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# Rotating Bending Fatigue Behavior of AlSi10Mg Fabricated by Powder Bed Fusion-Laser Beam: Effect of Layer Thickness

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**Abstract:** A single batch of AlSi10Mg powder was used to fabricate two groups of round bars via horizontal printing, employing an identical strategy except for one parameter in the process of powder bed fusion - laser beam. The parameter is layer thickness, set at 50 and 80 μm for Group-1 and Group-2, respectively, resulting in laser energy densities of 29.95 and 18.72 J/mm³. Both materials exhibit similar microstructures; Group-1 has fewer and smaller defects than Group-2, leading to higher strength and ductility. Fatigue performance of low-cycle and long-life up to $10^8$ cycles under rotating bending was assessed, and the fracture surfaces were carefully examined under scanning electron microscopy. The S-N data converge to a single slope followed by a horizontal asymptote, indicating the occurrence of very-high-cycle fatigue (VHCF) in both cases. Group-1 shows higher fatigue strength in range of $10^4$ to $10^8$ cycles, and a greater failure probability in VHCF regime than Group-2. This is attributed to the larger defect size in Group-2, where the smaller control volume in rotating bending greatly increases the likelihood of encountering large defects compared to Group-1. At the defect edge, the microstructure shows distinct resistance to crack propagation under high and low loads.

**Keywords:** high-cycle fatigue; very-high-cycle fatigue; rotating bending fatigue; tensile behavior; additive manufacturing; powder bed fusion - laser beam; aluminium alloy; AlSi10Mg; fractography; stress intensity factor

## 1. Introduction

The advantage of additive manufacturing (AM) lies in its seamless integration with computer technologies: a three-dimensional geometric model of the part is first generated through computer-aided design, then sliced and converted into a format compatible with specific additive manufacturing equipment [1–5]. Powder bed fusion (PBF) is an AM technology that utilizes a high-energy beam (e.g., laser or electron beam, the former termed PBF-LB [6]) to selectively melt layers of metal or polymer powder, constructing 3D parts layer by layer. The process involves spreading powder onto a substrate, selectively fusing regions based on a digital model, and repeating the cycle until the part is complete. PBF methods [7–10] enable the fabrication of complex geometries, lightweight structures, and a broad range of materials (e.g., titanium [11–16], aluminum [17–19] and nickel [20–22]), making them widely used in aerospace and medical applications. Post processing steps such as de-powdering, heat treatment, and surface finishing are necessary to achieve the desired final properties. During the PBF-LB process, metal powder is uniformly spread across the build platform, and a laser beam with power $p$ follows a predefined path with scanning speed $s$ and hatch spacing $h$, acting on the surface of the powder to rapidly melt and solidify it, forming solid melt pools and melt track structures. The build platform then lowers by a certain distance (equal to the layer

thickness *t* of powder bed), powder is spread again, and laser melting continues in a cyclic manner until the entire part is fully formed. Throughout this process, the presence of different boundaries on the surface and within the part leads to variations in scanning strategies, which often results in the accumulation of numerous metallurgical defects on or near the surface of the printed components [18,19,23].

According to Refs. [24–27], metal fatigue is a progressive structural degradation that occurs when a material is subjected to cyclic loading, leading to the initiation and propagation of cracks over time. Unlike static failure, fatigue failure can occur at stress levels significantly lower than the material's ultimate tensile strength (UTS) due to the accumulation of microscopic damage. The fatigue life $N_f$ (number of cycles to failure) of a metal component is influenced by factors such as maximum stress $\sigma_{max}$, stress amplitude, loading frequency *f*, residual stresses, microstructure, and environmental conditions. In additively manufactured (AMed) alloys, defects such as porosity, surface roughness, and residual stresses play a crucial role in determining fatigue performance, often necessitating post processing treatments to enhance durability and reliability [28–38]. With the development of modern industrial technology, traditional high-cycle fatigue (HCF, $10^5$ cycles < $N_f$ < $10^7$ cycles) has gradually become insufficient to meet the required safety life standards. As a result, research on very-high-cycle fatigue (VHCF, $N_f$ > $10^7$ cycles) has emerged over the past decades [39–49]. Recently, the VHCF of AMed alloys has received considerable attention [12,14–19,31,50–56]. However, most of the results have been obtained through ultrasonic loading, with a loading frequency of 20 kHz, applied in either axial tension-compression or tension-tension modes.

In the early stages of fatigue research [57–59] and VHCF studies [39,60–62], rotating bending was commonly used to load specimens, with a loading frequency of over 50 Hz, which falls within the range of conventional frequencies [19,63]. Additionally, in rotating bending, the applied stress or strain exhibits a linear gradient, with the maximum at the surface and the minimum at the core. This may lead to HCF and VHCF phenomena different from those observed under ultrasonic axial loading in AMed alloys [64–66]. Given these considerations, the paper conducts rotating bending fatigue experiments in the range of $4.2 \times 10^4$ to $1.3 \times 10^8$ cycles and provides a detailed study on the low-cycle fatigue (LCF), HCF, and VHCF behavior of AMed AlSi10Mg alloys produced by PBF-LB with two groups of processing parameters (varying layer thickness). Subsequently, the fracture surfaces of the specimens are analyzed using a scanning electron microscope (SEM) to determine the failure types of the material under rotating bending. The AM defect characteristics on the fracture surfaces, including size, location, and shape parameters, are examined in relation to LCF, HCF and VHCF lives. Finally, the stress intensity factor (SIF) values near critical AM defects are calculated, taking into account the failure characteristics and statistical defect data, providing a reference for the fatigue performance assessment of the AMed AlSi10Mg alloys.

## 2. Materials and Experiments

### 2.1. Specimen Fabrications

In order to investigate the effect of layer thickness on the LCF, HCF and VHCF of the AMed AlSi10Mg alloys via PBF-LB, two sets of specimens with different layer thicknesses of the powder bed were designed and fabricated in this subsection, while all other controllable printing parameters were kept identical to maintain a single-variable condition. Specifically, the powder layer thickness *t* was set to 50 μm for the first group (Group-1) and 80 μm for the second group (Group-2). During the fabrication of both groups, the laser power *p* was maintained at 370 W, the scanning speed *s* at 1300 mm/s, and the hatch spacing *h* at 0.19 mm. The volumetric laser energy density *E* is commonly used to characterize the amount of heat input per unit volume and serves as a comprehensive process parameter in studies of the PBF-LB [67], which is determined by:

$$E = \frac{p}{t \cdot s \cdot h} \tag{1}$$

Based on the processing parameters of the two groups of samples, the volumetric energy density of the first group was calculated to be 29.95 J/mm$^3$, while that of the second group was 18.72 J/mm$^3$. The latter is much lower than the former; however, both values are relatively low, indicating a state of insufficient heat input.

