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Posted Date: 2 February 2026

doi: 10.20944/preprints202207.0399.v102

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# Euclidean Relativity Improves Cosmology and Quantum Mechanics

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Special/general relativity (SR/GR) work for all observers, but they do not provide diagrams of nature that work for all observers. This is because they do not describe nature as an absolute manifold, where all action is due to an absolute parameter. We show: Euclidean relativity (ER) achieves precisely that. It describes a mathematical Master Reality, which is *absolute* 4D Euclidean space (ES). All objects move through ES at the dimensionless speed  $C$ . There is no time in ES. All action in ES is due to an *absolute*, external evolution parameter  $\theta$ . Every object experiences two projections from ES as space and time: The axis of its current 4D motion is its proper time  $\tau$ . Three orthogonal axes are its 3D space  $x_1, x_2, x_3$ . An observer's physical reality is the Minkowskian reassembly of his axes  $x_1, x_2, x_3, \tau$ . In this " $\tau$ -based Minkowskian spacetime" ( $\tau$ -MS),  $\tau$  is the new time coordinate and  $\theta$  converts to parameter time  $\vartheta$ . ER reproduces the Lorentz factor and gravitational time dilation, but gravity is Newtonian. Action at a distance is not a problem: Information is instantaneous in timeless ES. Only in  $\tau$ -MS does the time coordinate cause a delay. Presumably, gravity is carried by gravitons and manifests itself in  $\tau$ -MS as waves. ER rejects curved spacetime, cosmic inflation, expanding space, dark energy, and non-locality. Nevertheless, ER predicts time's arrow, the Hubble tension, and entanglement. There are two options: Physics either sticks to SR/GR and highly speculative concepts, or it breaks new ground with ER.

**Keywords:** spacetime; special relativity; general relativity; Hubble tension; dark energy; non-locality

Clocks measure proper time  $\tau$ . There are two ways to interpret  $\tau$ : In special relativity (SR) and general relativity (GR) [1, 2],  $\tau$  can parameterize an object's worldline in spacetime. In Euclidean relativity (ER),  $\tau$  is the time coordinate of  $\tau$ -based Minkowskian spacetime. Its metric has the same form as the metric of Minkowski spacetime. ER provides observer-independent diagrams of nature. There are no such diagrams in SR/GR.

SR and GR work for all observers. And yet, we show: ER must be applied to (a) the very early universe, (b) very distant objects (high-redshift supernovae), and (c) entangled objects (moving in opposite directions through 4D Euclidean space at the speed of light). In such extreme situations, a 4D Euclidean vector "flow of proper time" must be taken into account. *What is the key message of ER?* There is a mathematical reality beyond all physical realities. *Does ER make any quantitative predictions?* Yes, ER predicts the ten percent discrepancy in the published values of the Hubble constant (see Sect. 5.10).

**Request to all readers:** Avoid the following six pitfalls. Editors and reviewers of top journals fell into them. (1) *Do not apply the concepts of SR/GR to ER.* The only standards for a theory are its own concepts and measurement data. (2) *Do not play SR/GR off against ER.* ER provides relevant information that is not available in GR. (3) *Do not expect Einstein's field equations in ER.* In ER, gravity is Newtonian. (4) *Do not reject ER because it extends beyond an observer's reality.* ER is a physical theory because it predicts what we observe. (5) *Be curious.* New coordinates can bring us new insights. Coordinates in SR/GR are only labels that can be adjusted to simplify computations. In ER, coordinates are inherent properties of objects that cannot be adjusted (they refer to absolute 4D space). (6) *Be fair.* Top journals rejected ER because it does not yet reproduce all of GR's predictions. All papers on GR would then also have to be rejected until GR-based cosmology reproduces all of ER's predictions, such as the Hubble tension. The same standards must apply to all theories.

## 1. Introduction

The concepts of space and time in today's physics were coined by Albert Einstein. In SR, a flat spacetime is described by the Minkowski metric. The geometric framework for SR is Minkowski spacetime [3]. The muon lifetime [4] is an example that supports SR. In GR, a curved spacetime is described by the Einstein tensor. The deflection of starlight [5] and the accuracy of GPS [6] are two examples that support GR. Quantum field theory [7] unifies classical field theory, SR, and quantum mechanics (QM), but not GR.

Newburgh and Phipps [8] pioneer ER. Montanus [9, 10] adds a restriction: He considers a preferred reference frame in which a pure time interval is a pure time interval for all observers (see page 351 of [9]). He deprives ER of its key feature: full symmetry in all four axes. Montanus claims (see page 17 of [11]): The preferred frame is required to avoid "distant collisions" (without physical contact) and a character paradox (confusion of photons, particles, antiparticles). *Our formulation of ER does not prefer any frame.* There are no distant collisions: Only three axes are experienced as spatial. There is no character paradox: Characters appear in physical realities only. Montanus [10] derives the deflection of starlight and the precession of Mercury's perihelion. He also tries to derive Maxwell's equations in 4D Euclidean space [11], but fails to see that they are incompatible with SO(4).

Almeida [12] analyses geodesics in 4D Euclidean space. Gersten [13] shows that the Lorentz transformation is an SO(4) rotation in a mixed space  $x_1, x_2, x_3, t'$ , where  $t'$  is the Lorentz transform of  $t$ . There is also a website about ER: <https://euclideanrelativity.com>. Previous formulations of ER [8–13] merely rearrange the Minkowski metric of SR to give it a Euclidean appearance. We propose three steps to make ER work: (1) There is a mathematical Master Reality (4D Euclidean space) beyond all physical realities. (2) Every object experiences two projections from the Master Reality as space and time. (3) An observer's physical reality is the Minkowskian reassembly of his space and his time.

To this day, ER is rejected for various reasons: (a) GR has been confirmed very often. (b) There seem to be paradoxes in ER. (c) ER takes a new approach to gravity. Now we are at a turning point: (a) No scientific theory is "set in stone". (b) Projections avoid paradoxes. (c) In GR, information cannot travel faster than the speed of light  $c$ . Thus, gravity cannot be Newtonian in GR. In ER, action at a distance is not a problem because information is instantaneous in timeless 4D Euclidean space. Only in physical realities does the time coordinate cause a delay. For this reason, gravity can be Newtonian in ER.

It is instructive to compare three settings for describing motion. In *Newton's physics*, all objects move through 3D Euclidean space as a function of time. There is no speed limit. In *Einstein's physics*, all objects move through 4D non-Euclidean spacetime as a function of an internal parameter. The speed limit is  $c$ . In *Euclidean relativity*, all objects move through 4D Euclidean space as a function of an external parameter. The 4D speed of everything is dimensionless  $C$ . In physical realities, the parameter converts to parameter time.

## 2. Drawbacks of Special and General Relativity

In § 1 of SR [1], Einstein considers a reference frame "in which the equations of Newton's physics apply" (to a first approximation). If an object is at rest in this frame, its position in 3D space is determined using rigid rods and a 3D Euclidean geometry. If we also want to describe an object's motion, we have to define time. Einstein gives an instruction on how to synchronize two clocks at the points P and Q. At a time  $t_p$ , a light signal is sent from P to Q. At  $t_Q$ , it is reflected at Q. At  $t_p^*$ , it is back at P. The clocks synchronize if

$$t_Q - t_p = t_p^* - t_Q . \quad (1)$$

In § 3 of SR, Einstein derives the Lorentz transformation. The coordinates  $x_1, x_2, x_3, t$  of an event in a system K are transformed to the coordinates  $x'_1, x'_2, x'_3, t'$  in K' by

$$x'_1 = \gamma (x_1 - v_1 t) , \quad x'_2 = x_2 , \quad x'_3 = x_3 , \quad (2a)$$

$$t' = \gamma (t - v_1 x_1/c^2) , \quad (2b)$$

where K' moves relative to K in  $x_1$  at the constant speed  $v_1$  and  $\gamma = (1 - v_1^2/c^2)^{-0.5}$  is the Lorentz factor. Eqs. (2a–b) transform the coordinates from K to K'. Covariant equations transform the coordinates from K' to K. The metric of Minkowski spacetime is

$$c^2 d\tau^2 = c^2 dt^2 - dx_1^2 - dx_2^2 - dx_3^2 , \quad (3)$$

where  $d\tau$  is an infinitesimal change in the invariant  $\tau$ , and all  $dx_i$  ( $i = 1, 2, 3$ ) and  $dt$  are infinitesimal distances in coordinate space  $x_1, x_2, x_3$  and coordinate time  $t$ . Minkowski spacetime  $x_1, x_2, x_3, t$  is a construct because  $t$  is a man-made concept:  $t$  is a label that is not inherent in clocks. In GR,  $t$  retains its function as a label. We identify four drawbacks of SR and GR: (1) SR/GR work for all observers, but they do not provide diagrams of nature that work for all observers. (2) The GR-based Lambda-CDM model fails to predict time's arrow and the Hubble tension. It predicts other empirical facts (see Sect. 5) only by postulating highly speculative concepts (curved spacetime, cosmic inflation, expanding space, dark energy). (3)  $t$ -based QM predicts entanglement only by postulating another highly speculative concept (non-locality). (4) GR is probably incompatible with QM.

