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Article

Autonomous Decentralized Cooperative Control DC Microgrid Deployed in Residential Areas

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Abstract

This paper presents a novel DC microgrid configuration tailored for residential applications, aiming to harness renewable energy and enhance resilience against the growing threats of natural disasters and cyber-physical attacks—factors that increasingly expose the fragility of existing power grid systems. The proposed system employs autonomous decentralized cooperative control and introduces a distinctive battery-integrated DC-baseline architecture, wherein distributed batteries are directly connected to the grid’s baseline. This topology streamlines control: distributed batteries directly connected to the baseline handle forming and maintaining core grid, while DC/DC converters are dedicated solely to power exchange between power devices. A key factor is to employ weak-coupling grid for realizing autonomous decentralized control. By using the configuration, the system minimizes inter-device interference, thereby obtaining control independence of local devices. Comprehensive MATLAB/Simulink simulations of a four-house DC microgrid—modeled on a typical Japanese residential setting—demonstrate that an optimal configuration with 5 kW solar panels and 20 kWh batteries per household can achieve a renewable energy ratio exceeding 50%, while maintaining stable grid operation year-round, even with electric vehicle charging. The proposed system offers a balanced design with an estimated battery lifetime of approximately 25 years, paving the way for sustainable, resilient, and locally governed energy infrastructures.

Keywords: DC grid; residential microgrid; autonomous decentralized cooperative control; weak-coupling grid

1. Introduction

The power grid, alongside communication networks, water supply systems, and city gas infrastructure, is a vital lifeline of modern society. However, its vulnerabilities have become increasingly apparent in recent years due to the intensification of natural disasters and its susceptibility to targeted attacks such as terrorism and warfare [1–3]. Existing power grids typically rely on large-scale generation at power plants located far from urban centers—the primary consumers of electricity—and transmit power over long distances via transmission and distribution lines. This centralized structure introduces multiple points of fragility, particularly in large facilities and extended transmission pathways, making the system vulnerable to disruptions. In contrast, microgrids—comprising small-scale distributed energy resources such as solar, wind, and hydro generators, along with batteries—are gaining attention for their resilience [4,5]. These systems incorporate distributed energy sources into the grid and operate locally, generating and storing only the necessary amount of electricity near the point of consumption. Microgrids fundamentally reject the premise of long-distance power transmission, instead promoting “local production and consumption of electricity”.

As such, microgrids and conventional power grids are based on fundamentally different philosophies. Table 1 compares the two systems, highlighting differences not only in their conceptual approach to electricity usage but also in the types of power handled, grid topology, and control methods. Conventional grids employ high-voltage AC suitable for long-distance transmission, whereas microgrids handle low-voltage DC or AC, which is more accessible for power consumers.

Topologically, conventional grids follow a river-flow (tree) structure flowing from upstream generators to downstream consumers, while microgrids typically adopt a bus-type configuration, allowing for diverse topologies. Control methods also differ significantly. Conventional grids rely on centralized control by utility companies, whereas microgrids may incorporate autonomous decentralized cooperative control in addition to centralized schemes. Moreover, conventional grids are designed without power storage, requiring instantaneous balance between power generation and consumption (the principle of simultaneous supply and demand). Grid stability during short time scales depends on electrical inertia provided by upstream generators, which propagates through the transmission line to downstream loads, ensuring reliable operation of electrical devices. This necessitates strong electrical coupling between generators and end-use devices.

Microgrids, too, require electrical inertia for grid stability, but this is provided by distributed sources such as batteries. Typically, DC/DC converters or DC/AC inverters connected to these batteries emulate inertia to stabilize the grid [6,7]. As a result, multiple sources of electrical inertia are located near the loads, enabling the possibility of a weakly coupled grid structure, as discussed in Section 4.

Table 1. Comparison of existing power grids and microgrids.

	Existing power grid	Microgrid
Concept of power usage	Transporting electricity over long distances	Local production and consumption
Power source	Centralized	Distributed
Type of power	High-voltage AC	Low-voltage DC, (AC)
Grid topology	River-flow (Tree)	Bus, Ring, Mesh, etc.
Power flow	Unidirectional	Bidirectional
Control method	Centralized control	Decentralized control
Resilience	Low	High
Introducing RES*	Difficult	Easy
Major consumer	Industrial, Residential	Residential
Issue	Maintenance and management of grid	Cost reduction of storage batteries

* Renewable energy sources.

In summary, conventional power grids and microgrids differ fundamentally. While parts of the conventional grid—particularly downstream segments—may be replaced by microgrids in the future, a complete replacement is unlikely. Instead, the two systems are expected to coexist, complementing each other’s weaknesses.

This paper focuses on the design and operation of a DC microgrid applied for typical residential areas, where individual homes are interconnected via a DC baseline. Specifically, we consider deployment in residential areas in Japan, a disaster-prone country where disaster resilience is highly desirable. Assuming homes equipped with small solar panels and batteries, we simulate scenarios in which residents aim to live sustainably by maximizing renewable energy usage throughout the year under normal circumstances. We evaluate grid stability, required capacities for solar panels and batteries, energy exchange with the utility grid, and renewable energy ratios. Naturally, it is not possible to live a stable life solely through unstable renewable energy generation from solar power, so although the minimum amount of electricity required will be obtained from the utility grid, it will be kept to a minimum.

2. DC Microgrid

Microgrids can be implemented in both AC and DC formats. Conventional AC microgrids typically operate by borrowing or extending utility distribution grids during normal conditions and switching to islanded operation during disasters. Thus, they are essentially an extension of the utility grid.

In contrast, DC microgrids are built with independent grids separate from the utility grid, making them fundamentally distinct. DC microgrids may also employ autonomous decentralized cooperative control [8,9]. This control method eliminates centralized controllers and communication lines between devices, enhancing disaster resilience. Even if part of the grid is damaged, the remaining segments can maintain partial functionality.

However, in such systems, each power device must operate autonomously, making independent decisions based on its own assessment of grid conditions. This requires sophisticated self-regulation, typically performed by DC/DC converters connected to distributed power sources or by the power loads themselves. Devices sense local grid conditions—such as baseline voltage—and adjust their behavior to avoid negatively impacting the grid. In this case, since devices do not have a global view of the grid, optimization is limited to local performance rather than system-wide coordination. Therefore, autonomous decentralized cooperative control is inherently a form of local control. Section 4 provides a detailed explanation of how this local control is implemented within DC microgrids.

3. Battery-Integrated DC Baseline

We previously proposed a DC grid architecture in which batteries are directly connected to the grid baseline [10]. In conventional DC microgrids, as illustrated in Figure 1(a), batteries are typically connected to the baseline via DC/DC converters. These converters play a critical role in maintaining and stabilizing the grid, including the provision of pseudo-inertial characteristics. However, when a DC/DC converter is interposed, the battery’s inherent electrical inertia cannot be fully transmitted to the baseline due to limitations imposed by the converter’s rated power capacity. Moreover, electronic control introduces delays on the order of several milliseconds, during which certain power-load equipment may experience instability or even shut down.

To address this issue, we proposed a method for directly connecting batteries to the grid baseline, as shown in Figure 1(b), thereby transmitting their electrical inertia without degradation. Specifically, batteries are configured such that their terminal voltage closely matches the baseline voltage, enabling direct connection. When batteries are directly connected to the baseline, their intrinsic droop characteristics with respect to terminal voltage naturally facilitate coordinated operation among multiple batteries [10].

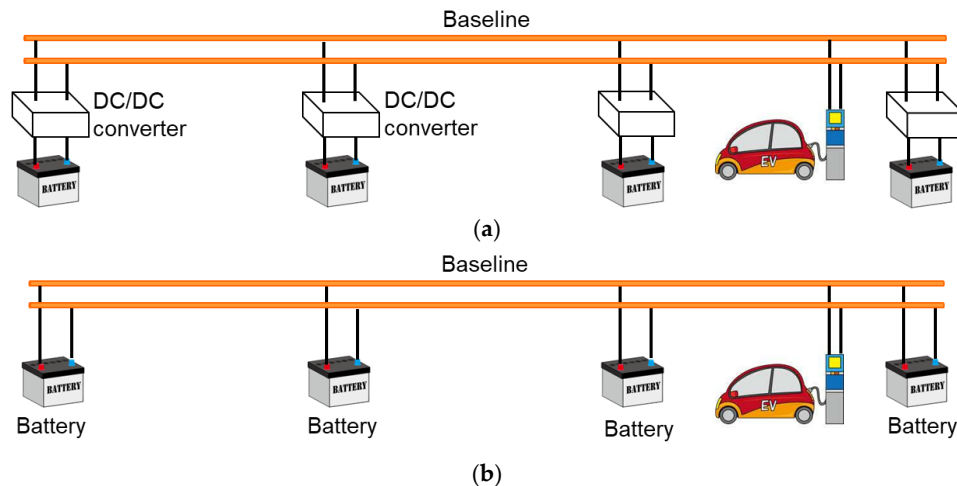


Figure 1. Conventional DC baseline (a) and battery-integrated DC baseline (b).

This configuration—where multiple small batteries are distributed and directly connected to the baseline—forms a battery-integrated DC baseline. It allows the fundamental grid-forming and sustaining functions to be handled by the distributed batteries themselves, without relying on DC/DC converters.

Inspired by the open systems interconnection (OSI) reference model [11] for communication networks, we define the grid functionality across four hierarchical layers, as shown in Table 2.

Table 2. Layering of grid functions.