To eliminate the potential influence of surface and subsurface defects accumulated during the printing process, all specimens were first fabricated as cylindrical rods and then machined and polished into rotating bending fatigue specimens according to the geometry as shown in Figure 1a. In addition, some cylindrical rods were machined into dog-bone shaped specimens for quasi-static tensile testing, as shown in Figure 1b, with a gauge length of 30 mm. It should be noted that all cylindrical rods were printed at 0°, meaning that the axis of both the cylindrical rods and the subsequently machined fatigue and tensile specimens was perpendicular to the build direction.
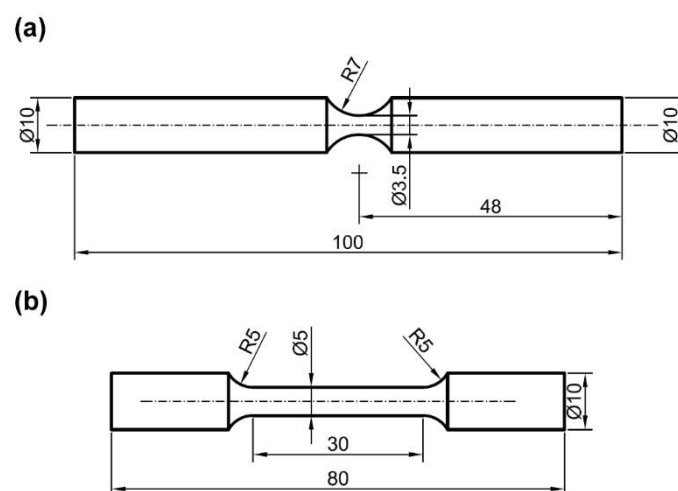


**Figure 1.** Specimen geometries (in mm) for rotating bending fatigue (a) and uniaxial tension (b).

## 2.2. Material Characterizations

This study conducted microstructural observations on two sets of specimens of the AMed AlSi10Mg alloy. First, cylindrical samples measuring Φ10 mm × 5 mm were obtained by electrical discharge wire cutting from the gauge and grip sections of the rotating bending fatigue specimens and quasi-static tensile specimens, serving as preliminary metallographic samples.

Before metallographic polishing, these small cylindrical samples were mounted in resin for easier handling. The polishing surfaces were then ground sequentially using abrasive papers ranging from 300# to 2000# until no visible scratches remained. Subsequently, the surfaces were polished using diamond polishing paste applied to a polishing cloth on a rotating polishing machine until a mirror-like finish was achieved. Finally, Keller's reagent [68] was prepared by mixing distilled water (190 mL), nitric acid (5 mL), hydrochloric acid (3 mL), and hydrofluoric acid (2 mL). The polished surfaces were then etched by immersion in this solution to obtain the metallographic specimens.

The prepared metallographic specimens were qualitatively observed and quantitatively characterized using an optical microscope (OM, Axiovert 200 MAT, Zeiss, Oberkochen, Baden-Württemberg, Germany) and a field emission SEM (Zeiss Gemini SEM 300), respectively. In addition, characterization of internal printing defects in these two batches of samples will be conducted using high-energy X-ray tomography. This technique is particularly suitable for capturing three-dimensional features of surface and internal defects in AMed materials due to its non-destructive nature and high resolution. It has already provided a considerable number of critical references for evaluating the fatigue performance of PBF-LB processed AlSi10Mg.

Prior to conducting rotating bending fatigue tests, several small cylindrical samples (Φ5 mm × 5mm) were obtained from the printed large-diameter rods using wire cutting to meet the requirements of the synchrotron radiation light source, thereby ensuring optimal imaging quality.

Subsequently, high-energy X-ray tomography was performed using the synchrotron radiation source with an X-ray energy of 26 keV and a projection exposure time of 0.5 seconds, achieving a spatial resolution of 3.25 μm. A vertical line (approximately perpendicular to the cylindrical base) within the small cylinder was selected as the rotation axis, and a projection image was recorded every 0.25° rotation. After completing a full 360° rotation, a series of projection images were acquired. These two-dimensional projections were converted into cross-sectional slice stacks perpendicular to the projection plane using PITRE software [69]. Finally, three-dimensional reconstruction was performed in AVIZO software [70].

### 2.3. Tensile and Fatigue Testing

The uniaxial quasi-static tensile test is one of the fundamental material mechanics experiments, from which basic mechanical properties such as yield strength, UTS, elongation, and elastic (Young's) modulus can be obtained.

First, a mechanical electronic extensometer (MTS 635.25F-05, MTS, MN, USA) with a gauge length of 25 mm is attached to the gauge section of the specimen. Subsequently, a uniaxial tensile test is conducted using an MTS Landmark high-frequency fatigue testing machine (with a maximum load capacity of ±100kN) at a loading rate of 1 mm/min and a strain rate of approximately $5 \times 10^{-4}$ /s. During the test, the machine continuously collects data on the force and displacement at the crossbeam, as well as the deformation of the specimen gauge section corresponding to the extensometer.

This subsection employs a cantilever beam-based fatigue testing machine (Giga Quad YRB200, Yamamoto, Osaka, Japan) to perform rotational bending fatigue loading. The specimen is treated as a cantilever beam, with one end connected to the main shaft and the other end loaded with weights to apply a bending moment. The motor drives the main shaft at a high speed of 3150 r/min through a belt drive. During the test, the machine automatically records the number of rotation cycles until the specimen fractures, at which point the recording stops.

The stress distribution under rotating bending loading differs from that under axial tension-compression or tension-tension loading. In axial loading, the stress on the cross section perpendicular to the loading axis of the specimen is generally uniformly distributed (excluding stress concentration caused by changes in cross-sectional geometry). In contrast, under rotating bending, the maximum stress is located at the specimen surface, and the normal stress on the cross section perpendicular to the specimen axis exhibits a gradient distribution, with the stress level being zero at the neutral axis of the cross section. If this gradient is linear, the maximum stress experienced by the specimen follows equation:

$$\sigma_{\max} = \frac{32 \cdot \alpha \cdot l \cdot F}{\pi \cdot d^3} \tag{2}$$

In the equation: $\alpha$ is the stress concentration factor at the specimen's minimum cross section, with a tabulated value of 1.07 according to Ref. [71]; $l$ is the distance from the plumb line of the loading weight to the specimen's minimum cross section, measured as 43.5 mm; $F$ is the applied load, calculated as the product of the total mass of all weights (including the load attached to the specimen, fixtures, springs, etc.) and the gravitational acceleration (taken as 9.8 N/kg); $d$ is the diameter at the specimen's minimum cross section, with a nominal value of 3.5 mm.

After the tests, all tensile and fatigue specimens fractured completely, which differs from the case under ultrasonic loading. The fracture surfaces were cleaned using ultrasonic cleaning in alcohol and acetone to remove dust and contaminants as much as possible. After drying, detailed morphological observation and analysis of the fracture surfaces of all failed specimens were carried out by using an SEM (JSM IT-300, JEOL, Tokyo, Japan).