SR/GR provide a "multi-egocentric description" (definition: nature is described as a relative manifold). Even *coordinate-free* formulations of SR/GR [14–16] lack absolute space and absolute time. ER provides a "universal description" (definition: nature is described as an absolute manifold). Physics has paid a high price for sticking to coordinate time  $t$ . ER predicts time's arrow and the Hubble tension. On top, it predicts other empirical facts (see Sect. 5) without postulating highly speculative concepts. Thus, the drawbacks are real. Michelson and Morley [17] refute the "aether" (absolute 3D space), but they do not refute absolute 4D space embedding countless 3D spaces with relative orientations.

SR/GR do not make false predictions. The drawbacks have much in common with the drawbacks of geocentrism, the "egocentric view" from Earth: SR/GR require unnecessary concepts, and they make fewer predictions. In the old days, it was tempting to believe that all celestial bodies would orbit Earth. Astronomers wondered about the retrograde loops of some planets and claimed: Earth orbits the sun! Nowadays, it is tempting to believe that the universe would be expanding. It is our turn to wonder: *What could it expand into?* The standard answer is: The universe creates new space within itself. *How could space be created?* *Since spacetime is a single entity, shouldn't time expand too?* Physics is at an impasse, but continues to reject ER. The human brain is smart, but susceptible to illusions.

The analogy between geocentrism and multi-egocentrism in SR/GR is not perfect, but it fits well: (1) After taking another planet as the center or after a transformation in SR/GR, the description is still geocentric or else egocentric. (2) Retrograde loops make geocentrism work, but heliocentrism can do without them. Dark energy and non-locality make cosmology and QM work, but ER can do without them. (3) Heliocentrism is not centered in Earth. ER is not centered in observers. (4) Heliocentrism overcomes geocentrism. ER overcomes multi-egocentrism. (5) Geocentrism was a dogma in the old days. SR/GR are dogmata nowadays. One may ask: *Didn't physics learn from history? Does history repeat itself?*

### 3. The Physics of Euclidean Relativity

Einstein merges 3D Euclidean space and coordinate time into a non-Euclidean spacetime. This step has far-reaching consequences because it also affects GR. There is an alternative description of nature that omits coordinate time  $t$ . Here is how we proceed: To determine an object's position in an observer's 3D space, we use the same rigid rods and the same 3D geometry (Euclidean geometry) as in SR. Regarding the time coordinate, we do not use  $t$ , but the proper time  $\tau$  measured by clocks. That is, we do not construct time.

**The ER postulates:** (1) *All objects move through 4D Euclidean space (ES) at the dimensionless speed  $C$ .* There is no time in ES. All action in ES is due to an absolute, external "evolution parameter"  $\theta$ . Every object experiences two orthogonal projections [19, 20] from ES as space and time: The axis of its *current* 4D motion is its proper time  $\tau$ . Three orthogonal axes are its 3D space  $x_1, x_2, x_3$ . (2) *The laws of physics have the same form in the physical realities of observers who move uniformly through ES.* An observer's "physical reality" is the Minkowskian reassembly of his 3D space and his proper time (see below). Observing is identical to projecting objects from ES onto his physical reality. His 3D space is the same in SR and ER because it is Euclidean in either theory. Our [first postulate](#) is stronger than the second SR postulate:  $C$  is absolute and universal. Our [second postulate](#) refers to physical realities. Variational principles [18] could be another way to derive ER. The metric of ES is

$$C^2 d\theta^2 = dX_1^2 + dX_2^2 + dX_3^2 + dX_4^2, \quad (4)$$

where  $d\theta$  is an infinitesimal change in the invariant  $\theta$ , and all  $dX_\mu$  ( $\mu = 1, 2, 3, 4$ ) are infinitesimal distances in ES. We prefer the four indices 1–4 to 0–3 to emphasize the SO(4) symmetry of ES. We fit ER to experimental data by setting  $C = 299\,792\,458$ . We define an object's 4D Euclidean vector "proper velocity"  $\mathbf{U}$  in ES. Its four components  $U_\mu = dX_\mu/d\theta$  are "proper speed". Thus, Eq. (4) is equivalent to our [first postulate](#).

$$U_1^2 + U_2^2 + U_3^2 + U_4^2 = C^2. \quad (5)$$

ES is a mathematical reality:  $C$ ,  $\theta$ ,  $X_\mu$ , and  $U_\mu$  ( $\mu = 1, 2, 3, 4$ ) are dimensionless. Every object is free to label the axes of its reference frame in ES. We consider two objects "r" (red) and "b" (blue). We may assume that "r" (or "b") labels the axis of its *current* 4D motion as  $X_4$  (or else  $X'_4$ ) and three orthogonal axes as  $X_1, X_2, X_3$  (or else  $X'_1, X'_2, X'_3$ ). According to our [first postulate](#), "r" (or "b") always moves in the  $X_4$  (or else  $X'_4$ ) axis at the speed  $C$ . Because of length contraction at the speed  $C$  (see [Sect. 4](#)), "r" does not experience  $X_4$  as space, but as what we call "time". "r" experiences  $X_1, X_2, X_3$  as space. If an object's world-line in ES is curved, all four axes continuously adapt to the current curvature.

To accomplish the transition from ES to an observer's physical reality, we add SI units to  $X_1, X_2, X_3, X_4$ , thus obtaining  $x_1, x_2, x_3, x_4$ . And then, we *reassemble* the axes  $x_1, x_2, x_3, x_4$  in a Minkowskian way (space and time are assigned opposite signs in the metric) to form  $\tau$ -based Minkowskian spacetime  $x_1, x_2, x_3, \tau$  ( $\tau$ -MS). The adjective "Minkowskian" refers to the metric. In  $\tau$ -MS,  $\tau$  is the new time coordinate and  $\theta$  converts to "parameter time"  $\vartheta$ . An observer's physical reality is not ES, but  $\tau$ -MS. The metric of  $\tau$ -MS is

$$c^2 d\vartheta^2 = c^2 d\tau^2 - dx_1^2 - dx_2^2 - dx_3^2, \quad (6)$$

which differs from Eq. (3) only in that  $\tau$  is replaced by  $\vartheta$ , and  $t$  is replaced by  $\tau$ . In  $\tau$ -MS,  $c = 299\,792\,458$  m/s. The following conversions apply to the quantities in  $\tau$ -MS.

$$\vartheta = \theta \text{ in seconds (s)}, \quad (7a) \quad 187$$

$$x_i = X_i \text{ (} i = 1, 2, 3 \text{) in light seconds (Ls)}, \quad (7b) \quad 188$$

$$x_4 = c\tau = X_4 \text{ in light seconds (Ls)}. \quad (7c) \quad 189$$

The metrics in Eqs. (3) and (6) have the same form. Thus, Minkowski spacetime and  $\tau$ -MS are mathematically identical. In particular, Maxwell's equations retain their form in  $\tau$ -MS, but  $\tau$  replaces  $t$ . *How do we synchronize clocks in ER?* We do not synchronize clocks in ER. Clocks measure proper time by themselves! The SO(4) symmetry of ES is incompatible with waves, but the SO(1,3) symmetry of  $\tau$ -MS is. *Waves exist in physical realities only.* An object's proper time always flows in the direction of its 4D motion. Thus, it makes sense to define a 4D Euclidean vector "flow of proper time"  $\mathbf{T}$  even if ES is timeless. 190  
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$$\mathbf{T} = \mathbf{U}/c. \quad (8) \quad 200$$