Layer No	Layer Name	Function	Methods
4	Application layer	Various applications that utilize grids	EMS*, Power trading
3	Power exchange layer	Power exchange between grid and devices, Connection to other grids, (droop control)	Control of DC/DC converters
2	Grid forming layer	Basic functions for forming and maintaining stable grid (Electrical inertia, droop control, Equalizing power distribution, Ground fault, short circuit and lightning strike protection)	Control of DC/DC converters, Batteries directly connected to baseline (AC or DC, Baseline voltage)
1	Physical layer	Physical medium that enables power exchange between power devices (Power line)	CV cable, etc. (2-core or 3-core, Grounding method)

* Energy management system.

- **Layer 1: Physical Layer**

This layer specifies the physical medium and standards for power exchange among devices connected to the grid. Common media include CV cables, with specifications covering conductor type, thickness, number of cores, insulation type, and grounding methods.

- **Layer 2: Grid Forming Layer**

This layer governs the essential functions for forming and maintaining the grid at a specified voltage. It defines the type of power (AC or DC), voltage range, frequency, and phase configuration (single-phase or three-phase). Mechanisms for electrical inertia, droop control for coordinated operation of distributed power sources, and power distribution balancing are included. Protection against ground faults, short circuits, and lightning strikes is also specified. In conventional DC grid, these functions are typically handled by DC/DC converters connected to distributed sources.

- **Layer 3: Power Exchange Layer**

This layer defines the mechanisms for power exchange between power devices and the grid, as well as between the grid and external systems such as utility grids or other microgrids. DC/DC or DC/AC converters are responsible for these functions.

- **Layer 4: Application Layer**

This top layer encompasses various applications that utilize the grid, such as energy management systems (EMS) or electricity trading platforms.

Table 3 compares devices responsibilities for each grid function between conventional DC microgrids and battery-integrated DC microgrids. In conventional DC grids, both Layer 2 (grid forming) and Layer 3 (power exchange) functions are handled by DC/DC converters. In contrast, the battery-integrated grid delegates Layer 2 functions to the distributed batteries directly connected to the baseline, allowing DC/DC converters to focus solely on Layer 3 functions. This separation simplifies control.

Table 3. Comparison of responsible devices between conventional DC grids and battery-integrated DC grids.

Grid function	Conventional DC microgrid	Battery-integrated DC microgrid
Power applications	Control of DC/DC converters (EMS*, Electricity trading, EV charging)	Control of DC/DC converters (EMS*, Electricity trading, EV charging)
Power exchange between grid and devices	DC/DC converters (Maintaining power supply, Power exchange)	DC/DC converters (Maintaining power supply, Power exchange)

Forming, maintaining and stabilizing grid	DC/DC Converters (Electrical inertia, Droop control, SoC equalization)	Distributed batteries directly connected to the baseline (Electrical inertia, Droop control, SoC equalization)
	Power cable	Power cable
* Energy management system.		

Figure 2 illustrates the devices responsible for each layer in both conventional and battery-integrated grids. In conventional DC grids, DC/DC converters connected to distributed sources must manage a wide range of controls across Layers 2 and 3, resulting in high complexity and control burden. To mitigate this, hierarchical control schemes have been proposed to prioritize control tasks and prevent interference [12,13].

In our battery-integrated baseline approach, these roles are clearly separated and simplified. Grid forming (Layer 2) is entrusted to the directly connected batteries, while DC/DC converters concentrate on power exchange (Layer 3). This significantly reduces the complexity of DC/DC converter control.

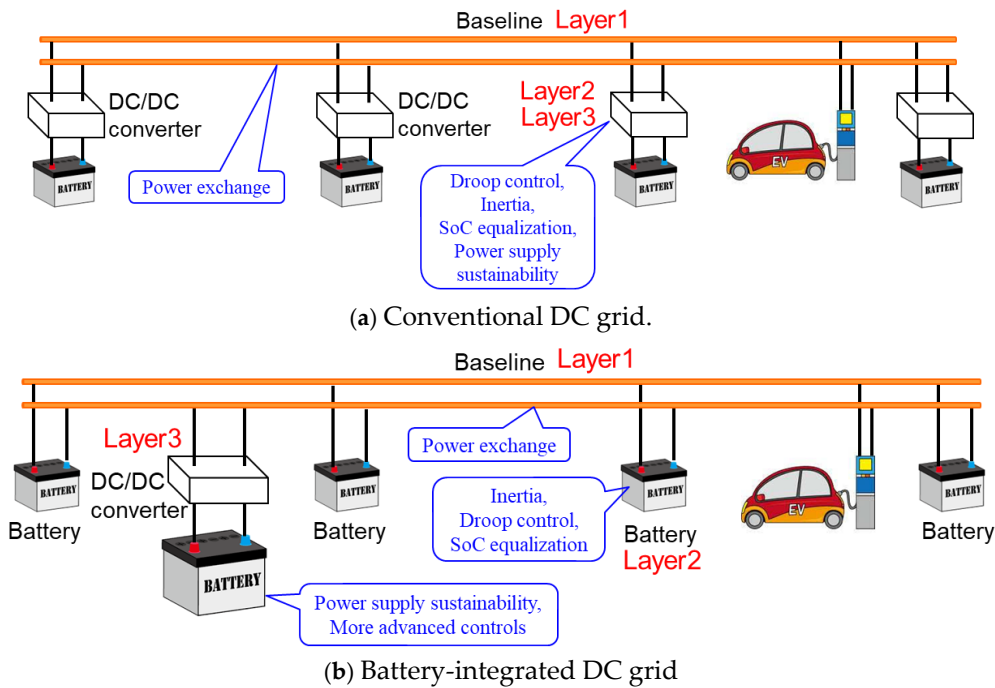


Figure 2. Comparison of the roles of each device between conventional DC grid (a) and battery-integrated DC grid (b).

4. Autonomous Decentralized Cooperative Control Realized by Weakly Coupled Grid Configuration

In conventional power grids, electrical inertia must be transmitted from upstream power generators to downstream power loads. To achieve this, the system relies on thick, high-capacity transmission and distribution lines operating at high voltages. In contrast, typical DC microgrids operate at relatively low voltages—around 400 V—baseline and their baseline power capacity are modest. This difference stems primarily from the relative positioning of the sources of electrical inertia and the power loads.

Figure 3 compares the magnitude of electrical inertia along the baseline between Japan’s conventional distribution grid (6.6 kV) and a DC microgrid (baseline voltage: 400 V). Here, the magnitude of electrical inertia is defined as the maximum instantaneous power that can be extracted at a given point on the baseline. Due to the conductor resistance of the baseline cable, the electrical

inertia decreases with distance from the inertia source, but near the inertia source, the magnitude is limited by the allowable current capacity of the baseline cable. Japan’s distribution grid uses relatively thick cables (22–150 square millimeters (SQ)) at 6.6 kV, allowing substantial electrical inertia to be transmitted even over distances exceeding 10 km. In contrast, DC microgrids use thinner cables (typically 8–14 SQ) at around 400 V, resulting in significantly lower electrical inertia and a more limited range of influence. However, because sources of electrical inertia—such as distributed batteries—are located near the power loads, even such weakly coupled grid can effectively distribute sufficient inertia across the baseline.

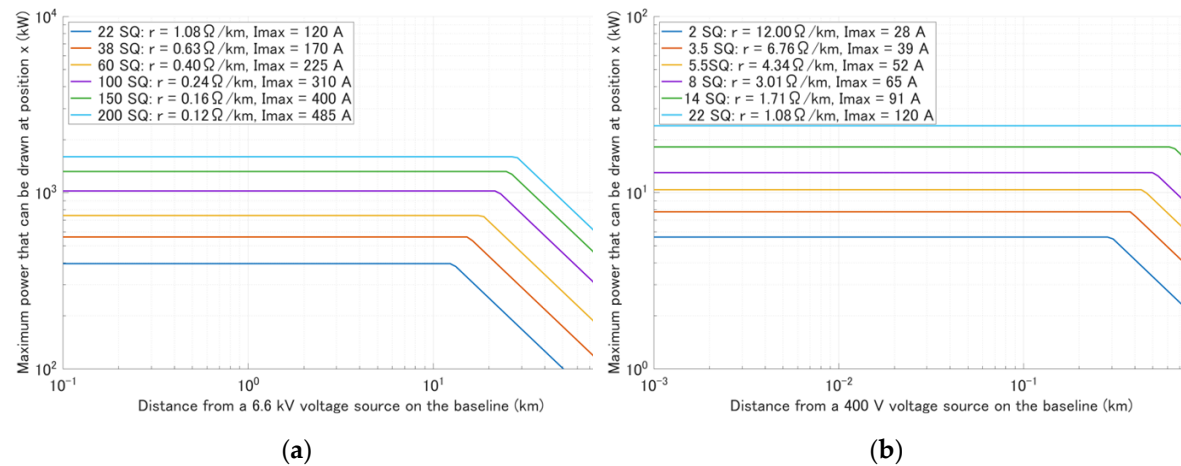
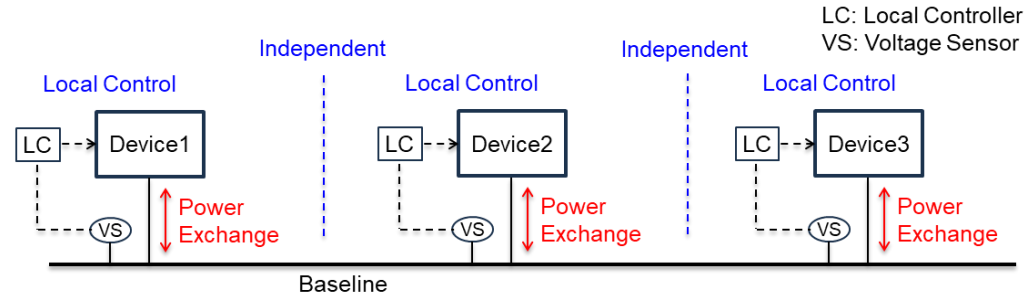


