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Article

Reference Frame Democracy in Interacting Systems: Another Step Towards The Unification of Quantum and Classical Mechanics

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Abstract

We extend our proof of mathematical equivalence between quantum and classical mechanics to interacting systems, towards the the complete unification framework. By demonstrating that reference frame integration of classical interacting trajectories yields the exact quantum propagators for multiparticle systems, we show that quantum entanglement emerges naturally from correlated reference frame transformations of classical dynamics. The key insight is that reference frame democracy and interaction dynamics operate on orthogonal degrees of freedom: boosts affect only center-of-mass motion while interactions govern relative coordinates. This factorization explains why quantum mechanics naturally separates into free center-of-mass propagation and interacting relative motion. We provide explicit derivations for two-particle systems with arbitrary interactions V(r), demonstrate the emergence of quantum bound states from classical orbital motion, and prove that the entire mathematical apparatus of non-relativistic quantum mechanics is equivalent to classical mechanics for interacting systems, viewed through the lens of reference frame democracy. The pencil dot insight thus extends further its revolutionary implications: there is no separate quantum world—only classical reality properly accounting for Einstein's relativity.

Keywords: quantum mechanics; classical mechanics; reference frame democracy; unification theory; Einstein relativity; center-of-mass motion; relative coordinates; interacting systems; wave function factorization; quantum entanglement; bound states; scattering theory; hydrogen atom; harmonic oscillator; phase factors; Bohr-Sommerfeld quantization; many-body systems; spacetime coherence theory; wave-particle duality; measurement problem; reduced mass; Coulomb potential; Schrödinger equation; quantum tunneling; orbital motion; energy levels; mathematical equivalence; boost transformations; invariance principle

1. Beyond Free Particles: The Next Challenge

Definition: Reference Frame Democracy

Reference frame democracy is the principle that no inertial reference frame is privileged in describing physical phenomena. Mathematically, this means the complete physical description requires integrating over all possible reference frame boosts with equal weight and coherent phase factors:

$$\psi(\mathbf{r},t) = \int_{-\infty}^{\infty} \infty d3u \, \exp[i\phi(\mathbf{u};\mathbf{r},t)] \times [classical \, amplitude]$$

where

$$\phi(\mathbf{u};\mathbf{r},t)$$

is the boost-induced phase and

u

represents the boost velocity vector.

Our previous work demonstrated that quantum mechanics emerges from classical mechanics through reference frame integration for free particles [1]. The mathematical equivalence was exact: integrating a classical trajectory over all inertial reference frames yielded the precise Schrödinger propagator, while projecting quantum states onto specific frames recovered classical trajectories.

But physics rarely deals with free particles. The rich phenomena of atomic structure, chemical bonding, and condensed matter emerge from interactions between particles. If our framework truly captures the fundamental nature of quantum-classical equivalence, it must extend seamlessly to interacting systems.

The challenge appears formidable. Unlike free particles that follow straight-line trajectories x_0 + vt, interacting particles follow complex coupled dynamics where each particle's motion depends on all others. Coulomb forces create elliptical orbits, harmonic interactions produce oscillatory motion, and many-body systems exhibit chaotic behavior. How can reference frame integration handle such complexity?

The answer reveals one of the most beautiful mathematical structures in physics.

2. The Invariance Principle

Consider two particles with masses m_1 and m_2 interacting through a potential V(r) where $r = |x_1 - x_2|$ depends only on their separation. This covers the vast majority of physical interactions: Coulomb forces, harmonic oscillators, van der Waals attraction, and nuclear forces all depend on relative position rather than absolute coordinates.

The classical equations of motion are:

$$m_1\ddot{x}_1 = -\frac{\partial V}{\partial x_1} = -V'(r)\frac{\partial r}{\partial x_1} = -V'(r)\frac{x_1 - x_2}{r} \tag{1}$$

$$m_2\ddot{x}_2 = -\frac{\partial V}{\partial x_2} = -V'(r)\frac{\partial r}{\partial x_2} = -V'(r)\frac{x_2 - x_1}{r} = +V'(r)\frac{x_1 - x_2}{r}$$
 (2)

where we have used

$$\frac{\partial r}{\partial x_1} = \frac{x_1 - x_2}{r}$$

and

$$\frac{\partial r}{\partial x_2} = -\frac{x_1 - x_2}{r}$$

These equations reveal a crucial symmetry: the interaction depends only on the relative coordinate $r = x_1 - x_2$. Adding the equations of motion:

$$m_1\ddot{x}_1 + m_2\ddot{x}_2 = -V'(r)\frac{x_1 - x_2}{r} + V'(r)\frac{x_1 - x_2}{r} = 0$$
 (3)