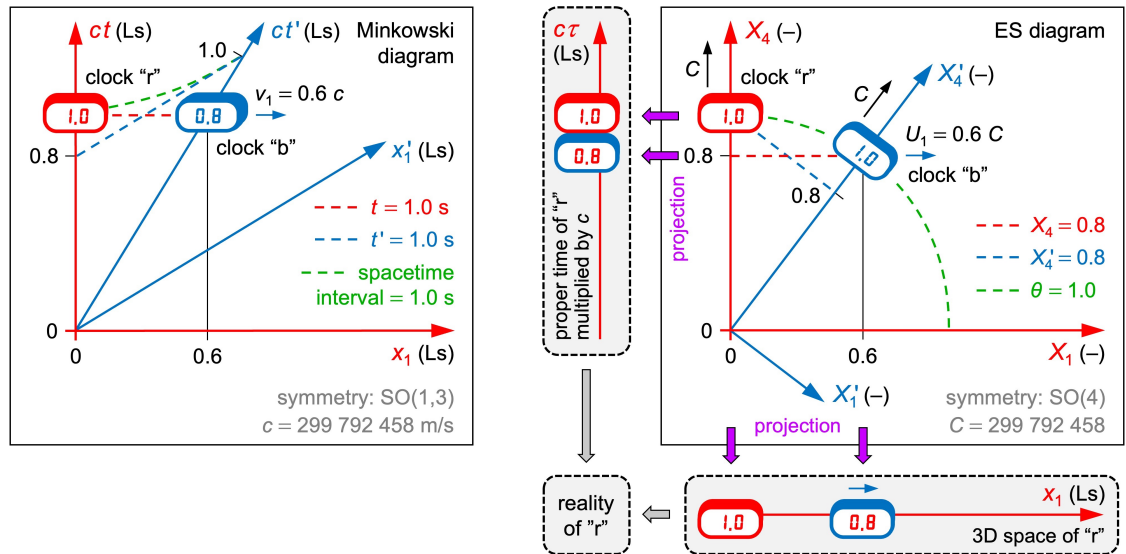
$\tau$ -MS is not a construct because  $\tau$  is a natural concept:  $\tau$  is inherent in clocks. Internal clocks of all objects, such as biological clocks, measure proper time  $\tau$ . In SR, the four coordinates are  $x_1(\tau), x_2(\tau), x_3(\tau), t(\tau)$ , where  $t$  is a man-made concept and  $\tau$  is an internal parameter. In ER, the four coordinates are  $x_1(\vartheta), x_2(\vartheta), x_3(\vartheta), \tau(\vartheta)$ , where  $\tau$  is a natural concept and  $\vartheta$  is an external parameter. Parameter time  $\vartheta$  increases monotonically while there is action in an observer's "universe" (synonyms: physical reality,  $\tau$ -MS). 201  
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It is instructive to compare  $\theta$ ,  $\vartheta$ , and  $\tau$ . The *evolution parameter*  $\theta$  is the invariant in ES and thus absolute. In ES, clocks are odometers that display  $\theta$ . *Parameter time*  $\vartheta$  is the invariant in  $\tau$ -MS and thus absolute. *Proper time*  $\tau$  is the time axis in  $\tau$ -MS. An observer experiences projections only. Thus, he experiences a projected time: Every clock measures its proper time  $\tau'$ , but this  $\tau'$  is projected onto his time axis. Thus, every clock displays  $\tau$  (not  $\tau'$ ) in his  $\tau$ -MS. *A clock can display different values in ES and  $\tau$ -MS because the projections contract traveled distance.* Since an observer does not move in his  $x_1, x_2, x_3$ , his clock displays both  $\tau$  and  $\vartheta$  according to Eq. (6). If Eq. (3) is applicable, Eqs. (3) and (6) give us 209  
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$$d\vartheta = dt \quad (\text{for uniformly moving objects}). \quad (9) \quad 218$$

**Remarks:** (1) Mathematically, ES is a 4D Euclidean manifold. Physically, three axes of ES are experienced as spatial and one as temporal. (2) Objects cannot be observed in ES. Our ES diagrams show objects (clock, rocket) only for better understanding. (3) Parameter time  $\vartheta$  is not a fifth dimension. In SR/GR, the parameter  $\tau$  is not a fifth dimension either. (4) In the standard notation of SR/GR, time is *always* the first (or fourth) coordinate. The same applies to  $\tau$ -MS, but here *any axis* of ES can be the preimage of the time axis in  $\tau$ -MS. (5) Do not confuse ER with a Wick rotation [21], where  $\tau$  is the parameter. 219  
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We consider two identical clocks "r" (red clock) and "b" (blue clock). In SR, "r" moves in the  $ct$  axis. "b" moves at the speed  $v_1 = 0.6c$ . **Fig. 1 left** shows that instant when either clock moved 1.0 Ls in  $ct$ . "b" moved 0.8 Ls in  $ct'$ . Thus, "b" displays "0.8". In ER, "r" moves in the  $X_4$  axis. "b" moves at the speed  $U_1 = 0.6C$ . **Fig. 1 right** shows that instant when 1.0 has elapsed in the evolution parameter  $\theta$  since both clocks left the origin of the diagram. "r" moved 1.0 Ls in  $c\tau$ . Thus, "r" displays "1.0" in the reality of "r". "b" moved 0.8 Ls in  $c\tau$  and 1.0 Ls in  $c\tau'$ . Thus, "b" displays "0.8" in the reality of "r" and "1.0" in the reality of "b" (not shown). Red digits on "b" indicate that "b" is read in the reality of "r". 227  
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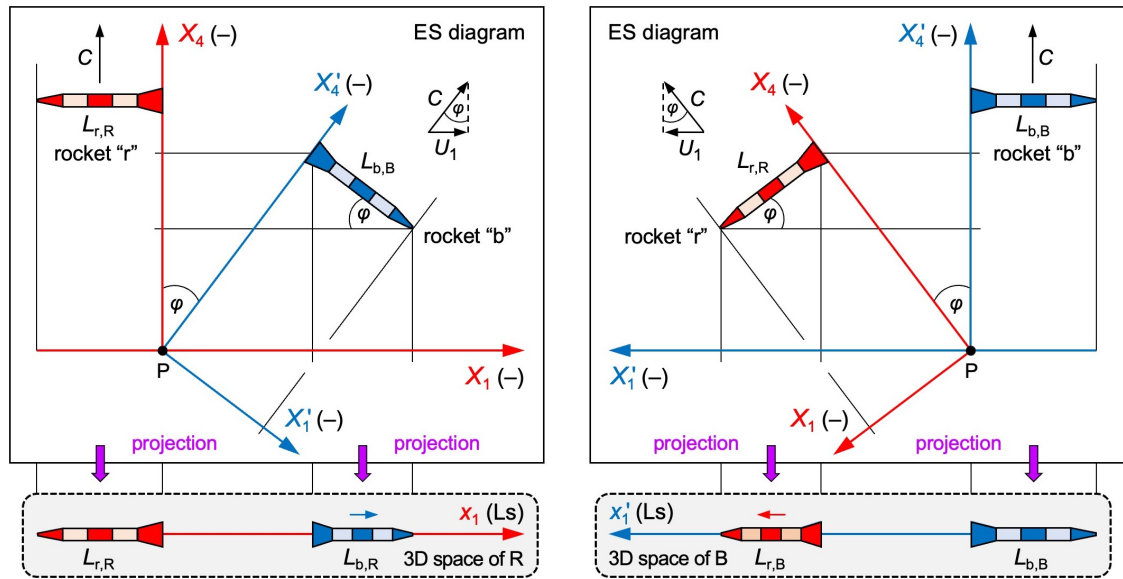
**Fig. 1** Minkowski diagram and ES diagram of two uniformly moving clocks. **Left:** "b" is slow with respect to "r" in  $t'$ . Coordinate time is relative ("b" is at different positions in  $t$  and  $t'$ ). **Right:** "b" is slow with respect to "r" in  $X_4$ . The evolution parameter is absolute (both clocks are at  $\theta = 1.0$ )

We assume that observer R (or B) moves with clock "r" (or else "b"). In SR and only for R ("b" measures  $\tau'$  and not  $t'$ ), B is at  $ct' = 0.8$  Ls when R is at  $ct = 1.0$  Ls (see Fig. 1 left). Thus, "b" is slow with respect to "r" in  $t'$ . In ER and independently of observers, B is at  $X_4 = 0.8$  when R is at  $X_4 = 1.0$  (see Fig. 1 right). Thus, "b" is slow with respect to "r" in  $X_4$ . In SR and ER, "b" is slow with respect to "r", but time dilates in different axes. Experiments do not reveal in which axis a clock is slow. SR and ER describe time dilation correctly if  $\gamma$  is reproduced by ER (see Sect. 4). If "b" reverses its  $x_1$  motion at  $x_1 = 0.6$  Ls, it hits "r" at  $x_1 = 0$ . In this instant (not shown), "r" and "b" display "2.0" in ES. However, "r" displays "2.0" and "b" displays "1.6" in the reality of "r". This twin paradox is resolved in the same way as in SR: "b" experienced a deceleration and an acceleration (see Sect. 4).

ES is absolute. According to our definition in Sect. 2, the description in ER is universal. Why is it beneficial? R and B experience different axes as temporal. This is why Fig. 1 left works for R only. In SR, a second Minkowski diagram is required for B, in which the axes  $x'_1$  and  $ct'$  are orthogonal. Here the description is multi-egocentric. Physicists do not care that two diagrams are required because there is no simultaneity (no "at once") for these two observers in SR. In ER, Fig. 1 right works for R and for B "at once" (at the same  $\theta = 1.0$ ). Not only are the axes  $X_1$  and  $X_4$  orthogonal, but also the axes  $X'_1$  and  $X'_4$ . ES diagrams are observer-independent Master Diagrams of nature. They show a mathematical Master Reality beyond all physical realities. Here the description is universal. Master Diagrams can be projected onto any observer's reality. This is a huge benefit (see Sect. 5).