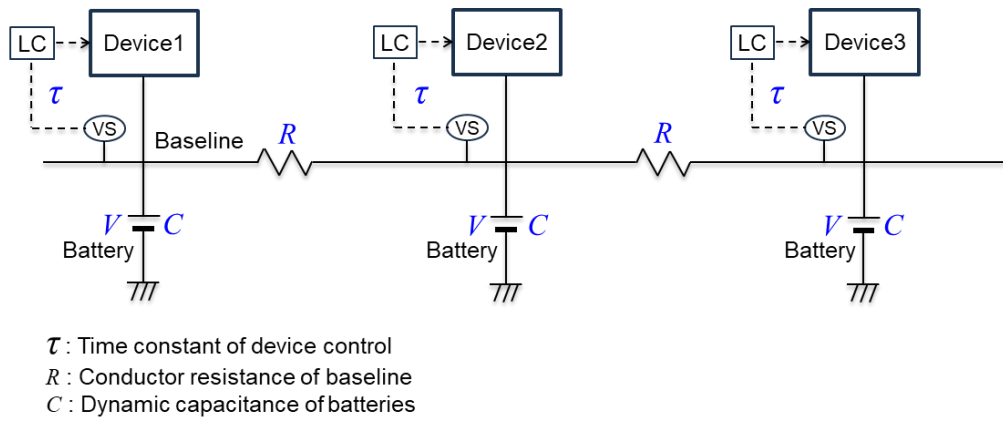
Figure 3. Electrical inertia on the baseline; (a) 6.6 kV distribution grid line; (b) 400 V DC microgrid baseline.

Weak coupling is also essential for implementing autonomous decentralized cooperative control. In this control paradigm, each device must operate independently without interference from neighboring devices, necessitating strictly local control. Typically, a device senses the grid state—such as the baseline voltage—at its connection point to the grid and determines its behavior accordingly. If the operation of adjacent devices affects this sensing, accurate assessment of the grid state becomes impossible (see Figure 4(a)). Strong electrical coupling through the baseline increases the likelihood of such interference.

To quantify this, a simplified equivalent circuit of a battery-integrated weakly-coupled DC grid is shown in Figure 4(b). Here, R represents the conductor resistance of the baseline between devices, C denotes the dynamic capacitance of the battery, and τ is the time constant of device control—typically less than several second, as seen in solar panel MPPT charging control systems.



(a) Need for independent device control



(b) equivalent circuit of a battery-integrated weakly-coupled DC grid

Figure 4. The need for local control to ensure the independence of each device control.

The conductor resistance R reflects the strength of coupling between devices. In weakly coupled grids, R is non-negligible, typically ranging from 0.1 to 1 Ω . The dynamic capacitance C of the battery is defined by the following equation:

$$C = \frac{dq}{dV} \quad (1)$$

where dq is the change in charge and dV is the resulting change in terminal voltage. Depending on battery type and capacity, C can be extremely large. For example, a 48 V, 40 Ah lithium iron phosphate battery yields a capacitance exceeding 1,000 F. Thus, the CR time constant, determined by the battery capacitance and conductor resistance, is typically much larger than the device control time constant τ , as indicated by the following inequality:

$$\tau \ll CR \quad (2)$$

This ensures the independence of each device's control, enabling effective local regulation. Although the control actions of neighboring devices may influence the sensing point via the baseline, such effects occur on a slower timescale than the control response of devices, preserving control autonomy.

Even in weakly coupled grids, gradual power exchange between devices remains feasible. Therefore, if a state-of-charge (SoC) imbalance arises among distributed batteries directly connected to the baseline, it will naturally self-balance over time [14]. Additionally, when a large power load—such as EV charging—is introduced, the local baseline voltage may begin to drop. However, the resulting voltage differential induces a compensating current flow, suppressing the voltage drop and stabilizing it at a fixed level.

5. Simulation Model for a Residential Microgrid

To analyze the operation of the battery-integrated, weakly coupled DC grid, we constructed a simulation model using MATLAB/Simulink. Device models were developed to emulate the operation of lithium iron phosphate (LiFePO_4) batteries, silicon solar panels, and residential electricity consumption. The solar panel model outputs hourly power generation based on input parameters including hourly temperature and global solar radiation data at the installation site, rated panel output, and installation efficiency. Historical meteorological data for major cities in Japan can be downloaded from the Japan Meteorological Agency's website [15]. Residential electricity consumption was modeled statistically based on the average monthly energy usage of a typical four-person household in Japan (Table 4) [16], and the hourly consumption pattern shown in Figure 5 [17]. Although seasonal variations exist, we use an annual average profile for simplification. To reflect household-level variability, random fluctuations were introduced into each home's power consumption. These power devices operate autonomously without central control.

The baseline voltage is centered at 380 V, with an allowable operating range of $\pm 10\%$, i.e., 340 V to 420 V. All power-load devices, generation units, and storage systems are assumed to operate normally within this voltage range. Each device model monitors the voltage at its connection point (baseline voltage) and operates autonomously and in a decentralized manner because centralized controller is not present. Therefore, if the baseline voltage remains within the allowable range, autonomous decentralized cooperative control is considered to be functioning properly.

- Power exchange with the utility grid is governed by the following rules:
- When the baseline voltage drops below 360 V, the microgrid begins receiving power from the utility grid at a fixed rate, continuing until the voltage recovers to 370 V.
 - When the baseline voltage exceeds 400 V, the microgrid begins sending power to the utility grid at a fixed rate, continuing until the voltage drops to 390 V.
 - Outside these conditions, no power exchange occurs.

This control scheme ensures that the baseline voltage remains within the permissible range, even during periods of low solar generation or excess production.

The opposite end of the baseline is left open for future expansion. Given the increasing prevalence of home-based electric vehicle (EV) charging, we also considered a scenario in which House 3 (the third house from the left) is equipped with EV charging infrastructure.

The baseline connecting the houses consists of CV cables with a conductor thickness of 8 SQ, and each segment is uniformly set to 50 meters in length. Table 5 summarizes the specifications of the microgrid. The installation efficiency of the solar panels—determined by factors such as orientation and tilt angle—is uniformly assumed to be 50%.

Table 5. Parameters of the simulation model.

	Solar panel		Battery		EV charging infrastructure
	Rated output power (kW)	Installation efficiency (%)	Capacity (kWh)	Initial SoC (%)	
House 1	5	50	20	50	none
House 2	5	50	20	50	none
House 3	5	50	20	50	5 kW
House 4	5	50	20	50	none

6. Simulation Results

6.1. Without EV Charging Infrastructures

We first examined the case without electric vehicle (EV) charging infrastructure. Figure 7 shows the annual variation and a detailed view of the January monthly variation in total solar power generation within the microgrid. Since all houses are located within a 100-meter radius, we assumed uniform solar irradiance across all photovoltaic (PV) installations. Power generation peaks between April and May, decreases during the rainy season (June–July), and is slightly lower in August due to high ambient temperatures. In winter (December–February), generation is reduced due to shorter daylight hours and snowfall.

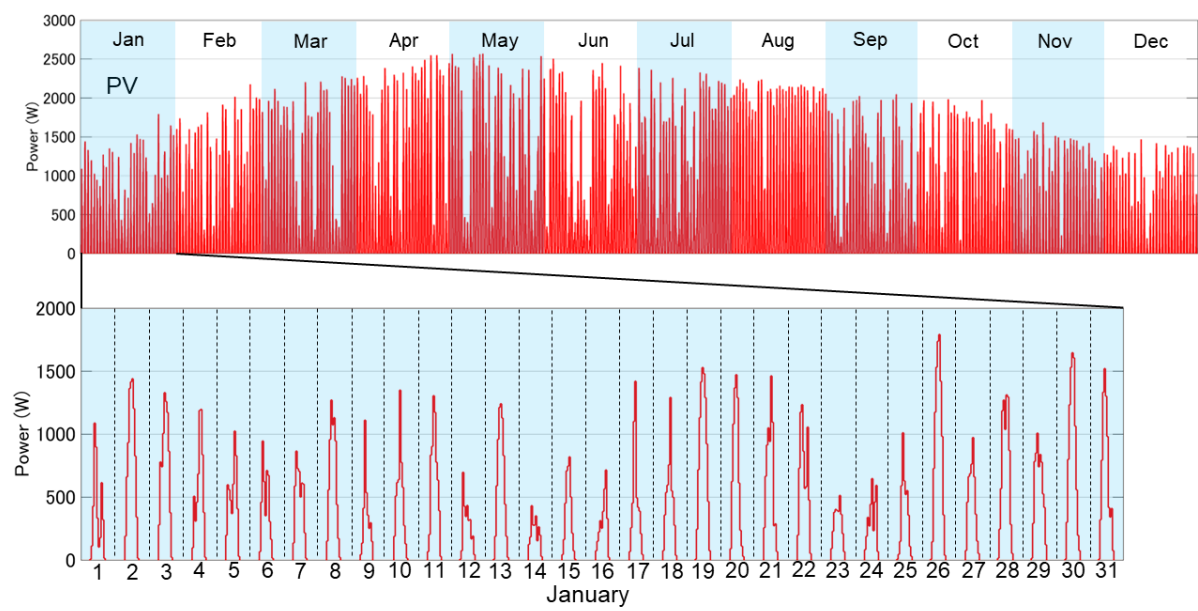


Figure 7. Annual variation and a detailed view of the January monthly variation in total solar power generation within the microgrid.