This immediately implies conservation of total momentum:

$$\frac{d}{dt}(m_1\dot{x}_1 + m_2\dot{x}_2) = m_1\ddot{x}_1 + m_2\ddot{x}_2 = 0 \tag{4}$$

Therefore:

$$P = m_1 \dot{x}_1 + m_2 \dot{x}_2 = \text{constant} \tag{5}$$

Now consider a reference frame boost by velocity u. Under this transformation:

$$x_1(t) \to x_1(t) - ut \tag{6}$$

$$x_2(t) \to x_2(t) - ut \tag{7}$$

The crucial observation: the relative coordinate is **invariant**:

$$r = x_1 - x_2 \to (x_1 - ut) - (x_2 - ut) = x_1 - x_2 = r$$
 (8)

Therefore, the interaction V(r) is completely unaffected by reference frame transformations. The complex interacting dynamics occur entirely within the relative coordinate, while reference frame democracy operates orthogonally on the center-of-mass motion.

3. Center of Mass and Relative Coordinates

Let us formalize this insight using the standard coordinate transformation:

Center of mass:
$$X = \frac{m_1 x_1 + m_2 x_2}{M}$$
 where $M = m_1 + m_2$ (9)

Relative coordinate:
$$r = x_1 - x_2$$
 (10)

Reduced mass:
$$\mu = \frac{m_1 m_2}{M}$$
 (11)

The inverse transformation is:

$$x_1 = X + \frac{m_2}{M}r\tag{12}$$

$$x_2 = X - \frac{m_1}{M}r\tag{13}$$

In these coordinates, the classical dynamics separate completely:

Center of mass:
$$M\ddot{X} = 0$$
 (14)

Relative motion:
$$\mu \ddot{r} = -V'(r)$$
 (15)

The center of mass moves freely with constant velocity $V_{CM} = P/M$, while the relative coordinate evolves according to the interaction potential with reduced mass μ .

4. Reference Frame Integration for Interacting Systems

Following our established framework, we construct the phase factor for reference frame transformations. Under a boost by velocity u, each particle acquires a phase:

$$\phi_{\text{total}}(u; x_1, x_2, t) = \frac{1}{\hbar} \left[m_1 u(x_1 - x_1 0 - v_1 0 t) + m_2 u(x_2 - x_2 0 - v_2 0 t) - \frac{1}{2} (m_1 + m_2) u 2t \right]$$
(16)

where

$$(x_10, v_10)$$

and

$$(x_20, v_20)$$

are the initial positions and velocities.

We can rewrite this entirely in terms of center-of-mass coordinates. First, note that:

$$m_1 x_1 + m_2 x_2 = MX$$
 where $X = \frac{m_1 x_1 + m_2 x_2}{M}$ (17)

$$m_1 v_1 0 + m_2 v_2 0 = M V_{\text{CM}}$$
 where $V_{\text{CM}} = \frac{P}{M}$ (18)

Substituting these relations into the phase factor:

$$\phi_{\text{total}}(u; x_1, x_2, t) = \frac{1}{\hbar} \left[m_1 u(x_1 - x_1 0 - v_1 0 t) + m_2 u(x_2 - x_2 0 - v_2 0 t) - \frac{1}{2} (m_1 + m_2) u 2t \right]$$
(19)

$$= \frac{u}{\hbar} [m_1(x_1 - x_10) + m_2(x_2 - x_20) - (m_1v_10 + m_2v_20)t] - \frac{Mu2t}{2\hbar}$$
 (20)

$$= \frac{u}{\hbar} [M(X - X0) - MV_{\text{CM}}t] - \frac{Mu2t}{2\hbar}$$
 (21)

$$= \frac{Mu}{\hbar} [(X - X0) - V_{\rm CM}t] - \frac{Mu2t}{2\hbar}$$
 (22)

$$\phi_{\text{total}}(u; X, r, t) = \frac{M}{\hbar} \left[u(X - X0 - V_{\text{CM}}t) - \frac{1}{2}u2t \right]$$
(23)

This is identical to the free particle phase factor for the center of mass: the relative coordinate r does not appear in the phase at all.

5. The Factorization Theorem

The two-particle wave function emerges from reference frame integration:

$$\psi(x_1, x_2, t) = \int_{-\infty} \infty du \, \exp[i\phi_{\text{total}}(u; X, r, t)] \times \Phi(r, t)$$
 (24)

where $\Phi(\mathbf{r},t)$ encodes the relative motion dynamics and does not depend on the boost parameter u.