#### 4. Geometric Effects in Euclidean Relativity

We consider two identical rockets "r" (red rocket) and "b" (blue rocket). Observer R (or B) is in the rear end of "r" (or else "b"). R (or B) experiences  $X_1, X_2, X_3$  (or else  $X'_1, X'_2, X'_3$ ) as his 3D space. R (or B) experiences  $X_4$  (or else  $X'_4$ ) as his proper time. Both rockets start at the same point P and at the same  $\theta$ . They move relative to each other at the constant speed  $U_1$ . The ES diagrams in Fig. 2 must satisfy our two postulates and the two initial conditions (same P, same  $\theta$ ). This is achieved by rotating the red and blue frames against each other. In ES diagrams, objects retain proper length. For better readability, a rocket's width is drawn in  $X_4$  (or  $X'_4$ ) although it should be drawn in  $X_2$  and  $X_3$  (or else  $X'_2$  and  $X'_3$ ).



**Fig. 2** ES diagrams of two uniformly moving rockets. Observer R (or B) is in the rear end of “r” (or else “b”). **Top left and right:** “r” and “b” move at the speed  $C$ , but in different 4D directions. The ES diagrams are identical. **Bottom left:** In the projection onto the 3D space of R, “b” contracts to  $L_{b,R}$ . **Bottom right:** In the projection onto the 3D space of B, “r” contracts to  $L_{r,B}$

Up next, we show: Projecting distances in ES onto the axes  $X_1$  and  $X_4$  causes length contraction and time dilation. Let  $L_{b,R}$  (or  $L_{b,B}$ ) be the length of rocket “b” for observer R (or else B). In a first step, we project  $L_{b,B}$  onto the  $X_1$  axis (see Fig. 2 left).

$$\sin^2 \varphi + \cos^2 \varphi = (U_1/C)^2 + (L_{b,R}/L_{b,B})^2 = 1, \quad (10)$$

$$L_{b,R} = \gamma_{ER}^{-1} L_{b,B} \quad (\text{length contraction}), \quad (11)$$

where  $\gamma_{ER} = (1 - U_1^2/C^2)^{-0.5}$  is equal to  $\gamma = (1 - v_1^2/c^2)^{-0.5}$  if  $U_1/C = v_1/c$ . The numerical values of  $C$  and  $c$  are equal. Because of  $U_1 = dX_1/d\theta$ ,  $v_1 = dx_1/dt$ , and Eqs. (7a–b),  $U_1/C = v_1/c$  if  $d\theta = dt$ . Eq. (9) tells us that  $d\theta = dt$  holds for uniformly moving objects. Since “r” and “b” move uniformly through ES, we conclude: ER reproduces the Lorentz factor. Orthogonal projections are not injective. Thus, ES is the Master Reality. In a second step, we project B’s traveled distance onto the  $X_4$  axis (see Fig. 2 left).

$$\sin^2 \varphi + \cos^2 \varphi = (U_1/C)^2 + (X_{4,B}/X'_{4,B})^2 = 1, \quad (12)$$

$$X_{4,B} = \gamma_{ER}^{-1} X'_{4,B}, \quad (13)$$

where  $X_{4,B}$  (or  $X'_{4,B}$ ) is the distance that B traveled in  $X_4$  (or else  $X'_4$ ). With  $X'_{4,B} = X_{4,R}$  (R and B travel the same distance in ES, but in different 4D directions), we calculate

$$X_{4,R} = \gamma_{ER} X_{4,B} \quad (\text{time dilation}), \quad (14)$$

where  $X_{4,R}$  is the distance that R traveled in  $X_4$ . Eqs. (11) and (14) tell us that ER confirms length contraction and time dilation. Which distances does R observe in  $X_4$ ? We rotate “b” until it serves as a ruler in  $X_4$ . In the 3D space of R, the ruler contracts to zero length. For R, the  $X_4$  axis disappears because of length contraction at the speed  $C$ . Our rockets are an example. To calculate the lifetime of a muon, we replace rocket “b” with a muon.

We now transform the coordinates of R (unprimed) to the ones of B (primed). R cannot measure the proper time  $\tau'$  ticking for B, and vice versa, but we can calculate  $\tau'$  from ES diagrams. Fig. 2 right tells us how to calculate the 4D motion of R in the coordinates of B. The transformation is shown in Eqs. (15a–b). It is a Euclidean 4D rotation by the angle  $\varphi$ . Adding multiple rotations does not violate Einstein's relativistic addition of velocities. In SO(4), 4D rotations are additive. In SO(1,3), velocities are not additive.

$$X'_{1,R}(\theta) = X_{4,R}(\theta) \sin \varphi = X_{4,R}(\theta) U_1/C , \quad (15a)$$

$$X'_{4,R}(\theta) = X_{4,R}(\theta) \cos \varphi = X_{4,R}(\theta) \gamma_{ER}^{-1} . \quad (15b)$$

Up next, we show: ER predicts the same gravitational time dilation as GR. We assume that initially our clocks "r" and "b" are very far away from Earth (see Fig. 3). Eventually, "b" falls freely toward Earth. "r" and Earth keep on moving in the  $X_4$  axis.

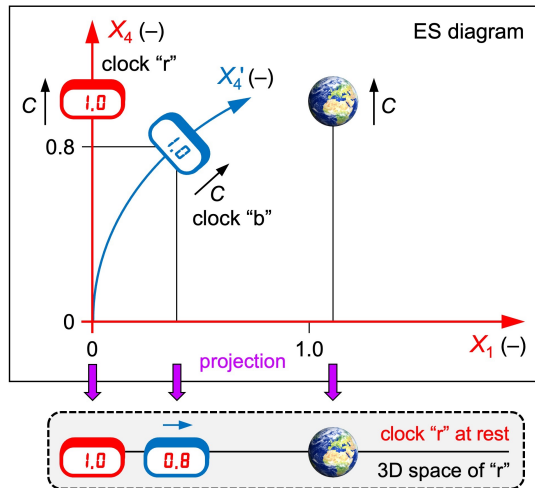


Fig. 3 ES diagram of two clocks and Earth. "b" falls freely toward Earth. It experiences gravity as an acceleration of other objects. Its  $X'_4$  axis is curved because  $X'_4$  indicates its current 4D motion

Because of Eq. (5), all accelerations in ES are transversal: The speed  $U_{1,b}$  of clock "b" in  $X_1$  increases at the expense of its speed  $U_{4,b}$  in  $X_4$ . We claim: *In ER, gravity is Newtonian.* We support our claim by showing that two assumptions reproduce the gravitational time dilation of GR: (1) Newton's gravitational potential  $\Phi$  holds in  $\tau$ -MS. (2)  $U_{1,b}/C = v_{1,b}/c$ . The Poisson equation for Newtonian gravity in  $\tau$ -MS is given by

$$\nabla^2 \Phi = 4\pi G \rho , \quad (16)$$

where  $G$  is the gravitational constant and  $\rho$  is the mass density in a considered volume. The gravitational field strength  $\mathbf{g} = -\nabla\Phi$  causes a force  $\mathbf{F} = m\mathbf{g}$  that accelerates a mass  $m$ . According to our first assumption, the kinetic energy of "b" in the  $x_1$  axis is

$$\frac{1}{2} m_b v_{1,b}^2 = G m_b m_{\text{Earth}} / r , \quad (17)$$

where  $m_b$  is the mass of "b",  $v_{1,b}$  is the speed of "b" in  $x_1$ ,  $m_{\text{Earth}}$  is the mass of Earth, and  $r$  is the distance of "b" to the center of Earth in  $x_1$ . In ES, Eq. (17) converts to

$$\frac{1}{2} M_b U_{1,b}^2 = G_0 M_b M_{\text{Earth}} / R , \quad (18)$$

where  $U_{1,b}/C = v_{1,b}/c$  according to our second assumption. The dimensionless quantities  $M_b, G_0, M_{\text{Earth}}, R$  are converted from  $m_b, G, m_{\text{Earth}}, r$ . Eqs. (5) and (18) give us

$$U_{4,b}^2 = C^2 - U_{1,b}^2 = C^2 - 2G_0M_{\text{Earth}}/R. \quad (19)$$

With  $U_{4,b} = dX_{4,b}/d\theta$  ("b" moves in the  $X_4$  axis at the speed  $U_{4,b}$ ) and  $C = dX_{4,r}/d\theta$  ("r" moves in the  $X_4$  axis at the speed  $C$ ), we calculate