## 3. Microstructure, Defect and Tensile Behavior

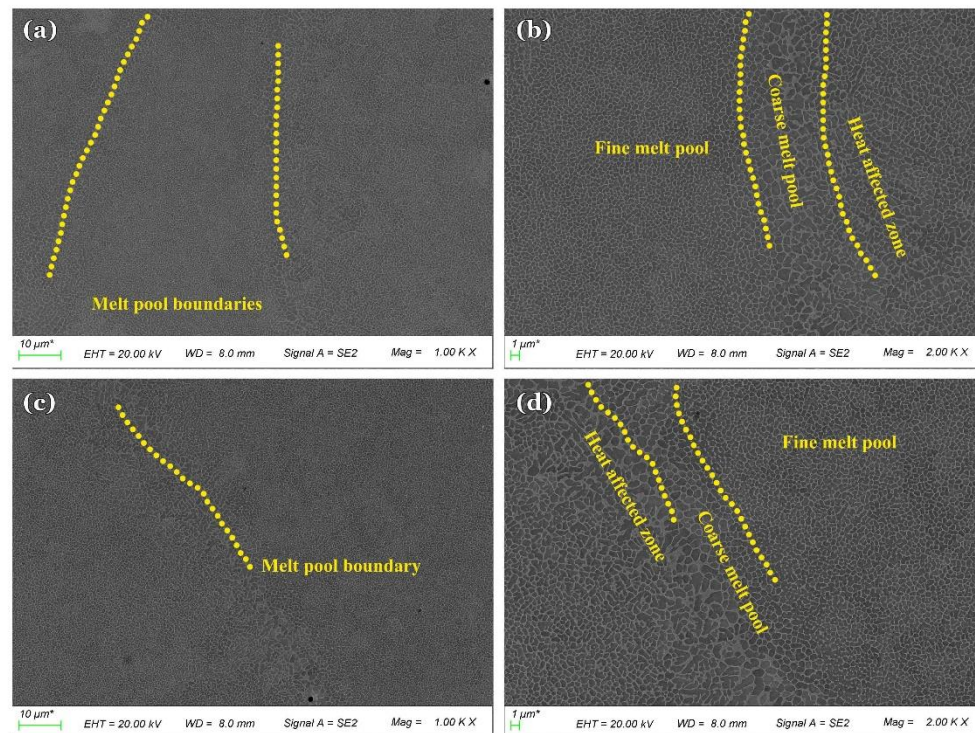### 3.1. Microstructural Features

Figure 2 presents the OM observations of metallographic samples from the AMed AlSi10Mg specimens. These images show cross sections perpendicular to the specimen axis and parallel to the build direction. Subfigures 2a and 2b correspond to the samples of Group-1 and Group-2, respectively.
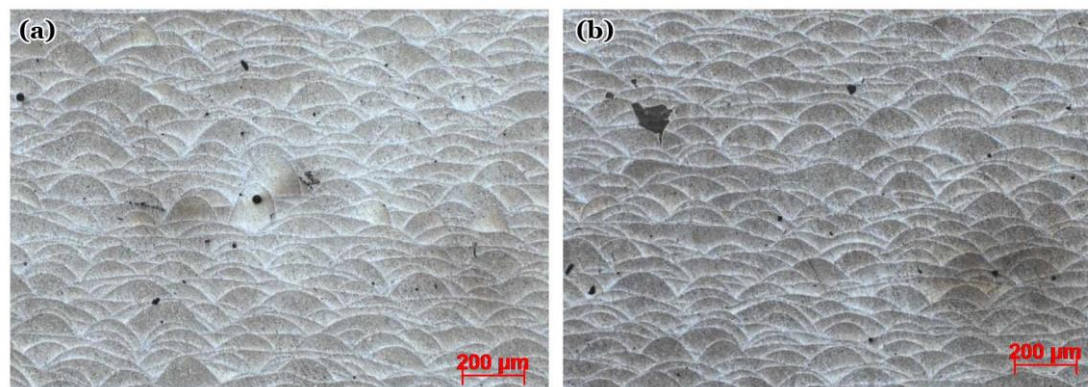


**Figure 2.** Optical micrographs along building direction for etched surfaces of metallographic samples cut from Group-1 (a) and Group-2 (b).

In both cases, distinct melt pool morphologies can be observed, which is one of the common characteristics of AMed eutectic alloys [17–19]. Differences can be seen between the interior and boundary regions of the melt pools, attributed to variations in the distribution of Si particles. The white regions in the images represent the melt pool boundaries, where Si particles are present at a lower density, while the gray areas indicate the interior of the melt pools, where Si particles are more densely distributed. This contrast arises because Si particles appear dark under the optical microscope, whereas the $\alpha$-Al matrix appears bright. As shown in Figure 3, in the secondary electron images obtained from the field emission SEM, the $\alpha$-Al matrix appears dark gray, while the Si particles appear bright white. The roughened morphology formed around the edges of the Si particles due to metallographic etching further enhances the contrast of the Si particles. Subfigures 3a,b and 3c,d present the secondary electron morphologies of the metallographic samples from Group-1 and Group-2 at different magnifications.

The overall morphologies are similar, with melt pool features faintly visible. In Figure 3 a and c, the melt pool boundary regions are composed of slightly coarser Si networks, while the enclosed interior areas consist of finer, more densely connected Si networks. At higher magnifications, as shown in Figure 3 b and d, across two adjacent melt pools, a clear trend of the Si network or $\alpha$-Al cell size increasing and then decreasing can be observed. In the fine regions, the equivalent diameter is less than 1 μm, while at the melt pool boundaries, it can reach the order of 5–6 μm. Three distinct regions can be clearly identified: melt pool fine zone (MP-fine), melt pool coarse zone (MP-coarse), and heat affected zone (HAZ). In the MP-fine, the Si networks are finer and uniformly distributed; in the MP-coarse, the Si particles are larger and more sparsely distributed; and in the HAZ, the Si networks exhibit irregular shapes and distributions.

**Figure 3.** Microstructure features of melt pool boundaries for Group-1 (a,b) and Group-2 (c,d).

### 3.2. Additive Manufacturing Defects

To further determine the three-dimensional morphology and distribution of printing defects, high-energy synchrotron X-ray computed tomography (CT) was performed on cross-sectional samples from the two groups of AMed AlSi10Mg specimens.

Figure 4 presents reconstructed cross-sectional slices obtained using PITRE software from direct high-energy X-ray projections of the specimen surfaces in their as-built state. The slice positions are indicated in the top-right corner of the figure. The slice positions were selected essentially at random, and the observed distribution of printing defects does not show any essential difference across locations. As shown in the figure, two typical types of pore-like printing defects can be identified: gas pores and lack-of-fusion defects. Gas pores are relatively small in size with more regular shapes, generally appearing equiaxed or ellipsoidal. In contrast, lack-of-fusion defects are usually larger and more irregular, often formed by the combination of several interconnected pores. Consistent with the observations from the cross-sectional metallographic samples, the second set of specimens with larger layer thickness exhibits an order-of-magnitude higher number of pore-type printing defects in the CT slices, and these defects frequently show larger projected areas.
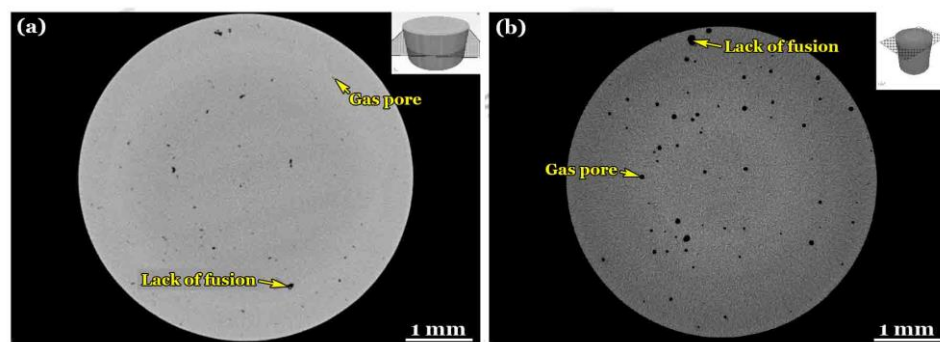


**Figure 4.** Defect distributions on cross sections of CT samples for Group-1 (a) and Group-2 (b).

However, metallographic cross sections or CT slices can only reflect the projected characteristics of pore-type printing defects on a single two-dimensional plane and cannot fully represent the three-dimensional distribution of these defects. Therefore, AVIZO software was used to stack and reconstruct these slice sets. The reconstruction results are shown in Figure 5, where subfigures 5a and 5b present the three-dimensional volume renderings of pore-type printing defects in the first and second groups of specimens. In these renderings, different colors correspond to different scales of defect equivalent sizes. The diameter of the sample cross section is 5 mm.

