

Generalized nonlinear constitutive law applied to steel trapezoidal sheet plates

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ABSTRACT: In the paper, a modified nonlinear finite element method for analysis of trapezoidal plates geometrically reduced to shallow-shell Reissner-Mindlin formulation is presented. Due to the method proposed the complex plate cross-section and nonlinear materials may be modelled and no implementation of advanced constitutive law via user subroutines is needed. The generalized nonlinear constitutive law is used to update the stiffness of the plate element. The method enables modeling of complicated cross-sections, such as steel trapezoidal sheets, metal facing sandwich panels or reinforced concrete. Additionally, for those geometrically complex sections an advanced nonlinear material may be adopted. To verify the proposed method, a selected trapezoidal sheets were modeled in a commercial software as full 3D shell structures. By comparing displacements and forces, it was shown that both models behave almost identically, however, the simplified model has about 300-400 times less degrees of freedom, thus it is much more efficient.

1 INTRODUCTION

Steel trapezoidal plates are common structures used in civil engineering to cover roofs of industrial buildings. Such structures are easy to produce, transport and install at the building site. Due to its specific structure, they are light and have a very high ratio of load capacity to its mass. They are cheap, both as the material itself and in installation, and especially profitable, if there is a large plain roof area to cover. Its main disadvantage is low acoustic insulation, however, this is usually not the problem for industrial buildings such as warehouses or production halls.

Typical designing of such structures is easy due to detailed technical catalogues with load capacity tables included and released by its producers. However, for deeper strength analysis of the whole system of roofing, namely, steel trapezoidal sheets, bearing beams, roof windows, inspection holes, etc., such a simplified approach seems to be useless. Also, the formulas according to international standards, such as PN-EN 1993-1-3: 2008 - Eurocode 3 are pointless to apply. Moreover, if one would like to take into account a nonlinear aspect of steel or any other material in the system, only the detailed numerical model, for example utilizing a finite element method may give the reliable answer.

On the other hand, simulating the full geometry of the trapezoidal sheets may lead to a computationally very expensive models. In the recent 2020 paper of Zakhimi et al., one may find differentiation on three generations of sheeting, namely, unstiffened (see Figure 1a), longitudinally stiffened (see Figure 1b-c), and longitudinally and transversely stiffened. Stiffening is obtained by embossing the sheets. Steel sheets have not only simple idealized trapezoidal shapes, like in Figure 1a, but also more challenging shapes with embossing in two directions to model, see Figure 1b-c. Those profiling sheets due to its additional longitudinal and transverse stiffness are also in common use. The examples of detailed modelling of trapezoidal sheets are

for instance available in the papers of Franco & Batista (2017) or Flodr et al. (2014). Franco & Batista analyzed what should be the outlines for longitudinal stiffeners called also intermediate stiffeners, in order to maximize the strength and economical objectives. Flodr et al. (2014) considered several numerical models with progressive complexity of modeling. In the paper, in each case the full geometry of trapezoidal sheets was used. As shown, this leads to computationally expensive models. The analytic approach, like the one shown by Mohammadi et al. (2015), is an alternative way to model steel trapezoidal sheets; this approach is not as versatile as the computational approach.