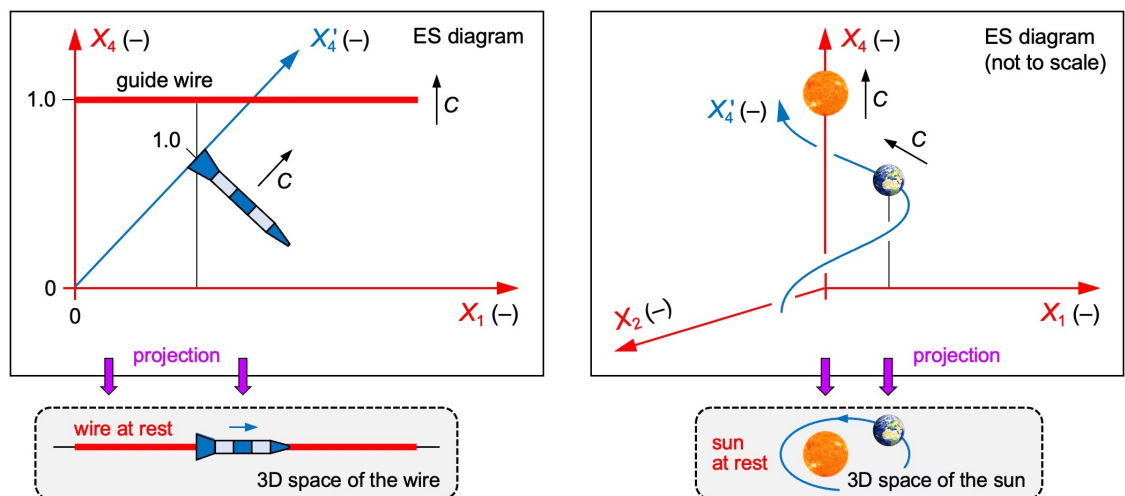
$$dX_{4,b}^2 = (C^2 - 2G_0M_{\text{Earth}}/R) (dX_{4,r}/C)^2, \quad (20)$$

$$dX_{4,r} = \gamma_{\text{grav}} dX_{4,b} \quad (\text{gravitational time dilation}), \quad (21)$$

where  $\gamma_{\text{grav}} = (1 - 2G_0M_{\text{Earth}}/(RC^2))^{-0.5}$  has the same form as in GR. Since we assumed  $U_{1,b}/C = v_{1,b}/c$ , the very same reasoning applies as for the Lorentz factor:  $U_{1,b}/C = v_{1,b}/c$  if  $d\theta = dt$ . Since spacetime in GR is locally Minkowskian, thus locally  $d\theta = dt$  according to Eq. (9), we conclude: *Locally, ER reproduces the gravitational time dilation of GR.* ER reproduces  $\gamma$  and  $\gamma_{\text{grav}}$ . Thus, the Hafele–Keating experiment [22] also supports ER.

We conclude: (a) In ER, gravity is Newtonian. (b) Gravitational time dilation is a direct consequence of Eq. (5). If an object accelerates in three axes of ES, it automatically decelerates in the fourth axis.  $\Phi$  follows a  $1/r$  law because ES is reduced to 3D space. Action at a distance is not a problem: Information is instantaneous in timeless ES. Only in  $\tau$ -MS does the time coordinate cause a delay. Presumably, gravity is carried by gravitons [23, 24] and manifests itself in  $\tau$ -MS as gravitational waves [25]. ER supports this idea even if gravitons have not yet been experimentally confirmed. Gravitons and gravitational waves could possibly be related to each other in the same way as photons and electromagnetic waves. We invite colleagues to explore this topic. *ER does not require curved spacetime.*

Fig. 4 teaches us how to read ES diagrams. **Problem 1:** A rocket moves along a guide wire. We assume that the wire moves in  $X_4$  at the speed  $C$ . Since the rocket moves in  $X_1$  and  $X_4$ , its speed  $U_4$  is less than  $C$ . *Doesn't the wire escape from the rocket?* **Problem 2:** Earth orbits the sun. We assume that the sun moves in  $X_4$  at the speed  $C$ . Since Earth moves in  $X_1, X_2$ , and  $X_4$ , its speed  $U_4$  is less than  $C$ . *Doesn't the sun escape from Earth?*



**Fig. 4** Two instructive problems. **Bottom left:** In the 3D space of a guide wire, a rocket moves along the wire. **Top left:** In ES, the wire escapes from the rocket. **Bottom right:** In the 3D space of the sun, Earth orbits the sun. **Top right:** In ES, the sun escapes from Earth. Note that this illustration is only an approximation because the sun orbits the center of the Milky Way

The last paragraph seems to reveal paradoxes. The fallacy lies in assuming that all four axes of ES are experienced as spatial at once. We solve the two problems by projecting ES onto the 3D space of that object which moves in  $X_4$  at the speed  $C$ . In Fig. 4 left, the guide wire does not escape from the rocket spatially. They age in different directions! The only relevant quantities for guiding the rocket are  $X_1, X_2, X_3, \theta$ . In the projection onto 3D space,  $X_4$  is projected away. Collisions in 3D space do not show up as collisions in ES because  $\theta$  is a parameter. In  $\tau$ -MS, two objects collide when their positions in 3D space and  $\vartheta$  coincide. As in SR/GR,  $\tau$  can be different. In Fig. 4 right, the sun does not escape from Earth spatially. They age in different and changing directions! The same applies to Earth and “b” in Fig. 3. ES diagrams do not show events, but an object’s position and its 4D vector  $T$ .

## 5. Empirical Evidence for Euclidean Relativity

Here we show that ER predicts 12 empirical facts. These facts include the three tests that Albert Einstein himself proposes to validate GR (see § 22 of [2]): gravitational redshift, the deflection of starlight, and the precession of Mercury’s perihelion.

### 5.1. Time’s Arrow

“Time’s arrow” stands for time that flows only forward. *Why can’t time flow backward?* Experienced time is the distance traveled in ES divided by  $C$ . Regardless of the direction of an object’s 4D motion, “distance traveled” is a monotonically increasing function.

### 5.2. Gravitational Redshift

Gravitational redshift is the decrease in frequency of radiation emerging from a gravitational well. Frequency is related to time. Since ER locally reproduces the gravitational time dilation of GR (see Sect. 4), ER locally predicts gravitational redshift.

### 5.3. Deflection of Starlight

Montanus [10] uses a Euclidean metric to derive the deflection of starlight by a spherical mass. On page 1387 of [10], he calculates the deflection angle  $\Delta\psi$ .

$$\Delta\psi = 4\mu/R, \quad (22)$$

where  $\mu$  is half the Schwarzschild radius and  $R$  is the distance of closest approach. For the calculation, see [10]. Since [10] is publicly available, we do not reproduce the calculation. Montanus uses the parameter  $t$  (see page 1368 of [10]) and a Lagrangian based on  $t$ . For starlight deflected by the sun and observed on Earth,  $t$  is as good a parameter as  $\vartheta$ . Here is why: *Because of the high speed  $C$ , the sun and Earth move almost uniformly through ES.* Thus,  $d\vartheta \cong dt$  according to Eq. (9). We conclude: ER and GR predict the same  $\Delta\psi$ .

### 5.4. Precession of Mercury’s Perihelion

Montanus [10] uses a Euclidean metric to derive the precession of orbits. On page 1389 of [10], he calculates the additional orbital angle  $\Delta\varphi$  covered per revolution.

$$\Delta\varphi = 6\pi\mu/(L(1 - e^2)), \quad (23)$$

where  $L$  is the semimajor axis and  $e$  is the eccentricity. For Mercury, Montanus estimates  $\Delta\varphi \cong 42.9''$  per century (see page 72 of [11]). Since [11] is not peer reviewed, further studies on this topic are required. Again,  $t$  is as good a parameter as  $\vartheta$  because Mercury also moves almost uniformly through ES. We conclude: ER and GR predict the same  $\Delta\varphi$ .