In order to quantitatively describe the size and shape of the defects, the equivalent diameter $d_{eq}$ and sphericity $d_s$ of each defect were calculated using the following equations:

$$d_{eq} = \left( \frac{6 \cdot v_d}{\pi} \right)^{1/3} \tag{3}$$

$$d_s = \frac{\pi^{1/3} \left( 6 \cdot v_d \right)^{2/3}}{s_d} \tag{4}$$

where $v_d$ is the defect volume, and $s_d$ is the defect surface area.

Obviously, more and larger pore-type printing defects are distributed in the CT samples of the second group of specimens. For quantitative analysis, Figure 6 presents the frequency histograms and cumulative frequency curves of the equivalent diameters of defects. As shown in Figure 6a, in Group-1, over 93% of the pore-type printing defects have an equivalent diameter smaller than 30 μm. Similarly, in Group-2, more than 88% of the defects are also smaller than 30 μm in equivalent diameter. This indicates that, for both sets of specimens, the vast majority of printing defects are small pores. In Group-1, the largest detected defect size is on the order of 150 μm, with a very low occurrence frequency of only 0.02%. In contrast, the largest detected defect in Group-2 reaches approximately 450 μm, also with a frequency of around 0.02%. Comparing Subfigures 6a and 6b, it can be seen that the distributions of pore-type printing defects in both groups follow a similar trend; however, the defect sizes in Group-1 are considerably smaller than those in Group-2. In short, the probability of large defects occurring in Group-2 is more than three times higher than in Group-1, and the maximum defect size in Group-1 is less than one-third of that in Group-2. For both groups, most defects are relatively small, and the probability of occurrence decreases gradually as the equivalent diameter increases.
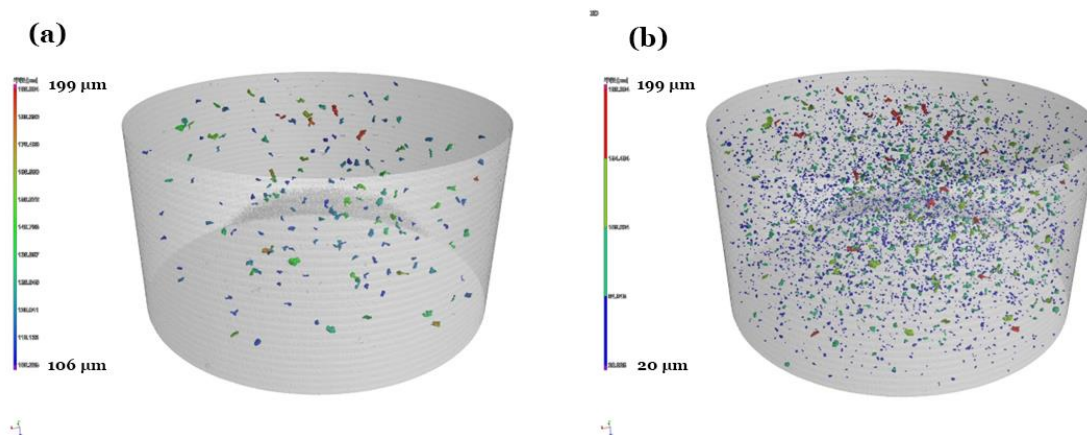


**Figure 5.** 3D defect distribution in CT samples for Group-1 (a) and Group-2 (b).
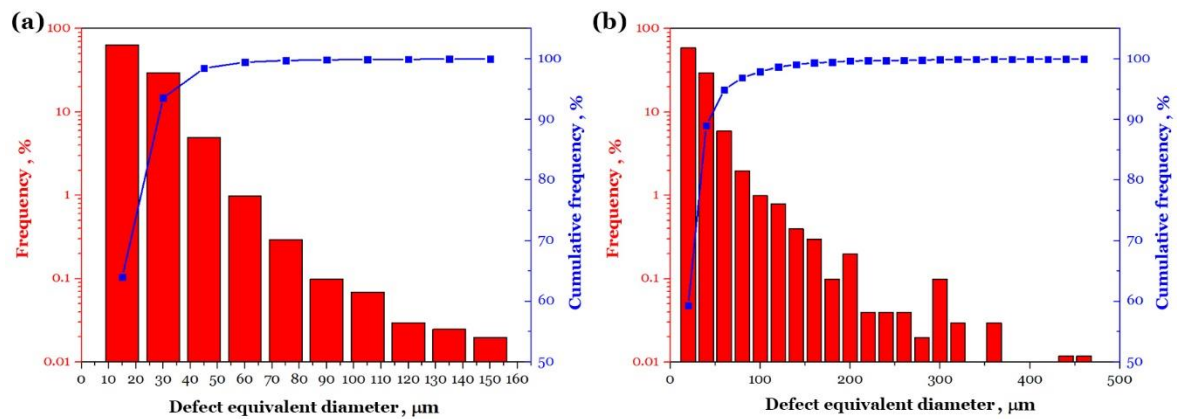
**Figure 6.** Defect statistics of Group-1 (a) and Group-2 (b) for the AMed AlSi10Mg.

### 3.3. Tensile Curves and Fractography

Figure 7 presents the engineering stress-strain curves obtained from uniaxially quasi-static tensile tests conducted in ambient air at room temperature for two sets of the AMed AlSi10Mg specimens. Based on these curves, the elastic modulus (Young's), yield strength (at 0.2% offset plastic strain), UTS, and elongation after fracture can be determined. The results show that for all these mechanical properties — including elastic modulus, yield strength, UTS, and elongation — the values for Group-2 specimens are lower than those for Group-1.
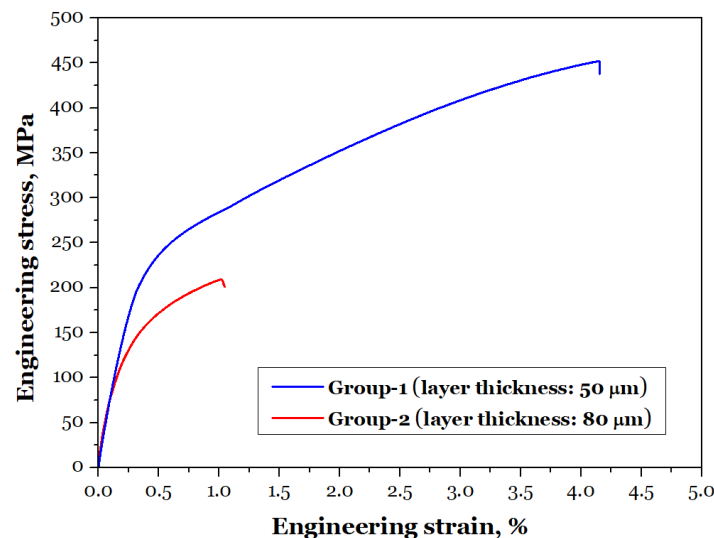