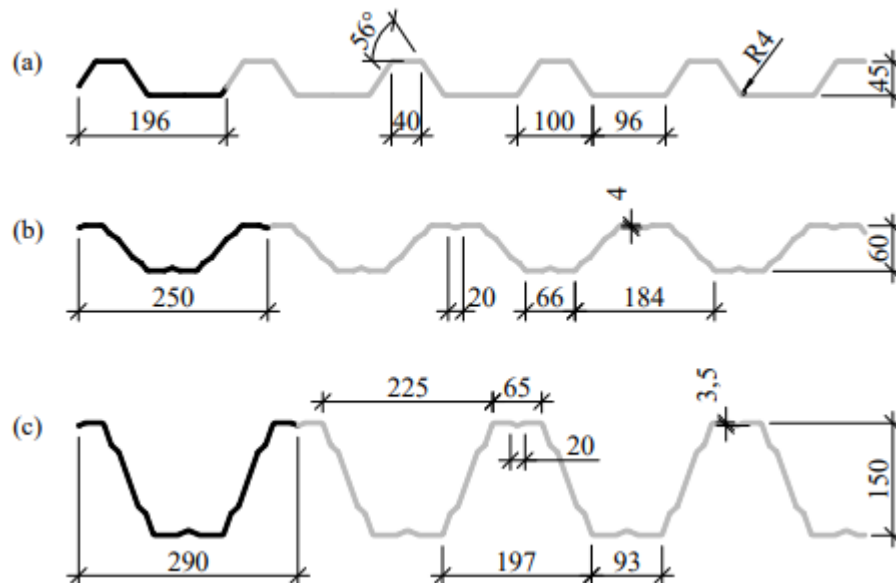


Figure 1. Examples of cross-sections of steel trapezoidal sheets used in civil engineering (a) T45 ($h = 45$ mm), (b) T60 ($h = 60$ mm) and (c) T150 ($h = 150$ mm).

The objective of this paper is to introduce the computational approach to simplify the modelling of the full geometry of trapezoidal sheets in order to obtain a faster and comparably accurate model of finite element method. Finite element method is currently the leading method used for strength analysis of structures. Thus, the proposed modification may be easily implemented in common engineering softwares, without the need of advanced knowledge of finite element special techniques or nonlinear material modelling. The approach utilized in this paper is called the generalized nonlinear constitutive law (GNCL). In the literature, for instance, it was applied to model beams and frame structures as an attractive alternative of modelling full 3D geometries and nonlinear complex constitutive laws of steel or concrete in composite structures, see Łodygowski (1982), Łodygowski & Szumigala (1992) and Szumigala (2007). In the paper of Mrówczyński et al. (2021), among others, the method was updated with the possibility of including shear effects (Timoshenko theory). The aim of this paper is to apply the GNCL method to model plate structures, in particular to effectively model steel trapezoidal sheets. The concept is original and was not applied before for plate structures. Otherwise the method is easy to use, if one would like to take into consideration in a simple plate modelling not only a complex geometry, but also material nonlinearities of steel instead of building an advanced and computationally expensive FEM model.

2 METHODS & MATERIALS

In Figure 2a, the overall algorithm of the proposed method is presented. After defining the input data (i.e. node coordinates, boundary conditions and cross-sections), the node displacements and internal forces are computed by using the finite element method. Based on the nodal displacements, the strains (normal strains ϵ_0 , shear strains γ and curvature κ) are computed, which makes it possible to determine the reduced stiffness of each element. For new stiffnesses, the displacements are computed and subsequent iterations are carried out until the increment of structure displacements is smaller than the assumed tolerance.

In Figure 2b, the stiffness reduction function begins with the division of the cross-section into smaller layers for which the areas and position are determined. Based on the strains determined in the main part of the algorithm, the reduced strains in each layer are determined, and then the reduced stresses, element stiffnesses and the position of the neutral axis are computed. Successive iterations are performed until the change of the position of the neutral axis is smaller than the assumed tolerance. The mathematical formulation of the method proposed may be found in Mrówczyński et al. (2021).