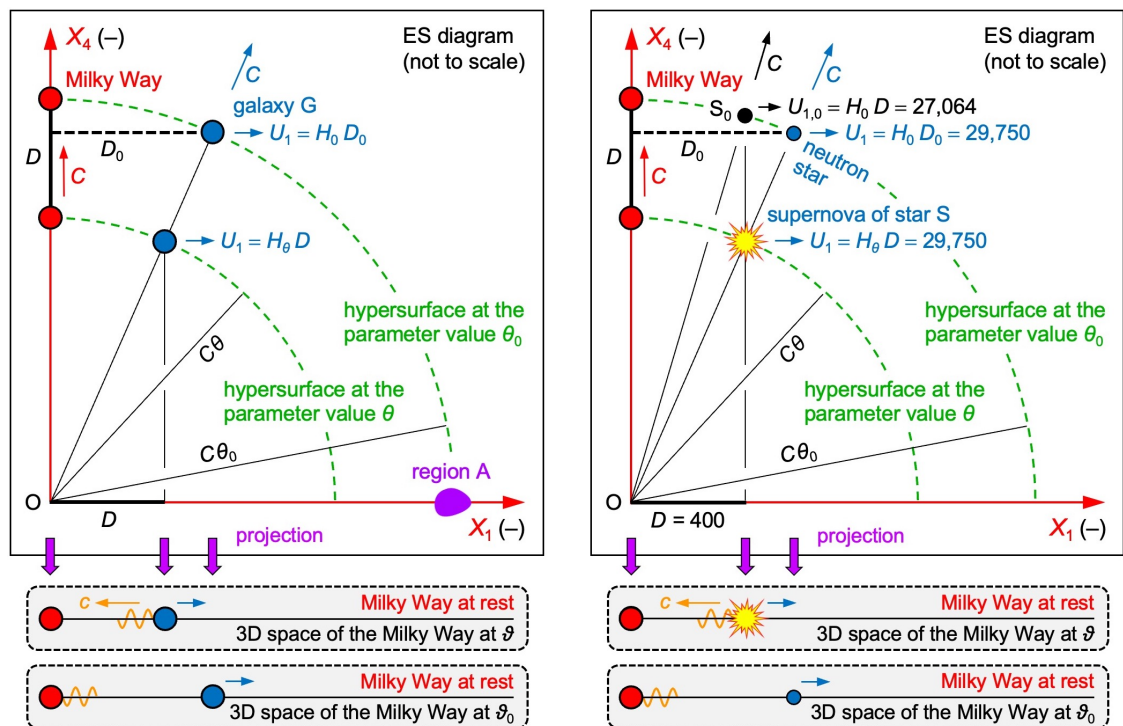
### 5.5. Cosmic Microwave Background (CMB)

Today's standard model of cosmology, the Lambda-CDM model [26, 27], is based on GR. In this model, the universe inflated from a singularity. The Big Bang occurred "everywhere". In Sects. 5.5 to 5.11, we outline an ER-based model of cosmology, in which the Big Bang can be localized: It injected a huge amount of energy into ES at an origin O. Parameter time has been ticking uniformly since the Big Bang. The Big Bang was a singularity in providing energy and radial momentum. Ever since the Big Bang ( $\theta = 0$ ), energy has been moving through ES at the speed  $C$ . Shortly after  $\theta = 0$ , all energy was highly concentrated. While it receded from the origin O, it became less concentrated and reduced to plasma particles. Recombination radiation was emitted that we observe as CMB today [28].

The ER-based model must be able to answer several questions: (1) Why is the CMB so isotropic? (2) Why is the CMB temperature so low? (3) Why do we still observe the CMB today? Some possible answers: (1) The CMB is scattered equally in the 3D space of Earth. (2) The plasma particles receded from O in ES at very high speeds (Doppler redshift, see Sect. 5.11). (3) Some of the recombination radiation reaches Earth after traveling the same distance in  $X_1, X_2, X_3$  (multiple scattering) as the Milky Way in  $X_4$  (for the axes, see Fig. 5).

### 5.6. Hubble–Lemaître Law

The Milky Way and a galaxy G recede from O at the speed  $C$  (see Fig. 5 left). G recedes from the  $X_4$  axis of the Milky Way at the speed  $U_1$ .  $D$  (or  $D_0$ ) is the distance of G to the Milky Way in the 3D space of the Milky Way at a specific value  $\theta$  (or else  $\theta_0$ ).  $U_1$  is to  $D$  as  $C$  is to the radius  $C\theta$  of a 3D hypersurface. All energy is within the 4D hypersphere. Its radius is parameterized by  $\theta$ . Because of various effects (gravitation, scattering, photon emission, pair production), some energy does not recede radially anymore.



**Fig. 5** ER-based model of cosmology. The green arcs show a 3D hypersurface that is expanding from the origin O of ES (location of the Big Bang) at the speed  $C$ . **Left:** A galaxy G recedes from O at the speed  $C$  and from the  $X_4$  axis at the speed  $U_1$ . **Right:** If a star  $S_0$  happens to be at the same distance  $D$  today at which the supernova of S occurred,  $S_0$  recedes more slowly from  $X_4$  than S

$$U_1 = CD/C\theta = D/\theta = H_\theta D , \quad (24)$$

where  $H_\theta = 1/\theta$  is the ER-equivalent to the Hubble parameter. If we observe the galaxy G today (we denote “today” by the value  $\theta_0$  and thus by the parameter time  $\vartheta_0$ ), the two speeds  $U_1$  and  $C$  remain unchanged. Thus, Eq. (24) turns into

$$U_1 = CD_0/C\theta_0 = D_0/\theta_0 = H_0 D_0 , \quad (25)$$

where  $H_0 = 1/\theta_0$  is the ER-equivalent to the Hubble constant,  $D_0 = D \theta_0/\theta$ , and  $C\theta_0$  is today’s radius of the hypersurface. Eq. (25) is an improved Hubble–Lemaître law [29, 30]. Cosmologists are already aware of the Hubble parameter. They are not yet aware that (a) the 4D geometry is Euclidean, (b)  $\theta$  and  $\vartheta$  are absolute, and (c) Eq. (25) relates  $U_1$  to  $D_0$  (not  $D$ ). Of two galaxies, the more distant one recedes faster, but each galaxy maintains its recession speed. G moves in  $X_4$  at the speed  $(C^2 - U_1^2)^{0.5}$ . Thus, a clock in G is slow with respect to a clock in the Milky Way in  $X_4$  by the factor  $C/(C^2 - U_1^2)^{0.5} = \gamma_{ER}$ . In the 3D space of the Milky Way, any light emitted by G at the parameter time  $\vartheta$  (orange wave in Fig. 5 left) moves at the speed  $c$  and arrives at the Milky Way at the parameter time  $\vartheta_0$ .

### 5.7. Flat Universe

An observer experiences neither ES nor the curved 3D hypersurface, but  $\tau$ -MS. Thus, his physical reality is a “flat universe” (his 3D Euclidean space and his proper time). This statement is true even if his worldline in ES is curved, as for clock “b” in Fig. 3.

### 5.8. Large-Scale Structures

Most cosmologists [31, 32] believe that an inflation of space shortly after the Big Bang is responsible for the isotropic CMB, the flat universe, and large-scale structures. The latter are said to have inflated from quantum fluctuations. We showed that ER predicts the isotropic CMB and the flat universe. ER also predicts large-scale structures if the fluctuations have been expanding with the hypersphere. *ER does not require cosmic inflation.*

### 5.9. Cosmic Homogeneity (Horizon Problem)

*How can the universe be so homogeneous on large scales?* In the Lambda-CDM model, two regions A and B at “opposite sides” of the universe are causally disconnected unless we postulate a cosmic inflation. Otherwise, information could not have been transferred. In the ER-based model, A is at  $X_1 = +C\theta_0$  (see Fig. 5 left) and B is at  $X_1 = -C\theta_0$  (not shown). A and B experience  $X_1$  (equal to their  $X'_4$ ) as their time axis. For A and for B, the  $X'_4$  axis disappears because of length contraction at the speed  $C$ . From their perspective, A and B have never been separated spatially, but their proper time flows in opposite 4D directions. This is how the two regions A and B are causally connected. Their opposite 4D vectors  $T$  do not affect causal connectivity as long as A and B stay together spatially.

### 5.10. Hubble Tension

Up next, we show: ER predicts the ten percent discrepancy in the published values of the Hubble constant (Hubble tension,  $H_0$  tension). We consider CMB measurements and distance ladder measurements. The values do not match:  $67.66 \pm 0.42$  km/s/Mpc according to team A [33].  $73.04 \pm 1.04$  km/s/Mpc according to team B [34]. Team B made efforts to minimize the error margins in the distance measurements, but there is a systematic error in its calculation: Team B assumes an incorrect cause of the redshifts.

We assume that team A's value is correct. We now simulate the supernova of a star S, which occurred at a distance of  $D = 400$  (corresponding to 400 Mpc in the 3D space of the Milky Way) from the Milky Way (see Fig. 5 right). The recession speed of S is calculated from the measured redshift. The redshift parameter  $z = \Delta\lambda/\lambda$  tells us how a wavelength of the supernova's light is either stretched by an expanding space (team B) or else Doppler-redshifted by receding objects (ER-based model). We assume that the supernova occurred at a specific value  $\theta$ , but we observe it today at  $\theta_0$ . While the supernova's light traveled the distance  $D$  in  $-X_1$ , the Milky Way traveled the same distance  $D$  in  $+X_4$ .

According to Eq. (24), we now plot  $U_1$  versus  $D$  for distances from 0 to 500 in steps of 25 (red points in Fig. 6). The slope of a straight-line fit through the origin is roughly ten percent higher than 67.66. This is because  $H_\theta$  is not a constant. If we compare the supernovae of two stars S and S', the more distant one recedes faster, but each star maintains its recession speed. That is, S and S' move uniformly through ES. Thus,  $d\theta = dt$  according to Eq. (9). Thus, as shown in Sect. 4,  $U_1/C$  in our plot is equal to  $v_1/c$ , which is calculated from the redshift. According to Eq. (25), we must plot  $U_1$  versus  $D_0$  to get a straight line (blue points). Since team B does not take Eq. (25) into account, its value of  $H_0$  is roughly ten percent too high. Ignoring the 4D Euclidean geometry in the distance ladder measurements overestimates the value of  $H_0$ . This line of reasoning explains the Hubble tension.