Since the phase depends only on center-of-mass coordinates, the integration factorizes:

$$\psi(x_1, x_2, t) = \left[\int_{-\infty} \infty du \, \exp\left[i\frac{M}{\hbar} \left(u(X - X0 - V_{\text{CM}}t) - \frac{1}{2}u2t\right)\right] \right] \times \Phi(r, t) \tag{25}$$

The integral in brackets is precisely our free particle result for the center of mass:

$$\psi_{\rm CM}(X,t) = \sqrt{\frac{M}{2\pi i\hbar t}} \exp\left[\frac{iM(X - X0 - V_{\rm CM}t)2}{2\hbar t}\right] \tag{26}$$

Therefore:

$$\psi(x_1, x_2, t) = \psi_{\text{CM}}(X, t) \times \psi_{\text{rel}}(r, t)$$
(27)

where:

 $\psi_{\rm CM}(X,t)$

is the free particle propagator for the center of mass

 $\psi_{\rm rel}(r,t)$

solves the relative motion Schrödinger equation:

$$i\hbar \frac{\partial \psi_{\rm rel}}{\partial t} = -\frac{\hbar 2}{2\mu} \frac{\partial 2\psi_{\rm rel}}{\partial r^2} + V(r)\psi_{\rm rel}$$
 (28)

6. Physical Interpretation: The Orthogonality of Democracy and Interaction

This factorization reveals a profound truth about the nature of quantum mechanics. Two distinct physical principles operate on orthogonal degrees of freedom:

Reference Frame Democracy: No inertial frame is privileged, so the complete physical description must integrate over all possible reference frames. This principle governs center-of-mass motion and produces free particle propagation regardless of internal interactions.

Interaction Dynamics: Forces between particles create correlations in their relative motion, leading to bound states, scattering, and complex many-body phenomena. These effects are confined to relative coordinates and are unaffected by reference frame transformations.

The quantum mechanical wave function emerges as the mathematical consequence of respecting both principles simultaneously. What we call "quantum entanglement" between particles is simply the correlation of their relative motion, while the mysterious "spreading" of wave packets is the manifestation of reference frame democracy applied to center-of-mass motion.

7. Examples and Applications

7.1. Harmonic Oscillator

For $V(r) = \frac{1}{2}kr^2$, the relative motion becomes a one-dimensional harmonic oscillator with frequency $\omega = \sqrt{(k/\mu)}$. The complete wave function is:

$$\psi(x_1, x_2, t) = \psi_{CM}(X, t) \times \psi_{HO}(r, t)$$
 (29)

where $\psi_H O(r,t)$ is the standard quantum harmonic oscillator solution. Reference frame democracy provides the center-of-mass spreading, while the harmonic interaction creates discrete energy levels in the relative coordinate.

7.2. Hydrogen Atom

For the Coulomb potential $V(r) = -ke^2/r$, the relative motion yields the familiar hydrogen atom energy levels and wave functions. The radial Schrödinger equation becomes:

$$-\frac{\hbar 2}{2\mu}\frac{d2u}{dr^2} + \left[-\frac{ke^2}{r} + \frac{\hbar 2l(l+1)}{2\mu r^2} \right] u = Eu$$
 (30)

where u(r) = rR(r) and $\mu = memp/(me + mp) \approx me$ is the reduced mass.

The bound state solutions yield the energy spectrum:

$$E_n = -\frac{\mu k 2e4}{2\hbar 2n2} = -\frac{13.6 \text{ eV}}{n2}$$
 (31)

The complete description includes:

- Center of mass: Free propagation of the proton-electron system with total mass M = me + mp
- **Relative motion**: Bound states with energy En = -13.6 eV/ n^2 and wave functions ψ nlm(r, θ , Φ)

The atomic structure emerges entirely from classical Coulomb dynamics in the relative coordinate, while reference frame democracy governs the motion of the atom as a whole.

7.3. Scattering Systems

For unbound states (E > 0), the relative motion describes classical scattering trajectories. The asymptotic wave function takes the form:

$$\psi_{\rm rel}(r,\theta) \to eikz + f(\theta) \frac{eikr}{r} \quad \text{as } r \to \infty$$
 (32)

where $k = \sqrt{(2\mu E)/\hbar}$ and $f(\theta)$ is the scattering amplitude.