Figure 8 illustrates the annual variation in electricity consumption across the four households, along with a detailed view of the January variation for House 4. In this graph, power consumption is represented as negative values, since power generation is defined as positive. While consumption varies by household, it statistically follows the distribution shown earlier. Higher consumption is observed in winter and summer due to air conditioning use.

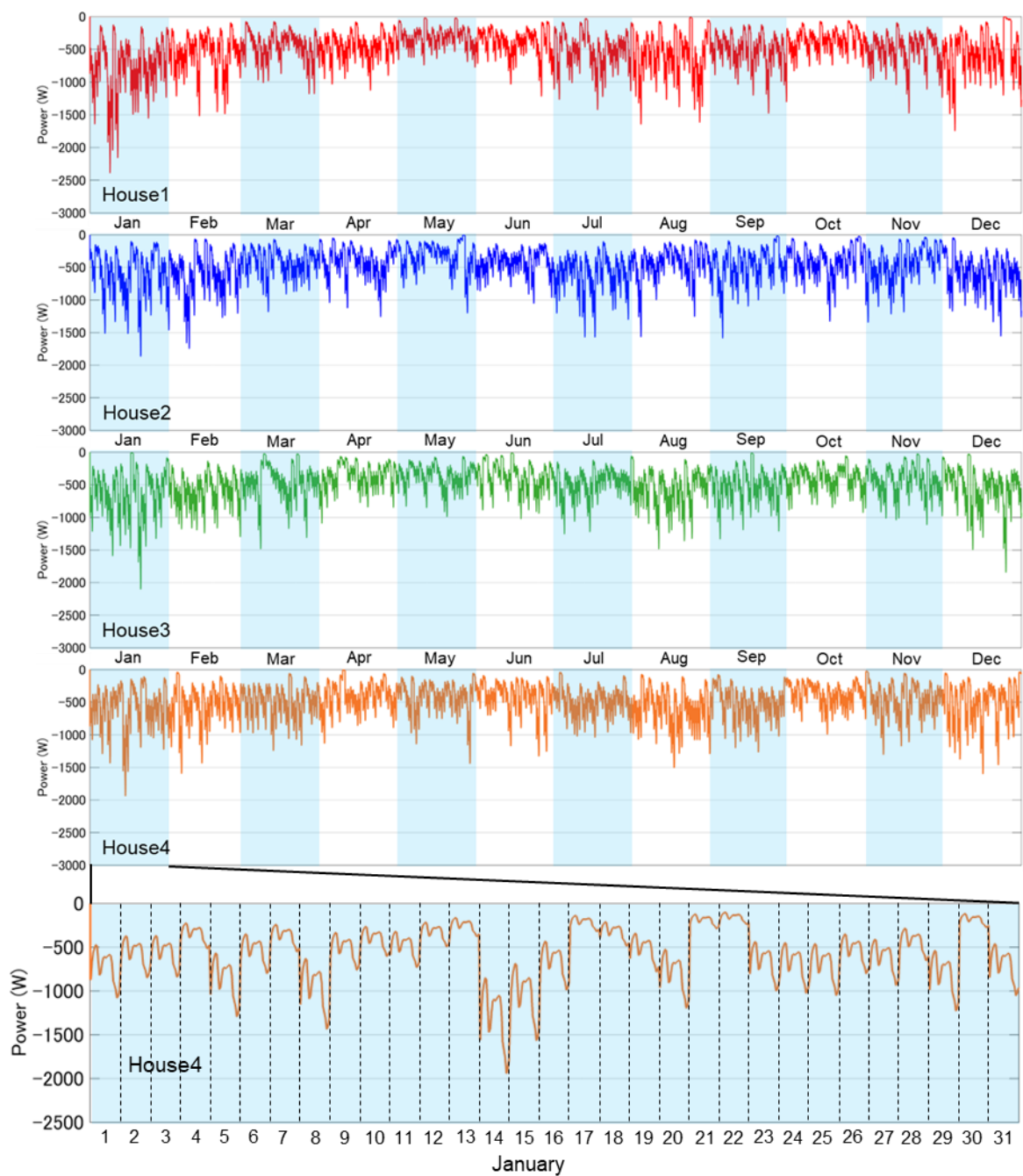


Figure 8. Annual variation in electricity consumption across the four households, along with a detailed view of the January variation for House4.

Figure 9 presents the annual variation in baseline voltage at each household’s connection point. Although temporal fluctuations occur, all voltages remain within the acceptable range of 340 V to 420 V. House 1, which is closest to the utility grid connection point, exhibits relatively small voltage fluctuations, while houses farther away show greater variation. In spring, high PV generation combined with moderate consumption leads to elevated voltage levels, whereas in winter, low generation results in voltages trending between 360 V and 380 V. Note that in this simulation, PV output is not curtailed even when baseline voltage is high; all generated power is absorbed into the microgrid.

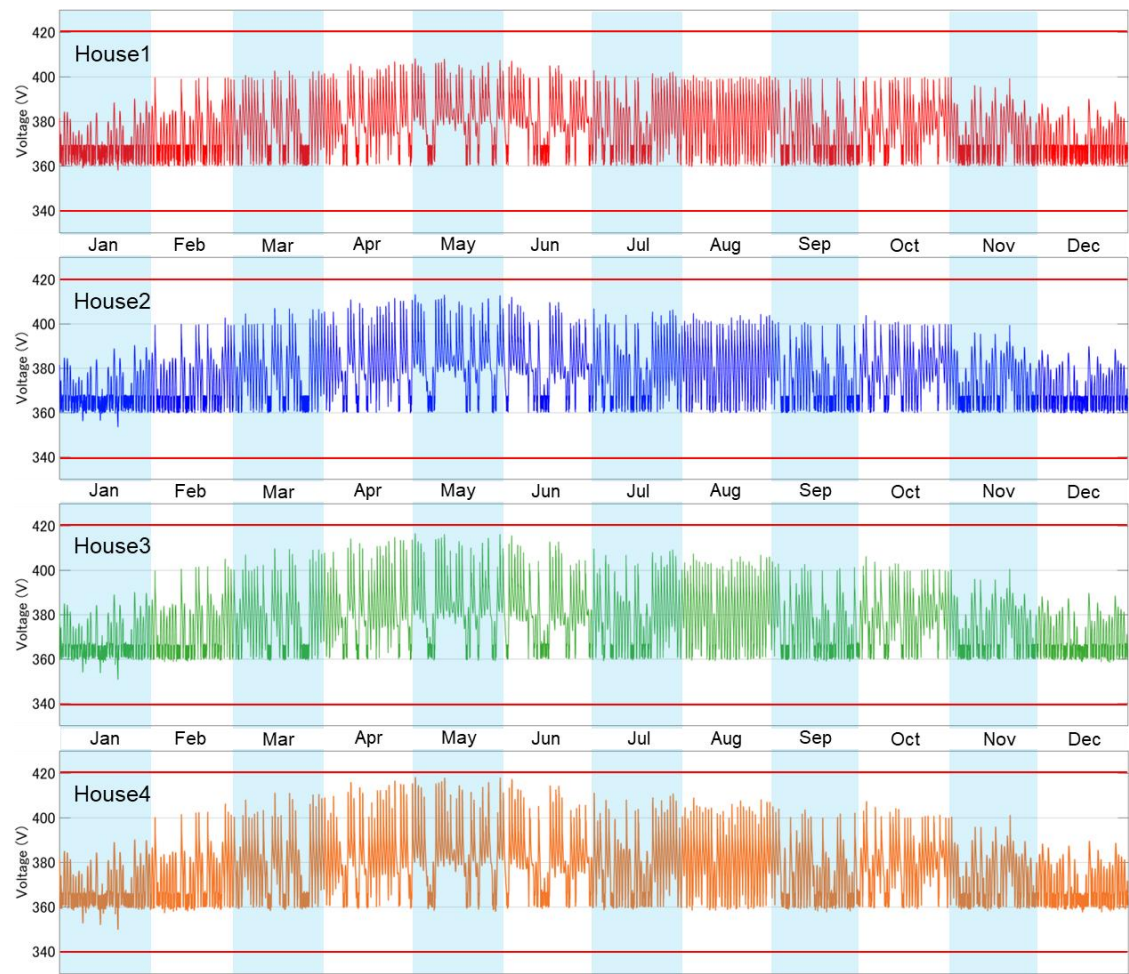


Figure 9. Annual variation in baseline voltage at each household’s connection point.

Figure 10 shows the charging and discharging power of the batteries installed in each house. Discharging is plotted as positive, and charging as negative. All batteries operate throughout the year, with Battery 1 (in House 1, near the grid connection point) exhibiting the most intense activity, reaching up to 4 kW. Figure 11 plots the cumulative charge/discharge current over time. Again, Battery 1 shows the highest activity, with an annual cumulative current of approximately 12 kAh. This corresponds to 120 full charge/discharge cycles for the installed 50 Ah battery. Given that lithium iron phosphate batteries typically have a cycle life of around 3,000 cycles [18–20], this suggests a battery lifetime of approximately 25 years.