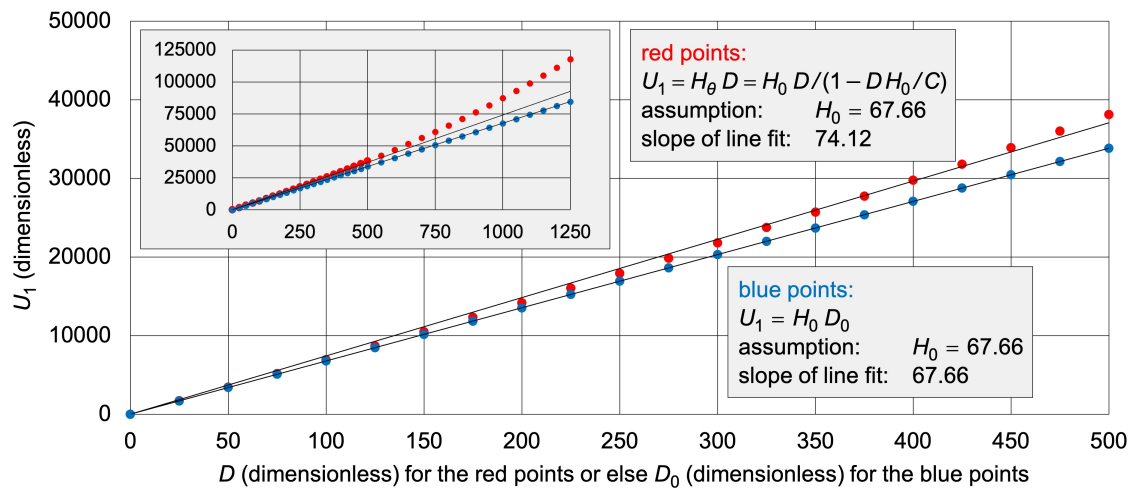


Fig. 6 Hubble diagram of simulated supernovae. The red points, as calculated according to Eq. (24), do not form a straight line. Because of Eqs. (24) and (27),  $U_1$  is not proportional to  $D$ . The blue points, as calculated according to Eq. (25), do form a straight line because  $U_1$  is proportional to  $D_0$

Eq. (25) requires the knowledge of  $D_0$ , but measurable magnitudes of supernovae are related to  $D$ . We solve this technical difficulty by rewriting Eq. (25) as

$$U_{1,0} = H_0 D , \quad (26)$$

where  $U_{1,0}$  is the recession speed in  $X_1$  of a star  $S_0$  that happens to be at the same distance  $D$  today at which the supernova of S occurred (see Fig. 5 right). We calculate

$$H_\theta = C/C\theta = C/(C\theta_0 - D) = H_0/(1 - DH_0/C) . \quad (27)$$

Inserting  $H_\theta$  from Eq. (24),  $H_0$  from Eq. (26), and  $U_1/C = v_1/c$  into Eq. (27) gives us

$$U_{1,0} = U_1/(1 + U_1/C) , \quad (28)$$

$$U_{1,0}/C = U_1/(C + U_1) = v_1/(c + v_1) . \quad (29)$$

We kindly ask team B to convert  $v_1$  to  $U_{1,0}$  according to Eq. (29). Because of Eq. (26), plotting  $U_{1,0}$  versus  $D$  then yields the correct value of  $H_0$ . Fig. 6 also tells us: The more high-redshift data are taken into account, the more the Hubble tension increases.

### 5.11. Cosmological Redshift

Up next, we identify a second systematic error. This error is even more serious than team B's error in the value of  $H_0$ . It concerns the supposed accelerating expansion of space and cannot be resolved within the Lambda-CDM model unless we postulate a dark energy. Most cosmologists [35, 36] believe in an accelerating expansion of space because the recession speeds increasingly deviate from a straight line when plotted versus the distance  $D$ . Indeed, an accelerating expansion of space would stretch each wavelength even further, thus causing these deviations. In the Lambda-CDM model, the moment of the supernova is irrelevant. All that matters is the duration of the light's journey to Earth.

In the ER-based model, all that matters is the moment of the supernova. Its light is redshifted by the Doppler effect. The longer ago a supernova occurred, the more  $H_\theta$  deviates from  $H_0$ , and thus the more  $U_1$  deviates from  $U_{1,0}$ . If a star  $S_0$  happens to be at the same distance of  $D = 400$  today at which the supernova of S occurred, Eq. (29) tells us:  $S_0$  recedes more slowly (speed of 27,064 and shortest arrow in Fig. 5 right) from  $X_4$  than S (speed of 29,750). *It does so because of the 4D Euclidean geometry.* The 4D vector  $T'$  of  $S_0$  differs less from  $T$  of the Milky Way than  $T''$  of S differs from  $T$ . Physicists "invented" dark energy [37] to explain an accelerating expansion of space. Dark energy is a stopgap solution for an effect that the Lambda-CDM model cannot explain. Earlier supernovae recede faster because of a greater  $H_\theta$  and not because of a dark energy.

Cosmological redshift and the Hubble tension have the same physical background: In Eq. (25), we must not confuse  $D_0$  with  $D$ . Because of Eqs. (24) and (27),  $U_1$  is not proportional to the distance  $D$ , but to  $D/(1 - DH_0/C)$ . Any expansion of space—uniform or else accelerating—is only virtual even if the Nobel Prize in Physics 2011 was awarded "for the discovery of the accelerating expansion of the Universe through observations of distant supernovae". This particular prize was awarded for an illusion. Most galaxies recede from the Milky Way, but they do so uniformly in non-expanding ES. ER clearly identifies dark energy, the driving force behind the supposed accelerating expansion, as an illusion. Most energy recedes radially from the origin O of ES because of the radial momentum provided by the Big Bang. *ER requires neither expanding space nor dark energy.*

Cosmological redshift and the Hubble tension are very strong empirical evidence that challenges the Lambda-CDM model. They force us to take the 4D Euclidean geometry into account, and  $T$  in particular. GR works well if  $T$  is irrelevant, but  $T$  is relevant for high-redshift supernovae: Their  $T'$  differs greatly from  $T$  of the Milky Way. Space is not driven by dark energy. *Each galaxy is driven by its momentum and maintains its recession speed.* Because of various effects (gravitation, scattering, photon emission, pair production), some energy does not recede radially anymore. Gravitational attraction enables nearby galaxies to move toward our galaxy. Table 1 compares two models of cosmology. The ER-based model does not require curved spacetime, cosmic inflation, expanding space, and dark energy. Thus, ER significantly improves cosmology. ER also improves QM (see Sect. 5.12).

Inflationary Lambda-CDM model based on GR	ER-based model of cosmology
There is no absolute space.	4D Euclidean space is absolute.
There is no absolute time.	Parameter time is absolute.
The Big Bang was the beginning of everything.	The Big Bang was an injection of energy into ES.
The Big Bang occurred "everywhere".	The Big Bang can be localized (origin O of ES).
Gravity is the result of a curved spacetime.	Gravity is Newtonian.
Shortly after the Big Bang, space was inflating.	There is no cosmic inflation.
Today, there is an accelerating expansion of space.	There is no expanding space.
Dark energy causes the accelerating expansion.	There is no dark energy.
This model does not predict the Hubble tension.	This model predicts the Hubble tension.

Table 1 Comparing two models of cosmology

5.12. Quantum Entanglement

Erwin Schrödinger coins the word "entanglement" in a comment [38] on the Einstein–Podolsky–Rosen paradox [39]. These three authors argue that QM does not provide a complete description of reality. Schrödinger’s neologism does not resolve the paradox, but it highlights our enormous difficulties in comprehending QM. John Bell [40] shows that QM is incompatible with local hidden-variable theories. Meanwhile, several experiments [41–43] have confirmed that entanglement violates locality in an observer’s 3D space. Quantum entanglement has been interpreted as a "non-local effect" ever since.

Up next, we show: ER "untangles" entanglement without the concept of non-locality. There is no violation of locality in 4D (!) space, where all four axes are fully symmetric. In Fig. 7, observer R moves in the  $X_4$  axis at the speed  $C$ . There are two pairs of objects. The first pair was created at the point P and moves in opposite directions  $\pm X'_4$  (equal to  $\pm X_1$  of R) at the speed  $C$ . The second pair was created at the point Q and moves in opposite directions  $\pm X''_4$  at the speed  $C$ . In his 3D space, R experiences the first pair as entangled photons. He experiences the second pair as entangled material objects, such as electrons. R has no idea how entangled objects "communicate" with each other in no time.