**Figure 7.** Tensile curves for the two groups of the AMed AlSi10Mg.

As shown in Figure 8, detailed observations of the quasi-static tensile fracture surfaces of both groups of specimens were conducted using the SEM. Compared with the first group, the fracture surfaces of the second group exhibit a large number of printing defects, which is the fundamental reason for the significant reduction in yield strength and ultimate tensile strength. These pore-type defects greatly weaken the overall stiffness of the specimens. In addition, the reduction in elongation is most likely attributed to the severe stress and strain concentrations around the pore-type defects during monotonic loading, which induce deformation localization and accelerate the damage accumulation process [72].
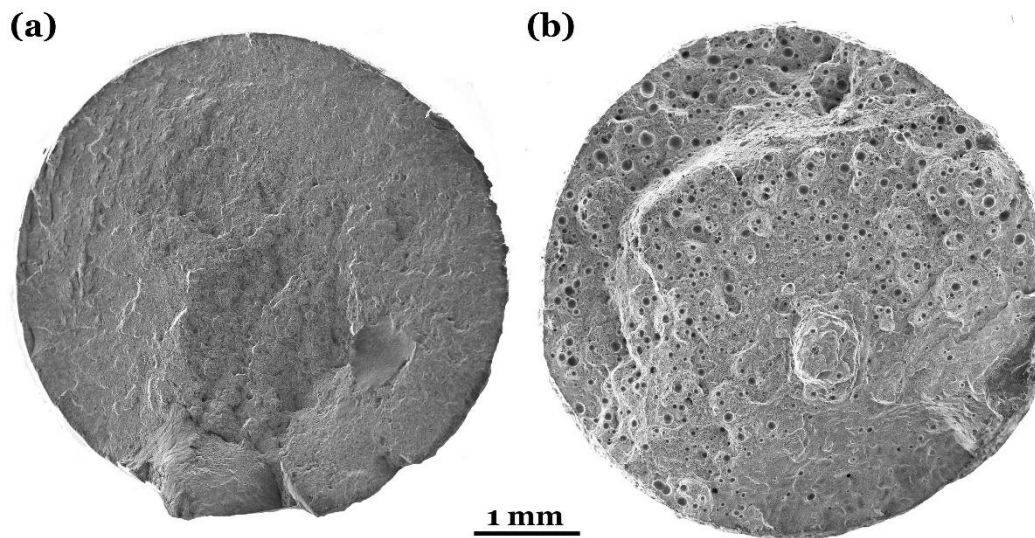
**Figure 8.** Representative SEM images of tensile fracture surfaces for Group-1 (a) and Group-2 (b).

## 4. Low-Cycle and Long-Life Fatigue Performance

*4.1. Fatigue Performance Analysis*

Figure 9 presents the S-N data for two groups of PBF-LB AlSi10Mg specimens tested in air at room temperature under a stress ratio of $R = –1$. In the figure, data points marked with arrows represent specimens that did not fracture by the time the number of cycles reached the value indicated on the horizontal axis. Overall, the LCF, HCF and VHCF performance of Group-1 is consistently superior to that of Group-2. As the number of cycles to failure increases from $3 \times 10^4$ to $3 \times 10^6$, the HCF limit of the Group-1 decreases from a maximum stress (equal to the stress amplitude) of $\sigma_{max} = 150$ MPa to approximately 80 MPa. In contrast, for Group-2, as the number of cycles to failure increases from $7 \times 10^4$ to $3 \times 10^6$, the HCF limit decreases from $\sigma_{max} = 100$ MPa to around 25 MPa. With a further increase in loading cycles, from $10^6$ to $10^8$ under rotating bending conditions, the fatigue limit in terms of maximum stress for Group-1 remains relatively stable in the range of 70–85 MPa. Similarly, the fatigue limit of Group-2 stabilizes in the range of $\sigma_{max} = 15$–25 MPa.
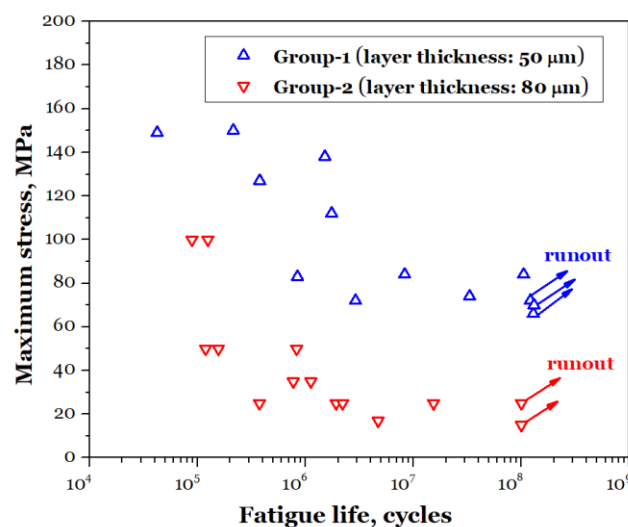


**Figure 9.** S-N data for the two groups of the AMed AlSi10Mg.

The S-N data indicate that both groups of the AMed AlSi10Mg specimens exhibit a clear VHCF plateau region under rotating bending loading, while in the HCF regime, the fitting curve of S-N data display a single linear slope. For Group-1 of specimens, the maximum applied number of cycles reached $1.3 \times 10^8$, with the highest fatigue fracture cycle count at $1.0 \times 10^8$, and a fatigue limit of approximately 70 MPa. In contrast, for Group-2, the maximum applied cycle count was $1.0 \times 10^8$, but the highest fatigue fracture cycle count was only $1.5 \times 10^7$, with a fatigue limit of approximately 15 MPa. Compared with Group-2, Group-1 demonstrates significantly superior fatigue performance.

### 4.2. Fatigue Fracture Surface Morphologies

To further investigate how printing defects affect the LCF, HCF and VHCF behavior of the AMed AlSi10Mg alloys under rotating bending loading, a detailed examination of the fatigue fracture surfaces was performed, according to Ref. [73].