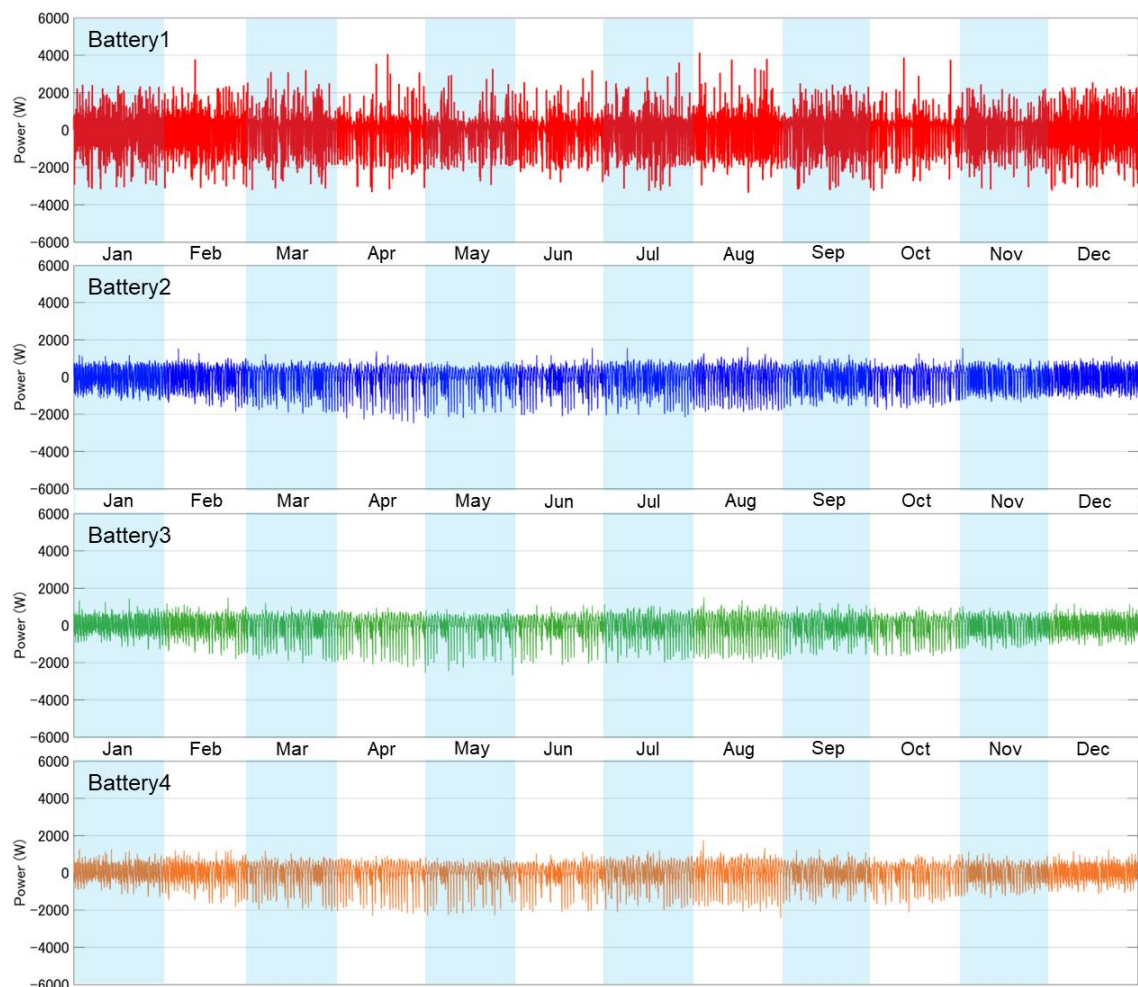


Figure 10. Annual variation of charging and discharging power of the batteries installed in each house.

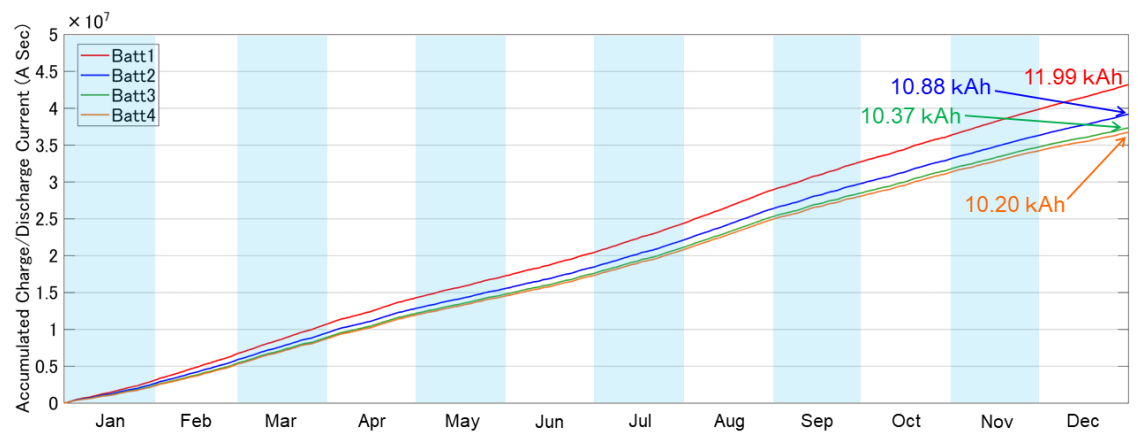


Figure 11. Cumulative charge/discharge current over time.

Figure 12 displays the current flowing through the baseline cables connecting the houses. Positive current indicates flow toward the right (away from the grid connection point). Cables closer to the grid (e.g., Cable 1) carry more current, but the maximum remains below 20 A — well within the 65 A rating of the 8 SQ CV cables. Thus, the maximum power transmitted through the baseline is around 7 kW, which is modest relative to the total load, confirming that power exchange is gradual and the grid remains weakly coupled.

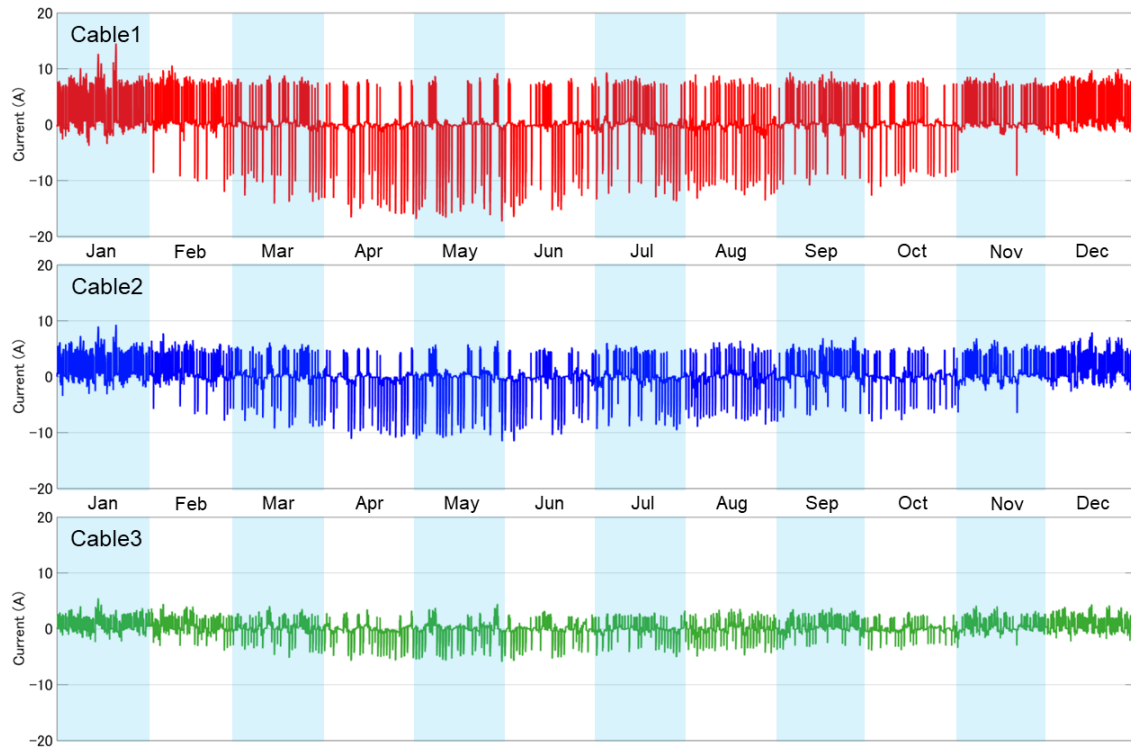


Figure 12. Current flowing through the baseline cables connecting the houses.

Figure 13 shows power exchange with the utility grid. Positive values indicate power received from the grid, and negative values indicate power sent to the grid. Naturally, more electricity is received from the utility grid in winter, and more electricity is sent to the utility grid from spring to summer.

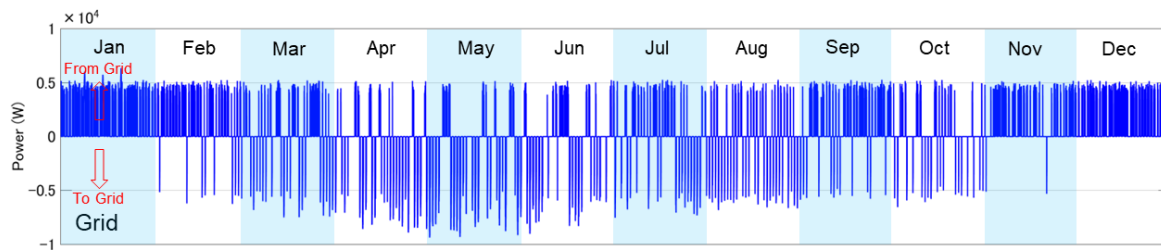


Figure 13. Power exchange with the utility grid.