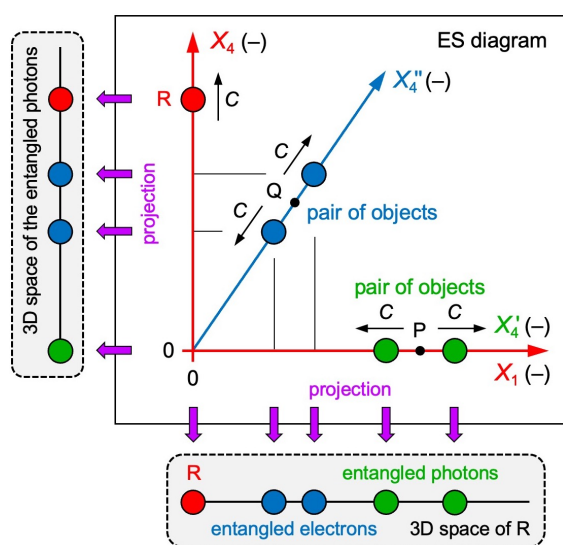


Fig. 7 Entanglement. Observer R moves in  $X_4$ . In his 3D space, one pair is experienced as entangled photons. The other pair is experienced as entangled electrons. In the photons’ 3D space, the photons stay together spatially. In the electrons’ 3D space (not shown), the electrons stay together spatially

For the photons (or electrons), the  $X'_4$  (or else  $X''_4$ ) axis disappears because of length contraction at the speed  $C$ . From their perspective, the entangled objects have never been separated spatially, but their proper time flows in opposite 4D directions. This is how they communicate with each other in no time. Their opposite 4D vectors  $\mathbf{T}$  do not affect local communication as long as the twins stay together spatially. *What the time axis is for entangled objects, a space axis—or a mix of space and time—is for the observer.* There is a “spooky action at a distance” (a phrase attributed to Albert Einstein) for observers only.

Entanglement and cosmic homogeneity have the same physical background: An observed object’s (or region’s) 4D vector  $\mathbf{T}'$  and its 3D space can be rotated with respect to an observer’s 4D vector  $\mathbf{T}$  and his 3D space. This is possible in ES only, where all four axes are fully symmetric. The SO(4) symmetry of ES enables the entanglement of photons and other objects [44]. ER predicts that any two objects created in pair production are entangled. This gives us a chance to falsify ER. Any measurement terminates one twin or rotates its 4D vector  $\mathbf{T}$ . The entanglement is destroyed. *ER does not require non-locality.*

## 6. Conclusions

Today’s physics lacks absolute space, an absolute, external parameter, and a vectorial concept of time. In ER, there is absolute space (ES), an absolute evolution parameter ( $\theta$ ), and a vector “flow of proper time” ( $\mathbf{T}$ ). Information hidden in ES,  $\theta$ , and  $\mathbf{T}$  is not available in SR/GR. ES is relevant for modeling an observer’s universe (the Minkowskian reassembly of two projections from ES).  $\theta$  is relevant for modeling galactic motion.  $\mathbf{T}$  is relevant for explaining cosmic homogeneity, cosmological redshift, and entanglement.

ER reproduces the Lorentz factor and—locally—the gravitational time dilation of GR. Thus, either GR or else ER is an approximation. GR is probably that approximation because  $\theta$  (or  $\vartheta$ ) suits QM better than  $t$ . For instance, time is not an operator in the Schrödinger equation, but an external parameter.  $\theta$  and  $\vartheta$  are such parameters. There is none in GR. In summary, we propose (a) replacing Minkowski spacetime with  $\tau$ -MS, (b) using ER in cosmology, and (c) using ER in QM. It is obvious that one paper cannot cover all of physics. It is also obvious that 12 predicted empirical facts in different (!) areas of physics are most likely not 12 coincidences. Some facts can be predicted without ER, but only by postulating curved spacetime, cosmic inflation, expanding space, dark energy, and non-locality. None of these concepts is required in ER. Occam’s razor makes no exceptions. *Either physics sticks to SR/GR and these highly speculative concepts, or it breaks new ground with ER.*

Einstein was awarded the Nobel Prize in Physics 1921 for his theory of the photoelectric effect [45] and not for SR/GR. Our results show that ER penetrates to a “deeper level”. Einstein, one of the most brilliant physicists ever, did not realize that nature’s fundamental metric is Euclidean. He sacrificed absolute space and absolute time. ER reinstates absolute space (not 3D space, but 4D space) and absolute time (not a time coordinate, but parameter time). In retrospect, it was man-made coordinate time that delayed the formulation of ER. For the first time ever, humanity grasps the true nature of time: *Experienced time is the distance traveled in ES divided by  $C$ .* The human brain is able to imagine that we all move at the speed of light. With that said, conflicts of humanity become all so small.

Is ER a physical or a metaphysical theory? That is a very good question because only in proper coordinates can we access ES, but the proper time  $\tau'$  ticking for another object cannot be measured. And yet, we can calculate it from ES diagrams, as shown in Eqs. (15b) and (7c). ES diagrams are observer-independent Master Diagrams of nature. It is true that observing is our primary source of knowledge, but concepts can mislead us if they originate from observing. Physics is more than just observing. For instance, we cannot observe time.

Coordinate time  $t$  works well in everyday life, but unfortunately  $t$  has also been applied to the very distant and to the very small. For this very reason, cosmology and QM benefit most from ER. *ER is a physical theory because it predicts what we observe.*

It seems as if Greek philosopher Plato anticipated ER in his famous *Cave Allegory* [46]: Humanity experiences projections, but it cannot observe the Master Reality beyond these projections. We laid the foundation for ER and demonstrated its strength. Paradoxes are only virtual. The key question in science is this: *How can we describe nature without postulating highly speculative concepts?* The answer leads to the truth. The pillars of physics are ER and QM. Together, they describe Mother Nature from the very distant to the very small. Everyone is welcome to test ER. Only in natural concepts does Mother Nature reveal her secrets. *Isn't it natural that she rewards an all-natural description of herself?*

**Acknowledgements:** I thank Siegfried W. Stein for his contributions to Sect. 5.10 and Figs. 2, 4, 5. After several unsuccessful submissions, he decided to withdraw his co-authorship. I thank Matthias Bartelmann, Walter Dehnen, Cornelis Dullemond, Xuan Phuc Nguyen, Dirk Rischke, Jürgen Struckmeier, Christopher Tyler, Götz Uhrig, and Andreas Wipf for asking inspiring questions about ER. My special thanks go to all reviewers and editors for investing some of their valuable, *proper* time.

**Comments:** (1) Further studies on gravity are required, but this is no reason to reject ER. GR seems to explain gravity, but GR is incompatible with QM unless we add quantum gravity. (2) In ES, there are no singularities and thus no black holes. Again, this is no reason to reject ER. Singularities conflict with QM. Projections of highly concentrated energy could possibly be interpreted as "black holes". (3) It often helps to match the symmetry. The symmetry of nature is SO(4). (4) Absolute time puts an end to discussions about time travel. Does any other theory explain time's arrow as clearly as ER? (5) Physics does not ask: Why is my reality a projection? Projections are less speculative than postulating curved spacetime *plus* cosmic inflation *plus* expanding space *plus* dark energy *plus* non-locality.

It takes open-minded editors and reviewers to evaluate a new theory that heralds a *paradigm shift*. Taking SR and GR for granted paralyzes progress. I apologize for my numerous preprint versions, but I received little support only. The preprints document my path. The final version is all that is needed. I did not surrender when top journals rejected ER. Interestingly, I was never given any valid arguments that would disprove ER. I was advised to consult experts or submit to other journals. Were the editors afraid of publishing against the mainstream? Did they underestimate the benefits of ER? I am told that predicting 12 empirical facts would be too much to be convincing. I disagree. A paradigm shift often leads to many new insights. Even good friends refused to support me. Every setback motivated me to formulate ER even better. Finally, I was able to identify four drawbacks of SR and GR.

A well-known preprint archive suspended my submission privileges. I was penalized because I showed that GR is not as general as it seems. I was told that I may submit only those articles that have appeared in a mainstream conventional journal. The editor-in-chief of a top journal replied: "Publishing is for experts only." One editor rejected ER because it would "demand too much" from his experts. Several journals rejected ER because it was "neither innovative nor significant". I like to speak of ER as "holistic physics", but unfortunately the reviewers did not accept this term. I do not blame anyone. Paradigm shifts are hard to accept. In the long run, ER will prevail because it predicts what we observe. These comments shall encourage young scientists to stand up for good ideas even if it is challenging: "unscholarly research", "fake science", "equations from entry-level textbooks", "too simple to be true". *Simplicity and truth are not mutually exclusive. Beauty is when they go hand in hand together.*

**Author Contributions:** The entire manuscript was written by the author.

**Data Availability:** The data that support the findings of this study are available within this article.

**Funding:** No funds, grants, or other support was received.

## Declarations

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**Competing Interests:** The author declares no competing interests.

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