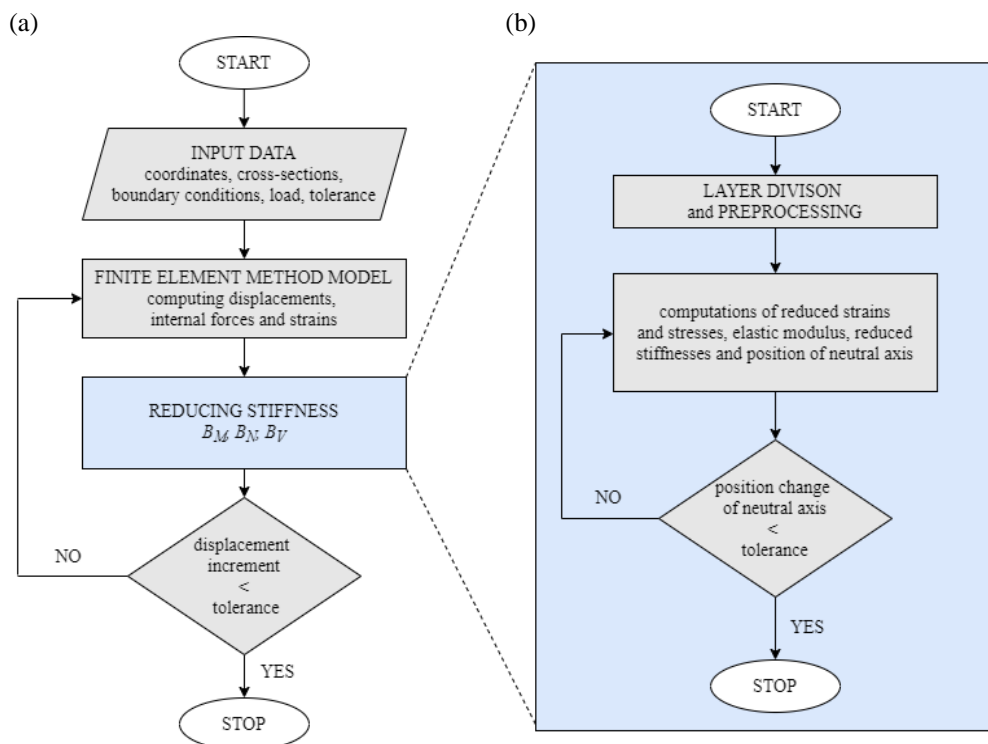


Figure 2. The GNCL algorithm: (a) the overall scheme and (b) the stiffness reduction function (where B_M is bending stiffness. B_N is tensile stiffness and B_V is shear stiffness)

Reissner–Mindlin plate is considered in this paper. Assuming the xyz coordinate system, the displacement field for plates reads:

$$u(x, y, z) = -z\theta_x(x, y), \quad (1)$$

$$v(x, y, z) = -z\theta_y(x, y), \quad (2)$$

$$w(x, y, z) = w_0(x, y), \quad (3)$$

where u , v are two in-plane mid-surface displacements, while w is out of plane mid-surface displacement of the plate; θ_x and θ_y are two rotations of the normal on the plane xz and yz :

$$\theta_x = \partial w / \partial x + \phi_x; \quad \theta_y = \partial w / \partial y + \phi_y, \quad (4)$$

noting that $\gamma_x = -\phi_x$ and $\gamma_y = -\phi_y$.

In both the xz and yz vertical planes, the normal rotation was obtained as the sum of two rotations: (i) the corresponding slope of the middle plane of the plate and (ii) the additional rotation ϕ , which results from the lack of orthogonality of the normal to the middle plane after deformation. Therefore, the rotations θ_x and θ_y cannot be calculated from the deflection only and become independent variables. This is the fundamental difference between Reissner–Mindlin and Kirchhoff–Love plate theories. Relationships between strains (membrane— $\boldsymbol{\varepsilon}$, bending— $\boldsymbol{\kappa}$ and shear— $\boldsymbol{\gamma}$) and displacements are:

$$\boldsymbol{\epsilon} = \boldsymbol{\varepsilon} + z\boldsymbol{\kappa}, \quad (5)$$

$$\boldsymbol{\varepsilon} = \begin{bmatrix} \varepsilon_x \\ \varepsilon_y \\ \gamma_{xy} \end{bmatrix} = \begin{bmatrix} \partial u / \partial x \\ \partial v / \partial y \\ \partial u / \partial y + \partial v / \partial x \end{bmatrix} = -z \begin{bmatrix} \partial \theta_x / \partial x \\ \partial \theta_y / \partial y \\ \partial \theta_x / \partial y + \partial \theta_y / \partial x \end{bmatrix}, \quad (6)$$

$$\boldsymbol{\kappa} = \begin{bmatrix} \kappa_x \\ \kappa_y \\ \kappa_{xy} \end{bmatrix} = - \begin{bmatrix} \partial \theta_x / \partial x \\ \partial \theta_y / \partial y \\ \partial \theta_x / \partial y + \partial \theta_y / \partial x \end{bmatrix} = - \begin{bmatrix} \partial^2 w / \partial x^2 \\ \partial^2 w / \partial y^2 \\ \partial^2 w / \partial x \partial y \end{bmatrix}, \quad (7)$$

$$\boldsymbol{\gamma} = \begin{bmatrix} \gamma_{xz} \\ \gamma_{xy} \end{bmatrix} = \begin{bmatrix} \partial w / \partial x + \partial u / \partial z \\ \partial w / \partial y + \partial v / \partial z \end{bmatrix} = \begin{bmatrix} \partial w / \partial x - \theta_x \\ \partial w / \partial y - \theta_y \end{bmatrix} = \begin{bmatrix} -\phi_x \\ -\phi_y \end{bmatrix}. \quad (8)$$

