569 deviates from the photogrammetric DTM across almost all slope classes. For all global DEMs used in
570 this study, the lowest RMSE values are found in gentle slope areas. For ASTER and SRTM 3 arc
571 seconds, RMSE values increase considerably for slopes larger than 10° ('steep' and 'very steep
572 slopes'), while this change is less for TDX and SRTM1. Wessel et al. [39,57] also found a considerable
573 rise in RMSE values above slopes of 10° ('steep slope'), however, our analysis differs slightly from
574 this findings and bin all slopes below 10° into 1 category while we separate into 5 bins below 10°
575 owing to our focus on gentle slope terrain. This may be related to limitations of the interferometric
576 technique to acquire accurate data over extremely rugged topography that is characterized by high
577 slopes and height variations. In such topographic, the radar beam is not able to illuminate all portions
578 of the ground surface; radar cannot see topographic masses that are occluded from its view. The low

579 backscattered power of radar signals from some “shadow” regions causes random error in the
580 interferometric phase [58] and thus the resulting heights from the observed phases are affected by
581 larger errors. Besides, due to the side-looking geometry of radar satellites, the layover effect is
582 assumed significant in terrain areas where variation in elevation exceeds 1.8m per pixel [51]. In
583 general, the compressed layover in the slant range geometry has a larger component in the direction
584 of ground range and therefore introduces errors in height information.

585 5. Conclusions

586 The quality of any spatial data needs to be validated by carrying out an in-depth accuracy
587 assessment before using the products for different applications. Thus, the objective of this study was
588 to evaluate the vertical accuracy of aerial photogrammetric DTM and four global digital elevation
589 models against in-situ orthometric heights derived from ellipsoidal heights and the EGM2008 geoid
590 heights on the one hand, and assessing the quality of the four global digital elevation models against
591 the aerial photogrammetric DTM measurements from the other. We used different sources of datasets
592 including ASTER, SRTM3, SRTM1 and TDX DEMs as well as Kinematic GNSS tracked point datasets
593 (2130 validation points) acquired from static Differential Global Navigation Satellite Systems
594 (DGNSS) geodetic positioning using dual-frequency receivers. Accordingly, the accuracy of the
595 photogrammetric DTM made available to us is convincingly in agreement with the ASPRS and
596 Ethiopian Mapping Agency's standards. The photogrammetric DTM is also observed to be more
597 accurate when compared to SRTM1 and SRTM3, ASTER and TDX. The DTM has an absolute vertical
598 error of 1.67 m at LE 95% confidence level, meeting the 100 cm vertical accuracy class of the ASPRS
599 standard.

600 Comparing to orthometric heights derived from RTK GNSS based ground truth ellipsoidal
601 heights and EGM2008 geoid, the accuracy of SRTM3 is considerably better than ASTER, and its
602 absolute elevation error is lower than the product specification of 16 m absolute accuracy at LE 90%.
603 Besides, in reference to in-situ orthometric heights, the accuracy of SRTM1 exceeds the accuracy of
604 the other three global DEMs, i.e. ASTER, SRTM3 and TDX. Moreover, SRTM1 and SRTM3 as well as
605 TDX showed better accuracy than ASTER when compared to the photogrammetric DTM across an
606 area of approximately 298 km², based on pixel-by-pixel comparison. The SRTM elevation models
607 (SRTM1 and SRTM3) noticeably deviate from photogrammetric DTM in areas characterized by
608 undulating terrain. In relatively flat areas, the two elevation models are in a good agreement.
609 Similarly, ASTER DEM considerably deviate from the photogrammetric DTM than the SRTM
610 elevation models. The residuals between ASTER and the photogrammetric DTM have significant
611 differences in all areas; however, the mismatch is larger in areas of steep slope. The discrepancy may
612 be attributed to shadow and layover effects of the C-band radar signal and low resolution of satellite
613 stereoscopic view compared to high-resolution aerial stereo images. When compared to the
614 photogrammetric DTM, TDX has better accuracy than the SRTM elevation models and ASTER DEM.

615 The study also showed the importance of reducing the elevation models to a more accurate local
616 geoid, in view of preserving the actual accuracy of the resulting DEMs or DTMs. We also found that
617 referring to the local AMSL datum would ignore significant variation of the local geoid model. In this
618 study, the EGM2008 geoid model differs from the AMSL datum by an amount ranging from -1.162
619 m to -0.618 m with a mean and standard deviation of -0.944 m and 0.122 m, respectively. Therefore,
620 before using any application, it is highly recommended to reduce the elevation models to a very

621 accurate local geoid model to reduce errors. Besides, further accuracy assessment studies are required
622 to evaluate the photogrammetric DTM using integration of static GNSS and Network-Based RTK
623 GNSS measurement. It is also important to compare the photogrammetric DTM against elevation
624 data that can be locally computed from remotely sensed radar images or LiDAR data. Finally, the
625 finding of the study confirmed that topographic datasets such as the photogrammetric DTM, TDX
626 and SRTM1 digital elevation models would play a unique role for earth sciences, environmental
627 research, urban planning, positioning and navigation services, environmental disaster monitoring
628 and management plans, defense and security applications in a country like Ethiopia having scarce
629 high resolution spatial datasets and very rugged topography.

630

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632 first draft of the manuscript, while H.B involved in data collection, data processing, analyzing the data and
633 conducting this study for the partial fulfillment of her MSc thesis research under the close supervision of T.B
634 and B.G. Besides, T.B, B.G, and M.V reviewed and edited the manuscript exhaustively as well as commenting
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782 Appendix I

783 **Table 2.** Common vertical accuracy classes for DEM points in non-vegetated and vegetated terrain (ASPRS, 2015).

Vertical accuracy class	RMSEz Non-Vegetated (cm)	Non-Vegetated Vertical Accuracy (NVA) (cm)	Vegetated Vertical Accuracy (VVA) at 95% (cm)	Equivalent class 1 contour interval per ASPRS 1990 (cm)	Equivalent class 2 contour interval per ASPRS 1990 (cm)
1 cm	1.0	2.0	3.0	3.0	1.5
2.5 cm	2.5	4.9	7.5	7.5	3.8
5 cm	5.0	9.8	15.0	15.0	7.5
10 cm	10.0	19.6	30.0	30.0	15.0
15 cm	15.0	29.4	45.0	45.0	22.5
20 cm	20.0	39.2	60.0	60.0	30.0
33.3 cm	33.3	65.3	99.9	99.9	50.0
66.7 cm	66.7	130.7	200.1	200.1	100.1
100 cm	100.0	196.0	300.0	300.0	150.0
333.3 cm	333.3	653.3	999.9	999.9	500.0

784