Figure 14 shows the cumulative power consumption of the entire microgrid, the amount of power received from the utility grid, and the amount of power transmitted to the utility grid. Total annual consumption is 16.24 MWh, corresponding to approximately 338 kWh per household per month—closely matching the statistical value in Table 4. The annual amount of power received from the utility grid is 4.86 MWh, yielding a renewable energy ratio (RER) of approximately 70%, calculated using Equation (3):

$$\begin{aligned} \text{RER} &= \frac{\text{Total power consumption} - \text{Received power from utility grid}}{\text{Total power consumption}} \\ &= \frac{16.24 - 4.86}{16.24} = 0.7 \end{aligned} \quad (3)$$

If the RER is calculated using equation (4), which considers the amount of power transmitted to the utility grid, it becomes 89%.

$$\text{RER} = \frac{\text{Total power consumption} - \text{Received power from utility grid} + \text{Transmitted power to utility grid}}{\text{Total power consumption}}$$
$$= \frac{16.24 - 4.86 + 3.08}{16.24} = 0.89$$

(4)

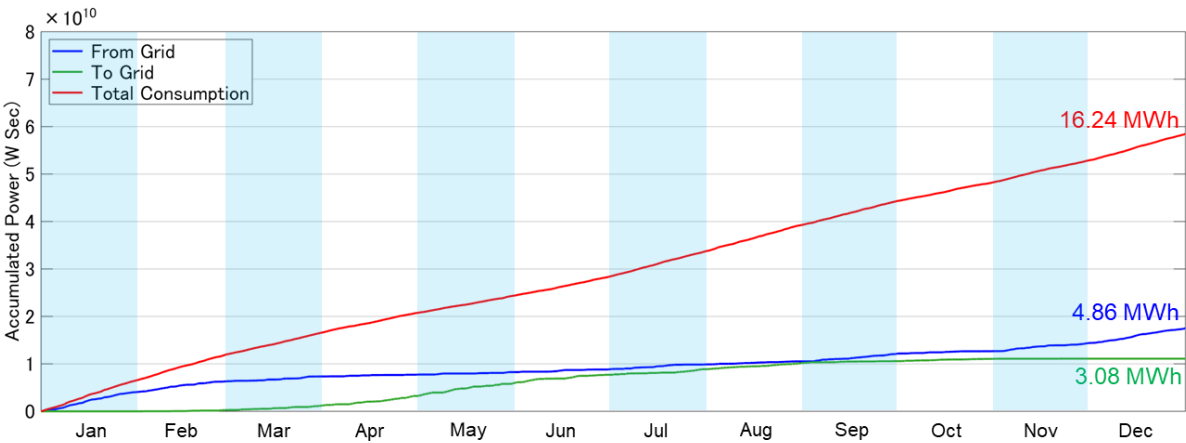


Figure 14. Cumulative power consumption, grid import, and grid export for the entire microgrid.

6.1. With an EV Charging Infrastructure

Next, we simulated the case where House 3 (the third house from the left in Figure 6) is equipped with EV charging infrastructure. In this scenario, EV charging occurs daily from midnight to 2:00 AM at 5 kW (10 kWh per session).

Figure 15 shows the annual baseline voltage variation at each household connection point. While House 1 remains within the acceptable range throughout the year, Houses 3 and 4—farther from the grid connection—occasionally fall below the lower voltage limit, as indicated by red circles. These events occur during nighttime EV charging, suggesting that even 5 kW of power load can significantly impact a microgrid of this scale.

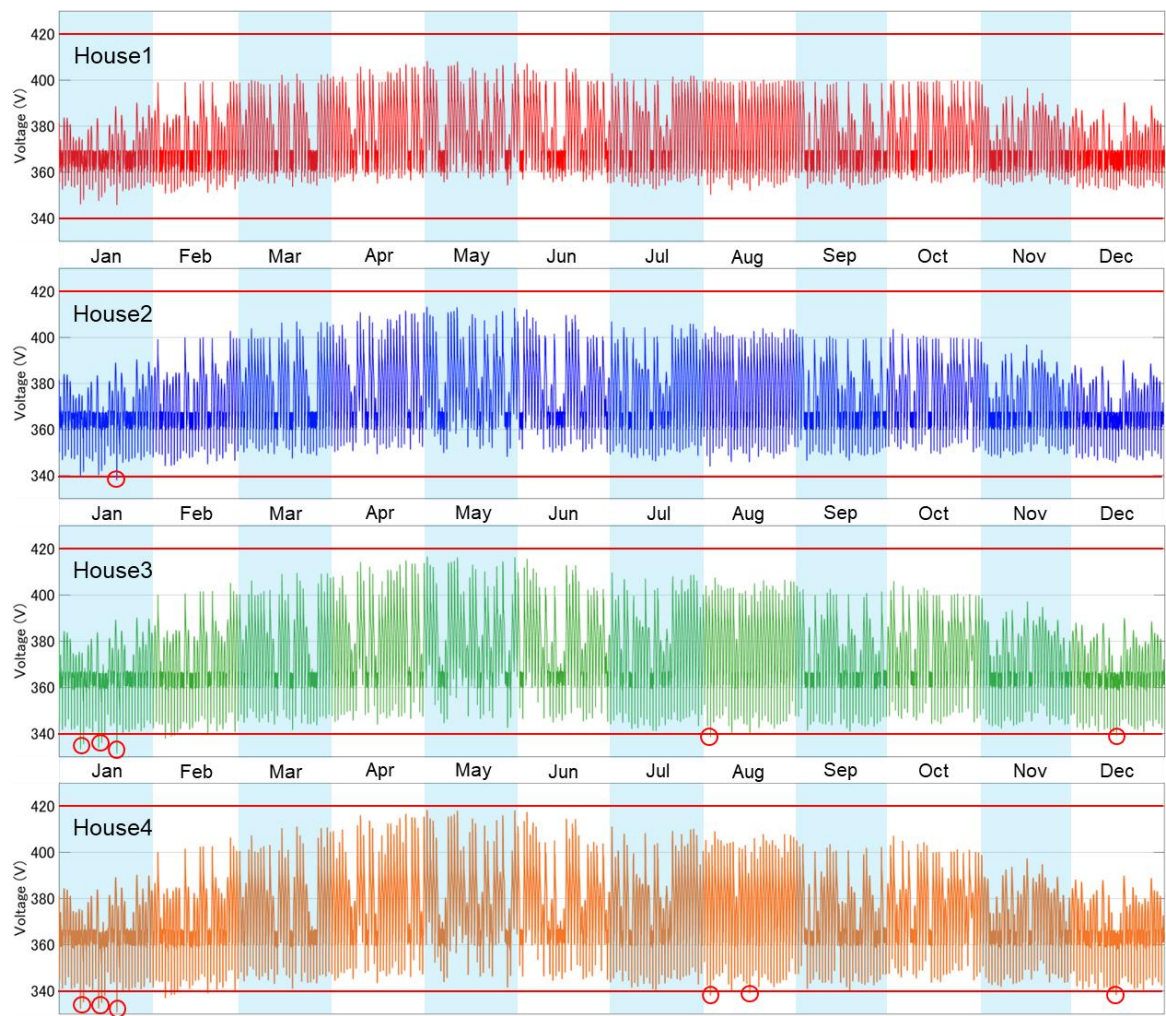


Figure 15. Annual variation in baseline voltage at each household’s connection point.

To mitigate this, we shifted the EV charging window to 2:00–4:00 AM, a period of lower household consumption as shown in Figure 5. Although the daily charging energy remains 10 kWh, the revised simulation (Figure 16) shows that voltage excursions below the acceptable range occur only once per year for Houses 3 and 4.