The stress–strain relations in local coordinates are given by:

$$\begin{bmatrix} \sigma_x \\ \sigma_y \\ \sigma_{xy} \end{bmatrix} = \frac{E}{1-\nu^2} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1-\nu}{2} \end{bmatrix} \begin{bmatrix} \varepsilon_x \\ \varepsilon_y \\ \gamma_{xy} \end{bmatrix}, \quad (9)$$

$$\begin{Bmatrix} \sigma_{xz} \\ \sigma_{yz} \end{Bmatrix} = \frac{kE}{2(1+\nu)} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{Bmatrix} \gamma_{xz} \\ \gamma_{yz} \end{Bmatrix}, \quad (10)$$

where k is a shear correction factor, or in the compact form

$$\boldsymbol{\sigma} = \mathbf{C} \boldsymbol{\varepsilon}, \quad \boldsymbol{\tau} = \mathbf{C}_s \boldsymbol{\gamma}. \quad (11)$$

The strain energy, U , reads

$$U = \frac{1}{2} \int_A (\boldsymbol{\varepsilon}^T \mathbf{D}^* \boldsymbol{\varepsilon} + \boldsymbol{\gamma}^T \mathbf{D}_s^* \boldsymbol{\gamma}) dA, \quad (12)$$

where

$$\mathbf{D}^* = \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B} & \mathbf{D} \end{bmatrix}, \quad \mathbf{D}_s^* = \mathbf{D}_s \quad (13)$$

and \mathbf{A} , \mathbf{B} , \mathbf{D} and \mathbf{D}_s are stiffnesses of the plates given by:

$$(\mathbf{A}, \mathbf{B}, \mathbf{D}) = \frac{1}{P} \iint \mathbf{C}(1, z, z^2) dx dz, \quad (14)$$

$$\mathbf{D}_s = \frac{1}{P} \iint \mathbf{C}_s dx dz, \quad (15)$$

where P is a wavelength period. For the sake of simplicity, the same stiffness in the y direction was used, which is obviously a false assumption, but does not disturb the solution of the considered here a problem of a unidirectional bending of the plate.

If the matrix \mathbf{B} becomes $\mathbf{0}$ then the membrane and bending effects are uncoupled and the neutral plane coincided with the plane xy . This means that the bending moments did not cause any membrane strains and the normal forces did not cause any curvature.

3 COMPUTATIONAL EXAMPLES

Here, three examples of a trapezoidal sheet with the cross-sections presented in Figure 1 are considered. The material parameters used in the reference model were selected in accordance with the specifications provided by the manufacturer. The initial sheet stiffnesses were calculated on the basis of equations (14) and (15), the characteristics used to compute \mathbf{A} , \mathbf{B} , \mathbf{D} and \mathbf{D}_s matrices are presented in Table 1.

Table 1. Cross-section characteristics of trapezoidal sheets in x-z plane.

Cross-section	Area [cm ²]	Inertia moment [cm ⁴]	Sheet thickness [mm]	Neutral axis position [cm]
T45	1.214	3.365	0.50	2.798
T60	1.516	8.285	0.50	3.029
T150	4.884	144.397	1.00	7.927

The reference models were built and calculated in Abaqus using S4 shell elements with 4 nodes and 6 degrees of freedom at each node. The number of finite elements used in each model was selected to accurately reproduce the cross-sectional geometry of the trapezoidal sheet and was equal to 15,678, 23,450, 22,244 for T45, T60 and T150, respectively. A static nonlinear displacement control analysis was used to generate force-displacement curves for later comparison with the curves obtained from the proposed algorithm described in Section 2, using simple shallow plate elements and GNCL.