The quantum scattering amplitude emerges from reference frame averaging over all possible classical trajectories that connect initial and final relative positions. The phase shift δl for angular momentum l is determined by the classical action:

$$\delta_{l} = -\frac{1}{\hbar} \int_{0} \infty \left[\sqrt{2\mu [E - V(r)] - \frac{\hbar 2l(l+1)}{r2}} - \sqrt{2\mu E} \right] dr$$
 (33)

The differential cross section becomes:

$$\frac{d\sigma}{d\Omega} = jf(\theta)j2 = \frac{1}{k2}j\sum_{l=0}^{\infty} \infty(2l+1)ei\delta_l\sin(\delta_l)P_l(\cos\theta)j2$$
(34)

This reproduces all standard quantum scattering results from classical trajectory analysis weighted by reference frame democracy.

8. Extension to N-Particle Systems

The framework generalizes naturally to N particles with pairwise interactions. Consider the Hamiltonian:

$$H = \sum_{i=1}^{n} N \frac{p_i 2}{2m_i} + \sum_{i < j} V_{ij} (j \mathbf{r}_i - \mathbf{r}_j j)$$
(35)

The center of mass coordinate:

$$\mathbf{X}_{\text{CM}} = \frac{\sum_{i=1} N m_i \mathbf{r}_i}{\sum_{i=1} N m_i} = \frac{\sum_{i=1} N m_i \mathbf{r}_i}{M_{\text{total}}}$$
(36)

remains subject to reference frame democracy and propagates freely since:

$$M_{\text{total}}\ddot{\mathbf{X}}_{\text{CM}} = \sum_{i=1}^{N} Nm_i \ddot{\mathbf{r}}_i = \sum_{i=1}^{N} N\mathbf{F}_i \text{ext} + \sum_{i < j} (\mathbf{F}_{ij} + \mathbf{F}_{ji}) = 0$$
(37)

The last equality follows because external forces are absent and internal forces cancel in pairs by Newton's third law.

The remaining 3N-3 relative coordinates can be chosen as:

$$\mathbf{r}_{ij} = \mathbf{r}_i - \mathbf{r}_j \quad \text{for } i, j = 1, \dots, N - 1$$
 (38)

These coordinates evolve according to the interaction dynamics and are unaffected by reference frame transformations.

Reference frame integration produces:

$$\Psi(\mathbf{r}_{1},\ldots,\mathbf{r}_{N},t) = \psi_{CM}(\mathbf{X}_{CM},t) \times \Psi_{rel}(\{\mathbf{r}_{ij}\},t)$$
(39)

where

$$\Psi_{re}$$

solves the (3N-3)-dimensional Schrödinger equation for the relative coordinates:

$$i\hbar \frac{\partial \Psi_{\text{rel}}}{\partial t} = \left[-\sum_{i < j} \frac{\hbar 2}{2\mu_{ij}} \nabla_{ij} 2 + \sum_{i < j} V_{ij} (j\mathbf{r}_{ij}j) \right] \Psi_{\text{rel}}$$
(40)

This explains why quantum mechanics naturally factorizes into center-of-mass and internal degrees of freedom for any isolated system.

9. Bound States and Classical Orbital Motion

One of the most striking applications concerns quantum bound states. In classical mechanics, bound motion corresponds to periodic or quasi-periodic orbits. In our framework, these classical orbits provide the foundation for quantum bound states through reference frame integration.

Consider a hydrogen-like atom where the classical motion consists of elliptical orbits with semimajor axis a and period T. The classical action over one complete orbit is:

$$S_{\text{classical}} = \oint p \, dr = \oint \sqrt{2\mu [E - V(r)]} \, dr \tag{41}$$

For the Coulomb potential $V(r) = -ke^2/r$ with energy E < 0, this evaluates to:

$$S_{\text{classical}} = 2\pi \sqrt{-2\mu E} \, a = 2\pi \sqrt{\mu ke^2} \tag{42}$$

The quantum energy levels emerge from the requirement that reference frame phases accumulate consistently over one orbital period. When we integrate over reference frame boosts, the total phase accumulated must be a multiple of 2π for constructive interference:

$$\frac{S_{\text{classical}}}{\hbar} = \frac{2\pi\sqrt{\mu ke2}}{\hbar} = 2\pi n \tag{43}$$

This yields the Bohr-Sommerfeld quantization condition:

$$\oint p \, dr = nh \quad \text{where } n = 1, 2, 3, \dots$$
 (44)

Solving for the energy levels:

$$\sqrt{\mu ke2} = n\hbar \quad \Rightarrow \quad E_n = -\frac{\mu k2e4}{2\hbar 2n2} = -\frac{R_{\infty}hc}{n2} \tag{45}$$

which reproduces the correct hydrogen spectrum.

The quantum wave function represents the reference frame superposition of all possible orientations and phases of the classical orbit, weighted by the appropriate quantum amplitudes.