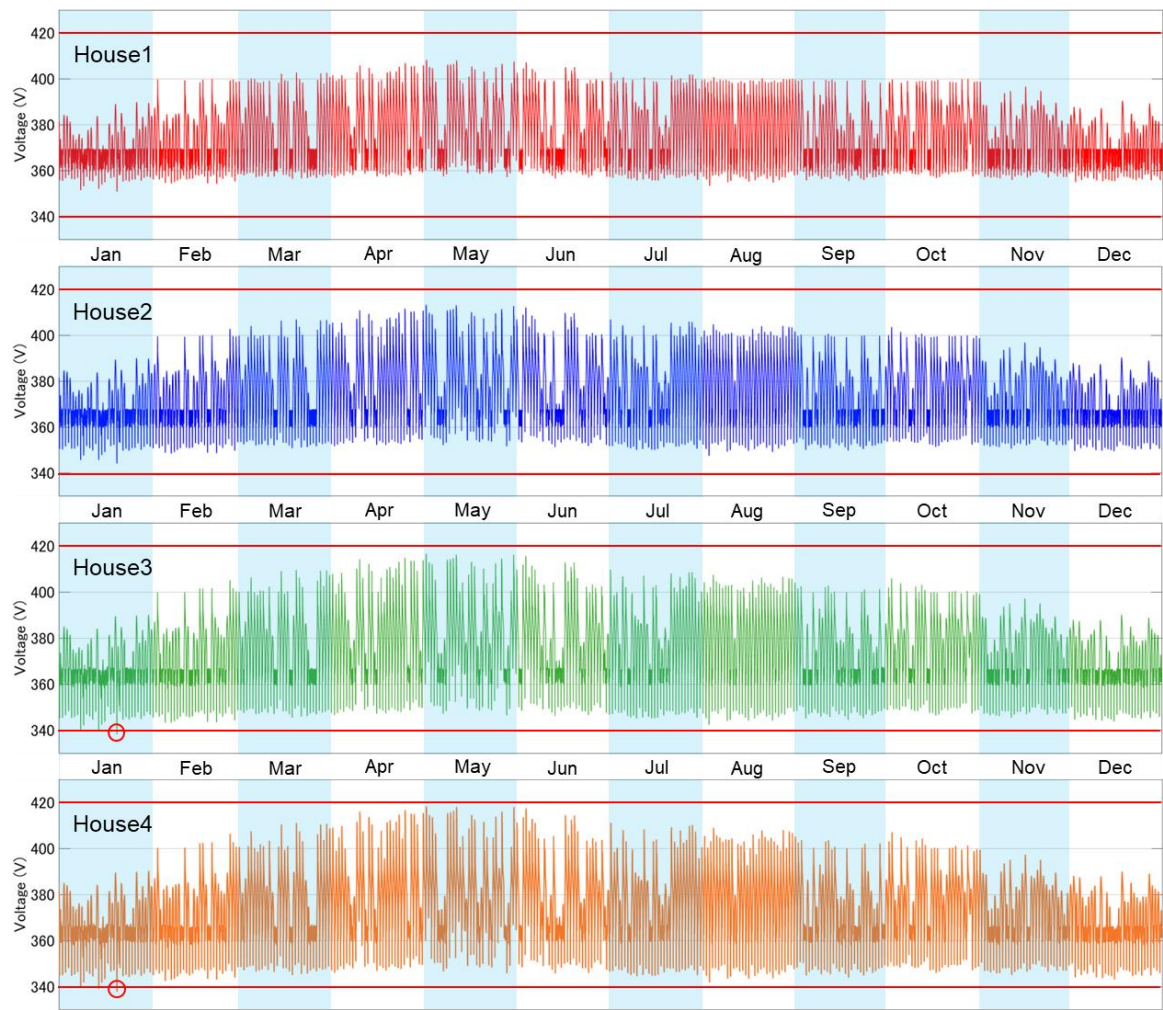


Figure 16. Annual variation in baseline voltage at each household’s connection point when EV charging times are shifted to between 2:00 and 4:00 AM.

In this case, the current flowing through the baseline is also within 20 A as shown in Figure 17. Figure 18 shows annual variation of charging and discharging power of the batteries installed in each house. In this case, Battery 1 continues to exhibit the most intense charge/discharge activity. The cumulative current (Figure 19) reaches 12.59 kAh, corresponding to an estimated battery lifetime of approximately 24 years.

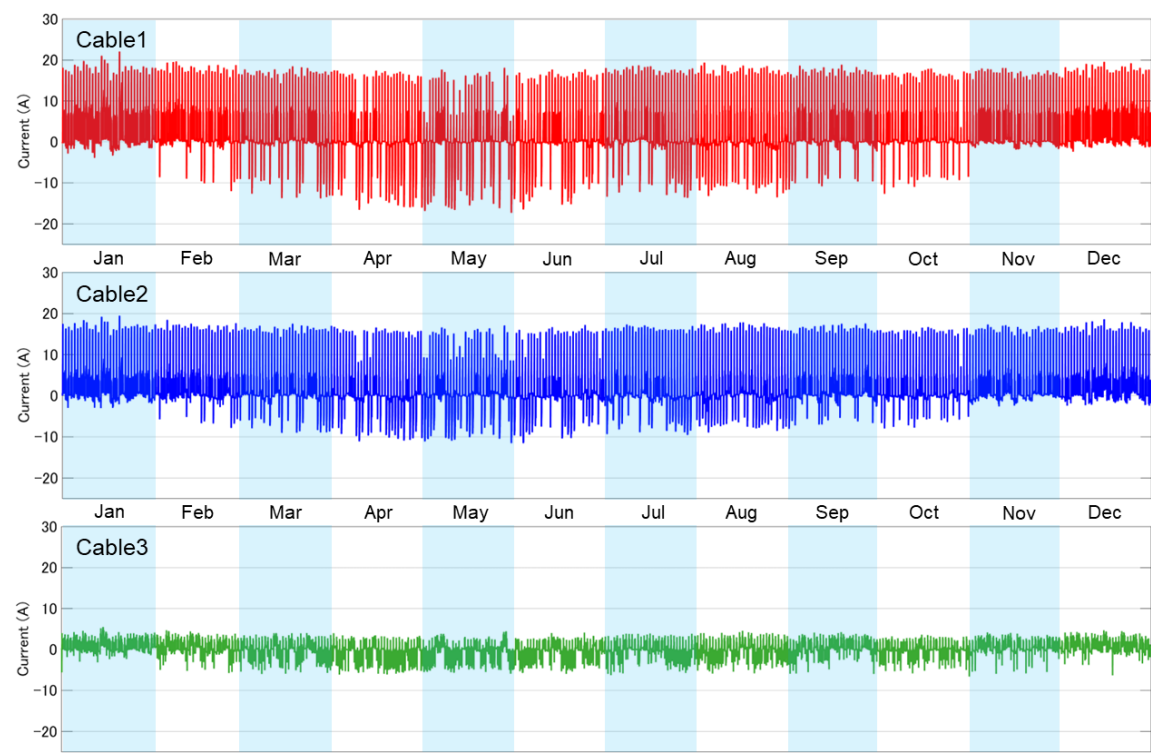


Figure 17. Current flowing through the baseline cables connecting the houses.

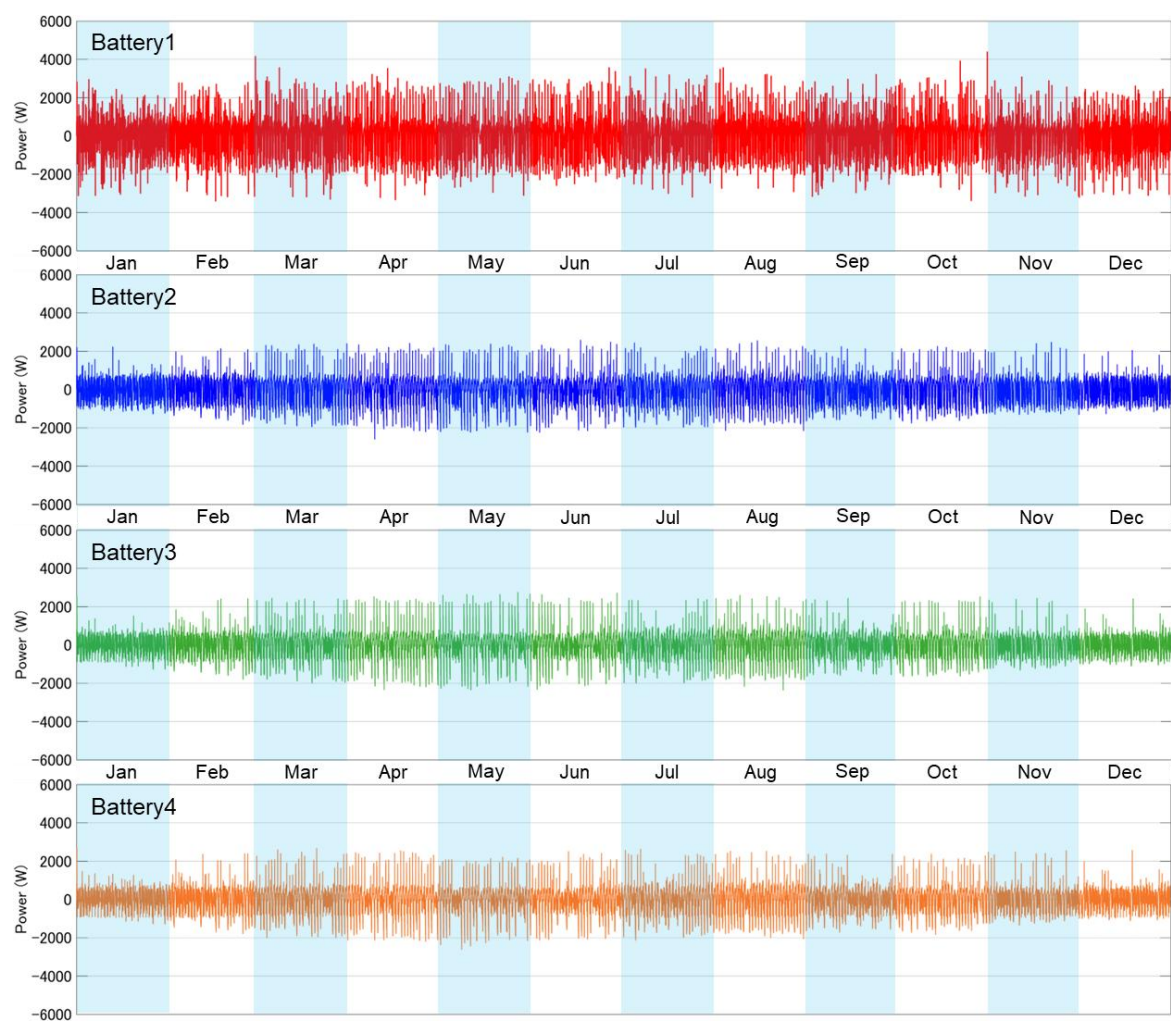


Figure 18. Annual variation of charging and discharging power of the batteries installed in each house.