4 COMPUTATIONAL RESULTS

In Figure 3, the deformed geometry of three trapezoidal sheets are presented, which were obtained from the full geometry reference models. The GNCL algorithm ensures the correct mapping of displacements, the stresses are calculated separately to reduce the equivalent stiffness. Later, only the section forces and moments are available.

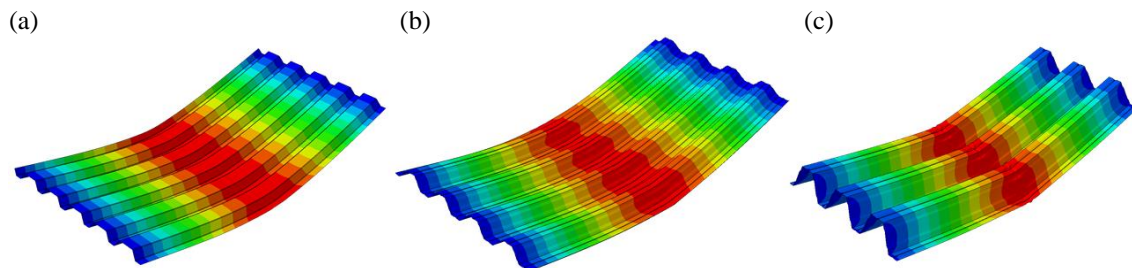


Figure 3. Displacement fields of finite element reference models for (a) T45 (15678 elements), (b) T60 (23450 elements) and (c) T150 (22244 elements).

Figure 4 shows a comparison of the force-displacement curves obtained from the reference models and from the simplified approach based on a simple shallow plate finite element (50 elements) and the GNCL algorithm described in Section 2. It should be noted that the number of elements used in the simplified (GNCL) models was about 300-400 times smaller than the number of elements used in the reference models.

Figures 3 and 4 show that the simplified methods presented here give results that both qualitatively and quantitatively do not differ from the results obtained from the reference models. The difference between the maximal values of force is not greater than 10 %, what is acceptable in civil structures, in which the safety factors are much greater. This shows that the approach proposed here can be successfully applied to such calculations.

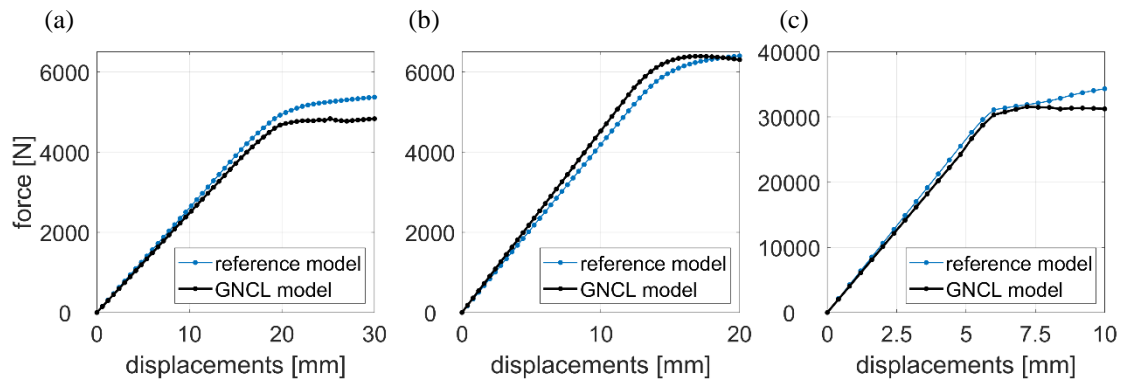


Figure 4. Force vs. displacement plots for trapezoidal sheet of (a) T45, (b) T60 and (c) T150.

5 CONCLUSIONS

In the paper, the generalized nonlinear constitutive law was applied to steel trapezoidal sheet plates. The comparison between the modelling of full geometry of trapezoidal sheets and simplified approach of GNCL algorithm was presented for three trapezoidal sheets commonly used by designers of such structures. As shown, using the full geometry leads to computationally expensive models. On the contrary, the GNCL method not only, enables faster and similar accurate computations, but also enables, utilizing the material nonlinearities.

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