Figure 10 presents the fatigue fracture surfaces under lower cycle conditions, where large un-melted defects are the primary source of crack initiation. In the high value of maximum stress or LCF regime, fatigue cracks tend to initiate from multiple un-melted defects located at or near the surface of the specimens. As shown in the figure, cracks begin to propagate from un-melted defects on several different planes, and as the cracks grow, "ridges" formed by the coalescence of fatigue cracks on different planes can be observed. As the cracks merge, the crack propagation area expands instantaneously. It is evident that the crack initiation mechanism is influenced by the interaction between the maximum stress and surface AM defects. Due to the higher stress levels, multiple cracks simultaneously reach the threshold of the stress intensity factor, leading to concurrent crack propagation [74,75].
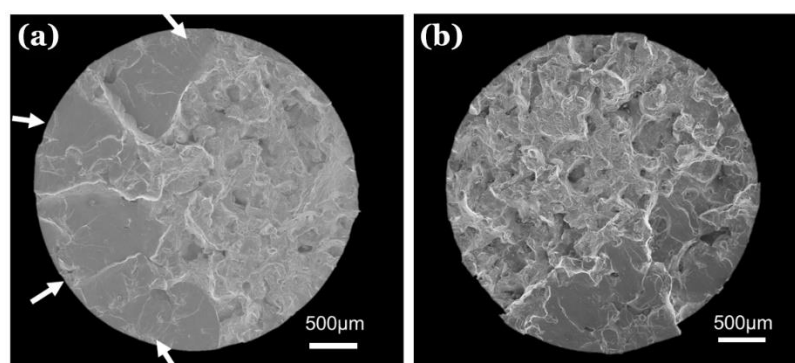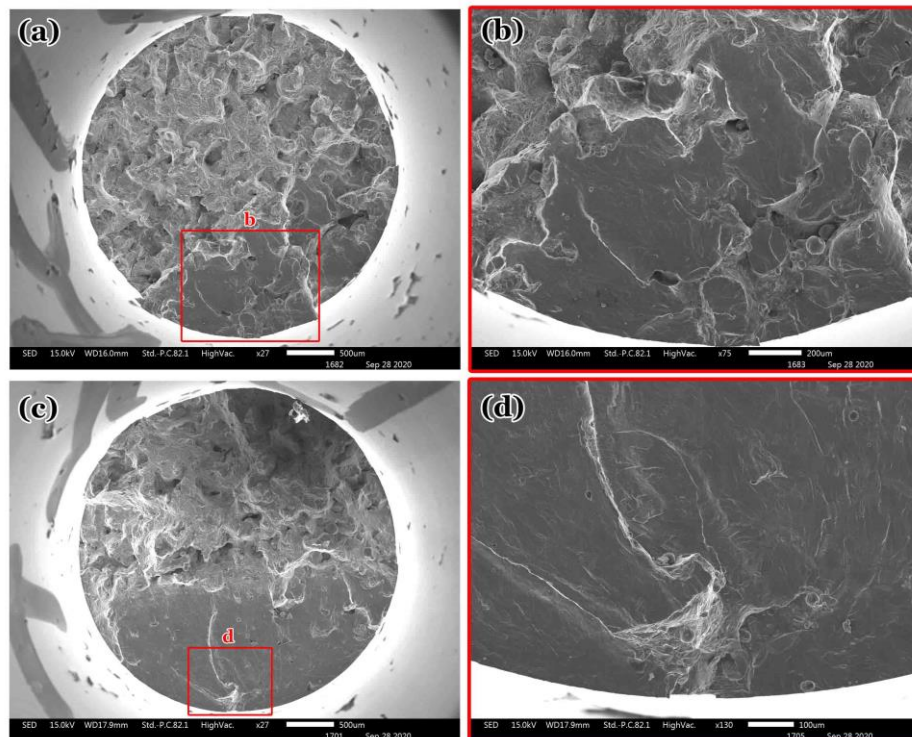


**Figure 10.** SEM images showing fracture surfaces of low-cycle fatigue for the AMed AlSi10Mg: (a) Group-1, $\sigma_{max}$ = 127 MPa, $N_f = 3.8 \times 10^5$ cycles; (b) Group-2, $\sigma_{max}$ = 100 MPa, $N_f = 1.2 \times 10^5$ cycles.

During the high-cycle and very-high-cycle stages, fatigue failure in both groups of specimens is dominated by a single crack source, as shown in Figures 11 and 12. After initiating from the unfused defects, fatigue cracks propagate into the crack growth region, exhibiting a semi-elliptical morphology. Comparing with the fracture surfaces under ultrasonic axial loading reported by Qian et al. [17], it can be observed that, under rotating bending conditions, cracks tend to initiate from surface and subsurface defects, with few originating from internal defects. This is due to the gradient distribution of stress across the specimen's depth under rotating bending fatigue, where the maximum stress occurs at the specimen surface, making internal cracking less common. Furthermore, fracture surface analysis reveals that the cracks initiate from unfused defects, not pore defects. This is because, under the same external loading conditions, unfused defects are larger and more irregular in shape, leading to more pronounced stress concentrations, making cracks more likely to initiate from these defects. This indicates that, compared to pore defects, unfused defects are more detrimental.
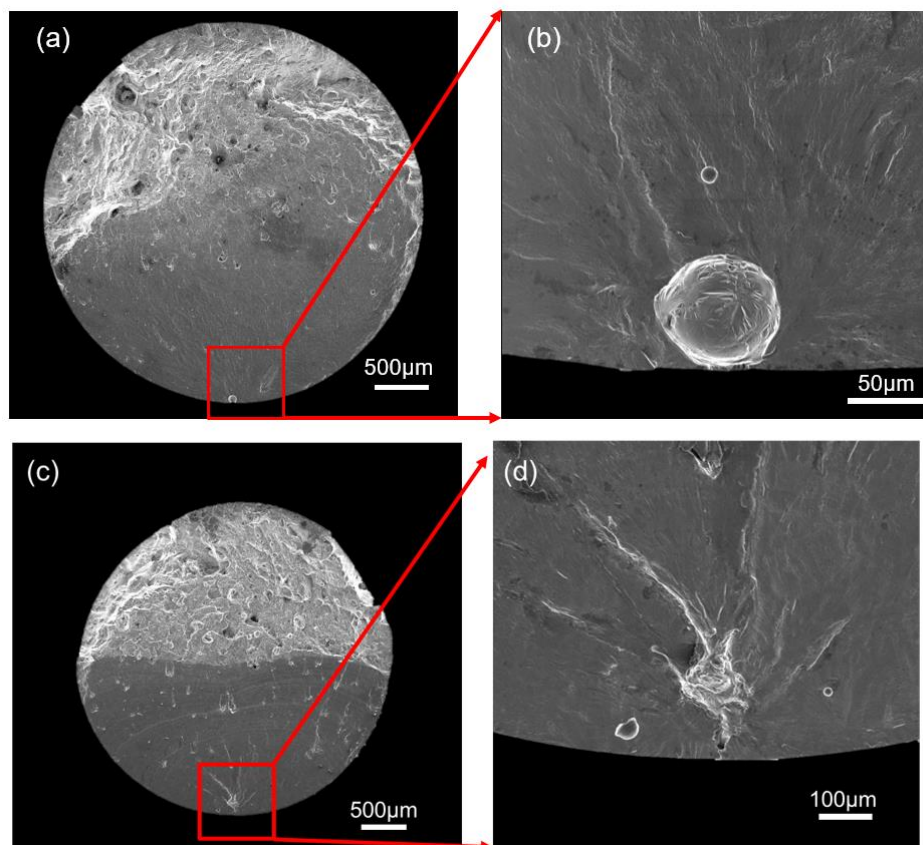
**Figure 11.** SEM images showing fracture surfaces of long-life fatigue for Group-1: (a,b) $\sigma_{max}$ = 112 MPa, $N_f$ = 1.8 × $10^6$ cycles; (c,d) $\sigma_{max}$ = 74 MPa, $N_f$ = 3.3 × $10^7$ cycles.



