

ON SLICED SPACES: GLOBAL HYPERBOLICITY REVISITED

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Abstract

We give a topological condition for a generic sliced space to be globally hyperbolic, without any hypothesis on the lapse function, shift function and spatial metric.

1 Preliminaries.

We begin with the definition of a *sliced space*, that one can read in [3], as a continuation of a study in [1] and [2] on systems of Einstein equations.

Let $V = M \times I$, where M is an n -dimensional smooth manifold and I is an interval of the real line, \mathbb{R} . We equip V with a $n + 1$ -dimensional Lorentz metric g , which splits in the following way:

$$g = -N^2(\theta^0)^2 + g_{ij}\theta^i\theta^j,$$

where $\theta^0 = dt$, $\theta^i = dx^i + \beta^i dt$, $N = N(t, x^i)$ is the *lapse function*, $\beta^i(t, x^j)$ is the *shift function* and $M_t = M \times \{t\}$, spatial slices of V , are spacelike submanifolds equipped with the time-dependent spatial metric $g_t = g_{ij}dx^i dx^j$. Such a product space V is called a *sliced space*.

Intuitively, the lapse and shift functions indicate how to relate coordinates between two slices M_t and $M_{t'}$; the lapse measuring time and the shift measuring changes in spatial coordinates.

For simplicity, we will consider $I = \mathbb{R}$.

The author in [3] considered sliced spaces with uniformly bounded lapse, shift and spatial metric; by this hypothesis, it is ensured that parametre t measures up to a positive factor bounded (below and above) the time along the normals to spacelike slices M_t , the g_t norm of the shift vector β is uniformly bounded by a number and the time-dependent metric $g_{ij}dx^i dx^j$ is uniformly bounded (below and above) for all $t \in I (= \mathbb{R})$, respectively.

Given the above hypothesis, in the same article the following theorem is proved.

Theorem 1.1 (Cotsakis). *Let (V, g) be a sliced space with uniformly bounded lapse N , shift β and spatial metric g_t . Then, the following are equivalent:*

1. (M_0, γ) a complete Riemannian manifold.
2. The spacetime (V, g) is globally hyperbolic.

In this article we review global hyperbolicity of sliced spaces, in terms of the product topology defined on the space $M \times \mathbb{R}$, for some finite dimensional smooth manifold M .

2 Strong Causality of Sliced Spaces.

Let $V = (M \times \mathbb{R}, g)$ be a sliced space. Consider the product topology T_P , on V . Since M is finite-dimensional, a base for T_P consists of all sets of the form $A \times B$, where $A \in T_M$ and $B \in T_{\mathbb{R}}$. Here T_M denotes the natural topology of the manifold M where, for an appropriate Riemann metric h , it has a base consisting of open balls $B_\epsilon^h(x)$ and $T_{\mathbb{R}}$ is the usual topology on the real line, with a base consisting of open intervals (a, b) . For trivial topological reasons, we can restrict our discussion on T_P to basic-open sets $B_\epsilon^h(x) \times (a, b)$, which can be intuitively called as “open cylinders” in V .

We remind the the Alexandrov topology T_A (see [4]) has a base consisting of open sets of the form $\langle x, y \rangle = I^+(x) \cap I^-(y)$, where $I^+(x) = \{z \in V : x \ll z\}$ and $I^-(y) = \{z \in V : z \ll y\}$, where \ll is the *chronological order* defined as $x \ll y$ iff there exists a future

oriented timelike curve, joining x with y . By $J^+(x)$ one denotes the topological closure of $I^+(x)$ and by $J^-(y)$ that one of $I^-(y)$.

We use the definition of global hyperbolicity from [4].

Definition 2.1. *A spacetime is globally hyperbolic, iff it is strongly causal and the “causal diamonds” $J^+(x) \cap J^-(y)$ are compact.*

We prove the following theorem.

Theorem 2.1. *Let (V, g) be a Hausdorff sliced space. Then, the following are equivalent.*

1. V is strongly causal.
2. $T_A \equiv T_P$.
3. T_A is Hausdorff.

Proof. 2. implies 3. is obvious and that 3. implies 1. can be found in [4].

For 1. implies 2. we consider two events $X, Y \in V$, such that $X \neq Y$; we note that each $X \in V$ has two coordinates, say (x_1, x_2) , where $x_1 \in M$ and $x_2 \in \mathbb{R}$. Obviously, $X \in M_x = M \times \{x\}$ and $Y \in M_y = M \times \{y\}$. Then, $\langle X, Y \rangle = I^+(X) \cap I^-(Y) \in T_A$. Let also $A \in M_a = M \times \{a\}$, where $a < x$ ($<$ is the natural order on \mathbb{R}) and $B \in M_b = M \times \{b\}$, where $y < b$. Consider some $\epsilon > 0$, such that $B_\epsilon^h(A) \in M$. Obviously, $B_\epsilon^h(A) \times (a, b) \in T_P$ and, for $\epsilon > 0$ sufficiently large enough, $\langle X, Y \rangle \subset B_\epsilon^h(A) \times (a, b)$. Thus, $\langle X, Y \rangle \in T_P$.

For 2. implies 1. we consider $\epsilon > 0$, such that $B_\epsilon^h(A) \in T_M$, so that $B_\epsilon^h(A) \times (a, b) = B \in T_P$. We let strong causality hold at an event P and consider $P \in B \in T_P$. We show that there exists $\langle X, Y \rangle \in T_A$, such that $P \in \langle X, Y \rangle \subset B$. Now, consider a simple region R in $\langle X, Y \rangle$ which contains P and $P \in Q$, where Q is a causally convex-open subset of R . Thus, we have $U, V \in Q$, such that $P \in \langle U, V \rangle \subset Q$. Finally, $P \in \langle U, V \rangle \subset Q \subset B$ and this completes the proof. \square

3 Global Hyperbolicity of Sliced Spaces, Revisited.

For the following theorem, we use Nash’s theorem, that finite-dimensional manifolds satisfy the Heine-Borel theorem (see [5]).

Theorem 3.1. *Let (V, g) be a Hausdorff sliced space, where $V = M \times R$, M is an n -dimensional manifold and g the $n+1$ Lorentz metric in V . Then, (V, g) is globally hyperbolic, iff $T_P = T_A$, in V .*

Proof. Given the proof of Theorem 2.1, strong causality in V holds iff $T_P = T_A$ and given Nash's theorem, the closure of $B_\epsilon^h(x) \times (a, b)$ will be compact. \square

We note that neither in Theorem 2.1 nor in Theorem 3.1 we made any hypothesis on the lapse function, shift function or on the spatial metric.

References

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