10. Resolution of Quantum Paradoxes

Our framework resolves several longstanding quantum paradoxes through classical understanding:

Wave-Particle Duality: Particles exhibit wave-like behavior because complete physical description requires integrating over all reference frames. The "wave" is the mathematical representation of this democratic averaging.

Measurement Problem: "Collapse" occurs when we project the full reference frame superposition onto a specific experimental frame, recovering classical trajectories.

Entanglement: Correlations between particles arise from their interacting classical dynamics in relative coordinates, not from mysterious "action at a distance."

Tunneling: Classically forbidden regions become accessible when we integrate over reference frames where the kinetic energy distribution permits penetration.

11. Experimental Implications

Our unification predicts that any experiment designed to "test quantum mechanics" is actually testing the validity of reference frame democracy. Deviations from quantum predictions would indicate violations of special relativity—an extremely unlikely scenario.

However, the framework suggests new experimental approaches:



Reference Frame Selectivity: By preferentially coupling experiments to specific reference frames (e.g., through gravitational fields), we might observe deviations from standard quantum behavior.

Macroscopic Quantum Systems: Large objects should still exhibit quantum spreading due to reference frame democracy, but with timescales proportional to mass. Ultra-precise measurements might detect this effect.

Relativistic Extensions: The framework extends naturally to special relativistic systems by replacing the Galilean boost with Lorentz transformations. For a particle with momentum p and energy $E = \sqrt{(p^2c^2 + m^2c^4)}$, the phase factor under a Lorentz boost with velocity u becomes:

$$\phi_{\rm rel}(u; x, t) = \frac{1}{\hbar c} \left[u(Et - px) - \frac{u2}{2c2}(E + pc) \right] + \mathcal{O}(u3/c3)$$
 (46)

Reference frame integration over relativistic boosts should reproduce Klein-Gordon and Dirac propagators, providing new tests of quantum field theory predictions.

12. Philosophical Implications

This further attempt at unification of quantum and classical mechanics through reference frame democracy resolves the conceptual divide that has puzzled physicists for over a century. There is no separate "quantum realm" with mysterious properties fundamentally different from classical physics.

Instead, quantum mechanics emerges as the mathematically inevitable consequence of taking Einstein's special relativity seriously. The uncertainty principle, wave-particle duality, and quantum entanglement are not fundamental mysteries but natural mathematical consequences of living in a universe without absolute reference frames.

The pencil dot that began our investigation encapsulates this entire worldview: even the simplest physical mark reveals that absolute rest does not exist, and therefore complete physical description must account for all possible states of motion. What we call "quantum mechanics" is simply this accounting procedure applied with mathematical rigor.

13. Connection to Spacetime Coherence Theory

This work provides the mathematical foundation for broader unified theories that treat matter, energy, and information as emergent phenomena from spacetime dynamics [8]. If quantum mechanics itself emerges from classical mechanics plus reference frame democracy, then the Standard Model and general relativity might similarly emerge from deeper geometric principles.

The coherence crystallization mechanism proposed in Spacetime Coherence Theory gains mathematical support from our demonstration that quantum behavior is not fundamental but emergent. Matter as "crystallized spacetime patterns" becomes a natural extension of matter as "reference frame averaged classical dynamics."

14. Conclusions

We have demonstrated that the mathematical equivalence between quantum and classical mechanics extends seamlessly to interacting systems. The key insight is that reference frame democracy and interaction dynamics operate on orthogonal degrees of freedom:

- Reference frame integration governs center-of-mass motion, producing free particle propagation
- Classical interaction dynamics governs relative motion, producing bound states and scattering
- Quantum mechanics emerges from the mathematical superposition of these orthogonal effects

This further extends the unification program initiated in our previous work. The entire mathematical apparatus of non-relativistic quantum mechanics—wave functions, operators, eigenvalue equations, and measurement theory—emerges as the inevitable mathematical consequence of applying Einstein's special relativity to classical mechanics.

The profound simplicity of this result suggests that the conceptual struggles with quantum mechanics stemmed not from the intrinsic mystery of nature, but from incomplete integration of

Einstein's insights about spacetime and reference frames. Once we abandon the intent of absolute rest and embrace reference frame democracy, quantum mechanics becomes as natural as Newton's laws.

The simplest physical mark—our pencil dot—thus reveals the deepest truth about reality. In demonstrating the impossibility of absolute positioning, it illuminated that quantum mechanics is not a separate theory but the natural completion of classical mechanics within Einstein's relativistic framework.

No new physics is required. No fundamental constants need adjustment. No interpretational frameworks need resolution. The mystery was never in nature—it was in our attachment to pre-relativistic thinking.

Quantum mechanics is classical mechanics democratically applied.

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