**Figure 12.** SEM images showing fracture surfaces of long-life fatigue for Group-2: (a,b) $\sigma_{max}$ = 25 MPa, $N_f$ = 1.9 × $10^6$ cycles; (c,d) $\sigma_{max}$ = 25 MPa, $N_f$ = 1.5 × $10^7$ cycles.

### 4.3. Instantaneous Fracture Surfaces and Features

At the end of the crack initiation stage, its SIF value is comparable to the threshold for long fatigue-crack propagation [76]. As the SIF continues to increase, the crack enters the steady-state growth stage. After the crack enters the stable growth stage, if the SIF value at the fatigue crack tip reaches the material's fracture toughness, the crack will undergo unstable propagation. Therefore, the area of the unstable fracture zone can, to some extent, reflect the material's fracture toughness [77,78].

Figure 13 shows the statistical analysis of the proportion of the unstable fracture zone area in the fracture surfaces of both sets of the AMed AlSi10Mg specimens. It can be observed that, with an increase in stress levels, the proportion of the unstable fracture zone area increases. However, for the specimens in Group-1 at 150 MPa and Group-2 at 100 MPa, although the applied maximum stresses are relatively high, the proportion of the unstable fracture surface is comparatively small. This is because, under these loading conditions, the specimens exhibit multiple crack origins, with several cracks propagating simultaneously, leading to more complete crack propagation compared to a single crack source. The smallest proportion of the unstable fracture zone area for Group-1 is 0.36, and the largest is 0.65. For Group-2, the smallest proportion is 0.5, and the largest is 0.82. The proportion of the unstable fracture zone area is significantly higher in Group-2 than in Group-1, indicating a substantial decrease in fracture toughness for Group-2. As seen in the fracture surfaces in Figure 12, a large number of unfused defects can be clearly observed at the crack front in Group-2 specimens. When the fatigue cracks propagate, these aggregated large unfused defects cause the fatigue cracks in Group-2 to undergo more easily unstable propagation, resulting in a decrease in fracture toughness.
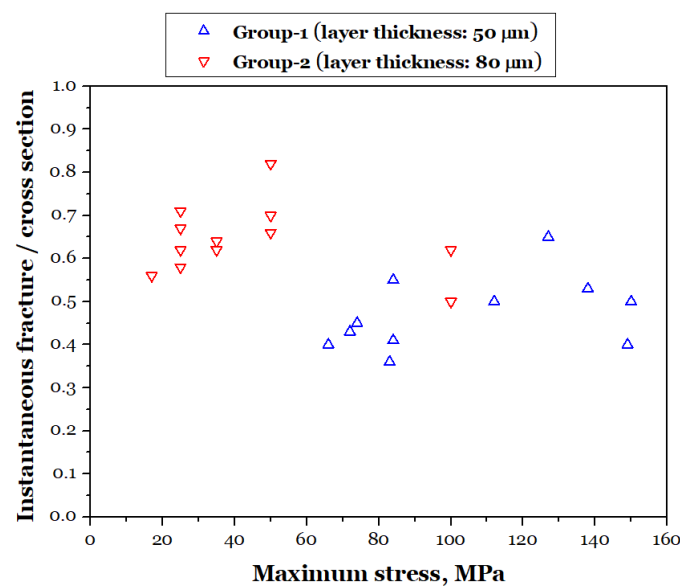


**Figure 13.** Area ratio of instantaneous fracture to specimen cross-section versus maximum stress.

### 4.4. Quantification of Fatigue-Dominating Defects

To quantitatively analyze the effect of defect characteristics on the LCF, HCF and VHCF performance of the AMed AlSi10Mg, ImageJ2 software [79] was used to quantify the characteristic parameters of critical defects in the fracture surfaces of each fatigue specimen. The equivalent defect size was determined using the method proposed by Murakami [25]. The defect depth is defined as the shortest distance from the center of the critical defect to the specimen surface. Additionally, defect sphericity $d_{sa}$ was introduced to describe the defect shape.

$$d_{sa} = \frac{area_d}{\pi \cdot r_{max}^2} \tag{5}$$

In the equation: $area_d$ represents the critical defect area; $r_{max}$ denotes the maximum distance from the defect center to the outer bounding contour of the AM defect; $d_{sa}$ is sphericity, a measure of circular similarity, which is a dimensionless value ranging from 0 to 1, where 0 indicates a highly irregular shape and 1 represents a perfect circle.

Figure 14a illustrates the variation of the equivalent diameter of critical defects on the fracture surface with the number of cyclic loads. It can be observed that, for both groups of specimens, there is no clear correlation between the equivalent diameter of the critical defect inducing crack initiation and fatigue life. For Group-1, the equivalent diameter of defects inducing crack initiation ranges from 62 to 136 μm. In contrast, for Group-2, the range is 170 to 454 μm. The data indicate that the critical defect size in Group-2 is significantly larger than in Group-1, with greater variability in defect size.

Figure 14b shows the relationship between the critical defect depth and the number of loading cycles for both groups of specimens. It can be observed that for Group-1, the defect depth ranges from 48 to 114 μm, while for Group-2, the defect depth ranges from 104 to 390 μm. These data suggest that the distribution of defects has a significant impact on the crack initiation location. The larger the defect size, the higher the probability of initiation at a deeper location.

As shown in Figure 14c, the defect sphericity for Group-1 of specimens ranges from 0.47 to 0.82, while for Group-2, it ranges from 0.17 to 0.62. It can be observed that the defects in Group-2 are more irregular in shape. The statistical results for the defect shape parameters indicate that the sphericity of defects in Group-2 is significantly lower than in Group-1, which is consistent with the correlation between defect size and shape observed in the previous CT analysis.
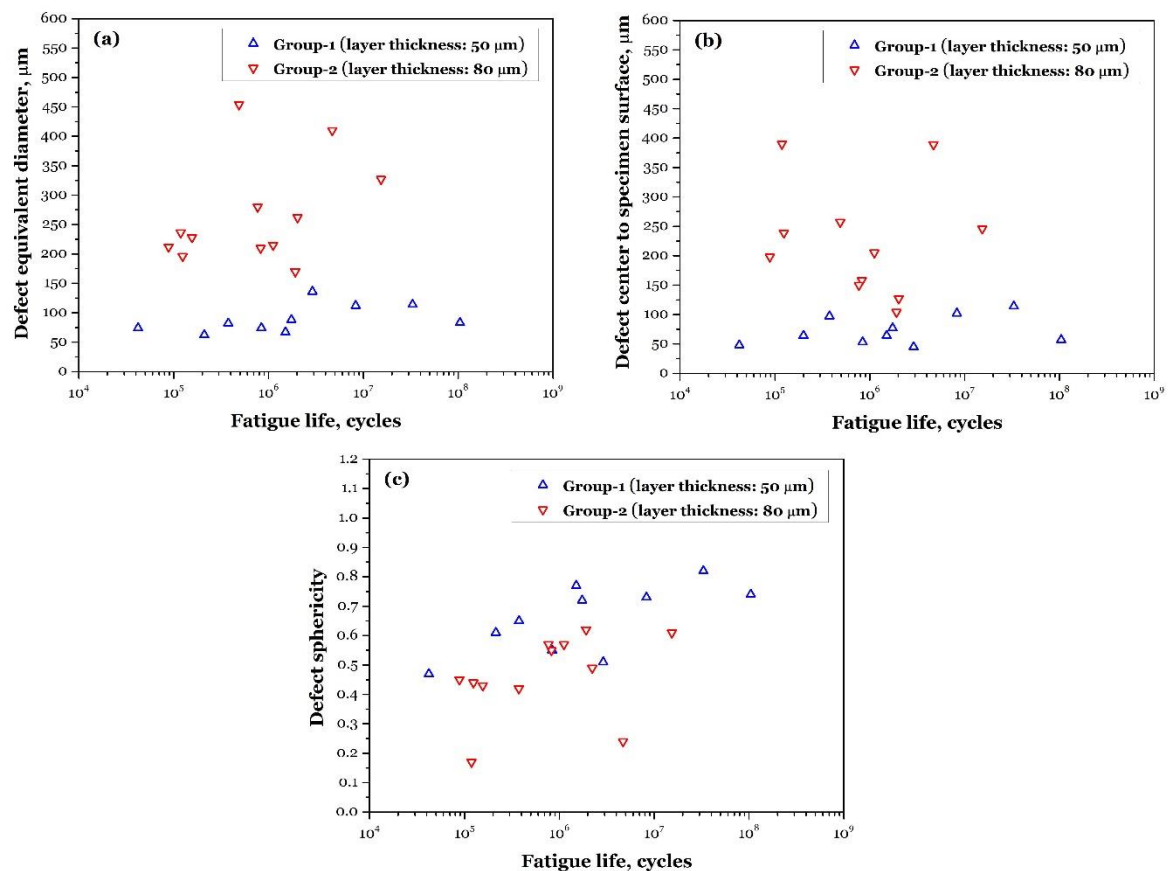