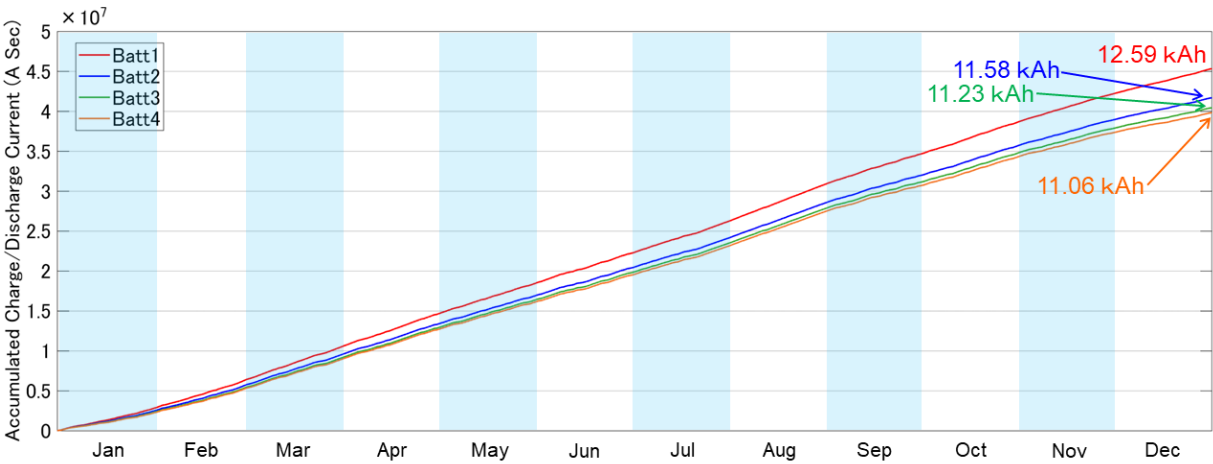


Figure 19. Cumulative charge/discharge current over time.

Figure 20 shows the cumulative power consumption of the entire microgrid, the amount of power imported from the utility grid, and the amount exported to it, in the scenario involving EV charging. Due to daily EV charging, the annual power consumption increases to 18.89 MWh, and the grid import rises to 8.27 MWh. Based on Equation (3), the renewable energy ratio is approximately 58%.

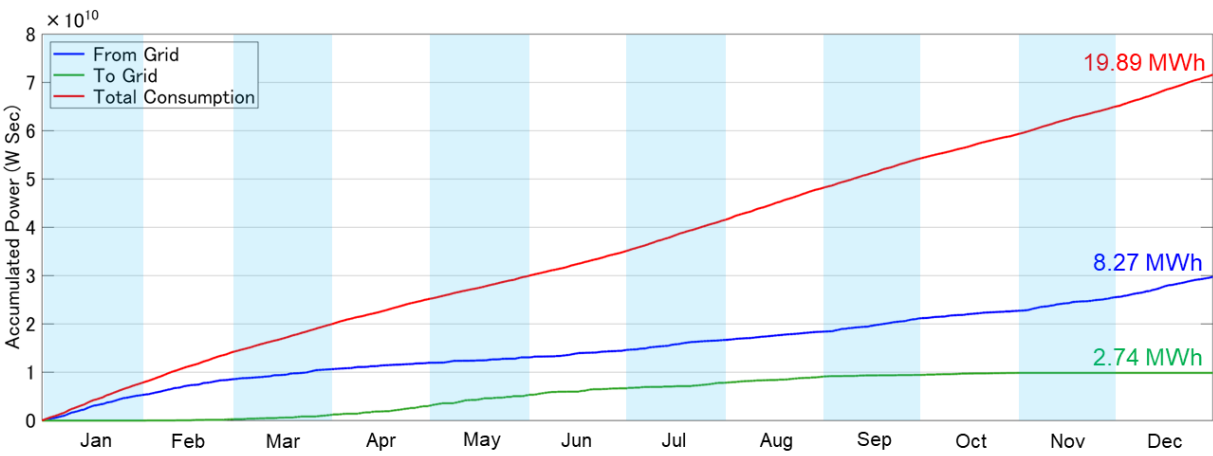


Figure 20. Cumulative energy consumption, grid import, and grid export for the entire microgrid.

7. Consideration of Required System Capacity

This section examines how the capacity of batteries and solar panels installed in each household affects the overall renewable energy ratio and grid stability. The simulation scenario is based on the case discussed in the previous section, where House 3 is equipped with EV charging infrastructure, and charging occurs daily from 2:00 AM to 4:00 AM.

In addition to the configuration—each household equipped with a 20 kWh battery and a 5 kW solar panel (installation efficiency: 50%)—we also evaluated cases with battery capacities of 5, 10, and 50 kWh, and solar panel rated outputs of 3 kW and 7 kW. The four-evaluation metrics were:

- 1. Renewable energy ratio (RER) calculated using Equations (3)
- 2. RER calculated using Equations (4)
- 3. Battery lifetime
- 4. Grid stability

Battery lifetime was estimated based on cumulative charge/discharge current, assuming lithium iron phosphate batteries with a cycle life of approximately 3,000 cycles. Grid stability was assessed by counting the number of annual instances in which the baseline voltage exceeded the allowable range; if this occurred more than three times per year, the grid was considered unstable.

Table 6 summarizes the simulation results for all combinations of battery and solar panel capacities. For each configuration, the upper-left value represents the RER calculated using Equation (3), the upper-right value using Equation (4), the lower-left value indicates battery lifetime in years, and the lower-right value shows the number of annual voltage excursions.

Compared to the baseline configuration (20 kWh battery and 5 kW solar panel), reducing the battery capacity to 10 kWh results in an RER below 50% (Equation 3), a shortened battery lifetime of 15 years, and six voltage excursions per year—indicating reduced performance and stability.

Similarly, reducing the solar panel output to 3 kW lowers both RER values below 50%, and results in four voltage excursions annually.

On the other hand, increasing the solar panel output to 7 kW yields an RER exceeding 100% (Equation 4), meaning annual generation surpasses consumption and grid export exceeds import. While this may not be problematic in itself, it poses a risk of excessive baseline voltage during high-generation periods in spring. Since generation curtailment was not applied in the simulation, the baseline voltage frequently exceeded the upper limit of the allowable range.

Increasing battery capacity to 50 kWh improves the RER to 68% (Equation 3) and extends battery lifetime to 53 years. However, this far exceeds the typical lifetime of solar panels and other electronic components (approximately 20 years), resulting in system imbalance and significantly higher costs.

Therefore, the configuration examined in the previous section—20 kWh battery and 5 kW solar panel—can be considered optimal in terms of performance, stability, and system balance.

Table 6. Summary of the impact of system capacity on RER, battery lifetime and grid stability.

Battery \ PV	3 kW		5 kW		7 kW	
	RER by eq. (3)	Battery lifetime	RER by eq. (4)	Number of errors	RER by eq. (3)	Battery lifetime
5 kWh	32%	8 years	43%	6	37%	9 years
	72%	6	40%	9 years	100%	>10
10 kWh	37%	16 years	43%	4	46%	15 years
	72%	6	65%	15 years	101%	>10
20 kWh	42%	29 years	43%	4	58%	24 years
	72%	2	81%	22 years	101%	>10
50 kWh	43%	67 years	43%	0	68%	53 years
	73%	0	81%	45 years	102%	>10

8. Conclusion

This study examined the configuration and characteristics of a DC microgrid designed for residential deployment, with the aim of realizing an eco-friendly lifestyle based on local production and consumption of solar-generated renewable energy. To ensure resilience against disasters and enable open, democratic management by local residents, we proposed a novel DC microgrid architecture based on autonomous decentralized cooperative control and a battery-integrated baseline.

In this configuration, the batteries directly connected to the grid baseline fulfill the essential functions of grid forming and maintaining. As a result, individual power devices—such as generators and loads—only need to monitor the voltage of the baseline to which they are connected. By

autonomously regulating their power exchange with the baseline to avoid destabilizing the grid, control complexity is significantly reduced.

To realize autonomous decentralized cooperative control, each device must operate independently, without interference from neighboring devices. This requires a weakly coupled grid structure, where electrical coupling between devices is sufficiently limited. We demonstrated that this can be achieved by ensuring that the CR time constant—determined by the dynamic capacitance of distributed batteries and the conductor resistance of the baseline—is much larger than the control time constant τ of each device. Consequently, the influence of neighboring devices on a given sensing point is relatively slow and minor, preserving control independence.

A DC microgrid model comprising four typical residential houses was constructed in MATLAB/Simulink, and its behavior was analyzed over one year under realistic conditions in a Japanese city. The results showed that equipping each household with a 5 kW solar panel and a 20 kWh battery enables stable grid operation and sustainable living with a renewable energy ratio exceeding 50%. Using lithium iron phosphate batteries with a cycle life of approximately 3,000 cycles, a service life of around 25 years can be expected—comparable to that of solar panels and other electronic components—resulting in a well-balanced and durable system.

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Abbreviations

The following abbreviations are used in this manuscript:

AC	Alternative current
CV cable	Cross-linked polyethylene insulated Vinyl sheath cable
DC	Direct current
EMS	Energy management system
EV	Electric Vehicle
MPPT	Maximum power-point tracking
OSI	Open systems interconnection
PV	photovoltaic
RES	Renewable energy source
SoC	State of charge
SQ	square millimeters (mm ²)

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