**Figure 14.** Size, location and shape of fatigue-initiating defect versus failure cycle.

Furthermore, unlike the patterns observed for defect size and depth, as the fatigue life increases, the shape of the critical defects becomes more regular. This suggests that under rotating bending

loading conditions, during the HCF and VHCF stages, cracks are more likely to initiate from unfused defects with a more regular shape. Cracks initiated and propagated from such regular-shaped unfused defects consume more fatigue cycles. Therefore, optimizing the process to prevent the formation of unfused defects, especially those with irregular shapes, in AMed components is crucial for enhancing fatigue performance.

From the above fracture surface analysis, it can be seen that fatigue cracks in the AMed AlSi10Mg alloys produced by PBF-LB under rotating bending loading conditions initiate from surface or near-surface unfused defects and gradually propagate, eventually leading to material fracture. The preceding paragraphs quantify the relationship between critical defect characteristics on the fracture surface and fatigue life. From the perspective of fracture mechanics, defects in the material can be assumed to be cracks. When the SIF at the crack tip reaches the threshold [76] for crack growth, the crack will begin to expand. To quantitatively characterize the relationship between AM defect (at specimen surface) induced fatigue crack initiation and early-stage growth behavior [80], this section uses the maximum stress of the SIF at the crack tip to describe it. The calculation method for the SIF of surface and internal (subsurface) defects are given by equations (6) and (7), respectively.

$$K_{max} = 0.5 \cdot \sigma_{max} \sqrt{\pi \sqrt{area_d}} \qquad (6)$$

$$K_{max} = 0.65 \cdot \sigma_{max} \sqrt{\pi \sqrt{area_d}} \qquad (7)$$

Figure 15 shows the distribution of the SIF at the critical defects in both groups of specimens as a function of fatigue life cycles. For Group-1, the SIF at the critical defects ranges from approximately 0.78 to 1.39 MPa·m$^{1/2}$. For Group-2, the SIF at the defects inducing crack initiation ranges from approximately 0.35 to 1.58 MPa·m$^{1/2}$. From the data, it can be seen that for Group-2, the presence of a large number and size of unfused defects reduces the intrinsic properties of the AMed material, and the threshold for crack initiation and early growth is significantly lowered.
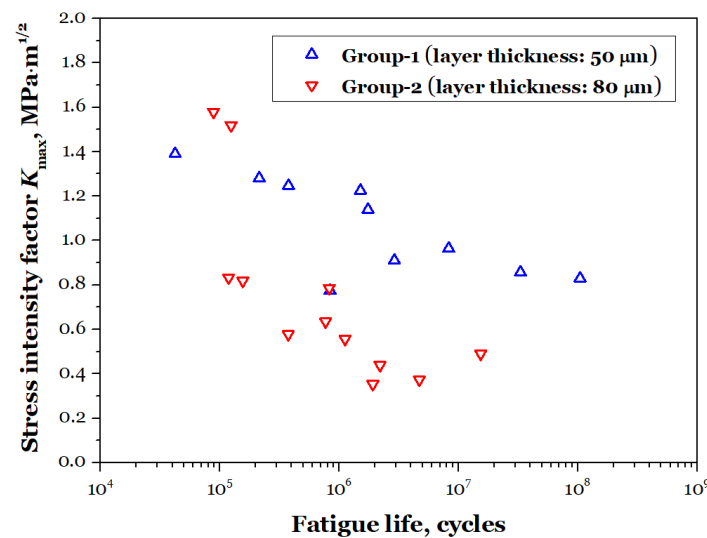


**Figure 15.** Stress intensity factor $K_{max}$ on fatigue-initiating defect versus failure cycle.

## 5. Conclusions

By using rotating bending and failure analysis, this paper investigates the low-cycle, high-cycle and very-high-cycle fatigue behavior of the AMed AlSi10Mg via PBF-LB with horizontal printing. The study focuses on two different processing parameters: powder layer thickness of 50 μm and 80 μm, corresponding to laser energy densities of 29.95 and 18.72 J/mm³. The following conclusions can be drawn:

1. Under rotating bending cyclic loading conditions, cracks initiate from surface or near-surface defects. Under high-cycle stress or low-cycle conditions, cracks tend to exhibit multi-source cracking

characteristics. In the low-stress or very-high-cycle phase, fatigue cracks initiate from a single crack source.

2. The powder bed thickness has a significant impact on tensile and fatigue properties. The second batch of specimens contains more and larger unfused defects. The tensile and fatigue performance of the first batch (50 μm layer thickness) is much higher than that of the second batch (80 μm layer thickness).

3. The fracture resistance of the second batch of specimens (80 μm layer thickness) is significantly lower than that of the first batch (50 μm layer thickness). The presence of AM defects in the material reduces the crack propagation threshold and fracture toughness of the AMed alloy.

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## Abbreviations

The following abbreviations are used in this manuscript:

| | |
|---|---|
| AM | Additive manufacturing |
| AMed | Additively manufactured |
| CT | Computed tomography |
| HAZ | Heat affected zone |
| HCF | High-cycle fatigue |
| MP-coarse | Melt pool coarse zone |
| MP-fine | Melt pool fine zone |
| OM | Optical microscope |
| PBF-LB | Powder bed fusion - laser beam |
| SEM | Scanning electron microscope |
| SIF | Stress intensity factor |
| UTS | Ultimate tensile strength |
| VHCF | Very-high-cycle fatigue |

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